

Totally Integrated Automation Portal		
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Change Position of Robot [FC6]

Change Position of Robot Properties

General

Name	Change Position of Robot	Number	6	Type	FC	Language	LAD
Numbering	Automatic						

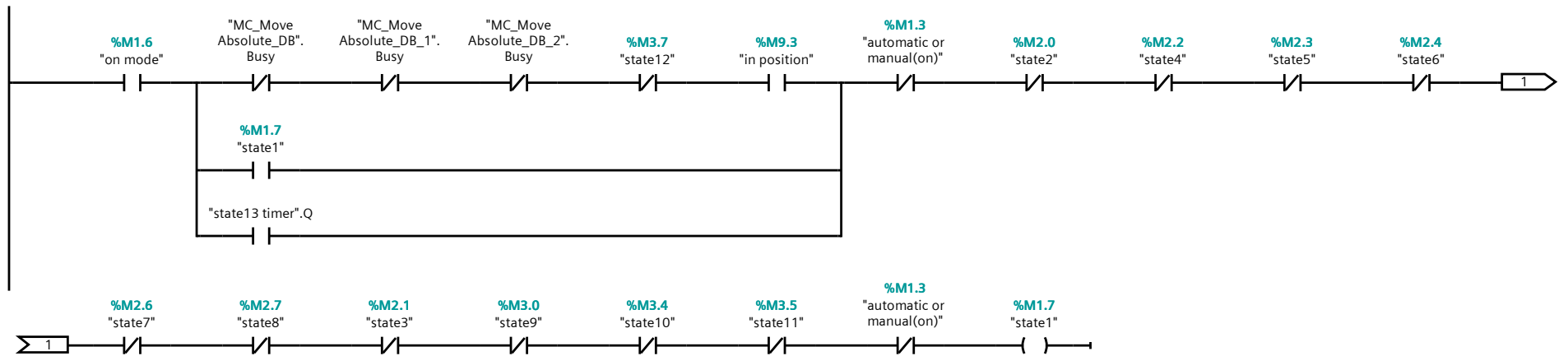
Information

Title		Author		Comment		Family	
Version	0.1	User-defined ID					

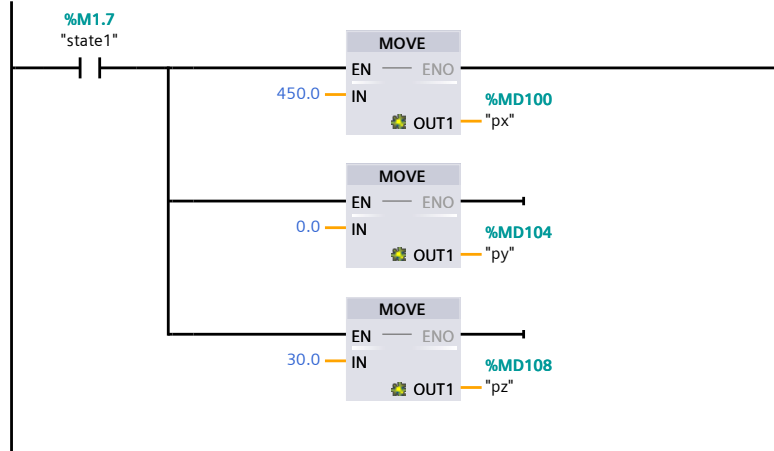
Name	Data type	Default value	Comment
Input			
Output			
InOut			
Temp			
Constant			
▼ Return			
Change Position of Robot	Void		

Network 1: STATE 1 ON

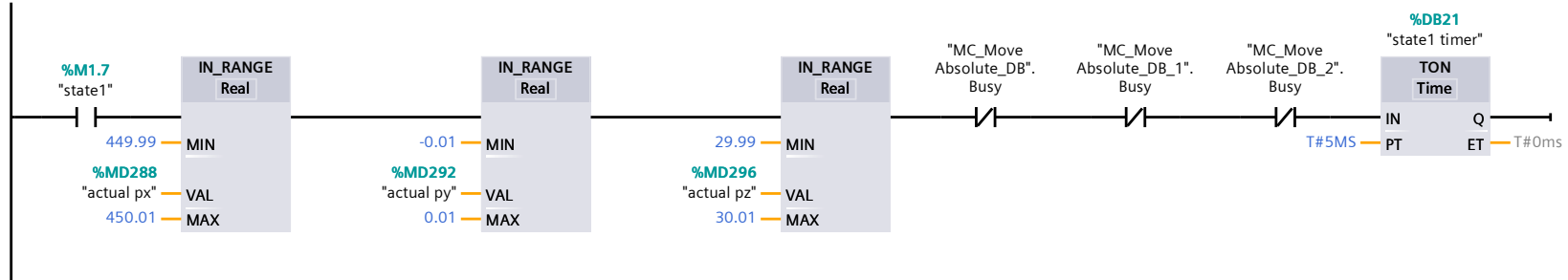
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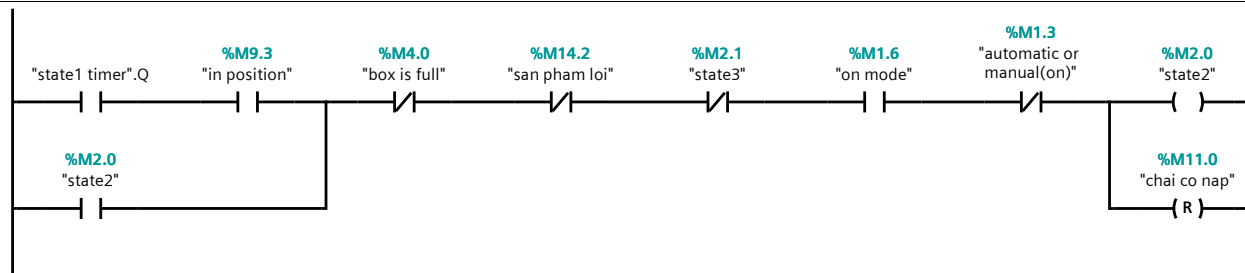
Network 2: Vi tri cua state1



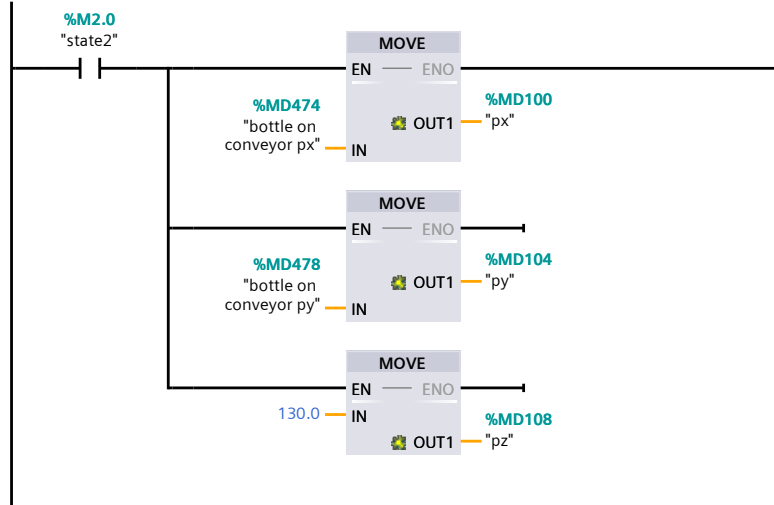
Network 3:



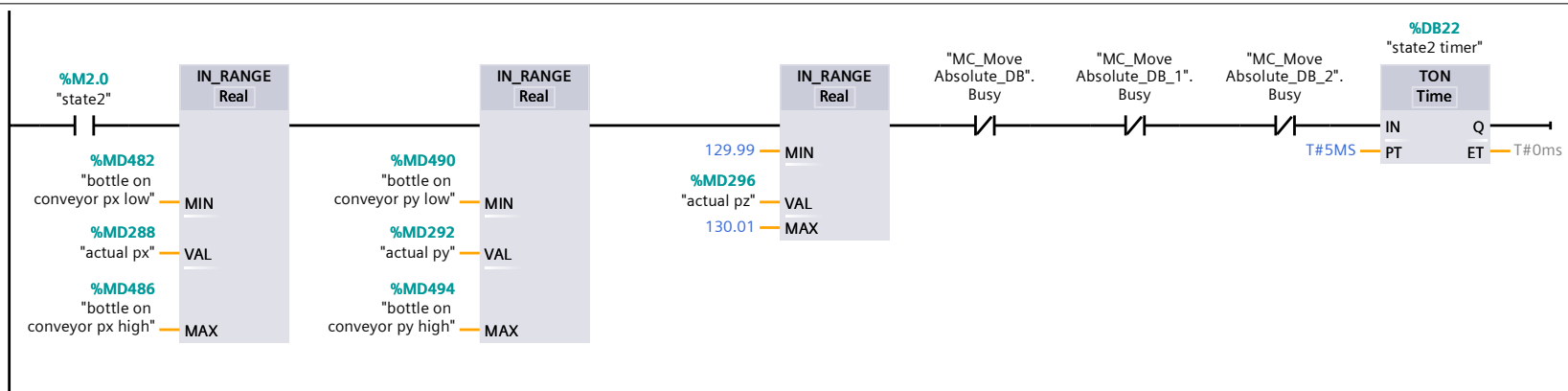
Network 4:



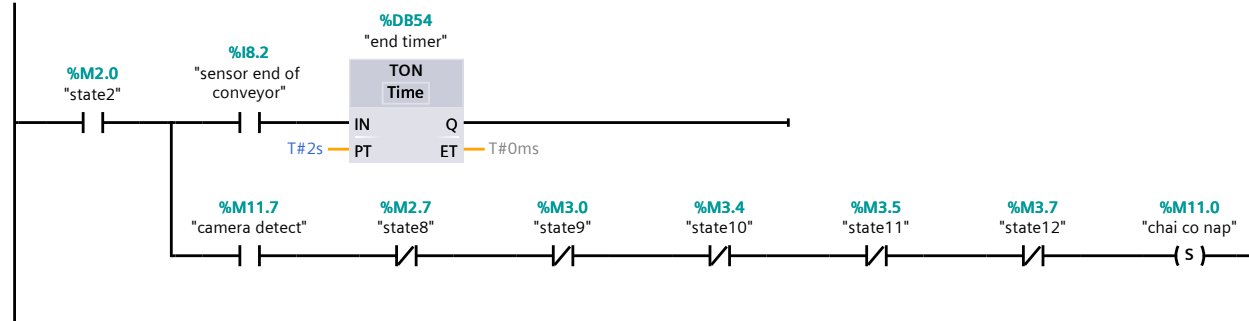
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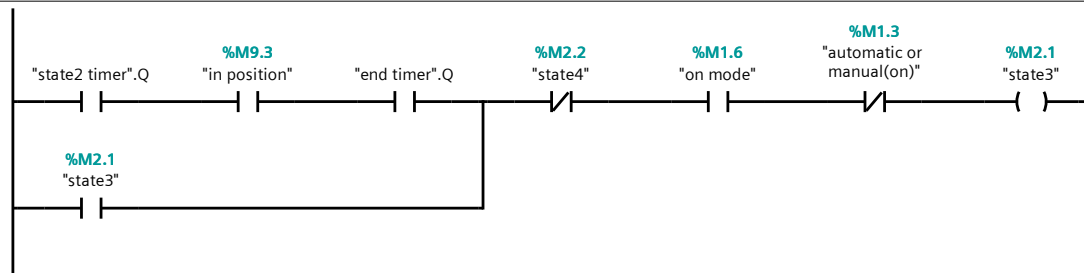
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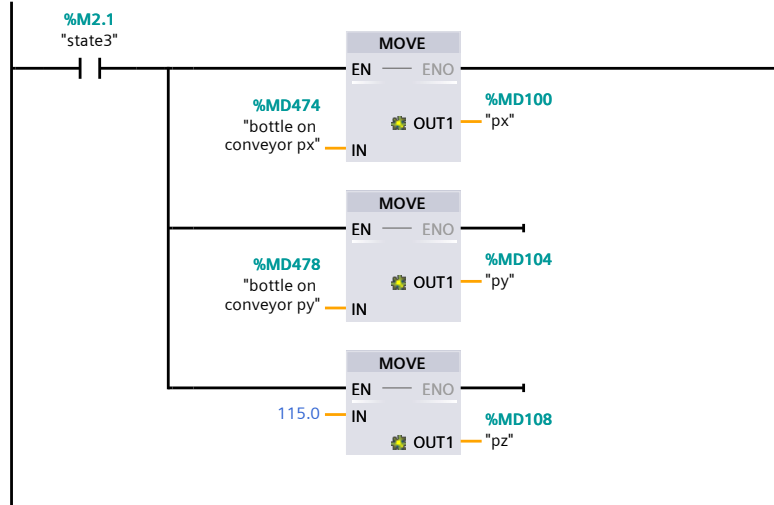
Network 7:



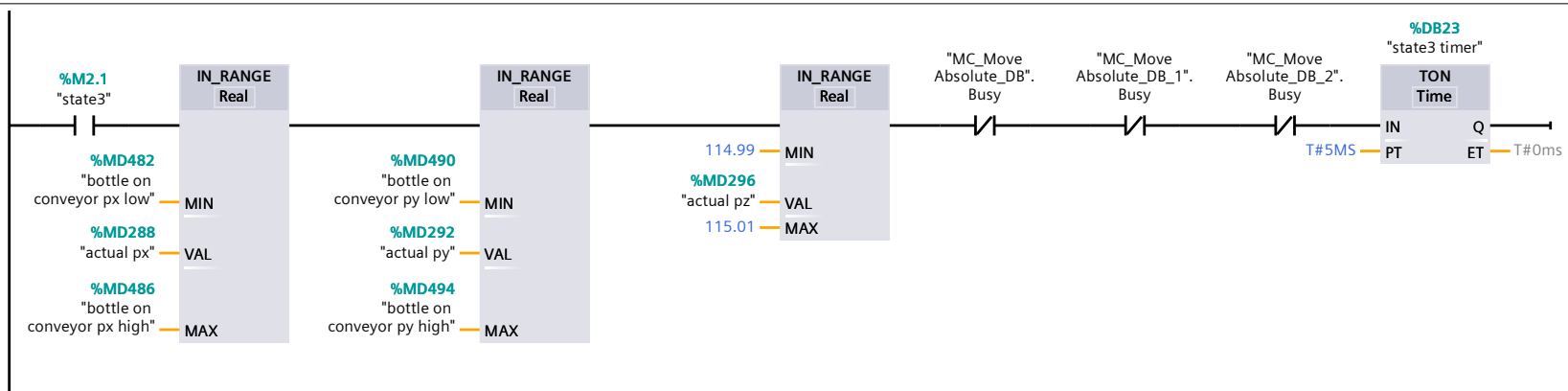
Network 8:



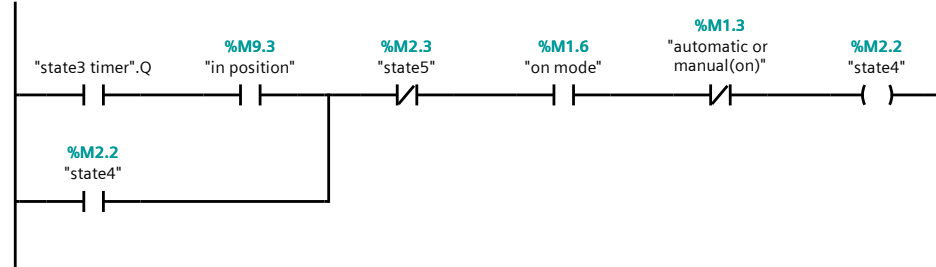
Network 9:



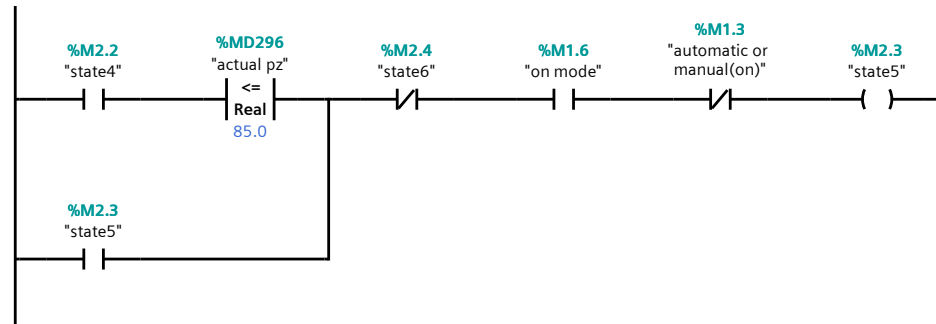
Network 10:



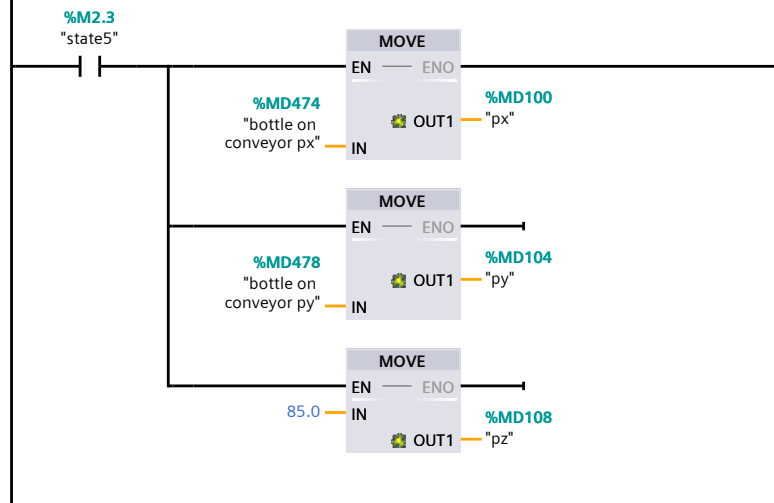
Network 11:



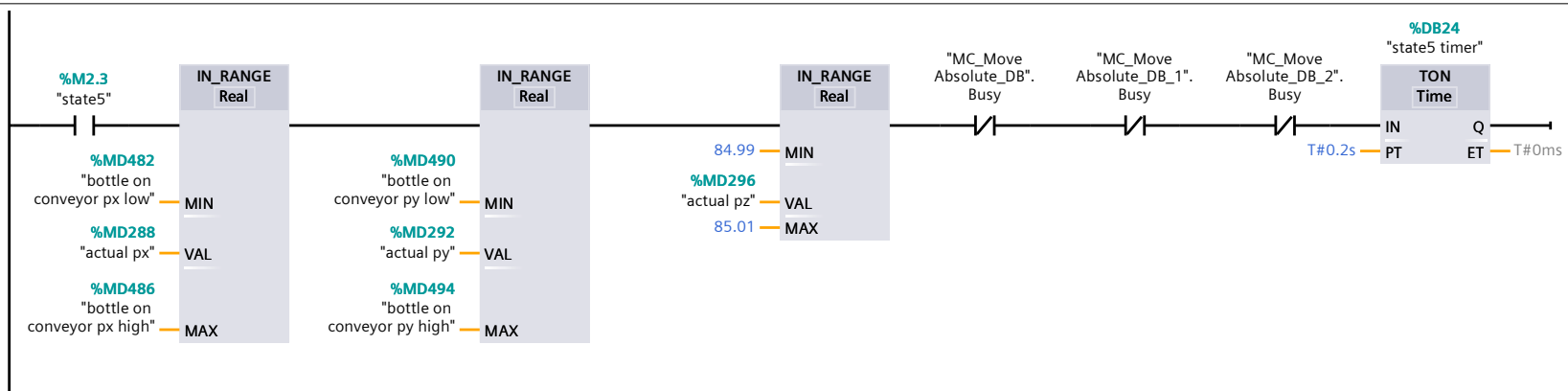
Network 12:



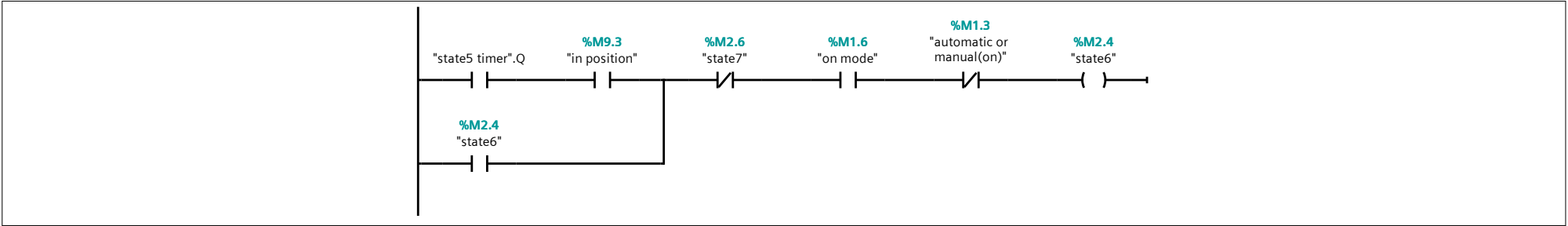
Network 13:



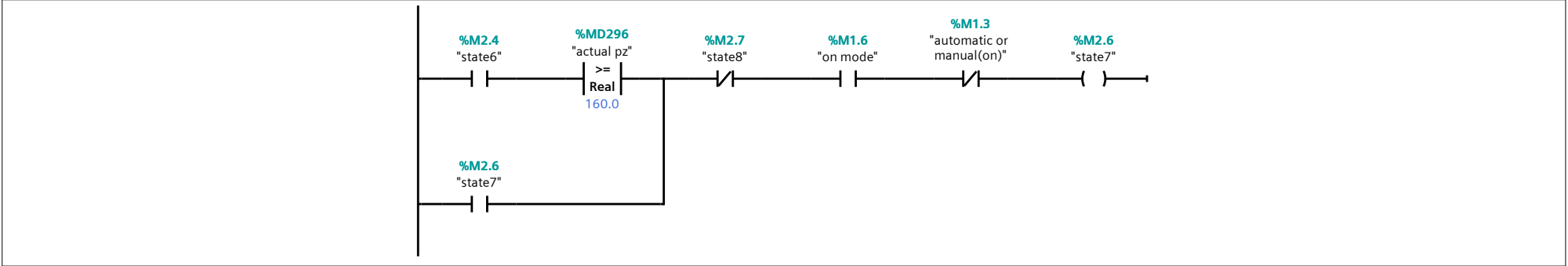
Network 14:



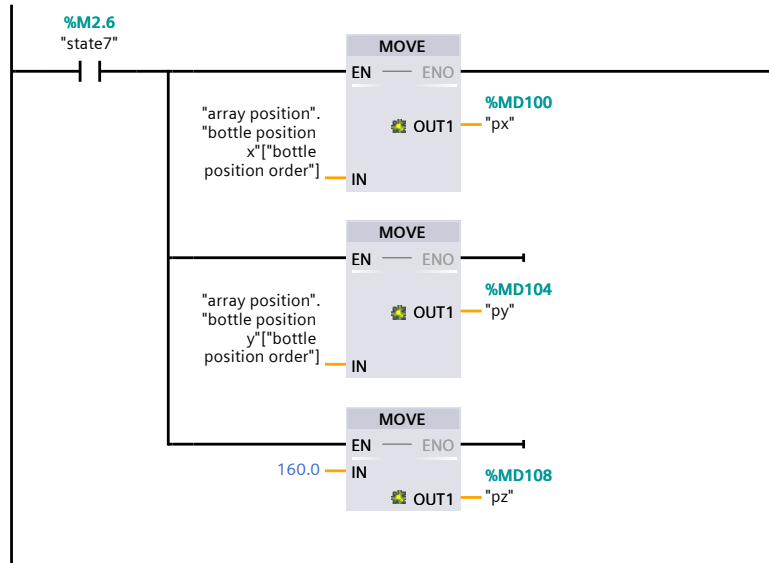
Network 15:



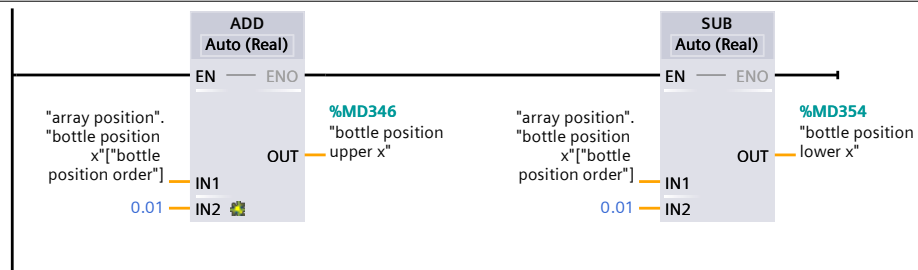
Network 16:



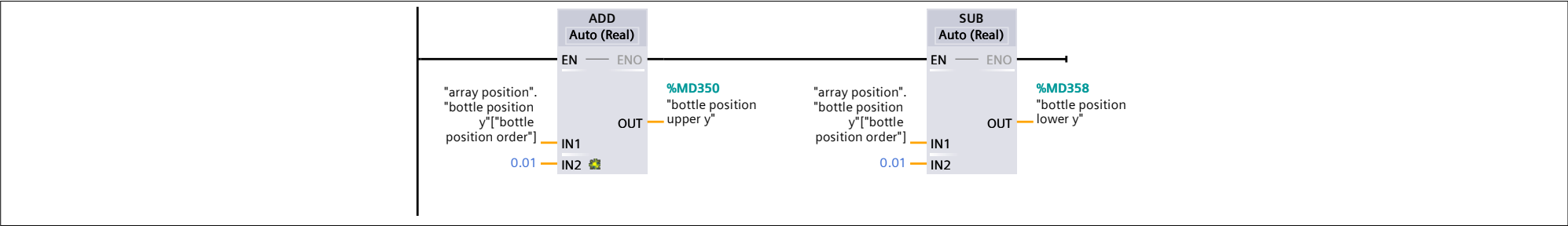
Network 17:



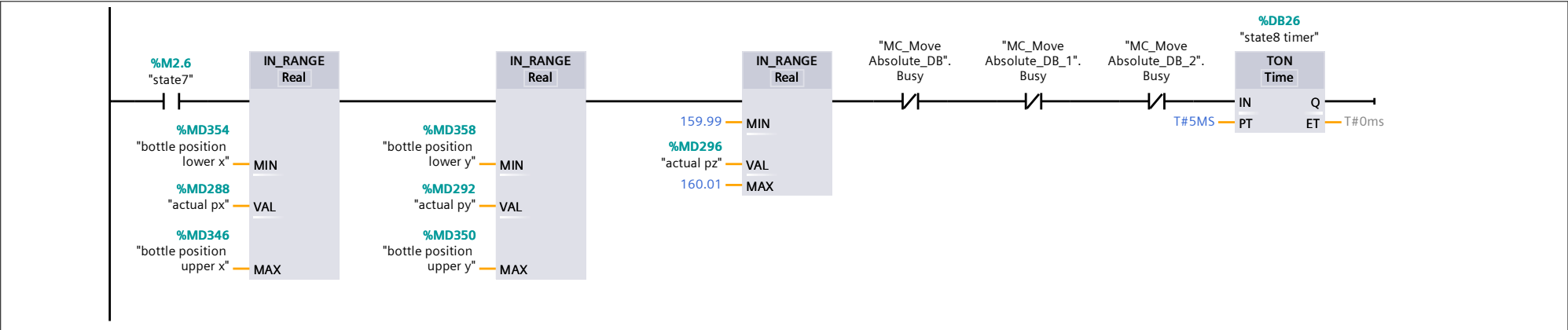
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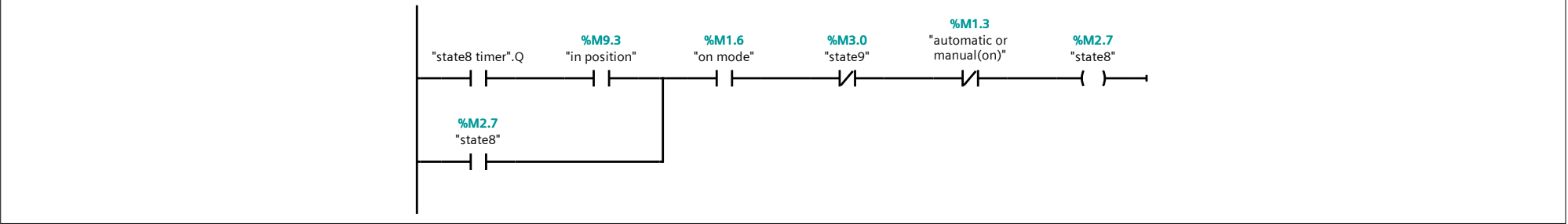
Network 19:



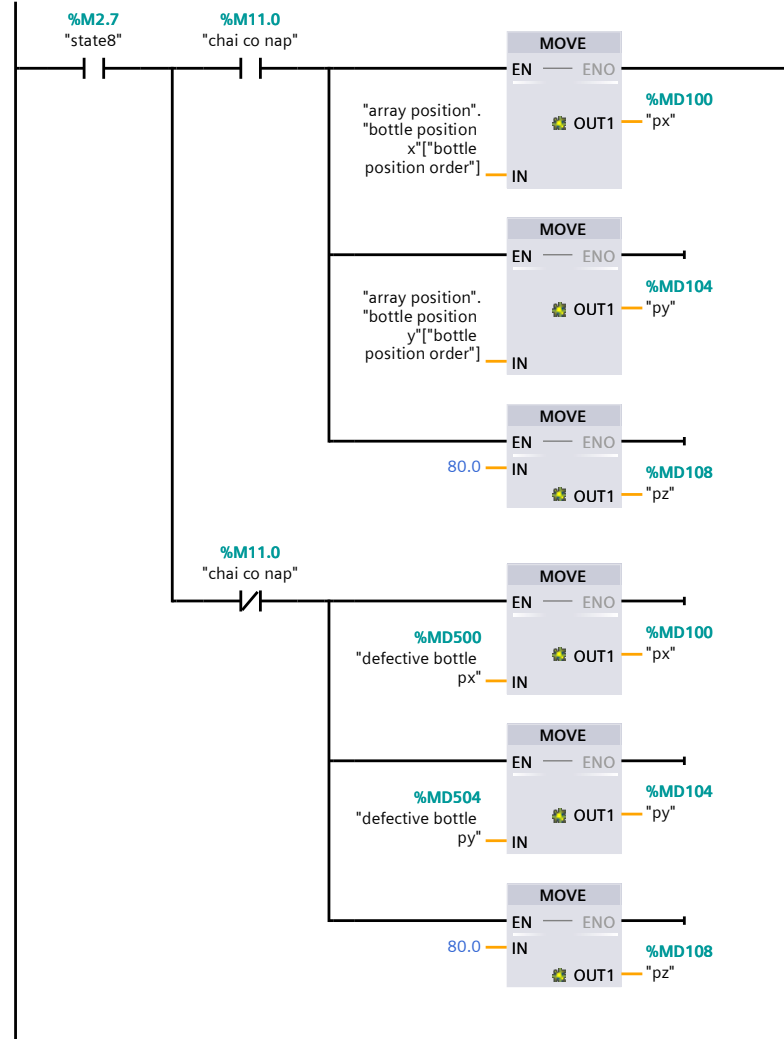
Network 20:



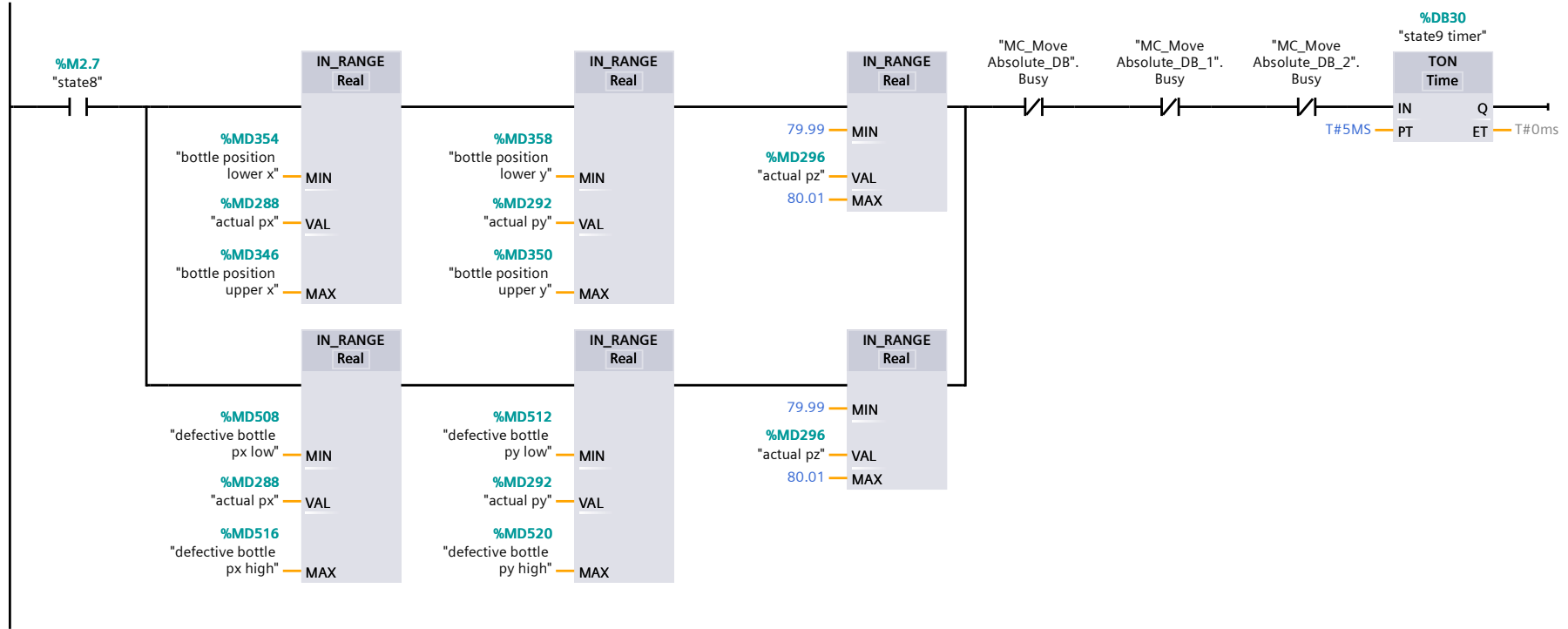
Network 21:



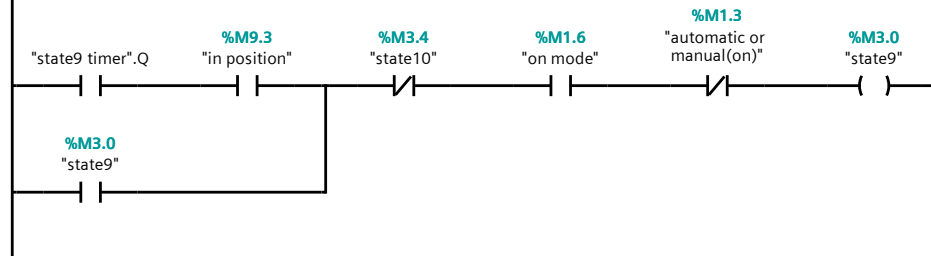
Network 22:



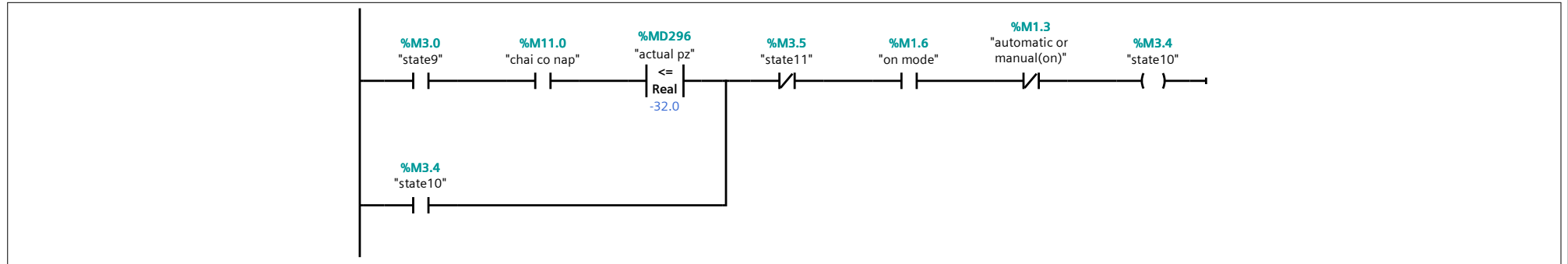
Network 23:



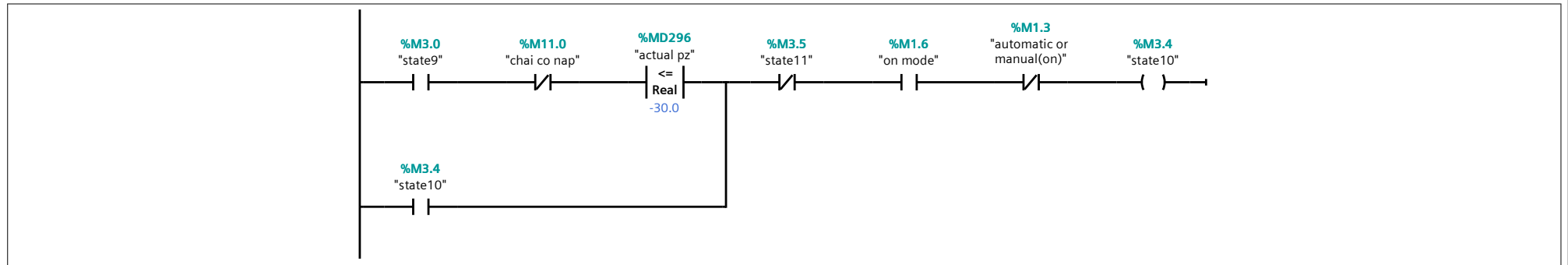
Network 24:



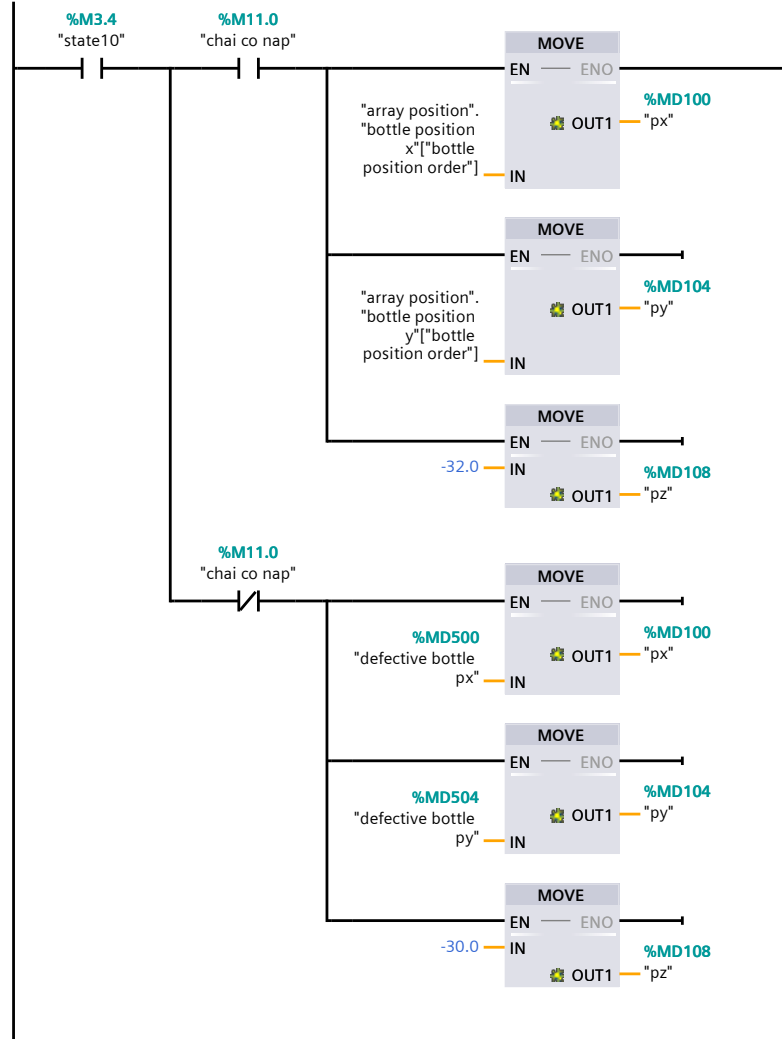
Network 25:



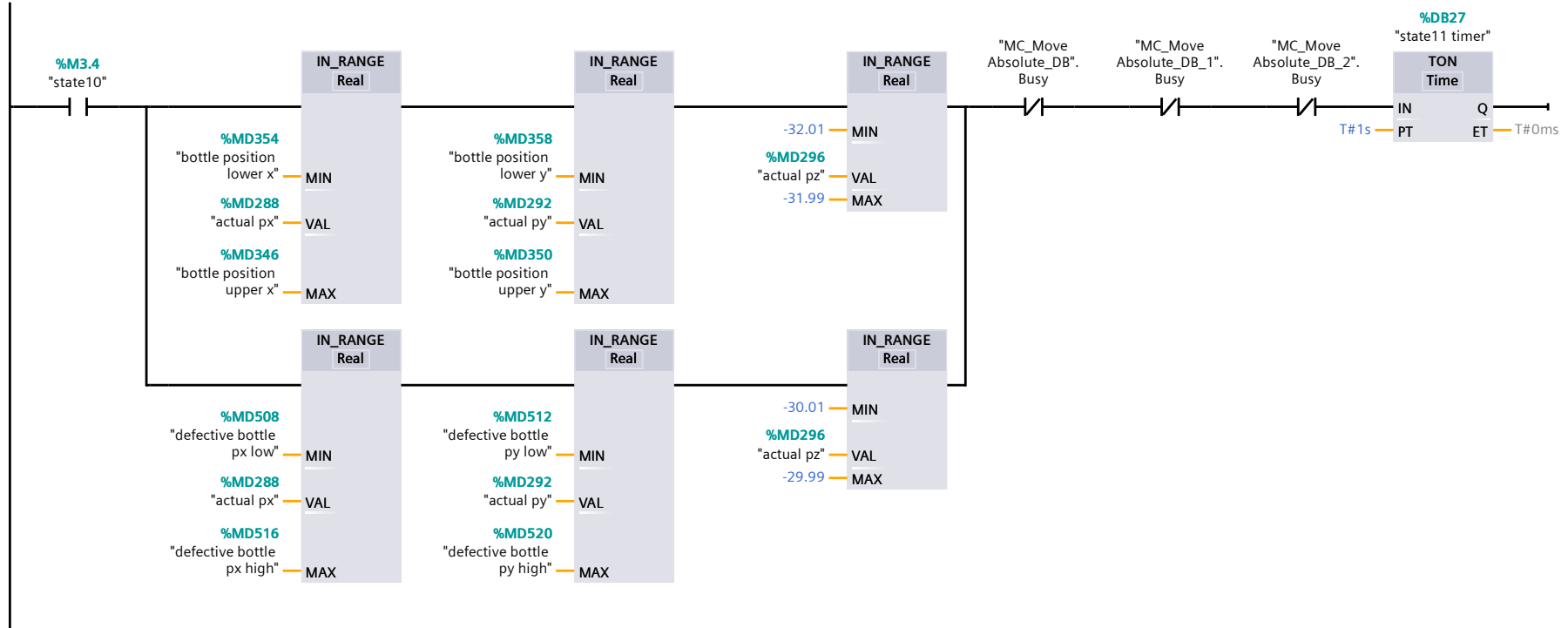
Network 26:



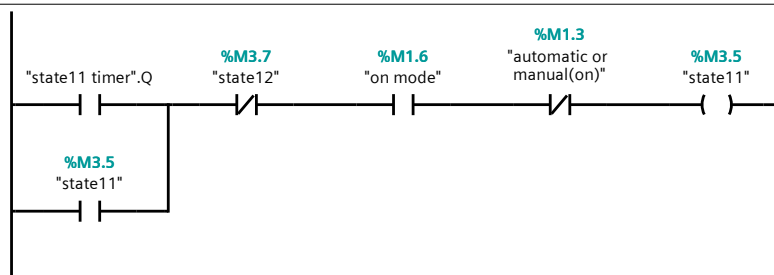
Network 27:



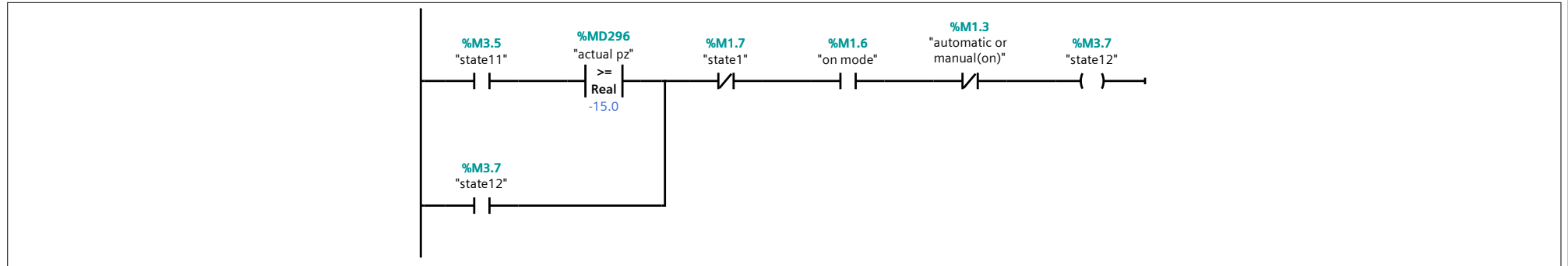
Network 28:



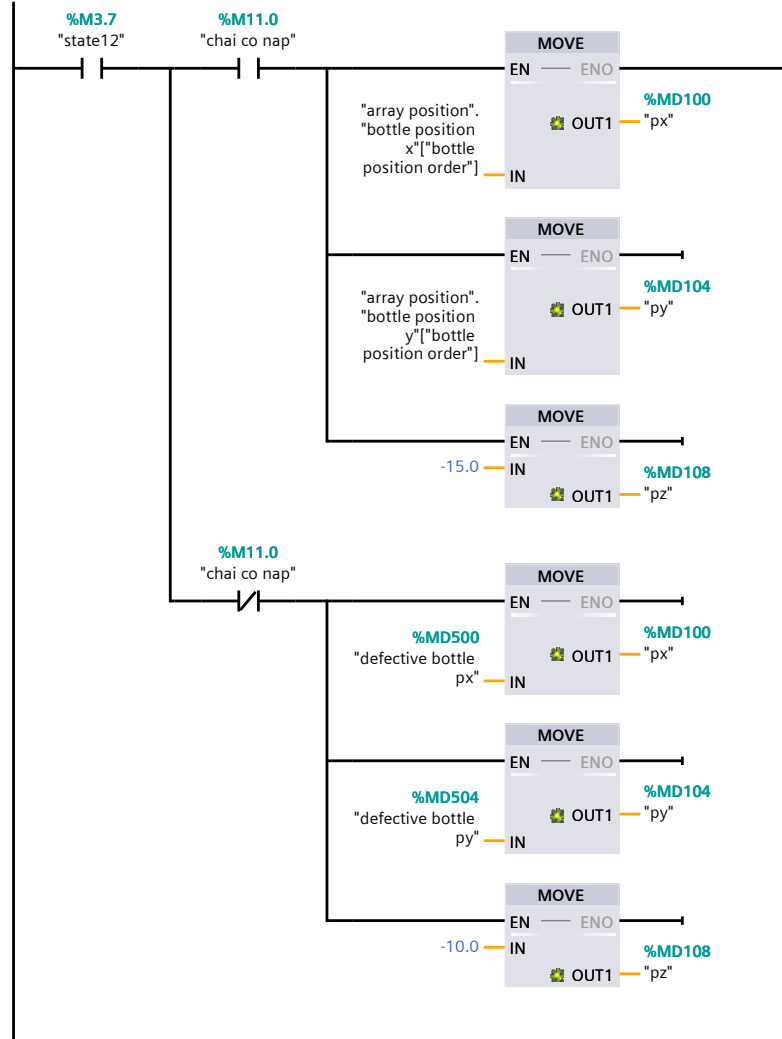
Network 29:



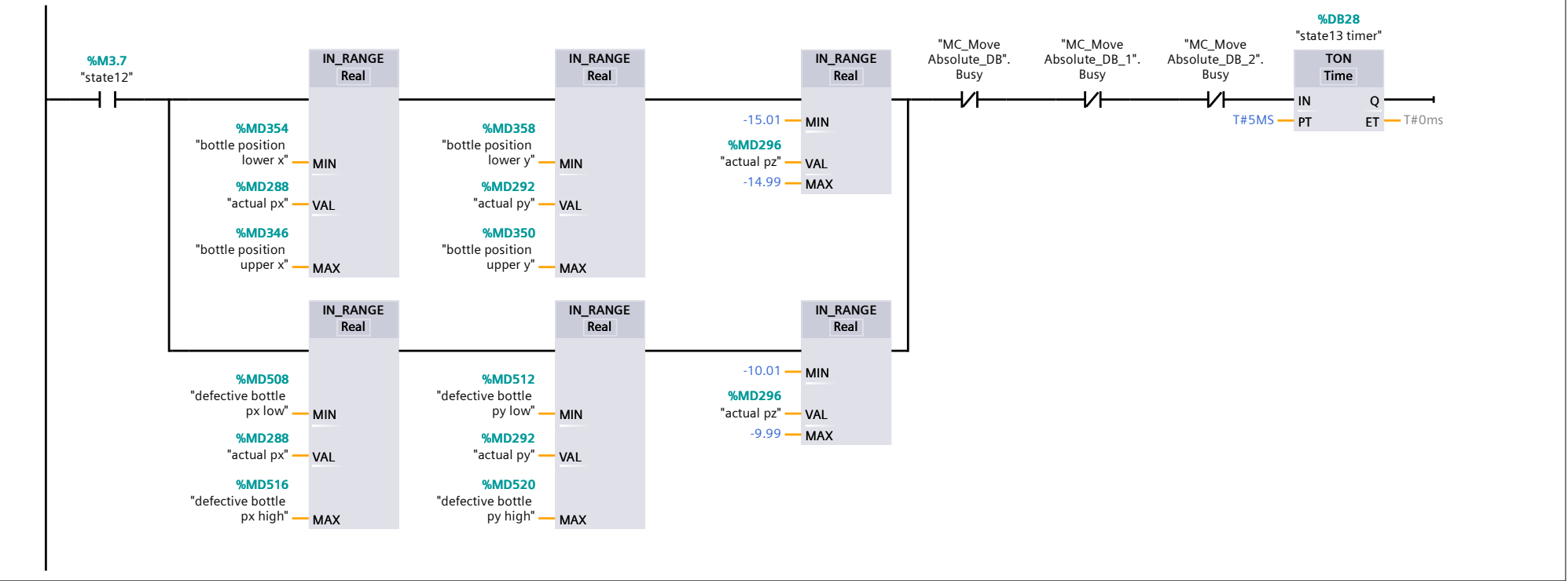
Network 30:



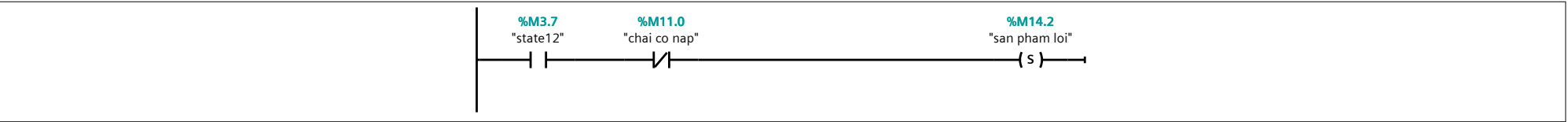
Network 31:



Network 32:



Network 33:



Network 34:

