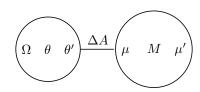
## Sum-Product notes

November 5, 2012



 $\mu = \Delta A\Theta$  Given any point  $\mu$  there exists a  $\theta$ . Given any point  $\mu'$  there is a  $\theta'$ .

When is the map 1-1? When the exponential family is not minimal. Variational methods are about moving from one representation to another. When it is 1-1,  $(\Delta A)^{-1}$  exists.

$$A\theta = \sup_{\mu \in M} \{ \langle \theta, \mu \rangle - A^*(\mu) \}$$

 $A\theta = \sup_{\mu \in M} \{ \langle \theta, \mu \rangle - A^*(\mu) \}$  This is discrete over complete sufficient statistics.

$$P_{\theta}(x) = \exp\{\sum_{s} \theta_{s} x_{s} + \sum_{s} (s, t \in E)(x_{s} x_{t})\}$$
  
$$\theta_{s} = \sum_{j,i} \theta_{s_{ij}} \perp_{s_{j}} (x, s)$$

$$\theta_s = \sum_{j,i} \theta_{s_{ij}} \perp_{sj} (x,s)$$

## Pseudo-marginals

$$\mu = \begin{cases} ll \mu_s(x_s) & \text{Nodewise} \\ \mu_{st} & (x_s, x_t - \text{Pairwise marginals of some distribution } P \end{cases}$$

 $\mu_{st}$  is only defined over edges of G.

$$\mathbb{L}_G = \begin{cases} llT_s(x_s) & s \in V \\ T_{st} & (s,t) \in E \end{cases}$$

Norm 
$$\sum_{x_s} T_s x_s = 1$$
  
Marginals  $\sum_{x_s} T_{st}(x_s x_t) = T_t(x_t)$ 

Marginals  $\sum_{x_t} T_{st}(x_s x_t) = T_t(x_t)$ 

 $Prop(I)\mathbb{L}G \supseteq M(G)$ 

If  $\mu \in M(G)$  it satisfies norm and marginal constraints  $\to \mu \in \mathbb{L}G$ 

There are exponential constraints for  $\mu$  and linear ones for  $\mathbb{L}(G)$ 

$$P(x_1, \dots, x_n)\mu_i(x_i) = P(x_i)$$
  
$$\mu_{i,j}(x_ix_j) = P(x_i, x_j)$$

If graph G is a tree T, then  $\mathbb{L}(T) = \mu(T)$  because nodewise and pairwise marginals are all we need.

Proof

 $L(G) \supseteq \mu_G$  (Shown). We want to show that  $\mathbb{L}(T) \subseteq \mu_T$ . We will take a  $\mu \in \mathbb{L}(T)$  such that it satisfies marginal constaints and show that it is consistent with regard to a joint distribution.

$$\mu_s(x_s), s \in V$$

$$\mu_{st}(x_s)(x_t), (s,t) \in T$$

$$P_{\mu}(x) = \prod_{s \in V} \mu_s(x_s) \prod_{s,t \in E} \frac{\mu_{st}(x_s x_t)}{\mu_s(x_s) \mu_s(x_s)} \text{ such that } \mu \text{ is consistent with regard to } P_{\mu}.$$

We can compute the Bethe-entropy of the tree-structure distribution. Suppose we have a tree-structured distribution with mean parameters  $\mu$ . Then we can write down the distribution in terms of  $\mu$ .

$$A_{(\mu)}^* = \operatorname{entropy}(P_{\mu})$$

$$= \mathbb{E}_{pm} |\log P_{\mu}(x)|$$

$$= \mathbb{E}_{pm} |\sum_{s \in V} \log \mu_s(x_s) + \sum_{s,t \in E} \log \frac{\mu_{st}(x_s, x_t)}{\mu_s \mu_t}|$$

$$= -\sum_s \mathbb{H}_s < \mu_s right > -\sum_{s,t \in E} I_{s,t}(\mu_{s,t})$$

$$\mathbb{H}_{Bethe}(\mu) = \sum_{s \in V} \mathbb{H}_s(\mu_s) - \sum_{s,t \in E} I_{s,t}(\mu + s, t)$$

$$= -A^*(\mu) \text{Exactly when } G \text{ is a tree}$$

Computing entropy in the general case is NP-hard, but we can approximate it when G is not a tree using the variational principle.

We can approximate to  $A(\theta)$  as so:  $A_{Bethe}(\theta) = \sup_{\mu \in \mathbb{L}(G)} \{ \langle \theta, \mu \rangle + \mathbb{H}_{Bethe}(\mu) - I \}$ 

We get sum-product from the fixed point update driven solution of optimization problem I.

$$\mu_{st}(x_t) = \Psi_{st}(x_s, x_t) \Pi_{v \in N(S)_t} \mu_{v_s}(x_s)$$

This is a nonconvex problem. If we do coordinate descent on the dual, we can get to a local minimum. Regular sum-product often oscillates between very large  $(O(v^2))$  parameters.

## Reparamaterization

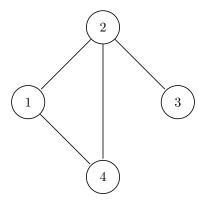
Suppose we solve sum-product to a local minimum  $\tau^*$  (a local minimum of J). Then  $P_{\tau^*}(x) = I\Pi_{s \in V} T_s^*(x_s) \Pi_{s,t \in E} \frac{T_{st}^*(x_s, x_t)}{T_s^*(x_s) T_t^*(x_t)}$ 

We know that if G is a tree and  $T^* = \mu^*$ , then  $P_{T^*} = P_{\theta}$  and  $P_{T^*}(x) = P_{\theta}(x)$ 

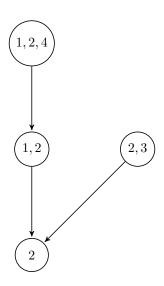
So it always holds that  $P_{\theta}(x) = P_{T^*}(x)$ 

## Hypergraphs

Define a hypergraph  $G \in (V, E)$  with nodes  $v \in V$  and hyperedges  $e \in E$  such that  $e \subseteq E$ . A normal graph is a hypergraph with 2-node edges. We can write the following graph as E = (1, 2)(2, 3)(1, 4)(2, 4) or we can write E = (1, 2, 4), (2, 3)



Suppose we have the hypergraph with edges E = (1, 2, 4), (2, 3), (1, 2), (2). Then we have a nodefor each superedge and we connect  $h \to g$  if  $g \in h$ . These form a partially ordered set with regard to set inclusion.

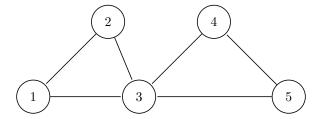


A general graphical model has subsets over cliques. The hypergraph edges correspond to cliques. We can do inference on these cliques.

Given a set of sufficient statistics  $\mathbb{L}(G) = T_n(x_n)$ , such that  $\sum_n T_n(x_n) = 1$  we have g, h such that  $f \subseteq h$ :

$$\sum_{x_h} |x_g T_n(x_n) = T_g(x_g)|$$

For the following graph



(1, 2, 3) and (3, 4, 5) must be consistent.

 $H_{hypertree}(\mu) = \sum_{n \in E} c(h) H_h(\mu_k)$  where c(h) are overcounting numbers.  $\sup_{\mu \in \mathbb{L}_G} \{ <\theta, \mu > + H_{HT}(\mu) \}$ 

Message passing here is generalized beleif propagation.