# 直交基底、直交行列、Gram-Schmidtの直行化法

正規直交

ベクトル $q_1 \cdots q_n$ は

$$q_i^T q_j egin{cases} 0 & i \neq j ig($$
直交ベクトル $ig) \\ 1 & i = j ig($ 単位ベクトル $: \|q_i\| = 1 ig) \end{cases}$ 

射影と最小2乗:正規直交の場合

もしAの列が正規直交ならば

$$A^{T}A = \begin{bmatrix} \cdots & a_{1}^{T} & \cdots \\ \cdots & a_{2}^{T} & \cdots \\ \cdots & \vdots & \cdots \\ \cdots & \vdots & \cdots \\ \cdots & a_{n}^{T} & \cdots \end{bmatrix} \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ a_{1} & a_{2} & \cdots & a_{n} \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix} = I$$

これにより、射影行列は

$$P = AA^T$$
,  $\overline{x} = A^Tb$ 

となる

#### 3.3.1

$$A = [1, -2; 1, -1; 1, 1; 1, 2]$$

A =

$$b = [-4; -3; -1; 0]$$

b =

-4 -3

-3 -1

ans =

0

$$C = \frac{1}{2}c$$

$$c = 2C$$

$$D = \frac{1}{\sqrt{10}}d$$

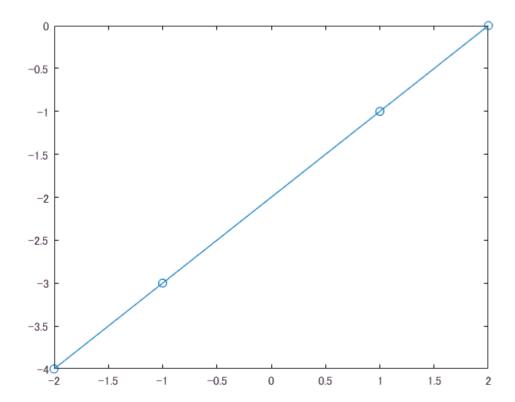
$$d = \sqrt{10}D$$

$$A2 = [A(:,1)*(1/4),A(:,2)*(1/10)]$$

$$y = -2 + t$$

$$t = [-2, -1, 1, 2]$$

plot(t,-2+t,'-0')



#### A \* x

ans =

- 4

-3 -1 0

0

## norm(A\*x-b)

ans =

## 3.3.2

b = [0;3;0]

b =

0 3 0

a1 = [2/3; 2/3; -1/3]

a1 =

2/3 2/3 -1/3

```
a2 = [-1/3; 2/3; 2/3]
  a2 =
       -1/3
        2/3
        2/3
 a1 * a1'*b
  ans =
        4/3
        4/3
        -2/3
  a2 * a2' *b
  ans =
       -2/3
        4/3
        4/3
 A = [a1, a2]
  A =
        2/3
                      -1/3
        2/3
                       2/3
       -1/3
                       2/3
 A * A' * b
  ans =
        2/3
        8/3
         2/3
3.3.3
 a3 = [2/3; -1/3; 2/3]
  a3 =
        2/3
       -1/3
        2/3
 a3 * a3' * b
  ans =
       -2/3
```

1/3 -2/3

A = [a1, a2, a3]

2/3

-1/3

2/3

A =

a1 \* a1'\*b+a2 \* a2' \*b + a3 \* a3' \* b

#### 直交行列

正規直交の列を持つ正方行列

$$Q^{T} Q = I$$

$$QQ^{T} = I$$

$$Q^{T} = Q^{-1}$$

例1

$$Q = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

$$Q^{T} = Q^{-1} = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$

#### 例2

交換行列Pは直交行列

$$P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$P^{-1} = P^{T} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$P^{-1} = P^{T} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$