Section 3.2: Properties of Determinants:

Note: The secret of determinants lies in how they change when row operations are performed.

⇒ We observed these changes in the previous section while exploring how elementary now operations effect det(A)

*Theorem (Row Operations):

Let A be a square matrix.

(i) (ombining:

added to another nuw IF a multiple of one row A is det(B) = det(A) to produce matrix B, then:

(ii) Interchanging:

If two rows of A are interchanged to produce

B, then: det(B) = - det(A)

(iii) Scaling:

IF one now of A is multiplied by some scalar "K" to produce B, then: det(B) = Kdet(A)

* Note: The 3 properties of this theorem help us to find the determinant of a matrix more efficiently & effectively! <u>Example</u>: State which property of determinants is illustrated in the equation below:

$$\begin{bmatrix} -3 & 3 & -5 \\ 6 & -4 & 2 \\ -9 & 5 & -3 \end{bmatrix} = -\begin{bmatrix} 6 & -4 & 2 \\ -3 & 3 & -5 \\ -9 & 5 & -3 \end{bmatrix}$$

Answer:

* Given:

$$B = -\begin{bmatrix} 6 & -4 & 2 \\ -3 & 3 & -5 \\ -9 & 5 & -3 \end{bmatrix}$$

k Describe the Row-Operation:

Matrix B is attained by interchanging R, & Rz of Matrix A.

:. The Property of Determinants used is Interchanging

If two rows of A are interchanged to produce B, then: det(B) = - det(A)

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Example: State which property of determinants is illustrated below:

$$\begin{bmatrix} -9 & -1 & -1 \\ -27 & -6 & -7 \\ 9 & -8 & -9 \end{bmatrix} = \begin{bmatrix} -9 & -1 & -1 \\ 0 & -3 & -4 \\ 9 & -8 & -9 \end{bmatrix}$$

Answer:

*Given:
•
$$A = \begin{bmatrix} -9 & -1 & -1 \\ -27 & -6 & -7 \\ 9 & -8 & -9 \end{bmatrix}$$

*Describe the Elementary Row Operation:

IF a multiple of one Row of A is odded to another Row to produce B, then: det(B) = det(A)

$$\begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = 3. \implies B = \begin{bmatrix} a & b & c \\ d & e & f \\ 8q & 8h & 8i \end{bmatrix}$$

Answer:

* Given:

$$A = \begin{bmatrix} a & b & c \\ d & e & F \\ g & h & i \end{bmatrix}$$
 $\exists \det(A) = 3$

$$ext{det}(x) = 3$$

* Describe the Row-Operation on A to produce B:

$$: det(B) = 8(3) = 24$$

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Example: If
$$A = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}$$
 & $det(A) = 4$,
$$\begin{bmatrix} g & h & i \end{bmatrix}$$

Find the determinant of the matrix: $B = \begin{bmatrix} a & b & c \\ g & h & i \\ d & e & F \end{bmatrix}$

Answer:

* Describe the Row-Operation on A to produce B:

- · Iransformation: R3 R2 (Rows 243 are interchanged)
- · Elementary Matrix: E = [1 0 0]

$$\Rightarrow$$
 Since R₂ & R₃ of A are interchanged to produce B, then: det (B) = - det (A)

Example: If
$$A = \begin{bmatrix} a & b & c \\ d & e & F \end{bmatrix}$$
 & $det(A) = 7$, then find the determinant of matrix: $B = \begin{bmatrix} a & b & c \\ bd+q & be+h & bF+i \\ g & h & i \end{bmatrix}$.

Answer:

Answer:

Recall: Elementary Matrices can represent one and only one row-operation at a time:

⇒ By Factoring the common "6" out of Rz of BJ, we can now identify the now operation performed on A. <u>CAUTION</u>: We ignore the to below to identify the Rew-Operation on A, but do not Forget it in your final calculations.

* Describe the Row-Operation on A to produce B:

Tronsformation:
$$6 | K_2 + \frac{1}{6} | K_3 |$$

Flementary Matrix: $E = 6 | 0 | 0 | 0 |$

$$= | 0 | 0 | 0 |$$

⇒ Since "
$$R_z + \frac{1}{6}R_3$$
" of A is multiplied by a scalar "6" to produce R_z of B, then: $\det(B) = 420$ Arg. $\det(B) = 420$ Arg.

* Kerall: (Thm #2; Section 3.1) IF Matrix A is triangular, then det(A) is equal to the product of the entries along the main diagonal Example (Finding the determinant w/ row operations): Compute the det(A), where $A = \begin{bmatrix} 1 & -7 & 2 \\ -2 & 8 & -9 \end{bmatrix}$ Answer: Note: Here we use both Thm's 283 to find the det(A) w/o *First Row-Reduce [A:0] to echelon Form, being Ofactor Expansion : mindful of how each now operation w/ affect the det(x):

$$\begin{bmatrix} 1 - 4 & 2 & 0 \\ 0 & 0 & -5 & 0 \\ 0 & 3 & 2 & 0 \end{bmatrix}$$
 interchange $\mathbb{R}_{\mathbf{Z}} \neq \mathbb{R}_{\mathbf{Z}}$

* Compute the det (A):

By theorem #2 & theorem #3 (prop. 2), we know

$$det(A) = -(1)(3)(-5) = 15$$

Note: Another efficient application of theorem #3 is to Factor a common scalar cut of a single row, leaving the other rows untouched (Prop.#3: det(B) = Kdet(A))

Example (Using Row Operations to Find the Determinant):

Compute
$$det(A)$$
, where $A = \begin{bmatrix} 2 - 8 & 6 & 8 \\ 3 - 9 & 5 & 10 \\ -3 & 0 & 1 - 2 \\ 1 & -4 & 0 & 6 \end{bmatrix}$
Answer:

*Here are (at least) 2 options to get started here:

- i) Interchange R. & Ry
 ii) Factor common scalar, K=2, out of R,
- => Lets explore the later : (... why? We need "1" in the 1st pivot)

* Row-Reduce "A" to echelen form, being mindful of how

each row operation will affect det (A):

$$A = \begin{bmatrix} 2 & -8 & 6 & 8 \\ 3 & -9 & 5 & 10 \\ -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 \end{bmatrix} \times \begin{bmatrix} 1 & -4 & 3 & 4 \\ 3 & -9 & 5 & 10 \\ 1 & -4 & 0 & 6 \end{bmatrix} \times \begin{bmatrix} 1 & -4 & 3 & 4 \\ 3 & -9 & 5 & 10 \\ -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 \end{bmatrix} \times \begin{bmatrix} 1 & -4 & 3 & 4 \\ 1 & -2 & 10 \\ 1 & -4 & 0 & 6 \end{bmatrix} \times \begin{bmatrix} -3R_1 & 1 & -4 & 3 & 4 \\ 1 & -2 & 10 & -2 & -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 & -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 & -3 & -4 & 0 & 6 \end{bmatrix}$$

Example Continued...

Echelon Form :

*Note: We are ready to compute the det(A). Keep in mind:

* Compute the Determinant:

By theorem² (3.1) & theorem³ (prop. 3), we know that:

$$det(A) = 2[(1)(3)(-1)(1)] = 2[-18] = -36$$

*Row Operations & the Determinant *

\$ a square matrix A has been reduced to echelon Form "U" by row-replacement & row-interchanges. If there are "r" interchanges, then by Thm #3 (ii):

 $det(A) = (-1)^r det(U)$

Since U is in Echelon Form, it is a triangular matrix, & so we compute det(U) by taking the product of the entries along the main diagonal: det (u) = (un) (uzz) ... (unn)

UIF A is invertible, then:

- ·The entries Uic are all pivots (b/c An In & Uic NOT scaled to 1)
- $det(U) \neq 0$

@ TF A is NOT invertible, then:

- ·At least Unn is Zero (i.e. NOT a pivot position)
- det(U) = 0

Note: Although the echelon Form U described on the previous page is Not unique (b/c net ref) & the pivot are NOT unique => The Product of the pivots (i.e. The det(A)) is unique! (*W the except of a possible & :)

*Theorem ":

A square matrix is invertible IFF det(A) ≠0.

We can now add this? as the 13th logically equivalent statement to the "Invertible Matrix Theorem" (sect. 2.3)

*Fun/Useful Corollaries:

1) Det(A) = 0 When the Glumns of A are Linearly Dependent.

1 Det(A) = 0 when the ROWS OF A are Linearly Dependent.

* Recall:

·The Rows of A = The Columns of AT

- · Linearly Dependent Glumns of AT \Rightarrow AT is singular (invertible)
- · If AT is invertible, then A is invertible :

Note: (Helpful Hint):

Remember that it is easy to identify Linear Dependence by simply comparing the columns or the rows ("Same" => Dependence) 4/or n row is 7em :

Example (Linear Dependence & the Determinant):

Compute
$$det(A)$$
, where $A = \begin{bmatrix} 3 & -1 & 2 & -5 \\ 0 & 5 & -3 & -6 \\ -6 & 7 & -7 & 4 \\ -5 & -8 & 0 & 9 \end{bmatrix}$

Answer:

*Start by now-reducing "A" to echelon Form, being mindful of how each now-operation affects the det(A):

$$A = \begin{bmatrix} 3 & -1 & 2 & -5 \\ 0 & 5 & -3 & -6 \\ -6 & 7 & -7 & 4 \\ -5 & -8 & 0 & 9 \end{bmatrix} \xrightarrow{2R_1} \begin{bmatrix} 3 & -1 & 2 & -5 \\ + R_3 & 0 & 5 & -3 & -6 \\ 0 & 5 & -3 & -6 \\ -5 & -8 & 0 & 9 \end{bmatrix} \times \underbrace{STOP}_{R_2} :$$

Since $R_z = R_3$ the rows of A are linearly dependent and thus det(A) = 0.

Answer.

Example: Use determinants to find out if the matrix is invertible: [5 0 -1]

$$A = \begin{bmatrix} 5 & 0 & -1 \\ 2 & -6 & -4 \\ 0 & 5 & 3 \end{bmatrix}$$

Answer:

*Row-reduce A to echelon Form, being mindful of how each row operation affects the determinant:

(iii)
$$R_2 \mapsto 2R_2$$
(iii) $R_2 \mapsto 2R_2$
(iii) $R_2 \mapsto R_2$
(iv) $R_$

$$N - 6 \begin{bmatrix} 1 - 3 - 2 \\ 0 5 3 \\ 0 5 3 \end{bmatrix} * R_2 = R_3$$

$$3 \cdot \det(A) = 0 \implies 3 \circ \text{matrix A is NOT invertible}$$
Answer

Example: Use determinants to find out if the matrix

$$A = \begin{bmatrix} 1 & -1 & -3 & 0 \\ 0 & 1 & 5 & 4 \\ 4 & -2 & -3 & 4 \\ -1 & 2 & 8 & 5 \end{bmatrix}$$

* Row-Reduce Matrix A, being mindful of how each now

operation affects the determinant:

*Echelon Form: *

:
$$det(A) = -1 \neq 0$$
 & so A is invertible

Example: Use determinants to decide if the set of vectors

$$\begin{bmatrix} 3 \\ 5 \\ -6 \\ 4 \end{bmatrix}, \begin{bmatrix} 2 \\ -6 \\ 0 \\ 8 \end{bmatrix}, \begin{bmatrix} -2 \\ -1 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 3 \end{bmatrix}$$

Answer:

*Given:

A = $\begin{bmatrix}
3 & 2 & -2 & 0 \\
5 & -6 & -1 & 0 \\
-6 & 0 & 3 & 0 \\
4 & 8 & 0 & 3
\end{bmatrix}

*Note: Since Glumn 4 how only only on the nonzero entry, lets

one nonzero entry, lets

start <math>w$ a Gractur expansion down (61.44): down Col. # 4 ?

*Compute the det(A) by applying a Gractur Expansion down Glumn 4: det (A) = 0.14 C14 + 0.24 C24 + 0.34 C34 + 0.44 C44

$$det(A) = 0 + 0 + 0 + 3(-1)^{8} det \begin{bmatrix} 3 & 2 & -2 \\ 5 & -6 & -1 \\ -6 & 0 & 3 \end{bmatrix}$$

= 3 det
$$\begin{bmatrix} 3 & 2 & -2 \\ 5 & -6 & -1 \end{bmatrix}$$
 * Note: Lets now apply the Recursive Def. (since matrix is 3×3)

$$= 3\left(3\begin{bmatrix}-6-1\\0&3\end{bmatrix}-2\begin{bmatrix}5-1\\-6&3\end{bmatrix}+(-2)\begin{bmatrix}5-6\\-6&0\end{bmatrix}\right)$$

$$= 3[3(-18-0)-2(15-6)-2(0-36)]$$

$$= 3[3(-18)-2(9)-2(-36)] = 3[-54-18+72] = 3(0) = 0$$

: det(A) = 0 & so the Columns of A are a Linearly Dependent

Example (Row-Operations & the Determinant):

Compute
$$det(A)$$
, where $A = \begin{bmatrix} 0 & 1 & 2 & -1 \\ 2 & 5 & -7 & 3 \\ 0 & 3 & 6 & 2 \\ -2 & -5 & 4 & -2 \end{bmatrix}$

Answer:

* Note: Since Column 1 only has 2 nonzero entries, a cofactor expansion down Column 1 is a good place to start :

First row-reduce A to remove the last entry in Column 1 & then apply a cofactor expansion down G1. 1:

$$A = \begin{bmatrix} 0 & 1 & 2 & -1 \\ 2 & 5 & -7 & 3 \\ 0 & 3 & 6 & 2 \\ -2 & -5 & 4 & -2 \end{bmatrix} \xrightarrow{Rz} \begin{bmatrix} 0 & 1 & 2 & -1 \\ 2 & 5 & -7 & 3 \\ 0 & 3 & 6 & 2 \\ 0 & 0 & -3 & 1 \end{bmatrix}$$

So,

$$det(A) = a_{11}C_{11} + a_{21}C_{21} + a_{31}C_{31} + a_{41}C_{41}$$

$$= 0 + (-1)^{3} 2 det \begin{bmatrix} 1 & 2 & -1 \\ 3 & 6 & 2 \\ 0 & -3 & 1 \end{bmatrix} + 0 + 0$$

$$= -2 \det \begin{bmatrix} 1 & 2 & -1 \\ 3 & 6 & 2 \\ 0 & -3 & 1 \end{bmatrix}$$

= -2 det \[\begin{aligned} 1 2 -1 \\ 3 6 2 \\ 0 -3 1 \end{aligned} \]

* Note: From here there are several ways to proceed in computing the det(A): OApply Rocursive Def.

2 Cofactor Expansion

3 Raw-reduce to attain a mangular matrix, if

Example Continued...

* Lets apply row-operations to Further simplify the matrix:

$$-2 \det \begin{bmatrix} 0 & 2 & -1 \\ 3 & 6 & 2 \\ 0 & -3 & 1 \end{bmatrix} \xrightarrow{-3R_1} -2 \det \begin{bmatrix} 1 & 2 & -1 \\ 0 & 0 & 5 \\ 0 & -3 & 1 \end{bmatrix} \xrightarrow{\text{(ii)}} -2 \det \begin{bmatrix} 1 & 2 & -1 \\ 0 & 0 & 5 \\ 0 & -3 & 1 \end{bmatrix} \xrightarrow{\text{(iii)}}$$

$$\Rightarrow = (=2) \det \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & 1 \\ 0 & 0 & 5 \end{bmatrix}$$

*Echelen Form = A triangular Matrix

$$\det(A) = 2[(1)(-3)(5)] = 2(-15) = -30$$

Example: Combine the methods of now-reduction & cofactor expansion to compute the determinant:

$$A = \begin{bmatrix} -1 & 3 & 8 & 0 \\ 4 & 2 & 4 & 0 \\ 6 & 6 & 8 & 6 \\ 5 & 3 & 5 & 3 \end{bmatrix}$$

Answer:

* Note: Keep in mind that I infinitely many ways to find the det (A). The following is only one of many correct ways to approach this problem:

*Since Column 4 has only two nonzero entries, lets try a cofactor expansion down Glumn 41

OUse R3 as a pirot to eliminate the 4th entry in R4:

$$A = \begin{bmatrix} -1 & 3 & 8 & 0 \\ 4 & 2 & 4 & 0 \\ 6 & 6 & 8 & 6 \\ 5 & 3 & 5 & 3 \end{bmatrix} \xrightarrow{12R_3} \begin{bmatrix} -1 & 3 & 8 & 0 \\ 4 & 2 & 4 & 0 \\ 6 & 6 & 8 & 6 \\ 2 & 0 & 1 & 0 \end{bmatrix}$$

3 Compute the det(A) using a Cofactor Expansion Down Col. 4.

$$det(A) = \alpha_{14}C_{14} + \alpha_{24}C_{24} + \alpha_{34}C_{34} + \alpha_{44}C_{44}$$
io,
$$det(A) = 0 + 0 + 6(-1)^{7}det\begin{bmatrix} -1 & 3 & 8 \\ 4 & 2 & 4 \\ 2 & 0 & 1 \end{bmatrix} + 0$$

Example Continued...

$$= -6 \det \begin{bmatrix} -1 & 3 & 8 \\ 4 & 2 & 4 \\ 2 & 0 & 1 \end{bmatrix}$$

3 Compute the det(A) by the Recursive DoF:

$$\det(A) = -6\left(-1\det\begin{bmatrix} 2 & 4 \\ 0 & 1 \end{bmatrix} - 3\det\begin{bmatrix} 4 & 4 \\ 2 & 1 \end{bmatrix} + 8\det\begin{bmatrix} 4 & 2 \\ 2 & 0 \end{bmatrix}\right)$$

$$= -6\left[-(2-0) - 3(4-8) + 8(0-4)\right]$$

$$= -6\left[-2 + 12 - 32\right]$$

$$= -6\left[-22\right]$$

$$= 132$$

* Column Operations *

Note: We can perform operations on the columns of a matri; in a way that is similar to the row operations we have considered:

*Theorem 5:

If A is an nxn matrix, then $det(A^T) = det(A)$.

Each statement in theorem³ is true when the word "row" is replaced everywhere by "column".

To Verify:

· Apply each property in thm. 3 to the transpose

* A Row-Operation on AT >> A Column-Operation on A*

Note: Column Operations are useful For theoretical purposes & some hand-calculations, but we will continue to only use row-operations in numerical computations.

*Theorem # 6 (The Multiplicative Property):

IF A & B are n×n matrices, then: det(AB) = det(A) det (B).

:NARNING: This I does NOT hold true For the sum of matrices.
In General, det (A+B) ≠ det (A) + det (B).

Example: Verify thm #6 For the Following matrices:
$$A = \begin{bmatrix} 6 & 1 \\ 3 & 2 \end{bmatrix} \quad \text{4} \quad B = \begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}$$

Answer:

O Find the product AB & then compute its determinant:

$$AB = \begin{bmatrix} 6 & 1 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 24+1 & 18+2 \\ 12+2 & 9+4 \end{bmatrix} = \begin{bmatrix} 25 & 20 \\ 14 & 13 \end{bmatrix}$$

3) Find det(A) & det(B), and take their product:

$$\det(A) = (b)(z) - (1)(3) = 12 - 3 = 9$$

$$det(B) = (4)(2) - (3)(1) = 8 - 3 = 5$$

Example: Compute [det(B)]3 where: B = |2 0 1

Answer:

(Recall (Thm 6): If Ad B are nxn matrices, then)

*First, Lets compute the det (B), to verify]:

$$B = \begin{bmatrix} 2 & 0 & 1 \\ 1 & 2 & 4 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 4 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \times$$

$$-\begin{bmatrix} 1 & 2 & 4 \\ 0 & -4 & -7 \\ 0 & 0 & -3 \end{bmatrix}$$

$$-\begin{bmatrix} 1 & 2 & 4 \\ 0 & -4 & -7 \\ 0 & 0 & -3 \end{bmatrix} \Rightarrow \begin{bmatrix} :. \det(B) = -(1)(-4)(-3) \\ = -12 \end{bmatrix}$$

*Since det(B) \$= 0, B is invertible.

Echelon Form :

* Applying Theorem # 6:

Since B is a 3×3, invertible matrix, then:

Example / Property: Show that if A is invertible,

then $det(A^{-1}) = \frac{1}{det(A)}$.

Prof: \$ A is an n×n, invertible matrix.

* Then, by definition:

$$- \det(A) \neq 0$$

$$\frac{\text{Gval: Show that } \det(A^{-1}) = \frac{1}{\det(A)}$$

* Since A is invertible, then by prop. of inverses:

·AT is an n×n, invertible matrix

* Since A & A are n×n matrices, then by theorem 6:

$$det(A) det(A^{-1}) = det(AA^{-1})$$

$$= det(I_n)$$

$$= 1$$

* Dividing both sides by "det(A)":

$$det(A) det(A^{-1}) = 1$$

$$det(A^{-1}) = \frac{1}{det(A)}$$

X

Example: Find a formula for det (rA) when A is an nxn matrix & r 1s any scalar.

Answer:

* Recall: (Theorem 3, property 3)

If one now of A is multiplied by some scalar "K"

To produce B, then: det(B) = Kdet(A)

*Since A has n-nows, if we factor the scalar "r"
out of each of the n-nows, then:

det(rA) = r det(A)

*A Linearity Property of the Determinant Function *

For an nxn matrix A, we can consider the det(A) as a Function of the n Glumn-Vectors in A.

*Note: Here we show that if all columns except one are held fixed, then det(A) is a <u>Linear Function</u> of that one variable (vector).

Let A be an nxn matrix ST:

Is that all columns are held fixed except the jth column, which is allowed to vary:

$$A = \begin{bmatrix} \vec{\alpha}_1 & \vec{\alpha}_2 & \cdots & \vec{\alpha}_{j-1} & \vec{\chi} & \vec{\alpha}_{j+1} & \cdots & \vec{\alpha}_n \end{bmatrix}$$

Define a Linear Transformation, T: R" - IR ST:

$$T(\vec{\chi}) = \det(A) = \det[\vec{\alpha}_1 \cdots \vec{\alpha}_{j-1} \vec{\chi} \vec{\alpha}_{j+1} \cdots \vec{\alpha}_n]$$

Then, by definition of a linear Transformation: