

Exam 3

Solution

Name:

Linear Algebra I: Exam 3 (Summer 2019)

Show ALL work, as unjustified answers may receive no credit. Calculators are not allowed on any quiz or test paper. Make sure to exhibit skills discussed in class. Box all answers and simplify answers as much as possible.

Good Luck! ☺

1. Linearly Independent Sets; Bases

Let $\vec{v}_1 = (1, 1, 1)$, $\vec{v}_2 = (1, 2, 3)$, $\vec{v}_3 = (1, 1, 2)$.

(a) [5 pts] Show that the vectors are Linearly Independent.

(b) [5 pts] Find the unique weights (scalars) c_1, c_2, c_3 such that $\vec{v} = (2, 1, 3)$ can be written as $\vec{v} = c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3$

$$(a) [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3 \ | \ \vec{0}] = \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & 2 & 1 & 0 \\ 1 & 3 & 2 & 0 \end{array} \right] \xrightarrow[\substack{-R_1 \\ +R_2 \\ N \cdot R_2}]{-R_1 \\ +R_3 \\ N \cdot R_3} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \end{array} \right] \xrightarrow[\substack{-2R_2 \\ +R_3}]{N \cdot R_3} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

∴ Since a pivot position \exists in row/column, NO free variables $\exists \Rightarrow A\vec{x} = \vec{0}$ has only the trivial solution & thus the columns of A , $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$, are Linearly Independent.

$$(b) c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3 = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3] \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \vec{v} \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 3 & 2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$

Row-reduce to rref:

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 1 & 2 & 1 & 1 \\ 1 & 3 & 2 & 3 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & 1 & 0 & -1 \\ 0 & 2 & 1 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 3 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 3 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 3 \end{array} \right]$$

$$\Rightarrow \begin{cases} c_1 = 0 \\ c_2 = -1 \\ c_3 = 3 \end{cases} \quad \& \quad \vec{v} = 0\vec{v}_1 + (-1)\vec{v}_2 + 3(\vec{v}_3)$$

2. Null Spaces, Column Spaces, and Linear Transformations

Define the Linear Transformation $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$ by $T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}\right) = \begin{bmatrix} x_1 + x_2 \\ x_2 - x_3 \\ x_1 + x_4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$

- (a) [5 pts] Find the column space of T .
 (b) [5 pts] Find the null space of T .
 (c) [2 pts] Find a basis for the column space of T .
 (d) [2 pts] Find the basis for the null space of T .

$$\Rightarrow [\vec{a}_1 \vec{a}_2 \vec{a}_3 \vec{a}_4] \vec{x} \rightarrow A\vec{x}$$

Hint: The column space of T is $\text{Col}(A)$ and the null space of T is $\text{Nul}(A)$, where A is the standard matrix of T ☺

(a) $\text{Col}(A) = (\text{all columns of } A) = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

(b) $[A | \vec{0}] = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \sim$

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix} \Rightarrow \begin{cases} x_1 = -x_4 \\ x_2 = x_4 \\ x_3 = x_4 \\ x_4 \text{ is free} \end{cases} \Rightarrow \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_4 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

st $x_4 \in \mathbb{R}$

∴ $\text{Nul}(A) = \left\{ \begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$

(c) Basis for $\text{Col}(A)$ = The pivot columns of A
 $= \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} \right\}$

(d) Basis for $\text{Nul}(A)$ = $\left\{ \begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$

Therefore: Since all 3 conditions are satisfied,
 $H+K$ is a subspace of V .

3. Vector Spaces and Subspaces

Let H and K be subspaces of a vector space V . Let $H+K = \{\vec{w} : \vec{w} = \vec{u} + \vec{v}, \vec{u} \in H \text{ and } \vec{v} \in K\}$.

[9 pts] Show that $H+K$ is a subspace of V .

Initial Conditions:

- ① H & K are subspaces of vector space V
- ② Let $H+K = \{\vec{w} : \vec{w} = \vec{u} + \vec{v}, \vec{u} \in H \text{ & } \vec{v} \in K\}$

① Show that $\vec{0}_V \in H+K$:

- Let $\vec{w} \in H+K$ st $\vec{w} = \vec{u} + \vec{v}$, where $\vec{u} \in H$ & $\vec{v} \in K$
- Since H & K are subspaces: $\vec{u} = \vec{0} \in H$ & $\vec{v} = \vec{0} \in K$
- Then: $\vec{w} = \vec{0} + \vec{0} = \vec{0} \in H+K$ ✓

② Show that $H+K$ is closed under addition:

- Let $\vec{w}_1, \vec{w}_2 \in H+K$ st $\begin{cases} \vec{w}_1 = \vec{u}_1 + \vec{v}_1 \\ \vec{w}_2 = \vec{u}_2 + \vec{v}_2 \end{cases}$, where
 - $\vec{u}_1, \vec{u}_2 \in H$
 - $\vec{v}_1, \vec{v}_2 \in K$

• Take the Sum: $\vec{w}_1 + \vec{w}_2 = (\vec{u}_1 + \vec{v}_1) + (\vec{u}_2 + \vec{v}_2) = \vec{u}_1 + \vec{v}_1 + \vec{u}_2 + \vec{v}_2$

→ $\vec{w}_1 + \vec{w}_2 = (\vec{u}_1 + \vec{u}_2) + (\vec{v}_1 + \vec{v}_2)$, where $\begin{cases} \vec{u}_1 + \vec{u}_2 \in H \\ \vec{v}_1 + \vec{v}_2 \in K \end{cases}$ *b/c H & K are subspaces
∴ $\vec{w}_1 + \vec{w}_2 \in H+K$ & Closed Under \oplus .

③ Show that $H+K$ is closed under scalar-multiplication:

- Let $\vec{w} \in H+K$ st $\vec{w} = \vec{u} + \vec{v}$, where $\vec{u} \in H$ & $\vec{v} \in K$
Let c be any scalar, $c \in \mathbb{R}$.
- Take the Product:

$c\vec{w} = c(\vec{u} + \vec{v}) = c\vec{u} + c\vec{v}$, where $\begin{cases} c\vec{u} \in H \\ c\vec{v} \in K \end{cases}$ *b/c H & K are subspaces
∴ $c\vec{w} \in H+K$ & Closed Under \odot

4. Null Spaces, Column Spaces, and Linear Transformations

Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear transformation and $\mathcal{B} = \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ be a basis for \mathbb{R}^3 . Suppose that $T(\vec{v}_1) = (-2, 1, 1)$, $T(\vec{v}_2) = (0, 1, -1)$, $T(\vec{v}_3) = (-2, 2, 0)$.

(a) [5 pts] Determine whether $\vec{w} = (-6, 5, 0)$ is in the range of T .

(b) [5 pts] Find a basis for the kernel of T .

$$* T: \mathbb{R}^3 \rightarrow \mathbb{R}^3 \quad \text{st} \quad T(\vec{v}) = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3] \vec{x} = \begin{bmatrix} -2 & 0 & -2 \\ 1 & 1 & 2 \\ 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$(a) \begin{bmatrix} -2 & 0 & -2 & | & -6 \\ 1 & 1 & 2 & | & 5 \\ 1 & -1 & 0 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & | & 3 \\ 1 & 1 & 2 & | & 5 \\ 1 & -1 & 0 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & | & 3 \\ 0 & 1 & 1 & | & 2 \\ 0 & -1 & -1 & | & -3 \end{bmatrix} \sim$$

$$\begin{bmatrix} 1 & 0 & 1 & | & 3 \\ 0 & 1 & 1 & | & 2 \\ 0 & 0 & 0 & | & -1 \end{bmatrix}$$

$\rightarrow \leftarrow$

System is inconsistent
 $\Rightarrow \vec{w}$ is NOT in the range.

$$(b) \begin{bmatrix} -2 & 0 & -2 & | & 0 \\ 1 & 1 & 2 & | & 0 \\ 1 & -1 & 0 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 1 & -1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & -1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} x_1 = -x_3 \\ x_2 = -x_3 \\ x_3 \text{ is free} \end{cases} \Rightarrow \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}, \quad \text{st } x_3 \in \mathbb{R}$$

Basis for the Kernel:

$$\mathcal{B} = \left\{ \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \right\}$$

5. Coordinate Systems

The set $B = \{1 + t^2, 2t - t^2, 1 - t + t^2\}$ be a basis for \mathbb{P}_2 .

[5pts] Find the coordinate vector $p(t) = 1 + 16t - 6t^2$ relative to B .

$$* B = \{\vec{b}_1, \vec{b}_2, \vec{b}_3\} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\}$$

$$* \vec{p}(t) = 1 + 16t - 6t^2 = \begin{bmatrix} 1 \\ 16 \\ -6 \end{bmatrix}$$

$$* \vec{p}(t) = c_1 \vec{b}_1 + c_2 \vec{b}_2 + c_3 \vec{b}_3 = [\vec{b}_1 \vec{b}_2 \vec{b}_3] \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} \quad \text{ST} \quad [\vec{p}]_B = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 2 & -1 & 16 \\ 1 & -1 & 1 & -6 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 2 & -1 & 16 \\ 0 & -1 & 0 & -7 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 7 \\ 0 & 2 & -1 & 16 \end{array} \right] \sim$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 7 \\ 0 & 0 & -1 & 2 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 7 \\ 0 & 0 & -1 & 2 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 7 \\ 0 & 0 & 1 & -2 \end{array} \right]$$

$$\Rightarrow \begin{cases} c_1 = 3 \\ c_2 = 7 \\ c_3 = -2 \end{cases}$$

$$\therefore [\vec{p}]_B = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 7 \\ -2 \end{bmatrix}$$

Bonus Question: Coordinate Systems

Let $B = \left\{ \begin{bmatrix} 1 \\ -4 \end{bmatrix}, \begin{bmatrix} -2 \\ 9 \end{bmatrix} \right\}$. Since the coordinate mapping determined by B is a linear transformation from \mathbb{R}^2 to \mathbb{R}^2 , this mapping must be implemented by some 2×2 matrix A .

[5pts] Find it.

*Hint: Multiplication by " A " should transform a vector into its coordinate vector, $[\vec{x}]_B$ \therefore

Recall: $\vec{x} = P_B [\vec{x}]_B$ or $P_B = [\vec{b}_1 \cdots \vec{b}_n]$

$\nRightarrow P_B^{-1} \vec{x} = [\vec{x}]_B$

... So $A = P_B^{-1}$ $\Downarrow \Downarrow$

Find P_B^{-1} :

* $P_B = [\vec{b}_1 \vec{b}_2] = \begin{bmatrix} 1 & -2 \\ -4 & 9 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

* $P_B^{-1} = \frac{1}{(ad-bc)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \frac{1}{(9-8)} \begin{bmatrix} 9 & 2 \\ 4 & 1 \end{bmatrix} = \begin{bmatrix} 9 & 2 \\ 4 & 1 \end{bmatrix}$

$\therefore A = \begin{bmatrix} 9 & 2 \\ 4 & 1 \end{bmatrix}$

Ans