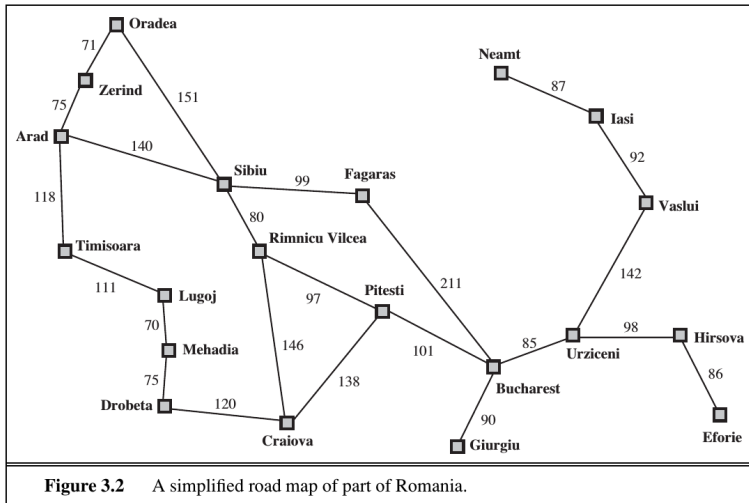


Informed (Heuristic) Search Strategies

- ▶ Evaluation function $f(n)$
- ▶ Heuristic function $h(n)$

Informed (Heuristic) Search Strategies



Straight Line Distances

Arad	366	Mehadia	241
Bucharest	0	Neamt	234
Craiova	160	Oradea	380
Drobeta	242	Pitesti	100
Eforie	161	Rimnicu Vilcea	193
Fagaras	176	Sibiu	253
Giurgiu	77	Timisoara	329
Hirsova	151	Urziceni	80
Iasi	226	Vaslui	199
Lugoj	244	Zerind	374

Figure 3.22 Values of h_{SLD} —straight-line distances to Bucharest.

Greedy Best-first Search

- ▶ Evaluation function $f(n)$ = $h(n)$

Greedy Best-first Search

$g(n)$

- Evaluation function $f(n) = \underline{h(n)}$

$h(B) = 0$

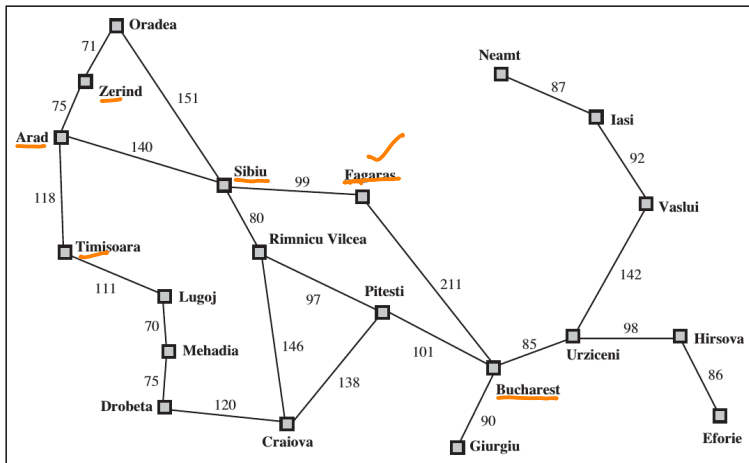


Figure 3.2 A simplified road map of part of Romania.

Greedy Best-first Search

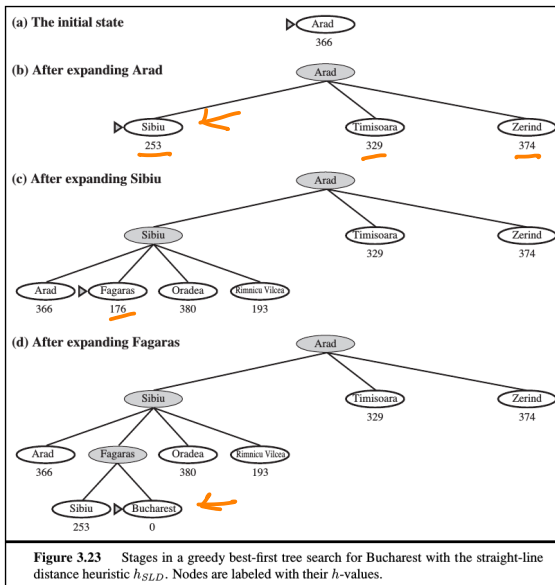
- ▶ Tree search



- ▶ Graph search



Greedy Best-first Tree Search



Greedy Best-first Tree Search

$h(w)$

N, V, E, W

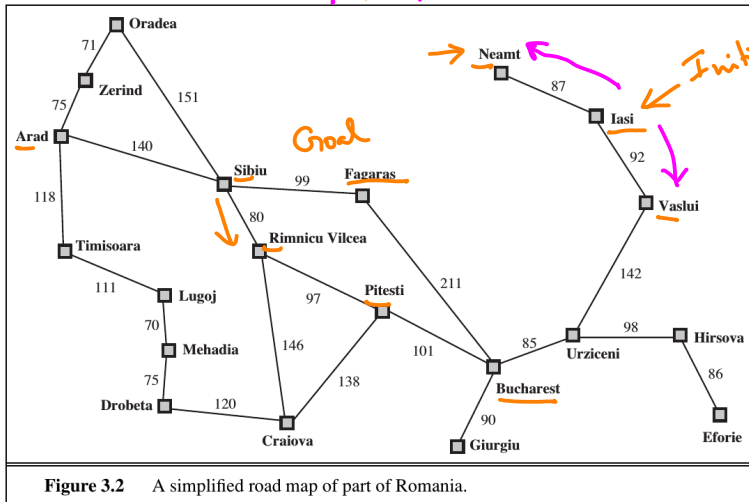


Figure 3.2 A simplified road map of part of Romania.

- ▶ Greedy Best-first Tree search for finite state space
 - ▶ Completeness?
 - ▶ Optimality?

- ▶ Greedy Best-first Tree search for finite state space
 - ▶ Completeness?
 - ▶ Optimality?
 - ▶ Time complexity?


- ▶ Greedy Best-first Tree search for finite state space
 - ▶ Completeness?
 - ▶ Optimality?
 - ▶ Time complexity? May not terminate.

- ▶ Greedy Best-first Tree search for finite state space
 - ▶ Completeness?
 - ▶ Optimality?
 - ▶ Time complexity? May not terminate.
 - ▶ Space complexity?

- ▶ Greedy Best-first Tree search for finite state space
 - ▶ Completeness?
 - ▶ Optimality?
 - ▶ Time complexity? May not terminate.
 - ▶ Space complexity? Linear in depth of the search tree.

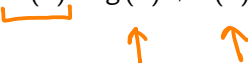
- ▶ Greedy Best-first Tree search for finite state space
 - ▶ Completeness?
 - ▶ Optimality?
 - ▶ Time complexity? May not terminate.
 - ▶ Space complexity? Linear in depth of the search tree.
- ▶ Greedy Best-first Graph search for finite state space
 - ▶ Completeness? ←
 - ▶ Optimality? ←

- ▶ Greedy Best-first Tree search for finite state space
 - ▶ Completeness?
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 - ▶ Optimality?
 - ▶ Time complexity? May not terminate.
 - ▶ Space complexity? Linear in depth of the search tree.
- ▶ Greedy Best-first Graph search for finite state space
 - ▶ Completeness?
 - ▶ Optimality?
 - ▶ Time complexity? $= O(b^m)$ ← 
 - ▶ Space complexity? $= O(b^m)$



► $f(n) = g(n) + h(n)$



A* tree search

A

$$g(A) = 0 \quad h(A) = 366$$

$$f(A) = 366$$

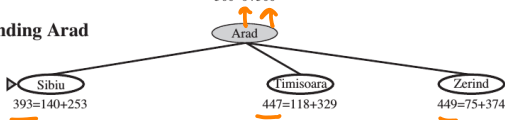
$g(n)$

$f(n)$

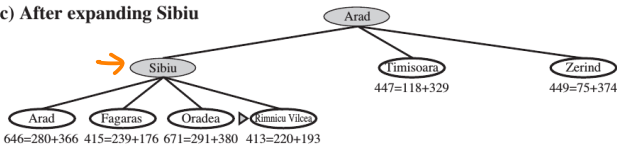
(a) The initial state



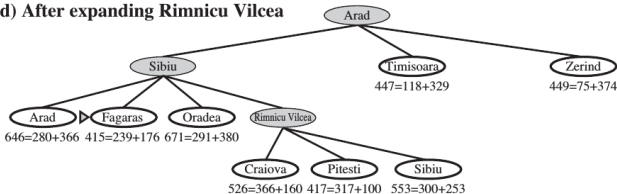
(b) After expanding Arad



(c) After expanding Sibiu

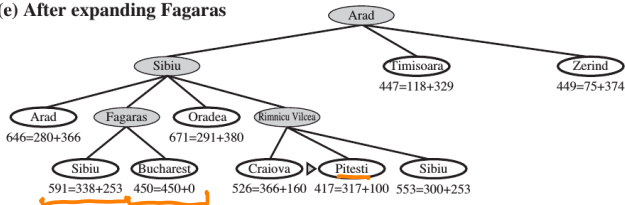


(d) After expanding Rimnicu Vilcea

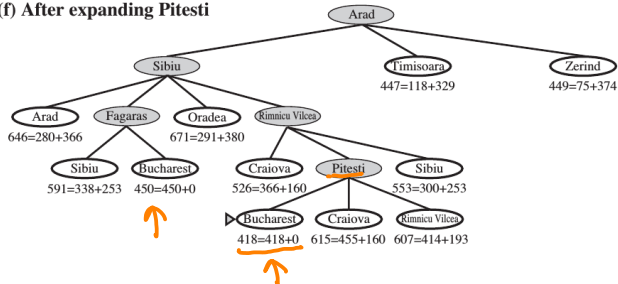


A* tree search

(e) After expanding Fagaras



(f) After expanding Pitesti



Uniform cost search vs. A* graph search

$$g(n)$$

$$g(n) + h(n)$$

$$g(G)$$

- ▶ Essentially, we have replaced the path function $g(n)$ in Uniform cost search with the evaluation function $f(n)$.

Uniform cost search vs. A* graph search

$g(\text{Goal})$

$f(\text{Goal})$

$g(n)$

- ▶ Essentially, we have replaced the path function $g(n)$ in Uniform cost search with the evaluation function $f(n)$.
- ▶ Can we be sure that when the goal state is popped out of the priority queue in A* graph search the function $f(n)$ will be minimized?

$f(n)$

$$\begin{aligned} \rightarrow \underline{f(\text{Goal})} &= \underline{g(\text{Goal}) + h(\text{Goal})} \\ &= g(\text{Goal}) \end{aligned}$$

Conditions for non-decreasing $f(n)$ in A^* search

Consistent heuristic:

$$h(n) \leq c(n, a, n') + h(n')$$

