

KEY:

Power on

Decide tilt direction

Avoid obstacles

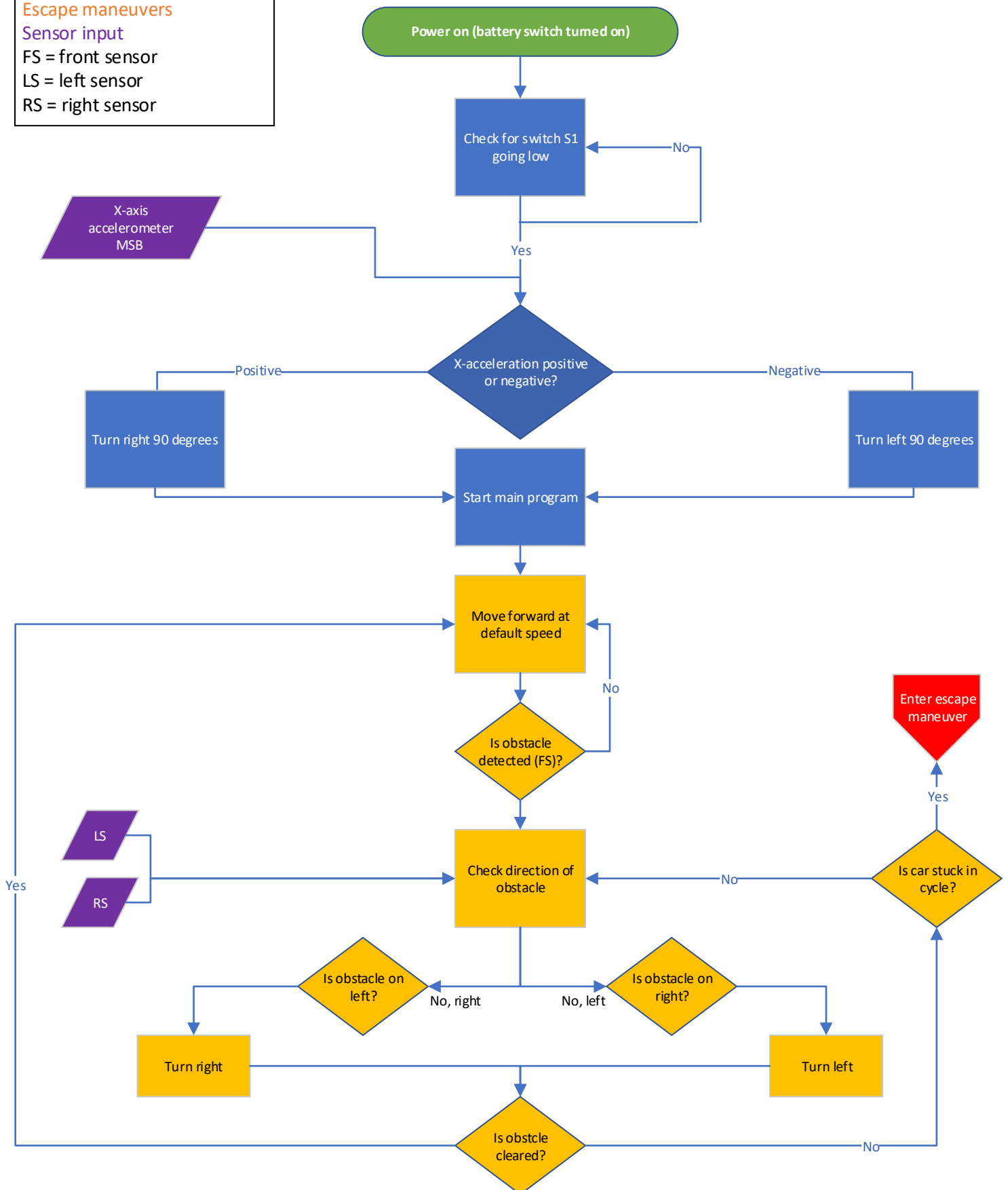
Escape maneuvers

Sensor input

FS = front sensor

LS = left sensor

RS = right sensor

Default Process

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Escape Maneuver Process

