Highway

Open source C++ library for performance-portable SIMD

Jan Wassenberg, Rhett Stucki

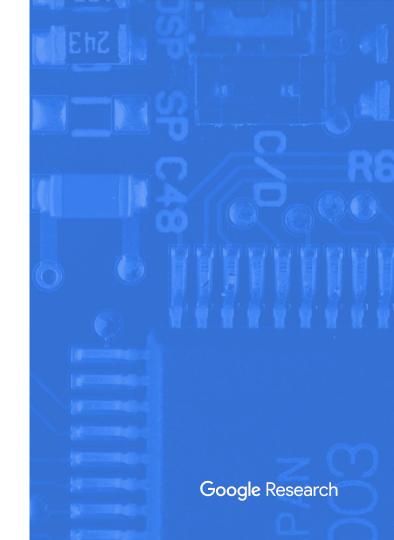


Agenda

- ⁰¹ What, why, how
- O2 Porting code
- ⁰³ Runtime dispatch
- O4 Design rationale
- ⁰⁵ Users

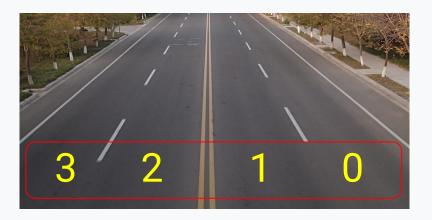
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What, why, how



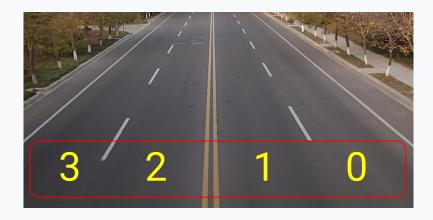
What is SIMD?

Single / sameInstruction / operation onMultipleData (lanes)



Why SIMD?

- Widely available
 - o X86, ARM, RISC-V, MIPS, ...
- Minimal incidental complexity
 - o Same address space
- Vendor-independent
 - >1 implementation of x86/ARM/RISC-V
- Widely scalable in cloud
 - No special provisioning



How: autovec?

OpenMP 4.0, armclang, Intel compiler

Minimal code changes

Brittle (maintenance, compiler upgrade)

Risk of poor codegen ("SIMD" memcpy)

```
movzx ecx, byte [rax+rdi*4+8] movd xmm1, ecx pinsrb xmm1, [rax+rdi*4+0], 1 pinsrb xmm1, [rax+rdi*4+12], 2 pinsrb xmm1, [rax+rdi*4+4], 3
```



How: assembly?

Used in FFMPEG

Potentially more efficient

Error-prone: major penalty for MOVAPS xmm0, xmm1 vs. VMOVAPS xmm0, xmm1

Laborious

- Porting: FMLA vs. vfmadd132ps, ...
- Manual register allocation



How: intrinsics?

Widely used, also on MSVC

Error-prone

Compiler bugs (see next slide)

Laborious

- Porting: _mm512_mask_mov_psvs. _mm256_blendv_ps
- Verbose: _mm256_load_si256(
 reinterpret_cast<
 const __m256i*>(ptr))



Compiler bugs

clang-6: incorrect codegen for partial vector writes. Workaround: memcpy instead of intrinsics

clang-6: incorrect ARMv7 codegen, read after write data hazard. Workaround: clobber memory

clang-6: suboptimal codegen for VBROADCASTI128. Workaround: inline assembly

clang-6: missing KORTEST for AVX-512. Workaround: treat masks as integers

clang-6: incorrect msan codegen. Abandoned: require clang-7

clang-7: unaligned spills in asan. User workaround: shorter variable lifetime

clang-8: various "Do not know how to split". Workaround: find op, replace with other

clang-8: inconsistent inlining/attribute requirements. Workaround: use pragma

clang-8: pragma must be at global scope. Workaround: HWY_BEFORE_NAMESPACE

clang-9: crash due to vector class constructor. Workaround: aggregate init

gcc 9.2: incorrect intrinsics for signed compare. Workaround: vector extension

Wasm: bleeding edge. Workaround: emulate missing/broken instructions



Google Research

How: Highway

Same code, multiple platforms

Reasonable to port (operator overloading)

Helps deal with compiler bugs

Reliable and predictable performance

Also designed for variable vectors (SVE)



Highway library

https://github.com/google/highway

Developed since 2017 Used in <u>JPEG XL image codec</u>

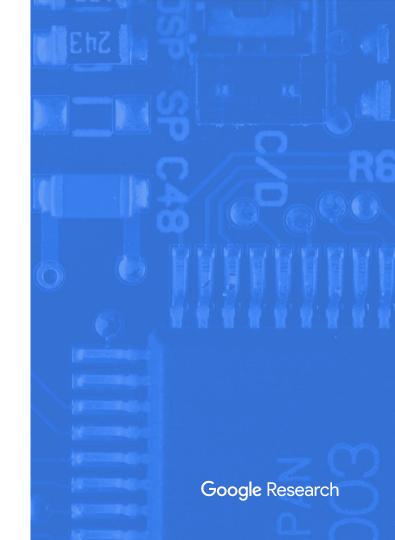
Collaborators: Jeffrey Lim, Rhett Stucki Advice:

Connor Fitzgerald Daniel Lemire Jyrki Alakuijala Povilas Kanapickas Rich Winterton



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Porting code



Annotate

```
AVX2: Clang/GCC require -mavx2 (unsafe) or function attribute
Could annotate each function with HWY_ATTR
Easy to forget, causes errors on other compilers
Or: single #pragma attribute/target (via HWY_*_NAMESPACE)
      Convenient
      Compiler-specific
      Must be outside namespace (thanks Robert Obryk!)
HWY_BEFORE_NAMESPACE();
namespace myproject {
namespace HWY_NAMESPACE {
HWY_ATTR void MyFunc(float* HWY_RESTRICT out) {}
   // namespace HWY_NAMESPACE
   // namespace myproject
HWY_AFTER_NAMESPACE();
```

Create vectors

```
// Defined by Highway:
template <typename Lane, size_t kLanes>
struct Simd { // Empty tag type
   using T = Lane;
};
Type128 Zero(Simd<float, 4> /*tag*/);
Type256 Zero(Simd<float, 8> /*tag*/);

// Your code
const HWY_FULL(float) d; // = Simd<float, ??>
const auto zero = Zero(d);
const auto one = Set(d, 1.0f);
```

Loops, memory

```
for (size_t x = 0; x < xsize;
                             ++x) {
                             x += Lanes(d)) {
  const float xval = rowx[x];
  const float yval = rowy[x];
+ const auto xval = Load(d, rowx + x);
+ const auto yval = Load(d, rowy + x);
  const float scaler = s + (yw * (1.0f - s)) /
                           (yw + yval * yval);
+ const auto scaler = s + (yw * (one - s)) /
                     MulAdd(yval, yval, yw);
- rownew[x] = scaler * xval;
  Store(scaler * xval, d, rownew + x);
```

Alignment

```
std::vector<float> rowx(128);
for (size_t x = 0; x < xsize; x += Lanes(d)) {
  // CRASH - unaligned
  const auto xval = Load(d, rowx.data() + x);
 // ...
  // less efficient
  const auto xval = LoadU(d, rowx.data() + x);
// unsafe for member variables and large vectors
HWY_ALIGN float rowx[128];
// works for member variables and large vectors
hwy::AlignedFreeUniquePtr<float[]> rowx =
hwy::AllocateAligned<float>(128);
```

Data layout

```
struct Point {
  float x;
  float y;
hwy::AlignedFreeUniquePtr<Point[]> points =
hwy::AllocateAligned<Point>(N);
const HWY_FULL(float) d;
// mixes x and y in vector
auto mixed = Load(d, &points.data().x);
hwy::AlignedFreeUniquePtr<float[]> all_x_then_y =
hwy::AllocateAligned<float>(N * 2);
auto only_x = Load(d, all_x_then_y.data());
auto only_y = Load(d, all_x_then_y.data() + N);
```

Branches

```
float RemoveRangeAroundZero(float w, float x) {
                  x > w ? x - w:
 return
                       x < -w? x + w : 0.0f;
template<class V>
V RemoveRangeAroundZero(V w, V x) {
  return IfThenElse(x > w, x - w,
        IfThenElseZero(x < Neg(w), x + w);
bool AllPositiveIntegers(int v) {
 return v >= 0;
template<class V>
bool AllPositiveIntegers(V v) {
 // avoids/hides 'zero'/'sign bit' constant
 return AllTrue(Abs(v) == v);
```

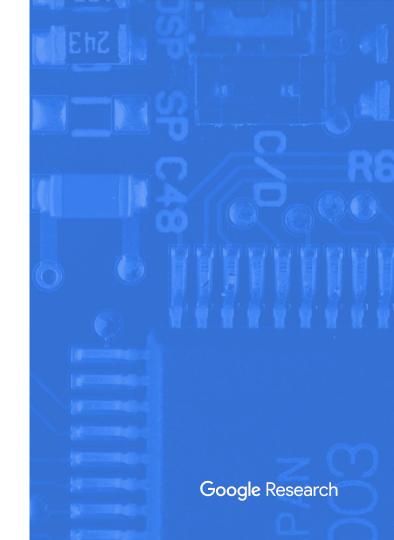
[Headers]

"Toggles" include guard macro - prevents multiple inclusion <u>within a particular target</u>

Thanks to Lode Vandevenne for this clever idea!

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Runtime dispatch



Multi-target

```
// At top of file, before other hwy includes
#undef HWY TARGET INCLUDE
#define HWY_TARGET_INCLUDE "path/filename.cc"
#include <hwy/foreach_target.h>
HWY_BEFORE_NAMESPACE();
// implementation - compiled once per target
HWY_AFTER_NAMESPACE();
#if HWY_ONCE
namespace myproject {
HWY_EXPORT(MyFunc); // defines function table
void Caller() {
  // dispatches to best available implementation
  HWY_DYNAMIC_DISPATCH(MyFunc)(args);
#endif
```

Definitions

Target = instruction set (e.g. AVX2)

Baseline = what compiler targets (= CPU requirement)

Determined by -mavx2 or HWY_BASELINE_TARGETS

Enabled = non-denylisted targets

Determined by known issues / HWY_DISABLED_TARGETS

Static target = best enabled baseline

Attainable = extra targets Highway can generate

Determined by compiler: all enabled on x86, or baseline

Superseded: baseline \ static target

If SSE4 baseline, skip scalar to reduce code size

[Dynamic] targets = configurable: { scalar | static | attainable | attainable | superseded }



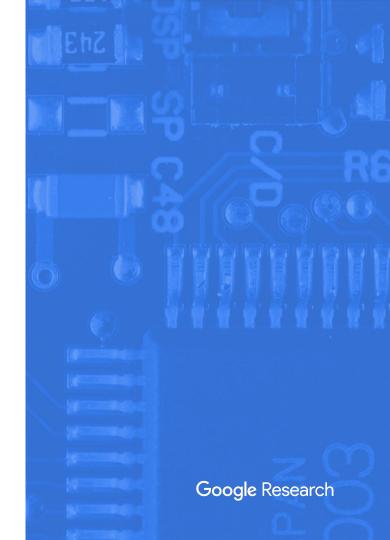
Dispatching

```
// Direct call into baseline from normal code:
// (Can make sense if baseline is sufficient -
// avoid generating for all targets)
HWY_STATIC_DISPATCH(MyFunc)(args);
SupportedTargets() // bitfield, depends on CPU
// Indirect call into best available SIMD:
HWY_DYNAMIC_DISPATCH(MyFunc)(args);
// Call for each target from anywhere:
hwy::RunTest(func, args);
gTest adapters also provided.
```

Google Research

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Design rationale



Simd<T, N>:: ?

SVE backend: as of 2021-05, vectors are sizeless types

Cannot be a class member

→ API based on overloaded functions

Can we have Load(V(), ptr)?

No, V is builtin on SVE, cannot indicate limit on #lanes

What about Load(V(), IntConst<N>, ptr)?

Error-prone - can break if not all call sites updated

⇒still have tag argument called Simd<T, N>

Why auto?

```
Rarely need to know vector type, can deduce

Even for output params: auto out = Undefined(d);

Large number of vector types (50-70)

Types: {u, i} x {8, 16, 32, 64}, f32, f64

Lanes: 1, 2, 4, 8, 16, 32, 64

For portability, encourage size-agnostic code

But: auto everywhere hard to read / understand

compromise: user-defined typedef:

using V = decltype(Zero(d)); or

using V = Vec<decltype(d)>;
```

Why not stack?

SVE: max size 256 bytes. Wasteful on stack

RISC-V V: large upper bound: 64K elements

One implementation actually has 16 KiB vectors.

→use hwy/aligned_allocator.h and actual size: Lanes (d)

Why >1 header?

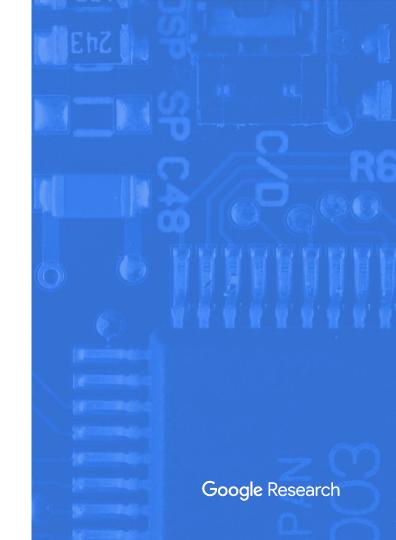
Including everything actually expensive (huge immintrin.h)

base.h for users / headers who just want
HWY_RESTRICT (function parameter) or
HWY_REP4 (define input for LoadDup128) etc.

targets.h useful for callers who want to know/influence which target is active

highway.h only for implementers of SIMD modules, not their users

Users



JPEG XL

Next-generation image compression. <u>ipeq.org/ipeqxl</u>

Uses integer (random generation) and floating-point:

- DCT, filtering, color conversion, noise synthesis
- Quantization, function approximations, ...

Runtime dispatch, 1.4x speedup from AVX2 to AVX-512

9 engineers using Highway, positive feedback

Also used in PIK which morphed into JPEG XL.



Example: RNG

```
class Xorshift128Plus {
  public:
    // 8 independent generators
    // (= single iteration for AVX-512)
    enum { N = 8 };

  HWY_INLINE HWY_MAYBE_UNUSED void
  Fill(uint64_t* HWY_RESTRICT random_bits) {
    // see next slide
  }

  // unsafe, requires class to be aligned
  HWY_ALIGN uint64_t s0_[N];
  HWY_ALIGN uint64_t s1_[N];
};
```

Porting RNG

Also related

HighwayHash: fast MAC/pseudorandom function

- Built around <u>SIMD multiply and permute</u>
- 64, 128, 256 bit result (1024 bit internal state)
- Difficult to create collisions (> 2⁶⁴ work)
- Similar SIMD via intrinsics + runtime dispatch

Randen: Abseil's random generator

- Cryptographic (<u>indistinguishable from random</u>)
- Faster than some common insecure generators
- Enabled by SIMD AES (x86, ARM, POWER)
- Simpler SIMD wrapper over intrinsics







janwas@google.com

highway-users@google.com

Staff Software Engineer