



[English](#) | [Japanese](#)

[Top](#) > [Tools](#) > [Filters](#) > [Multiple Feedback High-pass Filter Design Tool](#)

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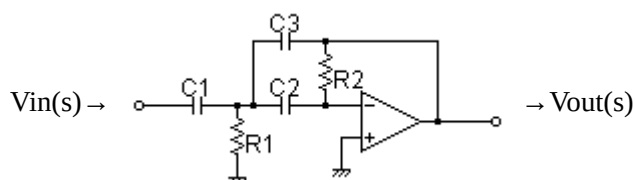
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# Multiple Feedback High-pass Filter Design Tool

This page is a web application that design a multiple feedback high-pass filter. Use this utility to simulate the Transfer Function for filters at a given frequency, damping ratio  $\zeta$ , Q or values of R and C. The response of the filter is displayed on graphs, showing Bode diagram, Nyquist diagram, Impulse response and Step response.

[Sample calculation](#)

**Calculate the transfer function for multiple feedback high-pass filter with R and C values**



Transfer function:

$$\frac{v_o}{v_i} = \frac{-s^2 \frac{C1}{C3}}{s^2 + s \frac{C1+C2+C3}{R2C2C3} + \frac{1}{R1R2C2C3}}$$



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VER

R1=  Ω

C1=  F

**Calculate the R and C values for the multiple feedback filter at a given frequency and Q factor**

R2=   $\Omega$       C2=  F  
C3=  F

p:pico, n:nano, u:micro, k:kilo, M:mega

### Frequency analysis

- ☒ Bode diagram
  - ☒ Phase    ☐ Group delay
- ☒ Nyquist diagram
- ☒ Pole, zero
- ☒ Phase margin
- ☒ Oscillation analysis

Upper and lower frequency limits:

f1=  - f2=  [Hz]

(frequency limits are optional)

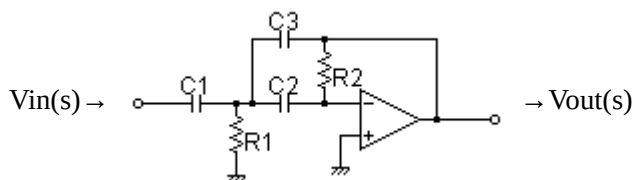
### Transient analysis

- ☒ Step response
- ☐ Impulse response
- ☒ Overshoot
- ☒ Final value of the step response

Simulation time:

0 -  [sec] (optional)

**Calculate**



Cut-off frequency:

$$f_c = \frac{1}{2\pi\sqrt{R_1 R_2 C_2 C_3}}$$

Transfer function:

$$\frac{V_{out}(s)}{V_{in}(s)} = \frac{s^2 K}{s^2 + 2\zeta(2\pi f_c)s + (2\pi f_c)^2}$$

$$Q = \frac{1}{2\zeta}$$

$$K = -\frac{C_1}{C_3}$$



$f_c =$   Hz

Gain  $K =$   at  $f = \infty$  Hz ( $K < 0$ )

#### Q factor | Damping ratio $\zeta$

☐ Quality factor  $Q =$

☒ Damping ratio  $\zeta =$

$C_1 =$   F  $C_2 =$   F

$C_3 =$   F

$C_1$ ,  $C_2$ ,  $C_3$  is optional. But when setting these capacitances,  $C_1$ ,  $C_2$  and  $C_3$  of all are needed to give, and  $K$  setting is ignored.

Select Capacitor Sequence: E6 ▾

Select Resistor Sequence: E24 ▾

**Frequency analysis**

- ☒ Bode diagram
  - ☒ Phase ☐ Group delay
- ☒ Nyquist diagram
- ☒ Pole, zero
- ☒ Phase margin
- ☒ Oscillation analysis

Upper and lower frequency limits:

f1 =  - f2 =  [Hz]

(frequency limits are optional)

**Transient analysis**

- ☒ Step response
- ☐ Impulse response
- ☒ Overshoot
- ☒ Final value of the step response

Simulation time:

0 -  [sec] (optional)**Calculate**

**Filter tools**[RC LPF](#)[RC HPF](#)[LR LPF](#)[LR HPF](#)[RLC LPF](#)[RLC HPF](#)[RLC BPF](#)[RLC BEF](#)[Sallen-Key LPF](#)[Sallen-Key HPF](#)[3rd order](#)[3rd order](#)[SallenKeyLPF](#)[SallenKeyHPF](#)[Multiple feedback  
LPF](#)[Multiple feedback  
HPF](#)[Multiple feedback  
BPF](#)[3rd order](#)[3rd order](#)[TwinT notch](#)[Multiple feedback](#)[Multiple feedback](#)[CB 2nd order](#)[Active filter](#)[LPE,HPF,BPF](#)[HPF](#)[Filter index](#)