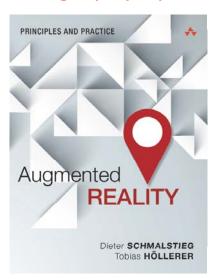
Virtual and Augmented Reality 2017-2018

Augmented Reality

Previous lectures

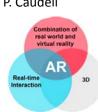
- Remembering ...
 - VR & AR definitions
 - What is the difference between VR & AR?
 - VR & AR applications
 - VR & AR hardware
 - HW limitations

Bibliography update

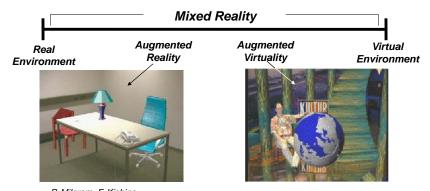


AR (Augmented Reality) Definition

- - AR concept was created in 1990, by Thomas P. Caudell
- AR definition (Azuma, 1997)
 - combines real & virtual worlds
 - interactively, in real-time
 - real & virtual objects are aligned in 3D
- AR is not limited to the view sense ...



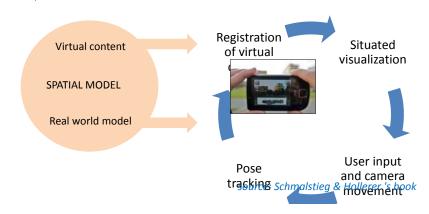
Reality-Virtuality Continuum



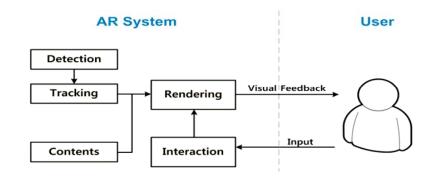
P. Milgram, F. Kishino,
"A Taxonomy of Mixed Reality Visual Displays",
SPIE Vol. 2351, Telemanipulator and Telepresence Technologies, 1994.

AR Feedback Loop

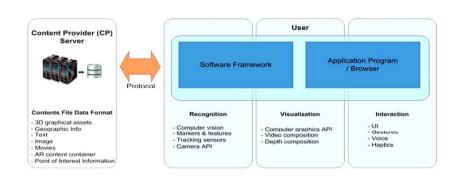
AR uses a feedback loop between human user and computer system.
The user observes the AR display and controls the viewpoint.
The system tracks the user's viewpoint,
registers the pose in the real world with the virtual content,
and presents situated visualization.



AR Workflow



AR Technologigal Components



source: www.coursera.org/learn/iot-augmented-reality-technologies

source: www.coursera.org/learn/iot-augmented-reality-technologies

AR hardware

- AR hardware
 - positioning:
 - vision / cameras
 - other sensors:
 GPS, wifi, compass, accelerometer, gyroscope
 - visualization:
 - monitor/display,
 - HMDs (optical-see-through / video-see-through)
 - projector
 - processing:
 - desktop/laptop
 - handheld

AR software

- Libraries
 - ARToolkit, ..., OSGART, Studierstube, Vuforia,...
 - FLARToolKit (integration of ARToolkit into Adobe Flash)
 - to do: search for more
- AR browsers
 - superimpose points of interest on a live video feed
 - Layar, Metaio, Wikitude, ...
 - to do: search for more
 - http://www.perey.com/ARStandards/survey-of-mobile-ar-browsers/
 - https://ercim-news.ercim.eu/en103/special/an-introduction-to-ar-browsers

Combining sensors and vision

- Sensors
 - Give us first information on where we are in the world, and what we are looking at
 - Are not sufficiently accurate (= wrongly placed augmentations)
 - Produce noisy output (= jittering augmentations)
- Vision
 - Is more accurate
 (= stable and correct augmentations)
 - Requires choosing the correct keypoint database to track from
 - Requires registering our local coordinate frame (online-generated model) to the global one (world coordinates)
- Hybrid (Vision + Sensors)

Vision-based AR

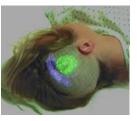
- Marker-based
 - fiducial markers
 - barcodes
- Marker-less (natural feature tracking)
 - Tracking from features of the surrounding environment
- Pros & Cons
 - **–** ...?



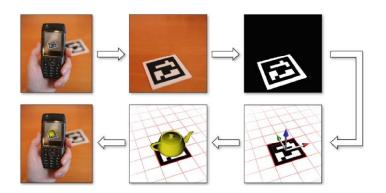




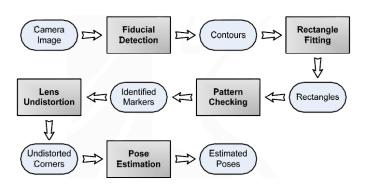




Marker tracking pipeline



Marker tracking overview



Natural feature tracking

