

2.3.3

$$\begin{aligned}
 & \begin{bmatrix} 2 & 0 & 0 \\ -3 & -5 & 0 \\ 9 & 6 & -2 \end{bmatrix} \xrightarrow{\frac{R_1}{2}} \begin{bmatrix} 1 & 0 & 0 \\ -3 & -5 & 0 \\ 9 & 6 & -2 \end{bmatrix} \xrightarrow{\begin{matrix} 3R_1+R_2 \\ = nR_2 \\ -9R_1+R_3 \\ = nR_3 \end{matrix}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -5 & 0 \\ 0 & 6 & -2 \end{bmatrix} \xrightarrow{\begin{matrix} R_2/-5 \\ R_3/2 \end{matrix}} \\
 & \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 3 & -1 \end{bmatrix} \xrightarrow{\begin{matrix} 3R_2-R_3 \\ = nR_3 \end{matrix}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \begin{array}{l} \text{There are 3 pivot positions} \\ \text{in 3 rows} \\ \Rightarrow \boxed{\text{invertible}} \end{array}
 \end{aligned}$$

2.3.4

$$\begin{aligned}
 & \begin{bmatrix} 4 & 0 & -4 \\ 3 & 0 & 5 \\ -4 & 0 & 9 \end{bmatrix} \quad \begin{array}{l} \text{Column \#2 is 0's} \Rightarrow \text{system has at most 2 pivot positions} \\ \Rightarrow \text{free variable, nontrivial solution } \exists \\ \Rightarrow \boxed{\text{NOT invertible}} \end{array}
 \end{aligned}$$

2.3.6

$$\begin{aligned}
 & \begin{bmatrix} 1 & -3 & -6 \\ 0 & 4 & 3 \\ -2 & 3 & 0 \end{bmatrix} \xrightarrow{\begin{matrix} 2R_1+R_3 \\ = nR_3 \end{matrix}} \begin{bmatrix} 1 & -3 & -6 \\ 0 & 4 & 3 \\ 0 & -3 & -12 \end{bmatrix} \xrightarrow{\frac{R_3}{-3}} \begin{bmatrix} 1 & -3 & -6 \\ 0 & 4 & 3 \\ 0 & 1 & 4 \end{bmatrix} \\
 & \xrightarrow{\begin{matrix} -R_2+4R_3 \\ = nR_3 \end{matrix}} \begin{bmatrix} 1 & -3 & -6 \\ 0 & 4 & 3 \\ 0 & 0 & 13 \end{bmatrix} \quad \begin{array}{l} 3 \text{ pivot positions} \Rightarrow \boxed{\text{invertible}} \end{array}
 \end{aligned}$$

2.3.7

$$\begin{array}{l} -R_1 \\ R_3 / -3 \end{array} \rightarrow \begin{bmatrix} 1 & 4 & 0 & -1 \\ 5 & 7 & 26 & -5 \\ 1 & 4 & -1 & -1 \\ 0 & -1 & 2 & 1 \end{bmatrix} \xrightarrow{R_1 - R_3 = nR_3} \begin{bmatrix} 1 & 4 & 0 & -1 \\ 0 & 1 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 5 & 7 & 26 & -5 \end{bmatrix} \xrightarrow{5R_1 - R_4 = nR_4}$$

$$\rightarrow \begin{bmatrix} 1 & 4 & 0 & -1 \\ 0 & 1 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 13 & -26 & 0 \end{bmatrix} \xrightarrow{R_4 / 13} \begin{bmatrix} 1 & 4 & 0 & -1 \\ 0 & 1 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & -2 & 0 \end{bmatrix} \xrightarrow{-R_2 + R_4 = nR_4}$$

$$\rightarrow \begin{bmatrix} 1 & 4 & 0 & -1 \\ 0 & 1 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \begin{array}{l} 4 \text{ pivots positions in 4 rows} \\ \Rightarrow \text{invertible} \end{array}$$

2.3.34

$$T(x_1, x_2) = (5x_1 - 9x_2, -5x_1 + 7x_2)$$

$$A = \begin{bmatrix} 5 & -9 \\ -5 & 7 \end{bmatrix}$$

$$\det(A) = 35 - 45 = -10 \neq 0 \quad \checkmark$$

\Rightarrow invertible

$$T^{-1} = \frac{1}{\det(A)} \begin{bmatrix} 7 & 9 \\ 5 & 5 \end{bmatrix} = \begin{bmatrix} \frac{-7}{10} & \frac{-9}{10} \\ \frac{-1}{2} & \frac{-1}{2} \end{bmatrix}$$

$$\Rightarrow T^{-1}(x_1, x_2) = \left(\frac{-7}{10}x_1 - \frac{9}{10}x_2, \frac{-1}{2}x_1 - \frac{1}{2}x_2 \right)$$