





















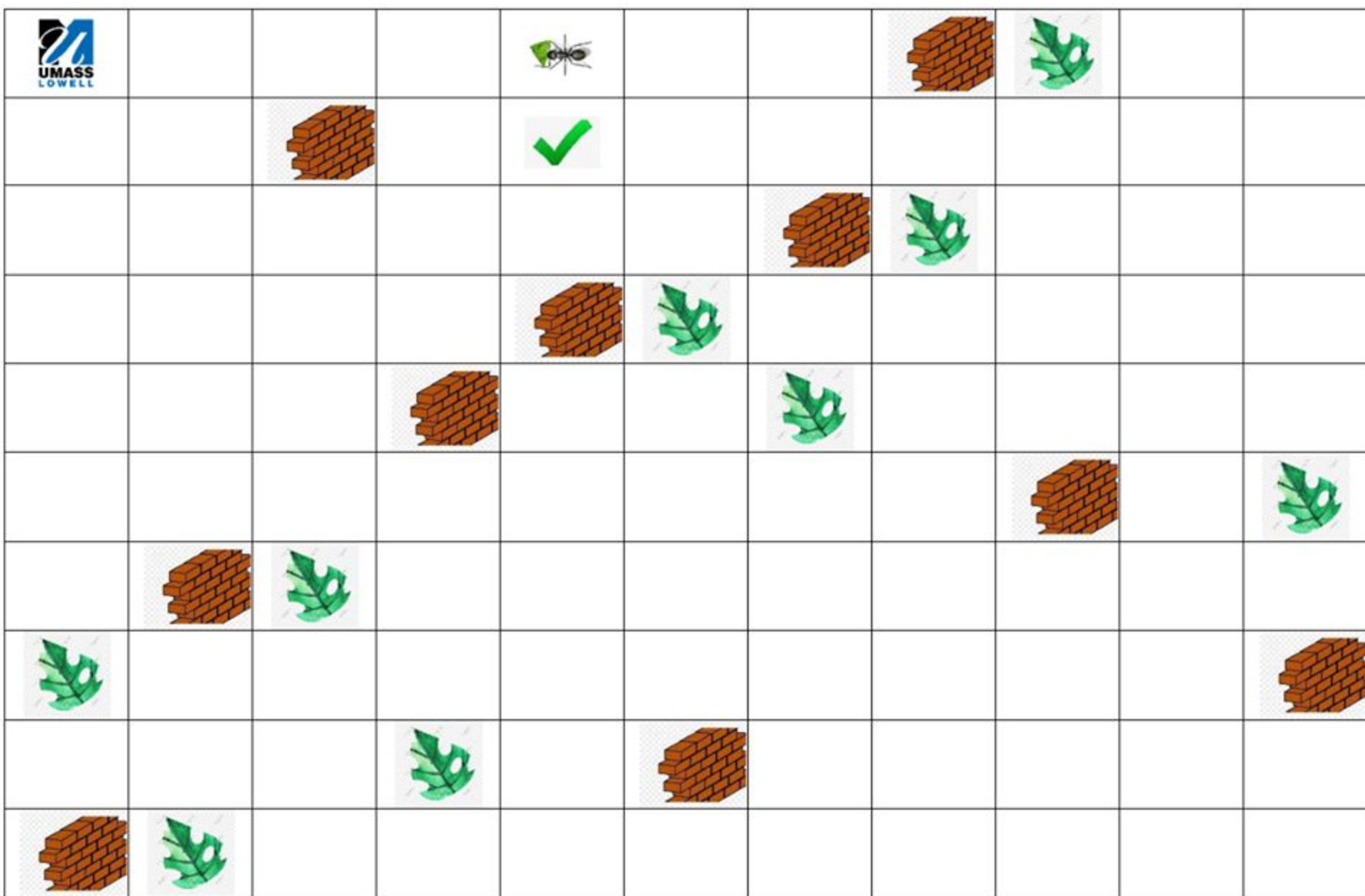
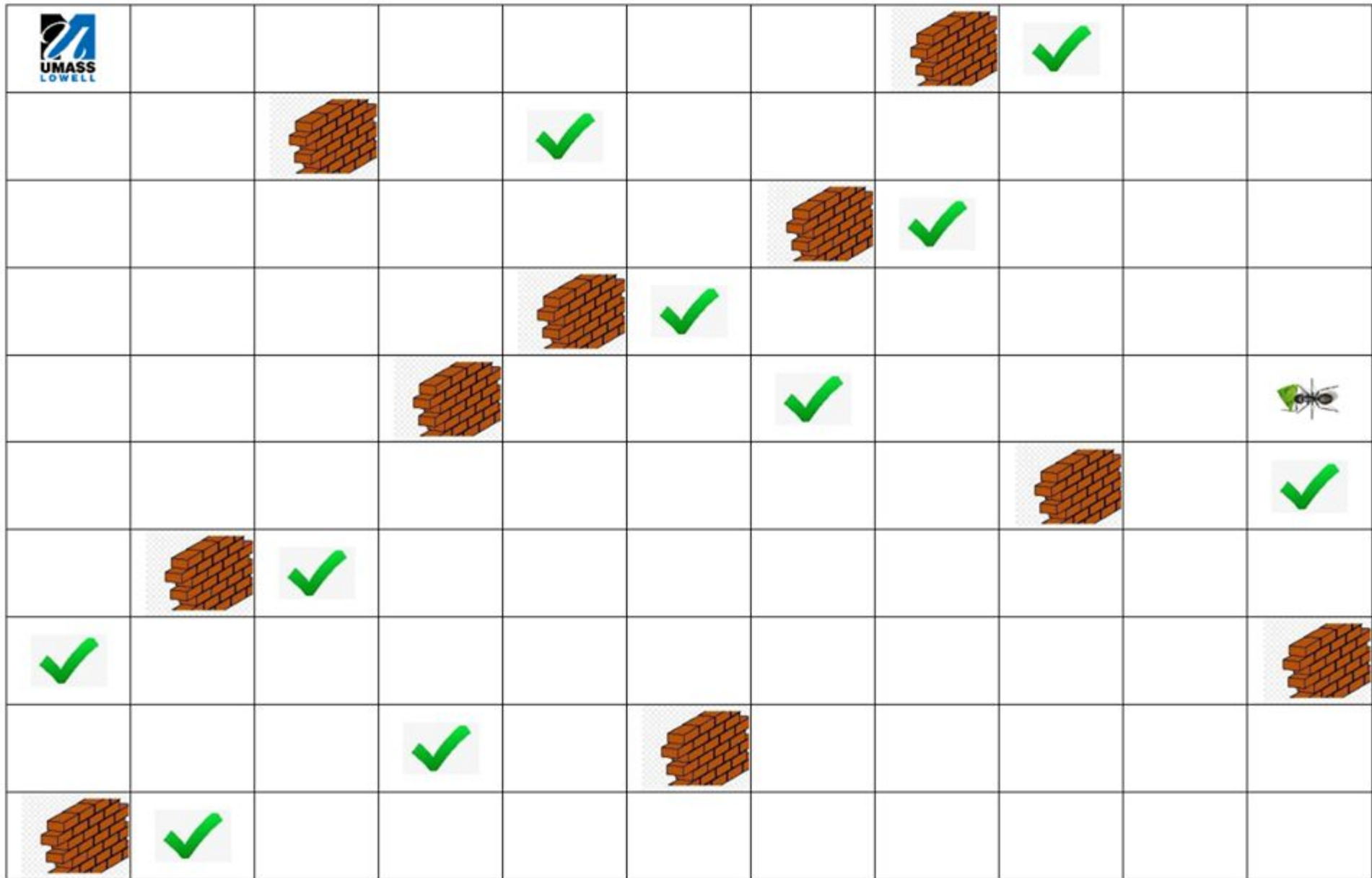


Project: Ant 's Nest Building

Students: Phong Vo, Giang Tran





CONCEPTION

- Developed using A* algorithm, C# and Visual Studio 2019
- Purpose: to optimize the path of the ant to be fewest of walks on round trips.
- Objects: 10 leaves for building up the nest. The leaves can be blocked by 10 bricks.
- Tricks: The ant must wisely reach out the leaves without hitting the bricks.
- Once the ant has a leaf in hands, it will head back to the nest, then continues returning to the field for another leaf.
- The loop of collecting the leaves is finished once all of 10 leaves are gathered. Then the game is finished.

ALGORITHM

Suppose n is an attainable state (there is a path from the initial state 0 to n). We define the evaluation function: $f(n) = g(n) + h(n)$

+ $g(n)$ is the cost from the original node n_0 to the current node n

+ $h(n)$ estimated cost from current node n to destination

+ $f(n)$ the estimated total cost of the path through the current node n to the destination

A heuristic estimate of $h(n)$ is considered to be acceptable if for every node n :

$$0 < h(n) < h^*(n)$$

Where $h^*(n)$ is the actual cost to go from node n to destination.

THANK YOU FOR LISTENING