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hw5_rl_q4_temporal_difference_learning

Question 4: Temporal Difference Learning

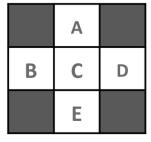
10/10 points (graded)

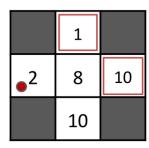
Consider the gridworld shown below. The left panel shows the name of each state A through E. The middle panel shows the current estimate of the value function V^π for each state. A transition is observed, that takes the agent from state B through taking action east into state C, and the agent receives a reward of -2. Assuming $\gamma=1, \alpha=\frac{1}{2}$, what are the value estimates after the TD learning update? (note: the value will change for one of the states only)

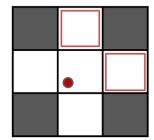


Observed Transition: B, east, C, -2







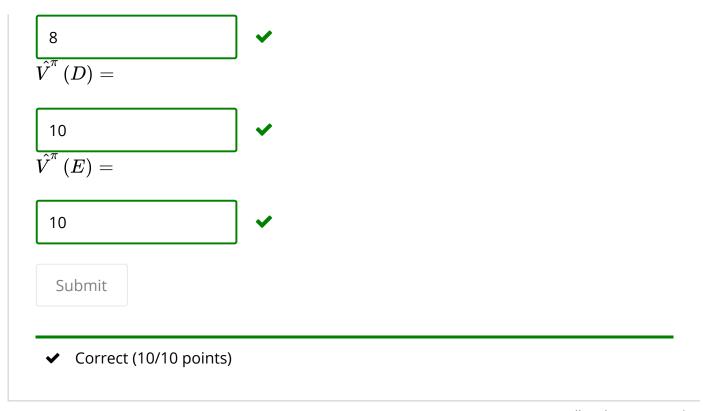


Assume:
$$\gamma$$
 = 1, α = 1/2 $V^{\pi}(s) \leftarrow (1-\alpha)V^{\pi}(s) + \alpha \left[R(s,\pi(s),s') + \gamma V^{\pi}(s')\right]$

$${\hat V}^{\pi}\left(A
ight)=$$



$$\hat{V}^{n}\left(B
ight) =$$



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