

### Lab 5: Garage Occupancy Counter

**Sign-Off Sheet** 

Student 1: Ciara Murphy

Student 2: Brandon Simpson

YOU ARE RESPONSIBLE TO COMPLETE ALL THE ASSIGNMENTS IN THE CHECK LIST BELOW IN ORDER TO GET FULL CREDIT FOR THE LAB...

Check List		
	Assignments	TA Sign-off
Pre-Lab (MUST be completed before the start of the lab)		
1.	Counter	
2.	FSM Car Entering/Exiting	
3.	Simulation	
Read Lab Write-up		
Lab part		
Create Source File for the following Modules:		
i.	BCD7SEG	
ii.	Slow Clock	
iii.	2-bit Counter	
iv.	4 to 1 Mux	
٧.	Decoder2-to-4	
vi.	BinarytoBCD	
vii.	8-bit-Counter	
viii.	Debounce	
ix.	FSM_Enter	
х.	FSM_Exit	
xi.	Top Module (put the system together)	
Project File(s) Unload on CANVAS (Import all files in one folder, zin it unload it)		

#### Project File(s) Upload on CANVAS (Import all files in one folder, zip it, upload it)

- 1. Upload Sign-off Sheet
- 2. Upload your project files (zip the folder), name your file as: lastname\_labn\_D'20

### Present your work

Record a 2-3 minute video showing that all parts of your lab functioned properly.

Show your work to TAs for the sign-off over Zoom.

Upload the Writing Assignment (Debugging and Troubleshooting errors FAQ's) - OPTIONAL

Due Date: 05/13/2020

<sup>\*\*</sup>Both Students MUST be present at Sign-off for any and all parts!!

## **Prelab 5: Garage Occupancy Counter**

## 1. Objective

The objective of this lab is to design an occupancy counter to display how many cars are currently parked in the garage. Fig. 1 shows a typical garage entrance with sensors on both entrance and exit gates.



Figure 1. Garage entrance and exit with photo sensors

### 2. Detecting Vehicle Entering the Garage

The basic design is to use a pair of photo sensors. When an object is between the optical transmit and optical receiver, the light is blocked and the corresponding output is asserted to '1'. Otherwise, the output is '0'. As shown in Fig. 1, we can determine if a car has entered the garage by monitoring the events (orders) of these 2 sensors.

The sequence can be described as the following:

- a) Initially, both sensor are unblocked (i.e., a and b signals are "oo")
- b) Sensor a is blocked (signals are "10")
- c) Sensor b is blocked (signals are "o1")
- d) Both sensors are unblocked ("oo")



Although it is not required for this lab design, you may consider the question: What if the car is very long (a limousine) or very short (a smart)?

## 3. Detecting Vehicle Exiting the Garage

The sequence will be the opposite as that of entering:

- a) Initially, both sensor are unblocked (i.e., c and d signals are "oo")
- b) Sensor d is blocked (signals are "o1")
- c) Sensor c is blocked (signals are "10")
- d) Both sensors are unblocked ("oo")



Although it is not required for this lab design, you may consider the questions: What if the car is very long (a limousine) or very short (a smart)? Could a pair of sensors be "11" or "00" in between steps b) and c)?

#### **IMPOTANT!**

When you press a button, there is a chance that the button will not simply go from open to close. Since a button is a mechanical device, the contacts can bounce. For a short period after the button is pressed the value you read from an IO pin may toggle between o and 1 a few times before settling on the actual value. To debounce a button, you just need to require that for a button to register as being pressed, it must look like its being pressed for a set amount of time. In this case, being pressed is when the value of the button is 1. If you read enough 1's in a row it is safe to assume that the button has stopped bouncing and you can register one button press. If you fail to do this and you are using the button to increment a counter, then the counter may increase by more than 1 per button press since it will appear that each bounce was a separate press.

### 4. Prelab Tasks

A. Design an 8-bit counter: The counter has two inputs (inc and dec). When inc = 1, the counter is incremented by 1. When dec = 1, the counter is decremented by 1. The block diagram is shown in Fig. 3. Write the Verilog code and test it through Vivado simulation.

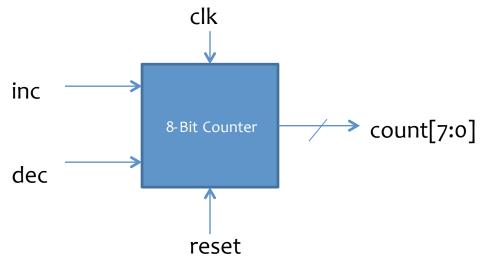


Figure 3. Block diagram of an 8 -bit counter

## module counter(

```
input
                             //clock
input
                             //reset
                             //increment
input
input
                             //decrement
output [7:0]
                             //count, max count is 255 (8-bit)
);
reg[7:0] current count = 0;
                                    //initially setting counter to zero
always @(posedge clk) begin
                                           //when positive edge of the clock arrives
       if(reset)
              current count <= 0;
```

endmodule

**B.** Design a finite state machine (FSM) to detect a car entering the garage: the FSM generates a pulse of signal (inc = 1) for one clock cycle for each car entry.

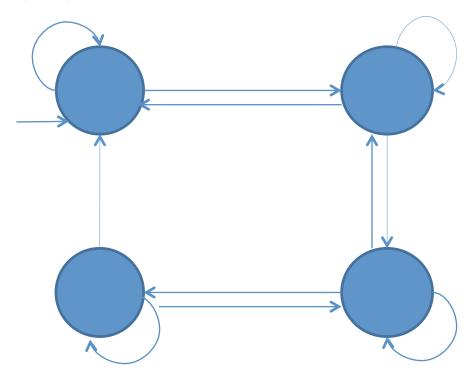


Figure 4. An example of the FSM for detecting the car entering the garage

There are many different ways to design such as FSM. You can design in a different way. Test your design using a simulation testbench in Vivado.

```
module FSM(
input clk,
input reset,
input sensor_1,
input sensor_2,
output count_flag);
```

```
localparam Soo = 0, So1 = 1, S10 = 2, FLAG = 3;
                                // Current State
  reg[1:0] current state = 0;
  reg[1:0] next state = 0;
                                        // Next State
  reg set flag = 1;
                                         // Flag for when to count
// Next state sequential logic
  always @(posedge clk) begin
    if (reset) current state <= Soo;</pre>
else current state <= next state;
  end
// Next state combinational logic
  always @(current state, sensor 1, sensor 2)
  begin
    case(current state)
       Soo: begin
              if (sensor 1 & ~sensor 2)
                     next_state = So1;
              else
                     next state = Soo;
       end
       So1: begin
              if (~sensor 1 & sensor 2)
                     next state = S10;
              else
                     next state = So1;
       end
       S10: begin
              if(~sensor 1& ~sensor 2)
                     next state = FLAG;
              else
                     next state = S10;
       end
       FLAG: begin
              next state = Soo;
       end
```

```
default: begin // Implied-latch free implementation
        next state = Soo;
      end
endcase
end
// Combinational output logic for each state
 always @(current state) begin
case (current state)
      Soo: begin
            set flag = o;
  end
      So1: begin
            set flag = o;
      end
      S10: begin
            set flag = o;
      end
      FLAG: begin
            set flag = 1;
      end
      default: begin
       set_flag = o;
     end
endcase
end
// Output assignment
//-----
assign count flag = set flag;
endmodule
```

Similarly, design a finite state machine (FSM) to detect a car exiting the garage: the FSM generates a pulse of signal (dec = 1) for one clock period for each car exit.

# 5. Prelab Signoff

You can signoff the prelab by demonstrating all the above 3 blocks in Vivado simulation environment.