

# Computer Vision

# Logistics:

- Homework 2 due today
  - Homework 3 out soon
- Will release to solutions if you email me



## Until now: low/mid level vision

- Low level
  - Pixel manipulations
  - Image corrections
  - Feature extraction
- Mid level
  - Images <-> images
    - Panorama
  - Image <-> world
    - Stereo
  - Images <-> time
    - Optical flow

## Why did we extract these features anyway?

- High level vision!
  - Image <-> semantics, meaning
- Make predictions about images, what's in them
  - How do we make predictions?
  - Hard coded rules?
  - Learn things from data!

Time to learn all of machine learning in one class

(haha not really)

## What is machine learning?

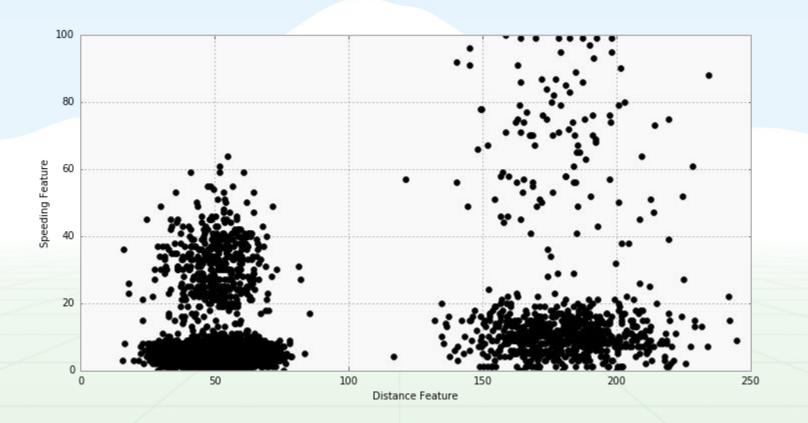
- Algorithms to approximate functions
  - Usually use lots of statistics
  - Usually minimize some form of loss function
- Supervised learning
  - Given inputs to a function, try to predict the output
  - Have lots of labelled examples
- Semi-supervised learning
  - Same but number of labelled examples < number of examples
- Unsupervised learning
  - Want to model unlabelled data
  - Find similarities and differences between subgroups of data
  - Learn functions to generate new data

# Unsupervised learning

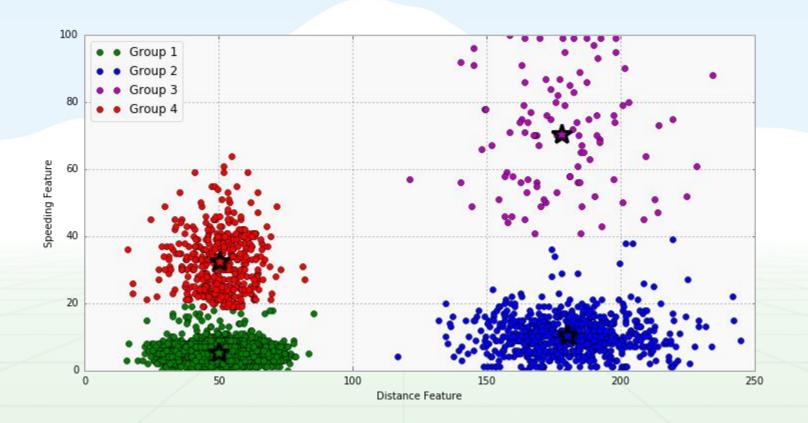
No labels, just looking for patterns in data

E.g. clustering, in data with multiple clusters, what are they, how big, etc.

# Clustering: finding groups in data



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Assume points are close to other points in group, far from points out of group

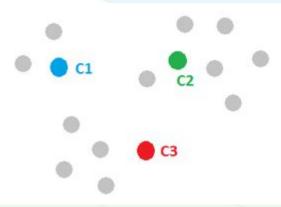
Algorithm:

Randomly initialize cluster centers

Assume points are close to other points in group, far from points out of group

#### Algorithm:

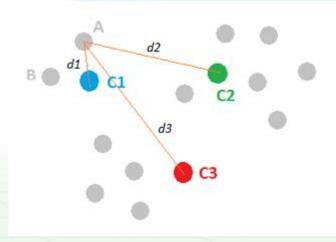
Randomly initialize cluster centers



Assume points are close to other points in group, far from points out of group

#### Algorithm:

Randomly initialize cluster centers
Calculate distance points <-> centers



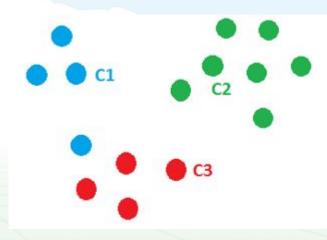
Assume points are close to other points in group, far from points out of group

#### Algorithm:

Randomly initialize cluster centers

Calculate distance points <-> centers

Assign each point to closest cluster center



Assume points are close to other points in group, far from points out of group

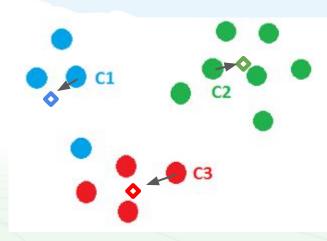
#### Algorithm:

Randomly initialize cluster centers

Calculate distance points <-> centers

Assign each point to closest cluster center

Update cluster centers: avg of points



Assume points are close to other points in group, far from points out of group

#### Algorithm:

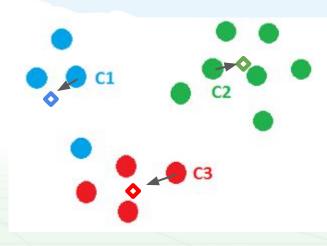
Randomly initialize cluster centers

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Assign each point to closest cluster center

Update cluster centers: avg of points

Repeat!

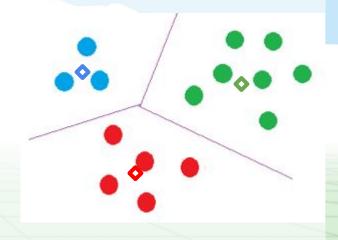


Assume points are close to other points in group, far from points out of group

#### Algorithm:

Randomly initialize cluster centers Loop until converged:

Calculate distance points <-> centers
Assign each point to closest center
Update cluster centers: avg of points



# Clustering on images

Group together pixels by color, automatic segmentation: k-means, k = 2





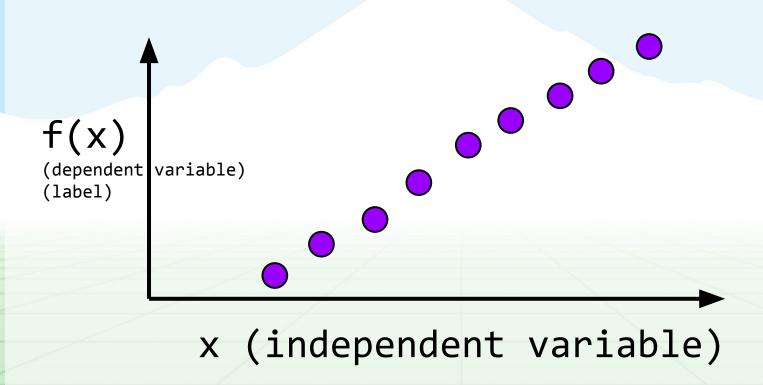
# Clustering on images

Group together pixels by color, automatic segmentation: k-means, k = 4

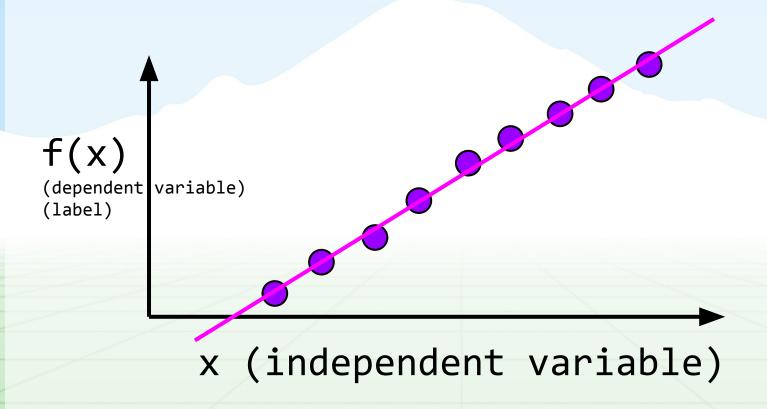




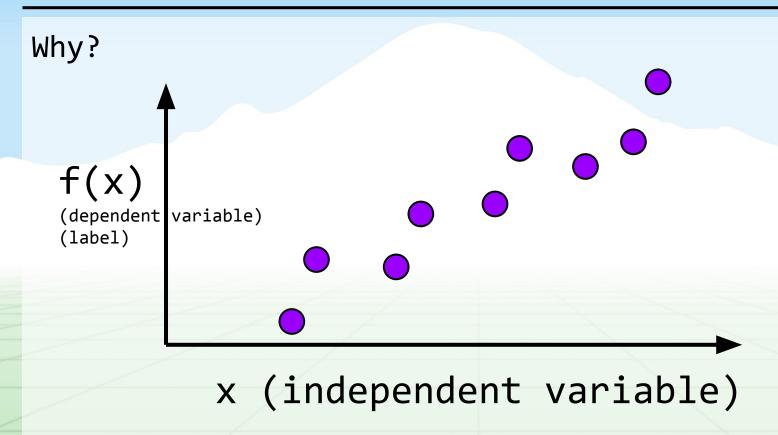
## Supervised Learning: Want to estimate f



## Here's one possible f\*



#### Data often has noise

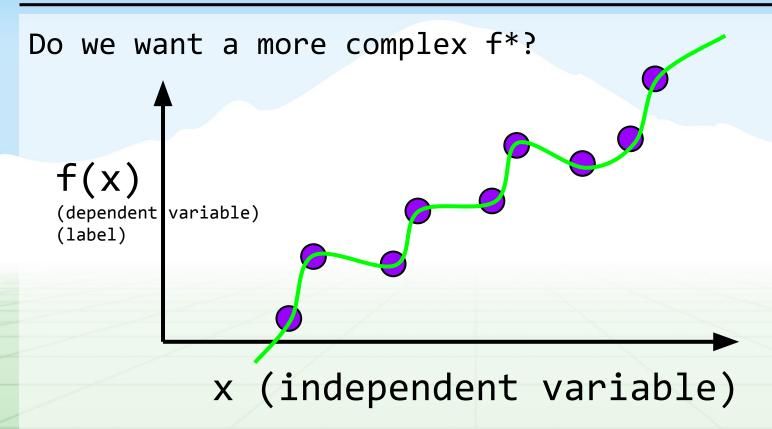


#### Data often has noise

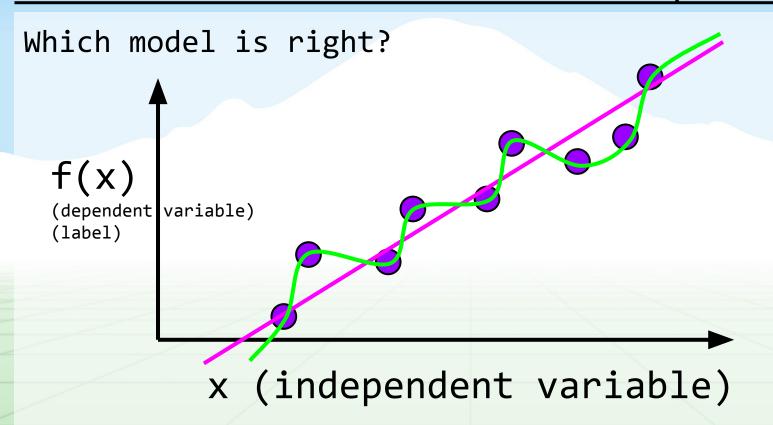
#### Why?

- Randomness
  - Static in phone lines, random distribution of photons hitting sensor, sensors aren't precise
- Mislabelled data
  - Common when humans label lots of data
- Variables outside of model
  - Variations might look like noise but are explained by a hidden, unknown variable

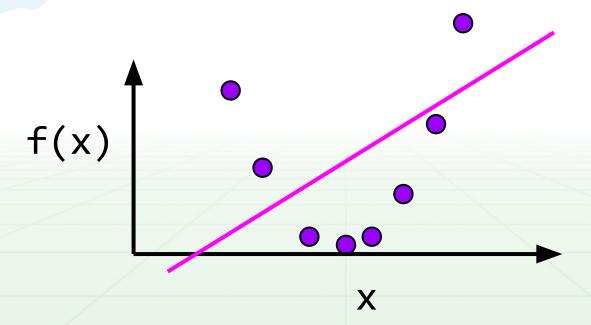
#### Data often has noise



## Sometimes the data is more complex

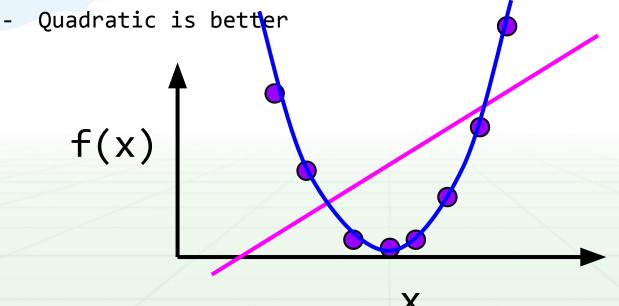


- Bias
  - Error from assumptions model makes about data
  - Linear model assumes data is linear, bad for data that isn't

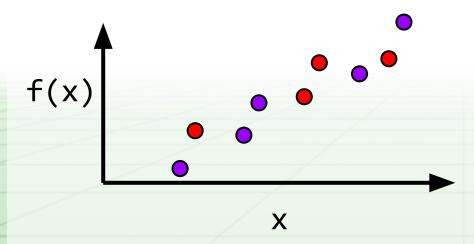


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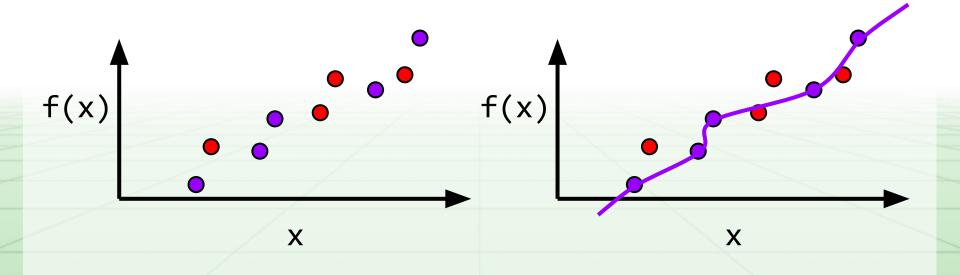
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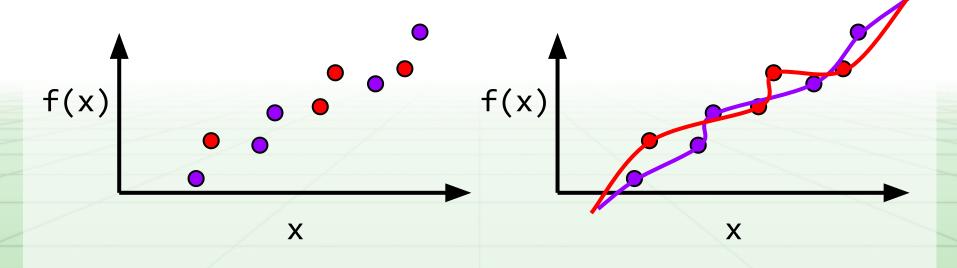
- Variance
  - Algorithm's sensitivity to noise
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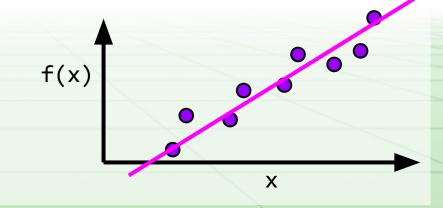


- Variance
  - Algorithm's sensitivity to noise
  - More complex algorithms are more sensitive!
  - High variance hurts generalization, overfitting

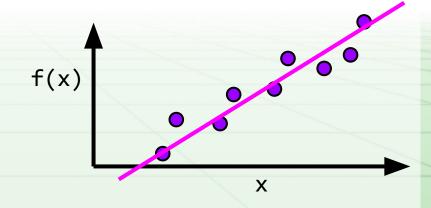


- Noise
  - Random variations in data
- Bias
  - Error from assumptions model makes about data
  - Less complex algorithms -> more assumptions about data
- Variance
  - Algorithm's sensitivity to noise
  - More complex algorithms are more sensitive!
  - High variance hurts generalization

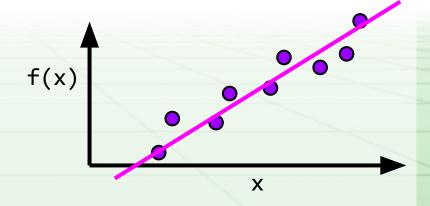
- $f^*(x) = ax + b$
- Learn a and b from data (how?)



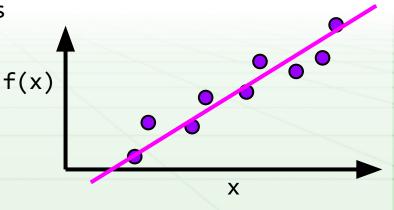
- f\*(x) = ax + b
- Learn a and b from data (how?)
  - Minimize squared error!
  - Loss function  $L(f^*) = \Sigma_i ||f(x_i) f^*(x_i)||^2$



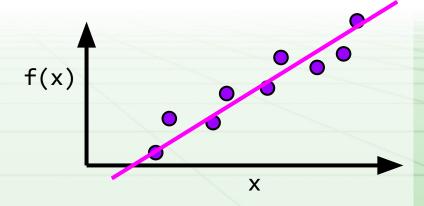
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  - Want argmin<sub>a,b</sub>[L(f\*)]
  - Extrema when derivative = 0



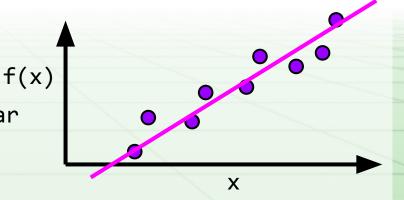
- $f^*(x) = ax + b*1$
- Learn a and b from data (how?)
  - Minimize squared error!
  - Loss function  $L(f^*) = \Sigma_i ||f(x_i) f^*(x_i)||^2$
  - Want argmin<sub>a,b</sub>[L(f\*)]
  - Extrema when derivative = 0
  - Solve linear system of equations
    - Ma = b
  - Already did this!



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- High bias: linear assumption
- Low variance
- Benefits:
  - Closed form solution
  - Fast to compute for new data



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- Learn a and b from data (how?)
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- Benefits:
  - Closed form solution
  - Fast to compute for new data
- Weaknesses:
  - Not very powerful, assumes linear
  - Underfit more interesting data

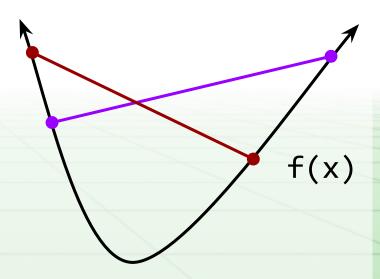


#### (Aside) Convex vs Non-convex

Convex function: connect any two points on graph with a line, that line lies above function everywhere

Why is it important? Any local extrema is global extrema!

If our loss function is convex, can set derivative = 0, solve for parameters (sometimes still no closed-form)

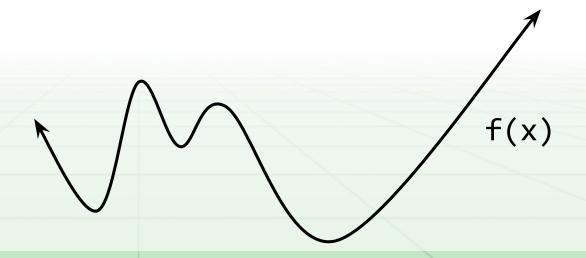


# (Aside) Convex vs Non-convex

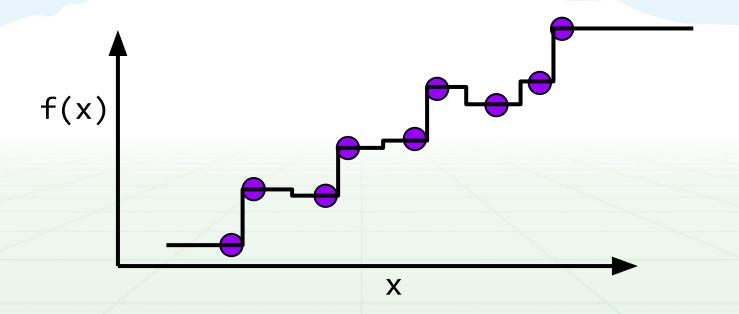
Non-convex function: no rules!

Local optima are not global optima

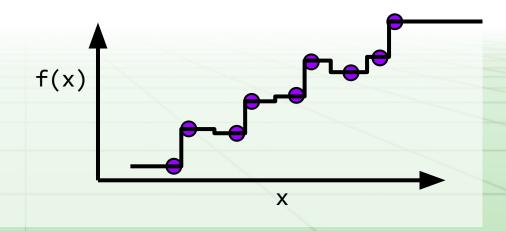
Usually no easy way to find global or local optima, harder to optimize



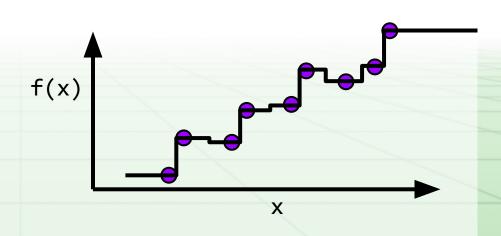
-  $f^*(x) = f(x')$  for nearest x' in training set



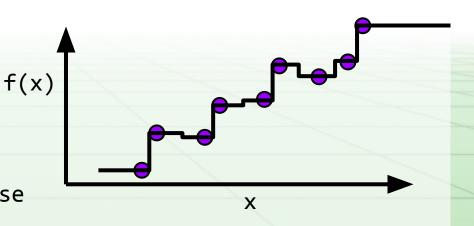
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- Benefits:
  - Super easy to implement
  - Easy to understand
  - Arbitrarily powerful, esp
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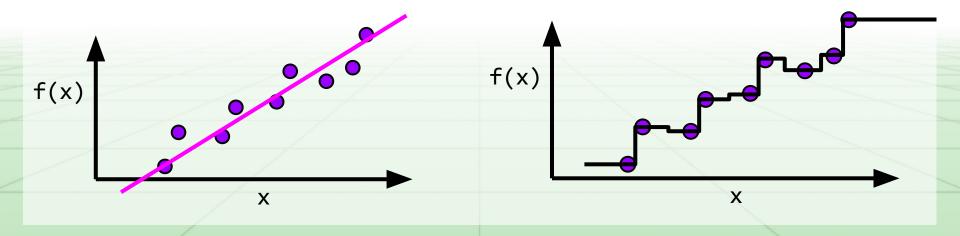


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- Weaknesses:
  - Hard to scale
  - Prone to overfitting to noise



### These are examples of regression

- Given training data
  - input variables X, output variables Y
- And new data point x'
- Predict corresponding output variables y'



### A different task: Classification

- Training data: points associated with a class
  - Also other data about that point
- Example: Does patient have the flu?
  - Binary classification (yes or no)
  - Different types of variables (continuous, discrete)

sore throat	runny nose	nausea	temp	chills	pain	age	days	diagnosis
no	yes	yes	101.3	yes	7	15	5	flu
yes	yes	no	98.8	no	3	74	3	not flu
yes	yes	no	100.1	yes	4	46	4	flu
yes	yes	yes	99.8	yes	6	27	1	flu
yes	no	no	98.4	yes	5	35	2	not flu
yes	yes	yes	99.0	no	3	42	4	not flu

### One approach: partitions

- Find best split or splits to data along one variable
- One possibility, Pr(flu) = (temp > 99.5)
  - Pretty accurate on our training data

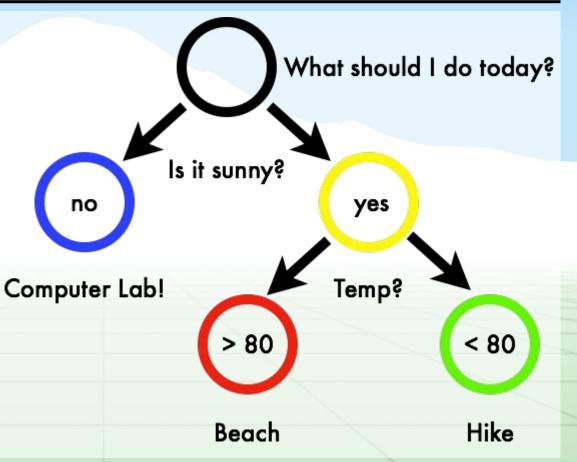
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yes	no	no	98.4	yes	5	35	2	not flu
yes	yes	yes	99.9	no	3	42	4	not flu

# Trees: layers of partitions

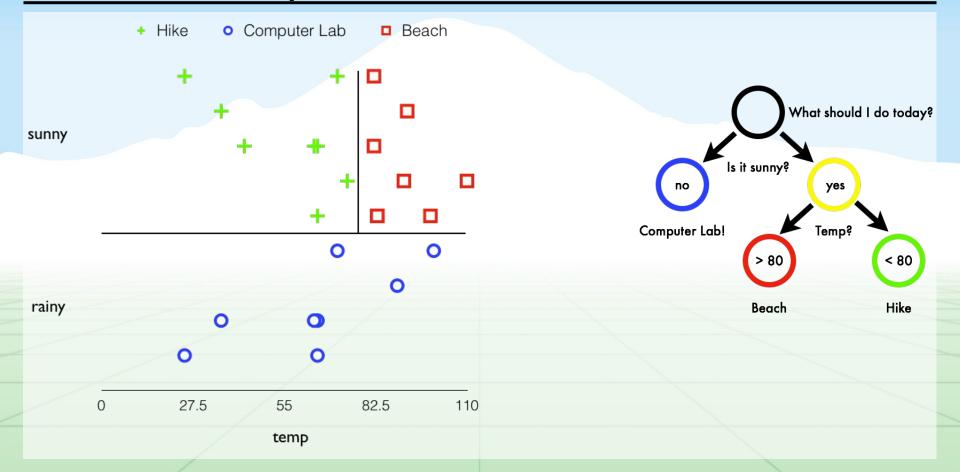
Very simple models

#### Benefits:

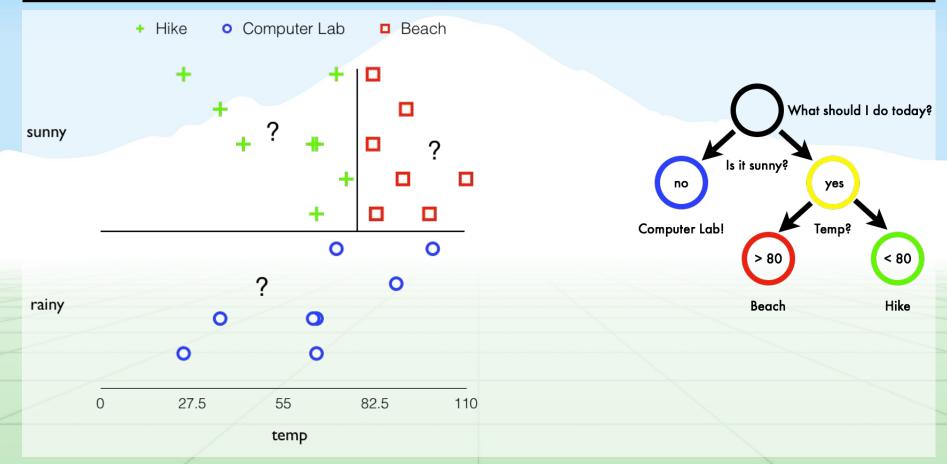
Interpretable
Easy to use
Good for applications
E.g. medicine



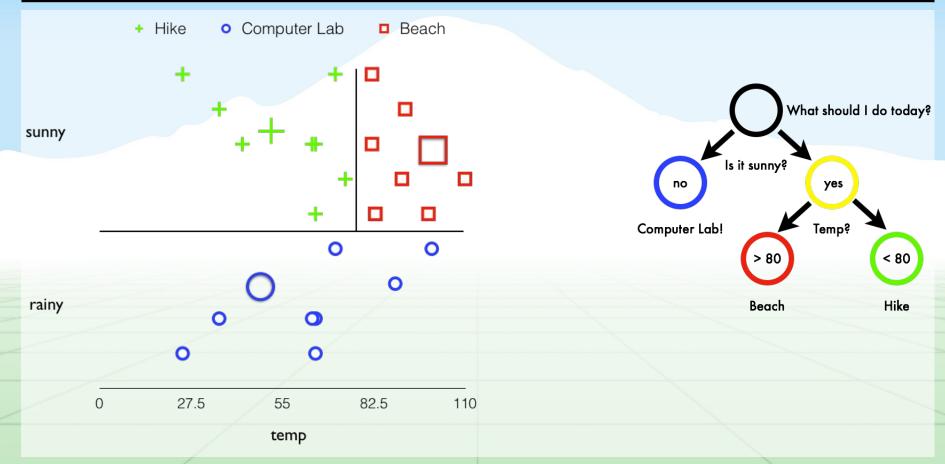
# Trees are partitions of data



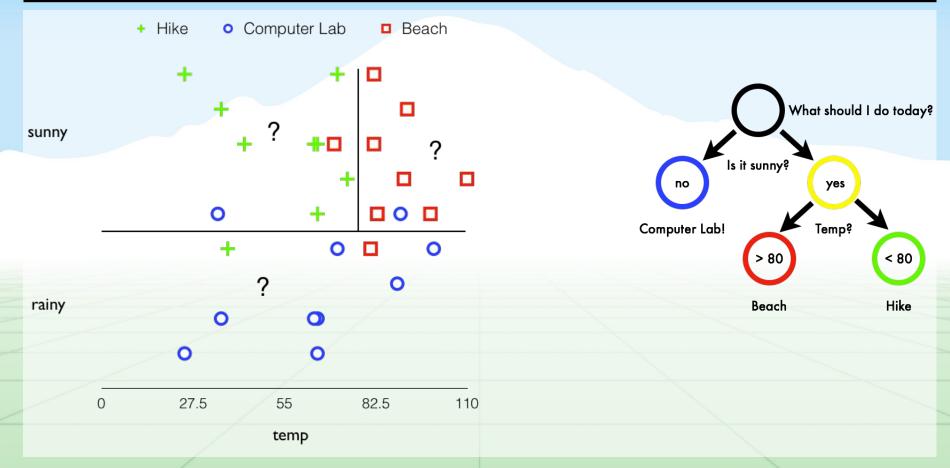
#### Predict new data based on what region it falls into



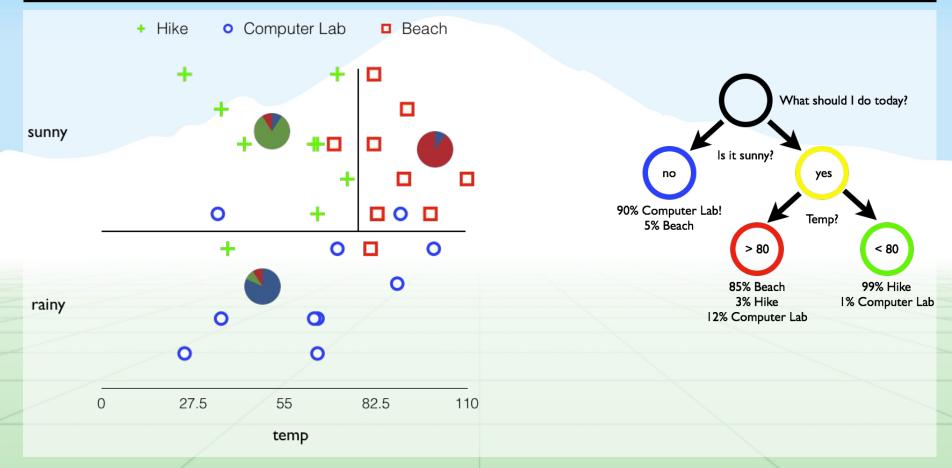
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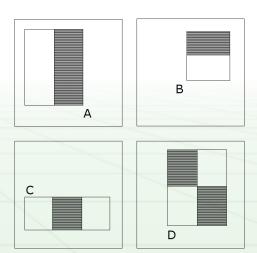


Want it to be very fast and accurate Run on a camera or cell phone, low cost

Use simple features and simple classifiers

#### Haar features:

Response =  $\Sigma$  pix in black region -  $\Sigma$  pix in white region

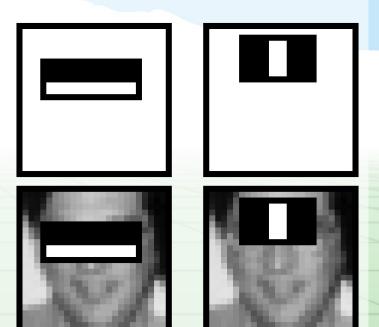


#### Why do Haar features work?

Eyes are generally darker than cheeks Bridge of nose lighter than eyes Etc.

#### Also, fast to compute!

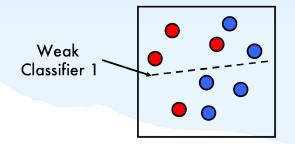
Integral images - fast sums
over regions.



Classifier: boosted partitions

#### Boosting

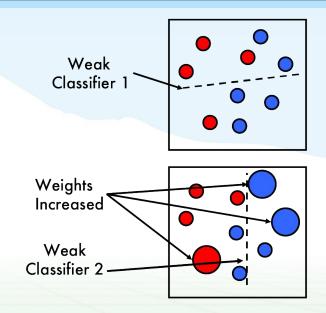
Way to make weak classifiers better Train a weak classifier



Classifier: boosted partitions

#### Boosting

Way to make weak classifiers better
Train a weak classifier
Reweight data we got wrong, train again

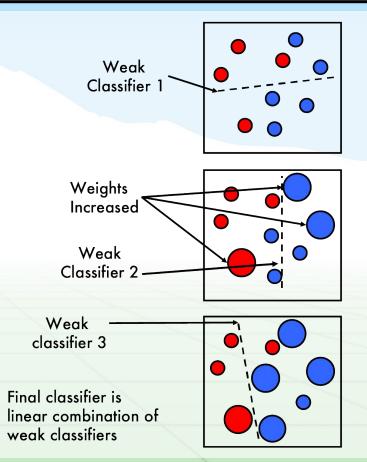


Classifier: boosted partitions

#### Boosting

Way to make weak classifiers better
Train a weak classifier
Reweight data we got wrong, train again
...and again
Until you feel like stopping

Final classifier is combination of these



Finally, use a cascade of classifiers

1st classifier

Very fast, throws out easy negatives

2nd classifier

Fast, throws out harder negatives

3rd classifier

Slower, throws out hard negatives

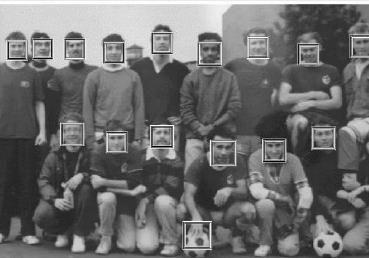
Only run slow, good classifiers on hard examples Fast classifier that is still very accurate

Haar features

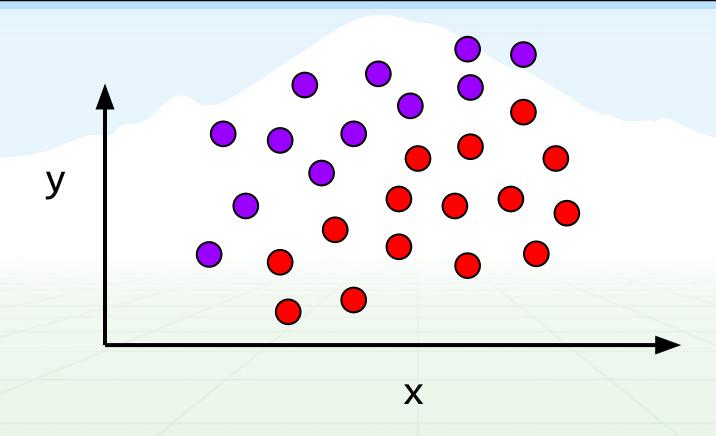
Cascade

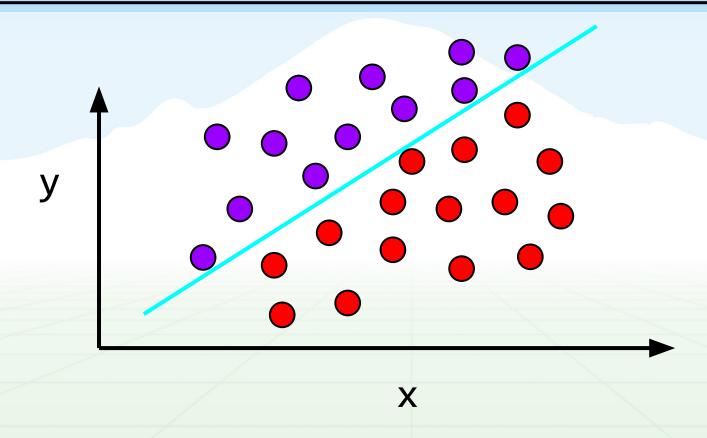
Of boosted classifiers

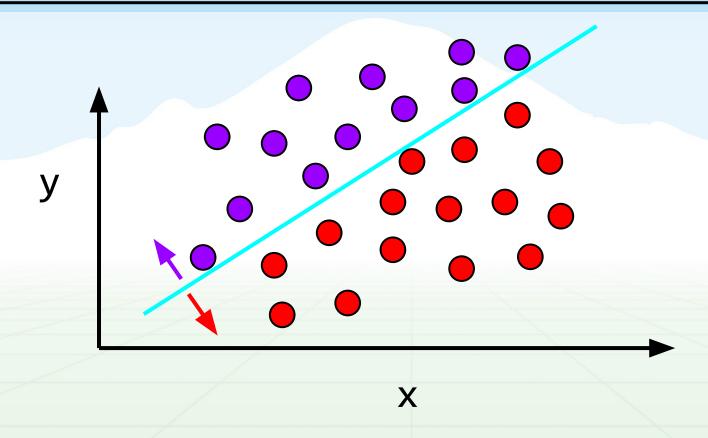




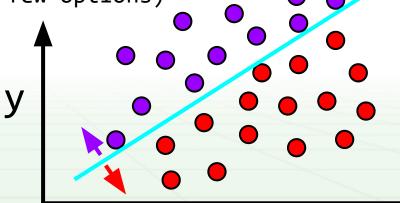




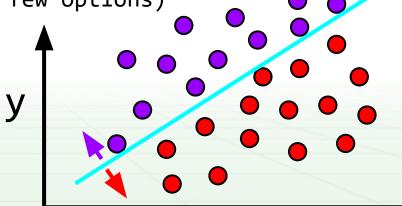




- Linear classifier
  - Given dataset, learn weights w
  - Output of model is weighted sum of inputs
  - P(purple  $| \mathbf{x}) = f(\mathbf{w} \cdot \mathbf{x}) = f(\Sigma_i(\mathbf{w}_i \mathbf{x}_i))$
  - Where f is some function (a few options)



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  - Where f is some function (a few options)
  - Typically a bias term:
    - $f(\Sigma_i(W_iX_i) + W_{bias})$



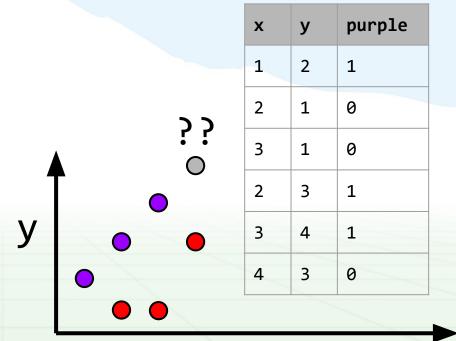
- Simple example:
  - Learned weights: [-1, 1]
  - o f is threshold at 0

0

V			•
,	0		
		•	•

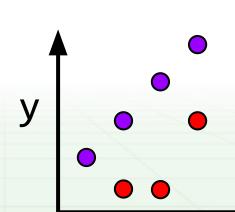
У	purple
2	1
1	0
1	0
3	1
4	1
3	0
	2 1 1 3 4

- Simple example:
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- New data point (4, 5)
  - $(w \cdot x) = (4,5) \cdot (-1, 1)$  = 4\*-1 + 5\*1 = 1





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  - $(w \cdot x) = (4,5) \cdot (-1, 1)$  = 4\*-1 + 5\*1 = 1
  - $\circ f(w \cdot x) = f(1) = 1$

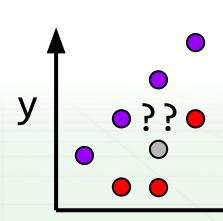


x	у	purple
1	2	1
2	1	0
3	1	0
2	3	1
3	4	1
4	3	0



- Simple example:
  - Learned weights: [-1, 1]
  - f is threshold at 0
- New data point (4, 5)
  - $\circ$  f(w·x) = 1
- New data point (3, 2)
  - $(w \cdot x) = (3,2) \cdot (-1, 1)$  = 3\*-1 + 2\*1 = -1
  - $\circ f(w \cdot x) = f(-1) = 0$

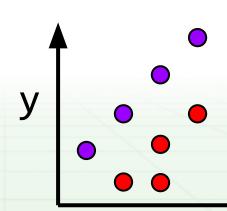
0



x	У	purple
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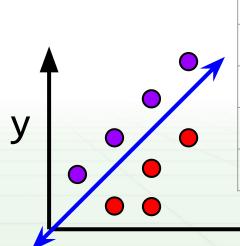
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x	у	purple
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- New data point (4, 5)
  - $\circ f(w \cdot x) = 1$
- New data point (3, 2)
  - $\circ f(\mathbf{w} \cdot \mathbf{x}) = 0$
- Decision boundary: x=y

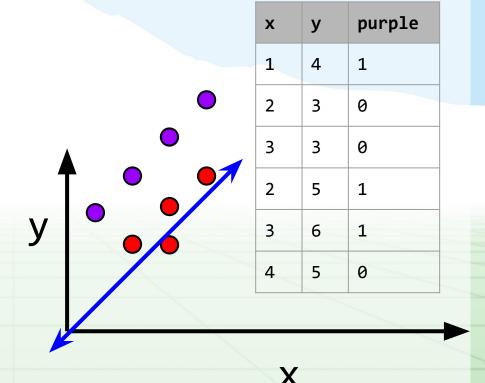


x	у	purple
1	2	1
2	1	0
3	1	0
2	3	1
3	4	1
4	3	0



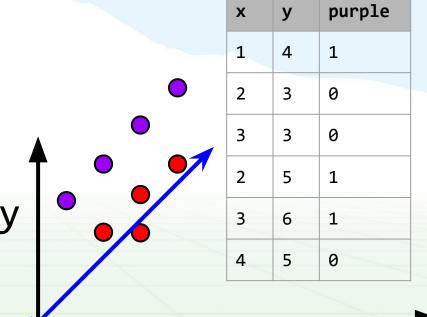
# What if data is shifted up by two?

- Need a bias!:
  - Learned weights: [-1, 1]
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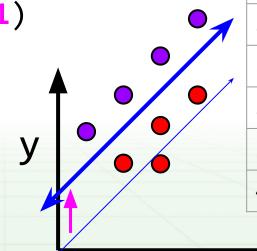
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X

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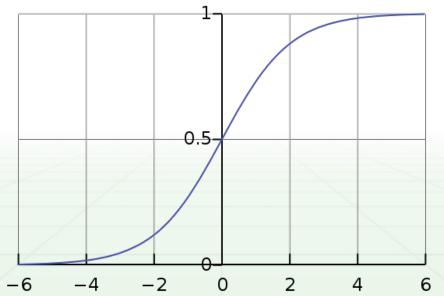
- Need a bias!:
  - Learned weights: [-1, 1, -2]
  - f is threshold at 0
- New data point (4, 7, 1)
  - $(w \cdot x) = (4,7,1) \cdot (-1,1,-2)$  = 4\*-1 + 7\*1 + 1\*-2 = 1
  - $\circ f(\mathbf{w} \cdot \mathbf{x}) = f(1) = 1$



x	у	purple
1	4	1
2	3	0
3	3	0
2	5	1
3	6	1
4	5	0

X

- Linear classifier, f is logistic function
  - $\sigma(x) = 1/(1 + e^{-x}) = e^{x}/(1 + e^{x})$
  - Maps all reals -> [0,1], probabilities!



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  - o In practice we use log likelihood, it's simpler later!!

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  - $\circ$   $\sigma(x) = 1/(1 + e^{-x}) = e^{x}/(1 + e^{x})$
- Want something to optimize!
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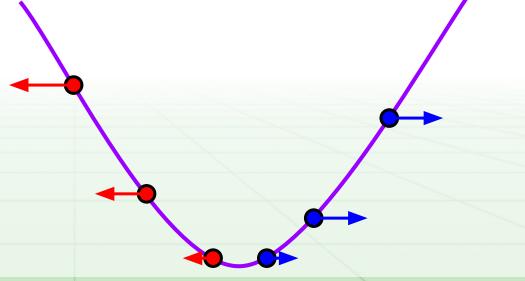
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  - $\circ = \sum_{i} [Y_{i} \log(\sigma(w \cdot X_{i})) + (1 Y_{i}) \log(1 \sigma(w \cdot X_{i}))]$
- Can we take derivative and set to 0?
  - No! :-( no closed form solution
  - BUT! We can still optimize

For some loss function  $L(\mathbf{w})$ , gradient  $\nabla L(\mathbf{w})$  points towards in direction of steepest ascent.

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In 1d, either points left or right

Algorithm:

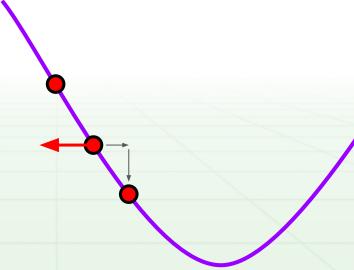
Take derivative
Move slightly in other
direction
Repeat

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Algorithm:

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Algorithm:

Take derivative
Move slightly in other
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Repeat

End up at local optima

#### Formally:

$$\mathbf{w}_{t+1} = \mathbf{w}_{t} - \eta \nabla L(\mathbf{w})$$

Where  $\eta$  is step size, how far to step relative to the gradient

Calculating  $\nabla L(\mathbf{w})$  can be hard, especially for big data, |data| very large.

What if we estimate it it instead?

How do we estimate things?

# Stochastic gradient descent (SGD)

Estimate  $\nabla L(\mathbf{w})$  with only some of the data

Which part of data?

Random sample! (it's unbiased)

How many points in the sample?

Who knows! It's up to you

# Stochastic gradient descent (SGD)

Estimate  $\nabla L(\mathbf{w})$  with only some of the data

#### Before:

$$\mathbf{W}_{t+1} = \mathbf{W}_{t} - \eta \Sigma_{i} \nabla L_{i}(\mathbf{W})$$
, for all i in |data|

#### Now:

$$\mathbf{W}_{t+1} = \mathbf{W}_{t} - \eta \; \Sigma_{i} \nabla L_{i}(\mathbf{W})$$
, for some subset j

Maybe even:

$$\mathbf{W}_{t+1} = \mathbf{W}_{t} - \eta \nabla L_{k}(\mathbf{W})$$
, for some random k

# of points used for update is called batch size

# (Aside) Loss vs Likelihood

Sometimes we have a loss function (cost, penalty, etc.) we want to minimize.

Sometimes we have a likelihood (reward, etc.) we want to maximize.

Does it matter?
No!

Just a sign flip, either climbing up the gradient or descending down.

Say we want to do SGD with batch size = 1

Want to maximize log  $L(w \mid X_i, Y_i)$  for random i =  $Y_i log(\sigma(w \cdot X_i)) + (1 - Y_i) log(1 - \sigma(w \cdot X_i))$ 

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#### But wait!

```
log(\sigma(x)) = log(1/(1 + e^{-x})) = -log(1+e^{-x})

log(1-\sigma(x)) = log(1 - 1/(1 + e^{-x})) = log(e^{-x}/(1 + e^{-x})) = -x-log(1+e^{-x})
```

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#### So:

$$\log L_{i}(w) = -Y_{i} \log(1 + e^{-(w \cdot X_{i})}) + (1 - Y_{i})[-(w \cdot X_{i}) - \log(1 + e^{-(w \cdot X_{i})})]$$
$$= Y_{i}(w \cdot X_{i}) - (w \cdot X_{i}) - \log(1 + e^{-(w \cdot X_{i})})$$

https://math.stackexchange.com/questions/477207/derivative-of-cost-function-for-logistic-regression

$$\log L_{i}(w) = -Y_{i} \log(1 + e^{-(w \cdot X_{i})}) + (1 - Y_{i})[-(w \cdot X_{i}) - \log(1 + e^{-(w \cdot X_{i})})]$$
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But wait again:

$$-x - \log(1 + e^{-x}) = - [\log(e^{x}) + \log(1 + e^{-x})] = - \log(e^{x} + 1)$$

So:

$$Y_i(w \cdot X_i) - (w \cdot X_i) - \log(1 + e^{-(w \cdot X_i)}) = Y_i(w \cdot X_i) - \log(1 + e^{(w \cdot X_i)})$$

Need to take derivatives:

$$\nabla \log L_{i}(\mathbf{w}) = \nabla Y_{i}(\mathbf{w} \cdot \mathbf{X}_{i}) - \nabla \log(1 + e^{(\mathbf{w} \cdot \mathbf{X}_{i})})$$

$$= Y_{i} \mathbf{X}_{i} - 1/(1 + e^{(\mathbf{w} \cdot \mathbf{X}_{i})}) * e^{(\mathbf{w} \cdot \mathbf{X}_{i})} * \mathbf{X}_{i} = \mathbf{X}_{i} [Y_{i} - e^{(\mathbf{w} \cdot \mathbf{X}_{i})}/(1 + e^{(\mathbf{w} \cdot \mathbf{X}_{i})})]$$

$$= \mathbf{X}_{i} [Y_{i} - \sigma(\mathbf{w} \cdot \mathbf{X}_{i})]$$

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$$\nabla \log L_i(w) = X_i[Y_i - \sigma(w \cdot X_i)]$$

So our weight update rule is:

$$\mathbf{W}_{t+1} = \mathbf{W}_t + \eta \mathbf{X}_i [\mathbf{Y}_i - \sigma(\mathbf{W}_t \cdot \mathbf{X}_i)]$$

Why plus?

Doing gradient ascent up the likelihood function