Rahul Kumar

SDE 2 | vernwalrahul@gmail.com | +49 1627074699 | Berlin, Germany | 2.5+ years of experience

EDUCATION

IIT KHARAGPUR

B.Tech in Computer Science

2016 - 2020 CGPA: 9.16 / 10.0

DAV KAPILDEV

Grad. May 2016 Ranchi, India Grade: 95.4%

SKILLS

Field

Robotics, Machine Learning, Systems, Cloud and DevOps, DBMS Languages

- C++ Python SQL TypeScript Libraries and Tools:
- Docker Flask RDS, DynamoDB Pytorch OpenCV ROS

Platform, Cloud and DevOps AWS

- Unix, Linux CDK, Cloudformation
- Lambda, S3, Sagemaker, SNS, SQS, Kinesis

LINKS

Github://vernwalrahul LinkedIn://vernwalrahul Medium://@rahulvernwal

COURSEWORK

Programming and Data Structures Algorithms Software Engineering Database Management System Compilers + Operating Systems Artificial Intelligence (AI) Machine Learning Reinforcement Learning

RESPONSIBILITIES

Information Retrieval

Image Processing

- Software Lead: Manual Annotation Cell Deployment in 3 FCs over multiple countries - Amazon, Berlin
- 6 months SDE intern mentor '22 -Amazon, Berlin
- MIT-IIT Robotics Workshop
- IEEE Robotics Winter Workshop
- Kharagpur Winter of Code 2017

Executive Head

- Code Club, IIT Kharagpur
- Kharagpur Open Source Society

EXPERIENCE

AMAZON ROBOTICS | SOFTWARE DEVELOPMENT ENGINEER (SDE) - 2

Oct 2022 - Till date | Berlin, Germany

Working Areas - Machine Learning, Large Scale Deployments, AWS

- Designed and implemented AWS services linking ground truth retrieval and automated annotations for production services
- Worked on integrating gallery storage with live inference system to retrieve items' reference images and dimensions for damage detection Models
- Mentored an intern on 6 months project to build Segmentation and Crop Service for live system and batch processing

AMAZON ROBOTICS | SOFTWARE DEVELOPMENT ENGINEER (SDE) - 1

Jan 2021 - Sept 2022 | Berlin, Germany

Working Areas - Docker, CI/CD pipeline, Operating System, AWS, Flask

- Worked on edge services for detecting tray items Virtual Physical Mismatchs (VPMs) at Amazon FCs
- Alpha launched in Oct'21 processing **1 million+ items per month**. Supported in beta deployment (launched Oct'22) increasing number of cells **8 folds**
- Setup CI/CD pipeline, integration test infrastructure for all the edge services
- Led deployment of 3 Manual Annotation Cells in different countries collecting 60k+ labelled captures in 2022 for damage detection

WADHWANI AI | SOFTWARE ENGINEER - INTERN

May 2020 - July 2020 | Mumbai, India

Working Areas - PCA, 3D Modelling

- Worked on adapting anthropometry models to learn shape space for newborns.
- Registered 3D models for a dataset of 100 newborns
- Worked on iterative optimization for SMIL model on registered dataset

AMAZON ROBOTICS | SOFTWARE ENGINEER - ROBOTICS INTERN

May 2019 - July 2019 | Seattle, USA

- Built end to end Stack for box picking using UR10 (6DoF Robotic Arm).
- Designed perception module to identify boxes from time of flight image.
- Integrated controller, motion planning and calibration modules.
- Deployed entire stack to AWS code pipeline.

PERSONAL ROBOTICS LAB | University of Washington

Research Intern Advisor: Prof. Siddhartha Srinivasa

May 2018 - July 2018 | Seattle, USA

Topic: Learning Sampling Methods for constrained space motion planning

- Devised non uniform sampling strategies to bias sampling in bottleneck regions.
- Devised algorithms to increase robustness of the generated graph.
- Our algorithm outperformed state of the art method on a wide range of problems | Accepted at IRoS '19

Working Areas - Deep Learning, AutoEncoders, Constrained Space Problems

AWARDS

2022	Top performer	RAI (Robotics and AI), Amazon
2019	Final Round Worldwide	Game of Drones NIPS'19 with Microsoft
2019	Final Round National	Smart India Hackathon
2017	Worldwide	RoboCup SSL First Indian Team
2016	All India Rank 9 th	KVPY Fellowship
2016	top 0.03% (AIR 266)	JEE Advanced

OTHER PROJECTS

LEARNING A ROBUST WALK ENGINE FOR NAO ROBOTS

Jul 19 - Apr 20 Advisor : Prof. Jayanta Mukhopadhyay

One of the major challenge in RoboCup Humanoid League is to enhance the speed and robustness of Nao walk engine. Together with my advisor, I worked to build a walk engine for Nao Robotcs through Reinforcement Learning. We evaluated various different algorithms like evolution strategies, PPO, DDPG, and Soft Actor Critic Method. Working Areas: Reinforcement Learning, Evolution Strategies, Imitation Learning.

ACTION/EVENT RECOGNITION FOR SAFETY ANALYTICS

DEC'17 - FEB'18 ADVISOR: PROF. PABITRA MITRA

Recognising actions in video clips by extending CNN in the time domain. The model developed to be most suited foran industrial setting like detecting accidents in a factory.

Working Areas: Computer Vision, ConvNets, Encoder Decoder Models

QUESTION GENERATION FROM RDF GRAPH VIA DISCRIMINATIVE RANKING

AUG'18 - NOV'18 ADVISOR : PROF. PLABAN BHOWMICK

Developed an application to automatically generate Q/A pairs from RDF graphs. It involves identification of popular-entities, extraction of their relation with other entities using hop distance. Extracted tokens are then fed to tranformations and ranking algorithm to produce a ranked list of questions.

Working Areas / Libraries: Knowledge Graph, Ranking Algorithm, SPARQL

MEDICAL OCR

Jan'18 - Mar'18

Worked in a team of 6 to build an OCR for detecting of medical professionals from prescriptions. Integrated Peter Norvig's spelling corrector algorithm to auto-correct misspelled words.

Working Areas: Computer Vision, Character Recognition, Spelling Correction

RRT SIMULATOR

REPOSITORY: RRTSIMULATOR

Developed an interactive GUI interface to simulate a path generated by RRTs avoiding obstacles using Python and Qt. Added Features for low level skill testing of individual robots. Tools and Libraries: OMPL, PyQt, ROS.

BLOCKCHAIN CERTIFICATES

An application on digital certificates using blockchain technology to avoid fraud certificates and speed up the verification process.

Won 3rd prize at National Level Hackathon.

TECHNICAL BLOGS

• Creating Your Messenger Bot with Python

21k views

How Should I Start with CNN

2.5k views

• An Introduction to Variational Auto-Encoder

1.1k views