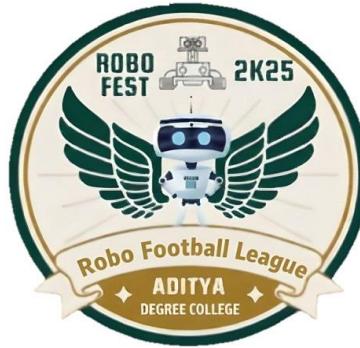


**DEPARTMENT OF**  
**ARTIFICIAL INTELLIGENCE**  
**ADITYA DEGREE & PG COLLEGE(A), KAKINADA**



**ROBOFEST 2K25**  
**ROBO FOOTBALL LEAGUE**

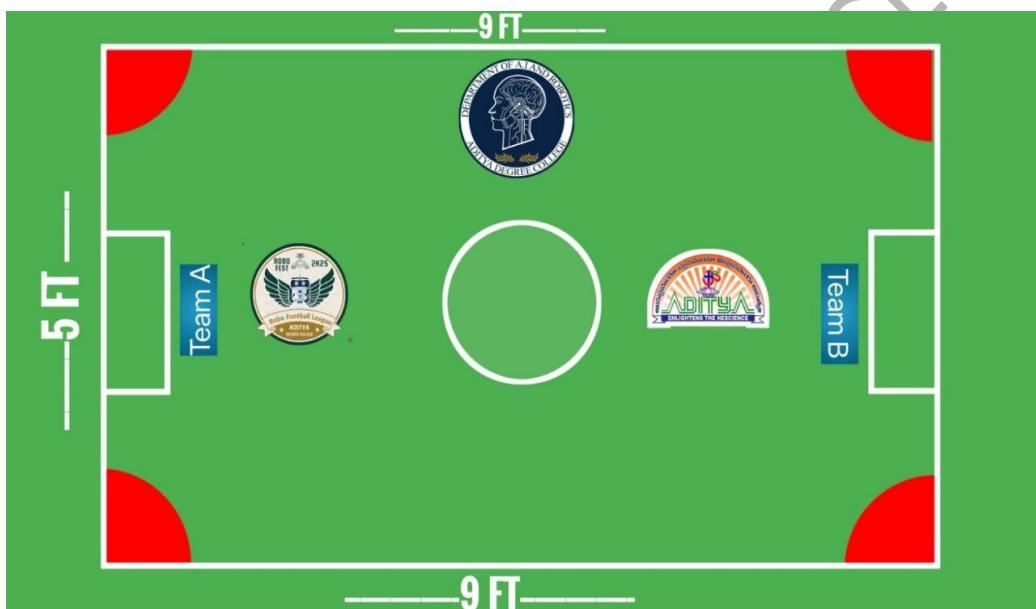
**Game Description, Rules and Scoring**

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## ***Game Description:***

ROBO FOOTBALL LEAGUE aims, to reflect the game of human football with robots. It is a technical competition where student-built robots compete to score goals by pushing a ball into the opponent's goal post. The robots can be either autonomous or manually controlled using Bluetooth, remote control, RF, Wi-Fi, or hand-gesture systems. Matches are played in a defined arena within a fixed time. The team scoring the maximum points wins the match. The event promotes creativity, teamwork, and practical robotics skills.



## ***Rule Changes:***

If the current Football Challenge appears to be mastered, the rules will undergo minor modifications.

## ***Rules and Regulations:***

### ***1. Teams***

- 1.1 Teams will consist of two robots in Double's category.
- 1.2 Team consists one robot in single's category.
- 1.3 Any substitution of robots is strictly forbidden and any team substituting robots will be disqualified from the tournament.
- 1.4 Teams will have three human participants.

## **2. Scoring**

- 2.1 A goal is scored when the ball crosses the goal line.
- 2.2 The team scoring the highest score will win the game.

<b>Colour of balls</b>	<b>Total No. of balls</b>	<b>Score</b>
<b>Red</b>	1	30(30 for each ball)
<b>Green</b>	5	100(20 for each ball)
<b>Blue</b>	7	70(10 for each ball)
<b>Total</b>	13	200

- 2.3 Fouls:

**Negative Score for Balls in the Red Zone:**

Red ball	-15
Green ball	-10
Blue ball	-5

Each team must clear their red zone within the allotted time otherwise foul rules will be applied.

## **3. Game Time**

- 3.1 Game will consist of 4 minutes.
- 3.2 The game clock will run without stopping throughout the game
- 3.3 It is a team's responsibility to be present before a game starts.
- 3.4 If time permits, finals games can be run over 4 minutes.

## **4. Game Play**

- 4.1 At the start of the game the judge will blow a whistle.
- 4.2 The game will start on the judge's command. All robots must be started immediately. Robots can be running, but must be held in a stationary position above the field.
- 4.3 Any robots that are started or released before the judge's command will be moved to initial position.

- 4.4 Any robots that are not on the field or started immediately, will be ruled as “damaged” and removed from the field for one minute.
- 4.5 If two opposing robots are tangled with each other, the judge can choose to separate them with minimal movement.
- 4.6 Team Captains are not permitted to touch robots at any time without the judge’s permission. If a scoring opportunity has been affected by the robot’s removal or incorrect replacement, that goal will not be awarded.
- 4.7 If a ball strikes the end wall beside the goals, play will not be stopped and the ball will be returned immediately to the centre spot on the field. If a robot occupies that spot, the ball will be placed as close as possible to the centre, but not directly in front of a robot.

## **5. Play Reset**

- 5.1 “Reset” will be called if the ball is stuck between multiple robots for a reasonable amount of time and has no chance of being freed, or if no robot has any chance of approaching the ball in a reasonable amount of time.
- 5.2 Any stuck robots will be immediately taken to their defensive penalty box. Some part of the robot must be in the penalty box.
- 5.3 Robots are permitted to remain running and held by the handle.
- 5.4 Any robot that cannot start within the given time will be considered as “damaged”.

## **6. Damaged Robots**

- 6.1 A robot will be considered damaged by the judge if it has serious breakages, it does not move correctly or respond to the ball.
- 6.2 Players can only remove robots from the field after being given the judge’s permission following the Team Captain’s request. This robot will be classified as damaged.
- 6.3 A damaged robot will be withdraw from competition as per team’s request.
- 6.4 If a robot is touched or removed without the judge’s permission penalty will be incurred.

- 6.5 A damaged robot must be repaired before it is returned to the field. If a robot is not, or cannot be repaired, it will be excluded from the remainder of the game.
- 6.6 A damaged robot can be returned to the field after being given the judge's permission. The robot is to be placed in the team's own penalty area and not in a position that advantages that robot i.e. Facing the ball.
- 6.7 If a robot turns over on its own accord or from a collision with its own team's robot, it will be considered damaged.
- 6.8 If a robot turns over as a result of a collision with an opposing robot, it will not be considered as damaged and can be righted by the judge and play.

## **7. Rule Clarification**

- 7.1 **“The Judge’s decision is considered as final during game play!”**
- 7.2 If competitors require a rule clarification they must do it immediately by requesting a “Judges Time Out”. The game clock will be stopped.
- 7.3 Mentors must not be involved in any rules discussion.
- 7.4 Video evidence will not be accepted.
- 7.5 Once the Head Judge and the game judge have come to a decision, no more discussion will be accepted.
- 7.6 Any further argument will result in a Yellow Card being issued, followed by a Red Card if the Team Captain or Mentor continues to argue.
- 7.7 A Red Card will result in that person being required to leave the competition area for the rest of the tournament.
- 7.8 Failure to respect a Red Card will result in permanent exclusion of the person from entire competition.
- 7.9 Touching the robot without the judge's permission is not allowed. After **two warnings**, any further violation will result in a **-5 score penalty**.
- 7.10 The Head Judge may be required to modify rules as a result of local conditions or circumstances. Participants will be notified of this at the earliest available opportunity.

## **8. Robot Specifications**

8.1 Construction and Programming of robots must be done exclusively by the students.

### **8.2 ROBOT CREATION GUIDELINES**

- The robot must be student-built.
- Robot can be Autonomous or wireless controlled- Bluetooth / hand-gesture/remote -control.
- Wired control robots will not be permitted.
- Robot size should not exceed 25 cm × 25 cm × 25 cm.
- Robot weight should not exceed 5kg including battery.

### **8.3 CONTROLLER OPTIONS (ANY ONE CAN BE USED)**

9. Teams may use any controllers Example (Arduino (UNO / Nano / Mega), ESP32 / ESP8266, Raspberry Pi (any model))

### **8.4. CONTROL METHODS ALLOWED**

- Teams are permitted to use any one of the following control methods:
- Bluetooth control (HC-05 / HC-06)
- Remote Controller (RC)
- RF modules (NRF24L01 / 433 MHz)
- Wi-Fi control
- Hand Gesture Control (using accelerometer sensors)
- Vision Sensors
- Depth Sensors
- Any proximity sensors

### **8.5. MECHANICAL & ELECTRICAL PARTS ALLOWED**

- DC gear motors
- Servo motors (for kicking or pushing mechanism)
- Motor drivers (L298N, L293D, BTS7960, etc.)
- Wheels (rubber or plastic)
- Chassis (metal, acrylic, or DIY)
- Jumper wires, PCB, breadboard
- Switches, LEDs (optional)

## *8.6. POWER SUPPLY*

- Rechargeable batteries only  
(Li-ion / Li-Po / Power bank, Ni-Cd / Alkaline)
- Teams must bring their own chargers.
- External power supply during match is allowed.

## *8.7 SAFETY RULES*

- No sharp edges on robots
- Batteries must be properly insulated
- Any robot causing damage may be disqualified.

## *8.8 FINAL NOTE*

- All teams must bring their own robots, controllers, batteries, and charging equipment. The hosting college will provide the area and basic power supply.

## ***9. Robot Assembly***

- 9.1 Robots can be modified during venue open or competition times. i.e. there is no quarantine before or between game.
- 9.2 Robots should not leave the competition area at any time until they have finished competition.

## ***10. Robot Control***

- 10.1 Robots must be able to be started manually.
- 10.2 The use of remote control any kind is allowed.
- 10.3 Robots must be able to move in all directions.
- 10.4 Bluetooth communication between robots is acceptable as long as it does not interfere with the performance of other robots.

## ***11. Finals Selection***

11.1 Teams will be selected for finals on the following criteria:

- Points scored
- Number of Goals Scored
- Goal Difference

- The winning team if the two tied teams competed against each other.

## ***12. Tied Elimination Finals***

12.1 If the scores are tied in an elimination final, a “**GOLDEN GOAL ROUND**” of 1 extra minute will be conducted, and the team which scores highest will be declared the winner.