

Shortest Paths

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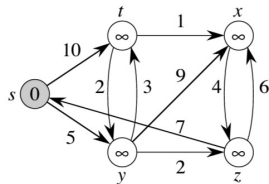
Greedy Dijkstra's Algorithm

Let $G = (V, E)$ be a weighted, directed graph with nonnegative weights.

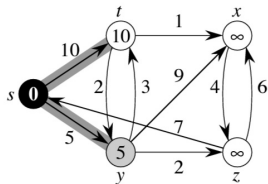
DIJKSTRA(G, w, s)

```
1  for each vertex  $v \in G.V$ 
2       $v.d = \infty$ 
3       $v.\pi = \text{NIL}$ 
4   $s.d = 0$ 
5   $S = \emptyset$ 
6   $Q = G.V$ 
7  while  $Q \neq \emptyset$ 
8       $u = \text{EXTRACT-MIN}(Q)$ 
9       $S = S \cup \{u\}$ 
10     for each vertex  $v \in G.Adj[u]$ 
11         if  $v.d > u.d + w(u, v)$ 
12              $v.d = u.d + w(u, v)$ 
13              $v.\pi = u$ 
```

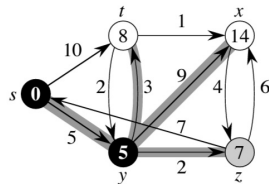
Execution of Dijkstra



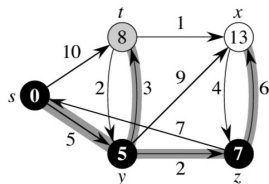
(a)



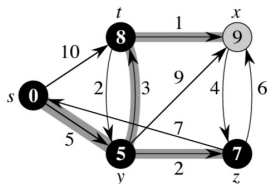
(b)



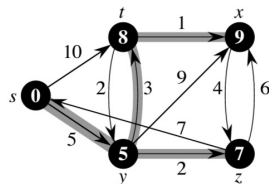
(c)



(d)



(e)



(f)

Correctness Proof of Dijkstra

Theorem 24.6. Dijkstra's Algorithm terminates with $u.d = \delta(s, u)$ for all $u \in V$, where $\delta(s, u)$ is the length of the shortest path from s to u .

Proof. By contradiction: u is added to S but $u.d \neq \delta(s, u)$. That is, there is a path from s to u but when u is selected, $u.d > \delta(s, u)$.

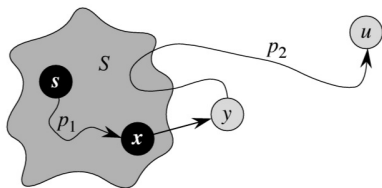


Figure 24.7 The proof of Theorem 24.6. Set S is nonempty just before vertex u is added to it. We decompose a shortest path p from source s to vertex u into $s \xrightarrow{p_1} x \rightarrow y \xrightarrow{p_2} u$, where y is the first vertex on the path that is not in S and $x \in S$ immediately precedes y . Vertices x and y are distinct, but we may have $s = x$ or $y = u$. Path p_2 may or may not reenter set S .

Correctness Proof of Dijkstra Continued

- Note that for all $v \in V$: $v.d \geq \delta(s, v)$.
- Let p be a shortest path from s to u , and y the first node $\in V - S$ on p . That is,

$$y.d = \delta(s, y).$$

- Thus, $u.d > \delta(s, u) = \delta(s, y) + \delta(y, u) = y.d + \delta(y, u) \geq y.d$.
- Hence, u should have not been chosen, a contradiction.

Runtime: $O(|V| \log |V| + |E|)$.

Floyd-Warshall's Algorithm

Finding all-pairs shortest paths on a directed graph $G = (V, E)$.

- Using DP.
- Formulation: Let $d_{ij}^{(k)}$ be the weight of a shortest path from node i to node j , where all intermediate nodes on the path are a subset of $\{1, 2, \dots, k\}$.
 - There are $\Theta(n^3)$ subproblems.
 - Want to compute $d_{ij}^{(n)}$ for all pairs (i, j) .
- Localization:

$$d_{ij}^{(k)} = \begin{cases} w_{ij}, & \text{if } k = 0, \\ \min \left\{ d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right\}, & \text{if } k \geq 1. \end{cases}$$

Let $D^{(n)}$ denote the matrix of shortest-path weights.

FLOYD-WARSHALL(W)

```
1   $n = W.rows$ 
2   $D^{(0)} = W$ 
3  for  $k = 1$  to  $n$ 
4      let  $D^{(k)} = \left(d_{ij}^{(k)}\right)$  be a new  $n \times n$  matrix
5      for  $i = 1$  to  $n$ 
6          for  $j = 1$  to  $n$ 
7               $d_{ij}^{(k)} = \min \left\{ d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right\}$ 
8  return  $D^{(n)}$ .
```

Runtime: $\Theta(n^3)$.

Shortest-Path Construction

- Let $\Pi^{(k)} = \left(\pi_{ij}^{(k)} \right)_{n \times n}$, where $\pi_{ij}^{(k)}$ is the predecessor of node j on a shortest path from node i with all immediate nodes in the path in $\{1, 2, \dots, k\}$.
- Let

$$\pi_{ij}^{(0)} = \begin{cases} \text{NIL}, & \text{if } i = j \text{ or } w_{ij} = \infty, \\ i, & \text{if } i \neq j \text{ and } w_{ij} < \infty. \end{cases}$$

- Let

$$\pi_{ij}^{(k)} = \begin{cases} \pi_{ij}^{(k-1)}, & \text{if } d_{ij}^{(k-1)} \leq d_{ik}^{(k-1)} + d_{kj}^{(k-1)}, \\ \pi_{kj}^{(k-1)}, & \text{if } d_{ij}^{(k-1)} > d_{ik}^{(k-1)} + d_{kj}^{(k-1)}. \end{cases}$$

Transitive Closure

- Determine if G contains a path from i to j for all pairs (i, j) .
- Define a **transitive closure** of G as the graph $G^* = (V, E^*)$, where

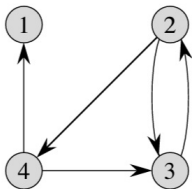
$$E^* = \{(i, j) \mid \text{there is a path from node } i \text{ to node } j \text{ in } V\}.$$

- Let

$$t_{ij}^{(0)} = \begin{cases} 0, & \text{if } i \neq j \text{ and } (i, j) \notin E, \\ 1, & \text{if } i = j \text{ or } (i, j) \in E. \end{cases}$$

- Let $t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee \left(t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)} \right)$.

Example



$$T^{(0)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$

$$T^{(1)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$

$$T^{(2)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$

$$T^{(3)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$T^{(4)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

Reweighting and Johnson's Algorithm

- Reweighting: Obtain nonnegative weight cycles while preserving shortest paths
- The following reweighting preserves shortest paths for any function $h : V \rightarrow R$:

$$\hat{w}(u, v) = w(u, v) + h(u) - h(v).$$

- Reason: Let $p = \langle v_0, v_1, \dots, v_k \rangle$ be any path from v_0 to v_k . Then

$$\begin{aligned}\hat{w}(p) &= \sum_{i=1}^k (w(v_{i-1}, v_i) + h(v_{i-1}) - h(v_i)) \\ &= w(p) + h(v_0) - h(v_k).\end{aligned}$$

Thus, $\hat{w}(p)$ is the smallest among all paths from v_0 to v_k under the new weights iff $w(p)$ is so under the old weights.

Nonnegative New Weight

- Add a dummy node s to every node $u \in G$ with $w(s, u) = 0$.
- Let $h(u) = \delta(s, u)$.
- By triangle inequality: $\delta(s, v) \leq \delta(s, u) + w(u, v)$, thus,

$$\hat{w}(u, v) = w(u, v) + h(u) - h(v) \geq 0.$$

Johnson's Algorithm

JOHNSON(G, w)

```
1  Add a dummy node  $s$  to every node  $u \in G$  with  $w(s, u) = 0$ .
2  if BELLMAN-FORD( $G', w, s$ ) == FALSE
3      Print "There is a negative-weight cycle"
4  else for each  $v \in G'.V$ 
5      Set  $h(u) = \delta(s, u)$ 
6      for each  $(u, v) \in G'.E$ 
7          Set  $\hat{w}(u, v) = w(u, v) + h(u) - h(v)$ 
8      for each  $u \in G.V$ 
9          run DIJKSTRA( $G, \hat{w}, u$ ) to compute  $\hat{\delta}(u, v)$  for all  $v \in G.V$ 
10     for each  $v \in G.V$ 
11          $d_{uv} = \hat{\delta}(u, v) + h(v) - h(u)$ 
12 return  $D = (d_{uv})$ 
```