

Bonus: +5
Name: PHONG VO

54/50 Excellent!

Linear Algebra I: Exam 1 (Spring 2020)

Show ALL work, as unjustified answers may receive no credit. Calculators are not allowed on any quiz or test paper. Make sure to exhibit skills discussed in class. Box all answers and simplify answers as much as possible.

Good Luck! ☺

1. Systems of Linear Equations

[6pts] Determine the value(s) of h for which the following linear system is consistent:

$$\begin{cases} 9x_1 + hx_2 = 9 \\ hx_1 + x_2 = -3 \end{cases}$$

$$[A : b] = \begin{bmatrix} 9 & h & 9 \\ h & 1 & -3 \end{bmatrix} \xrightarrow[R_2/h]{R_1/9} \begin{bmatrix} 1 & \frac{h}{9} & 1 \\ 1 & \frac{1}{h} & -3 \end{bmatrix} \quad (h \neq 0)$$

$$\xrightarrow[R_2]{R_1 - R_2} \begin{bmatrix} 1 & \frac{h}{9} & 1 \\ 0 & \frac{h}{9} - \frac{1}{h} & 1 + \frac{3}{h} \end{bmatrix}$$

The linear system is consistent if : $\begin{cases} \frac{h}{9} - \frac{1}{h} \neq 0 \\ h \neq 0 \text{ (to let the system be defined)} \end{cases}$

$$\Rightarrow \begin{cases} h^2 - 9 \neq 0 \\ h \neq 0 \end{cases}$$

$$\Rightarrow \begin{cases} h \neq 3 \checkmark \\ h \neq -3 \\ h \neq 0 \end{cases}$$

↑
these produce a consistent system :

2. The Matrix Equation, $A\vec{x} = \vec{b}$

Consider the following matrix equation:

$$\begin{bmatrix} 1 & 2 & 13 \\ 1 & -1 & -2 \\ 2 & 4 & 26 \\ 2 & 1 & 11 \\ 3 & 3 & 24 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -13 \\ 2 \\ -26 \\ -11 \\ -24 \end{bmatrix}$$

$$\begin{cases} x_1 + 2x_2 + 13x_3 = -13 \\ x_1 - x_2 - 2x_3 = 2 \\ 2x_1 + 4x_2 + 26x_3 = -26 \\ 2x_1 + x_2 + 11x_3 = -11 \\ 3x_1 + 3x_2 + 24x_3 = -24 \end{cases}$$

(a) [3pts] Write the given Matrix Equation as a System of Linear Equations.

(b) [9pts] Solve the system and write the general solution in a parametric vector form.

$$\begin{bmatrix} 1 & 2 & 13 & -13 \\ 1 & -1 & -2 & 2 \\ 2 & 4 & 26 & -26 \\ 2 & 1 & 11 & -11 \\ 3 & 3 & 24 & -24 \end{bmatrix} \xrightarrow[R_5/3]{R_3/2} \begin{bmatrix} 1 & 2 & 13 & -13 \\ 1 & -1 & -2 & 2 \\ 1 & 2 & 13 & -13 \\ 2 & 1 & 11 & -11 \\ 1 & 1 & 8 & -8 \end{bmatrix} \xrightarrow[R_1-R_3]{R_1-R_2, R_1-R_4} \begin{bmatrix} 1 & 2 & 13 & -13 \\ 0 & 3 & 15 & -15 \\ 0 & 0 & 0 & 0 \\ 0 & 3 & 15 & -15 \\ 0 & 1 & 5 & -5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 13 & -13 \\ 0 & 3 & 15 & -15 \\ 0 & 0 & 0 & 0 \\ 0 & 3 & 15 & -15 \\ 0 & 1 & 5 & -5 \end{bmatrix} \xrightarrow[R_1-R_5]{R_2-R_4} \begin{bmatrix} 1 & 2 & 13 & -13 \\ 0 & 1 & 5 & -5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 5 & -5 \end{bmatrix} \xrightarrow[R_1-R_5]{R_2-R_5} \begin{bmatrix} 1 & 2 & 13 & -13 \\ 0 & 1 & 5 & -5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 5 & -5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 13 & -13 \\ 0 & 1 & 5 & -5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{aligned} x_3 & \text{ is a free variable} \\ x_2 & = -5 - 5x_3 \\ x_1 & = -13 - 2x_2 - 13x_3 = -13 - 2(-5 - 5x_3) - 13x_3 \\ & = -3 - 3x_3 \end{aligned}$$

Beautiful!

Solution:

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -3 - 3x_3 \\ -5 - 5x_3 \\ 1x_3 \end{bmatrix} = \begin{bmatrix} -3 \\ -5 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ -5 \\ 1 \end{bmatrix}$$

Beautiful!

3. Solution Sets of Linear Systems

Consider the following:

$$A = \begin{bmatrix} 2 & 4 & 6 \\ 1 & 2 & 3 \\ -1 & -2 & -3 \end{bmatrix}, \vec{b} = \begin{bmatrix} -4 \\ -2 \\ 2 \end{bmatrix}$$

(a) [9pts] Solve the Nonhomogeneous System $A\vec{x} = \vec{b}$ and write the solution in parametric-vector form.

(b) [3pts] Using the parametric vector form of the solution in part (a), determine a particular solution.

(c) [3pts] Write the general solution for the Homogeneous System, $A\vec{x} = \vec{0}$, in parametric vector form.

$$a) [A \vec{x} : \vec{b}] \Rightarrow \left[\begin{array}{ccc|c} 2 & 4 & 6 & -4 \\ 1 & 2 & 3 & -2 \\ -1 & -2 & -3 & 2 \end{array} \right] \xrightarrow[R_3]{R_1 \leftrightarrow R_2} \left[\begin{array}{ccc|c} 1 & 2 & 3 & -2 \\ 2 & 4 & 6 & -4 \\ -1 & -2 & -3 & 2 \end{array} \right]$$

$$\begin{array}{l} R_1 - R_2 \\ = nR_2 \\ R_1 - R_3 \\ = nR_3 \end{array} \Rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & -2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} \bullet x_2, x_3 \text{ are free vars.} \\ \bullet x_1 \text{ is a basic var.} \end{array}$$

$$x_1 = -2 - 2x_2 - 3x_3 \Rightarrow \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$$

$$b) \text{ Make } \begin{cases} x_2 = 1 \\ x_3 = 1 \end{cases} \Rightarrow x_1 = -2 - 2 - 3 = -7 \Rightarrow \vec{x} = \begin{bmatrix} -7 \\ 1 \\ 1 \end{bmatrix}$$

$$c) A\vec{x} = \vec{0} \Rightarrow \left[\begin{array}{ccc|c} 2 & 4 & 6 & 0 \\ 1 & 2 & 3 & 0 \\ -1 & -2 & -3 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\Rightarrow x_1 = -2x_2 - 3x_3$$

$$\Rightarrow \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$$

Check for (b):

$$\vec{x} = \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -2-2-3 \\ 0+1+0 \\ 0+0+1 \end{bmatrix} = \begin{bmatrix} -7 \\ 1 \\ 1 \end{bmatrix}$$

Free

4. Linear Independence

Consider the following vectors:

$$\vec{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \vec{v}_4 = \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix}$$

(a) [3pts] Show that the following set of vectors is Linearly Dependent: $\{\vec{v}_1, \vec{v}_2\}$ (b) [7pts] Show that the following set of vectors is Linearly Independent: $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ (c) [7pts] Write \vec{v}_4 as a Linear Combination of $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$, if possible.

(a) $\begin{bmatrix} 1 & 2 & 0 \\ -1 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix} \xrightarrow[\substack{R_1 + R_2 \\ = nR_2 \\ R_1 - R_3 \\ = nR_3}]{\substack{R_1 + R_2 \\ = nR_2 \\ R_1 - R_3 \\ = nR_3}} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 0 & 1 & 0 \end{bmatrix} \xrightarrow{\frac{R_2}{3}} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} \xrightarrow[\substack{R_2 \\ -R_3 \\ = nR_3}]{\substack{R_2 \\ -R_3 \\ = nR_3}} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

$\Rightarrow \{\vec{v}_1, \vec{v}_2\}$ Independent ✓

(b) $\begin{bmatrix} 1 & 2 & 0 & 0 \\ -1 & 1 & 2 & 0 \\ 1 & 1 & 1 & 0 \end{bmatrix} \xrightarrow[\substack{R_1 + R_2 \\ = nR_2 \\ R_1 - R_3 \\ = nR_3}]{\substack{R_1 + R_2 \\ = nR_2 \\ R_1 - R_3 \\ = nR_3}} \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 3 & 2 & 0 \\ 0 & 1 & -1 & 0 \end{bmatrix} \xrightarrow{\substack{\uparrow \\ \downarrow}} \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 3 & 2 & 0 \end{bmatrix}$

$\xrightarrow[\substack{R_3 - 3R_2 \\ = nR_3}]{\substack{R_3 - 3R_2 \\ = nR_3}} \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 5 & 0 \end{bmatrix}$ pivot \exists in each row

\Rightarrow Linearly Independent ✓

(c) $\begin{bmatrix} 1 & 2 & 0 & -2 \\ -1 & 1 & 2 & 2 \\ 1 & 1 & 1 & 1 \end{bmatrix} \xrightarrow[\substack{R_1 + R_2 \\ = nR_2 \\ R_1 - R_3 \\ = nR_3}]{\substack{R_1 + R_2 \\ = nR_2 \\ R_1 - R_3 \\ = nR_3}} \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 3 & 2 & 0 \\ 0 & 1 & -1 & -3 \end{bmatrix} \xrightarrow{\substack{\uparrow \\ \downarrow}} \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 1 & -1 & -3 \\ 0 & 3 & 2 & 0 \end{bmatrix}$

$\xrightarrow[\substack{R_3 - 3R_2 \\ = nR_3}]{\substack{R_3 - 3R_2 \\ = nR_3}} \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 1 & -1 & -3 \\ 0 & 0 & 5 & 9 \end{bmatrix} \xrightarrow[\substack{5R_2 + R_3 \\ = nR_2 \\ R_3/5}]{\substack{5R_2 + R_3 \\ = nR_2 \\ R_3/5}} \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 5 & 0 & -6 \\ 0 & 0 & 1 & 9/5 \end{bmatrix} \xrightarrow{R_2/5}$

$\begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 1 & 0 & -6/5 \\ 0 & 0 & 1 & 9/5 \end{bmatrix} \xrightarrow{R_1 - 2R_2} \begin{bmatrix} 1 & 0 & 0 & 2/5 \\ 0 & 1 & 0 & -6/5 \\ 0 & 0 & 1 & 9/5 \end{bmatrix}$

OR: $\vec{v}_4 = \frac{2}{5}\vec{v}_1 - \frac{6}{5}\vec{v}_2 + \frac{9}{5}\vec{v}_3$ ✓

Excellent!

Bonus Question [5pts]:

Let $\vec{e}_1, \vec{e}_2, \vec{e}_3 \in \mathbb{R}^3$ be the elementary vectors in \mathbb{R}^3 , and let $\vec{y}_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, $\vec{y}_2 = \begin{bmatrix} -4 \\ 5 \\ 6 \end{bmatrix}$, & $\vec{y}_3 = \begin{bmatrix} 7 \\ 8 \\ -9 \end{bmatrix}$.

Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a Linear Transformation that maps \vec{e}_1 to \vec{y}_1 , maps \vec{e}_2 to \vec{y}_2 , and maps \vec{e}_3 to \vec{y}_3 .

Find the image under T of $\begin{bmatrix} 3 \\ 6 \\ 9 \end{bmatrix}$.

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \longrightarrow T(\vec{e}_1) = \vec{y}_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad \checkmark$$

$$\vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \rightarrow T(\vec{e}_2) = \vec{y}_2 = \begin{bmatrix} -4 \\ 5 \\ 6 \end{bmatrix} \quad \checkmark$$

$$\vec{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \rightarrow T(\vec{e}_3) = \vec{y}_3 = \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix} \quad \checkmark$$

So:

$$\begin{bmatrix} 3 \\ 6 \\ 9 \end{bmatrix} = 3\vec{e}_1 + 6\vec{e}_2 + 9\vec{e}_3 \quad \checkmark$$

$$\Rightarrow T\left(\begin{bmatrix} 3 \\ 6 \\ 9 \end{bmatrix}\right) = 3\vec{y}_1 + 6\vec{y}_2 + 9\vec{y}_3 = 3\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + 6\begin{bmatrix} -4 \\ 5 \\ 6 \end{bmatrix} + 9\begin{bmatrix} 7 \\ 8 \\ -9 \end{bmatrix} \quad \checkmark$$

$$= \begin{bmatrix} 3 - 24 + 63 \\ 6 + 30 + 72 \\ 9 + 36 - 81 \end{bmatrix} = \boxed{\begin{bmatrix} 42 \checkmark \\ 108 \checkmark \\ -36 \checkmark \end{bmatrix}}$$

+5

Awesome!