

FFT: Fast Polynomial Multiplications

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- So far we have learned five basic algorithm design techniques: (1) sorting and searching; (2) divide-and-conquer; (3) greedy selection; (4) dynamic programming, and (5) linear programming. Another common technique is to use math tricks (actually DP and LP are in this category).
- Fast Fourier transform for computing polynomial multiplications is a typical math trick.

Polynomials

- General form:

$$A(x) = a_0x^0 + a_1x + \cdots a_{n-1}x^{n-1} = \sum_{j=0}^{n-1} a_jx^j.$$

- $A(x)$ has **degree** k if its highest nonzero coefficient is a_k , denoted by $\text{degree}(A) = k$.
- The degree of a polynomial of **degree-bound** n may be any integer between 0 and $n - 1$.
- Unless otherwise stated, all polynomials we will consider have degree-bound n .

Evaluation and Summation

- Point evaluation (**Horner's rule**):

$$A(x_0) = a_0 + x_0(a_1 + x_0(a_2 + \cdots + x_0(a_{n-2} + x_0(a_{n-1}))) \cdots).$$

- Runtime of point evaluation: $\Theta(n)$.
- Summation:

$$A(x) + B(x) = \sum_{j=0}^{n-1} (a_j + b_j)x_j.$$

- Runtime of summation: $\Theta(n)$.

Multiplication and Convolution

- Multiplication: $C(x) = A(x)B(x)$, where $C(x)$ has degree-bound $2n - 1$,

$$C(x) = \sum_{j=0}^{2n-2} c_j x^j$$
$$c_j = \sum_{k=0}^j a_k b_{j-k}.$$

- $\mathbf{c} = (c_1, c_2, \dots, c_{2n-2})$ is called the **convolution** of $\mathbf{a} = (a_0, a_1, \dots, a_{n-1})$ and $\mathbf{b} = (b_1, b_2, \dots, b_{n-1})$, denoted by $\mathbf{c} = \mathbf{a} \otimes \mathbf{b}$.
- Runtime: $\Theta(n^2)$.
- Note: Since $C(x)$ belongs to polynomials of degree-bound $2n$, for computational convenience, we will treat $C(x)$ as a polynomial of degree bound $2n$ (rather than $2n - 1$).

Representations

- **Coefficient representation:** A polynomial of degree-bound n can be represented by $(a_0, a_1, \dots, a_{n-1})$.
- **Point-value representation:** $\{(x_0, y_0), \dots, (x_{n-1}, y_{n-1})\}$, where $y_i = A(x_i)$ and $x_i \neq x_j$ if $i \neq j$.
- Given a polynomial, computing a point-value representation is straightforward and the runtime is $\Theta(n^2)$.

- **Interpolation:** The process from point-value representation to coefficient representation.
- **Lagrange's formula:** For any set $\{(x_0, y_0), \dots, (x_{n-1}, y_{n-1})\}$ of n point-value pairs with pairwise different x_k , there is a unique polynomial $A(x)$ of degree-bound n such that $y_k = A(x_k)$ for $k = 0, \dots, n-1$, where

$$A(x) = \sum_{k=0}^{n-1} y_k \frac{\prod_{j \neq k} (x - x_j)}{\prod_{j \neq k} (x_k - x_j)}.$$

This indicates the **uniqueness of interpolating polynomials**.

Point-value Representations and Operations

- Suppose

$$A : \{(x_0, y_0), \dots, (x_{n-1}, y_{n-1})\}$$

$$B : \{(x_0, y'_0), \dots, (x_{n-1}, y'_{n-1})\}.$$

- Addition:

$$C(x) = A(x) + B(x) : \{(x_0, y_0 + y'_0), \dots, (x_{n-1}, y_{n-1} + y'_{n-1})\}.$$

- Multiplication needs extended point-value representations on $2n$ points:

$$A : \{(x_0, y_0), \dots, (x_{2n-1}, y_{2n-1})\}$$

$$B : \{(x_0, y'_0), \dots, (x_{2n-1}, y'_{2n-1})\}.$$

Then

$$C(x) = A(x)B(x) : \{(x_0, y_0 y'_0), \dots, (x_{2n-1}, y_{2n-1} y'_{2n-1})\}.$$

Multiplications

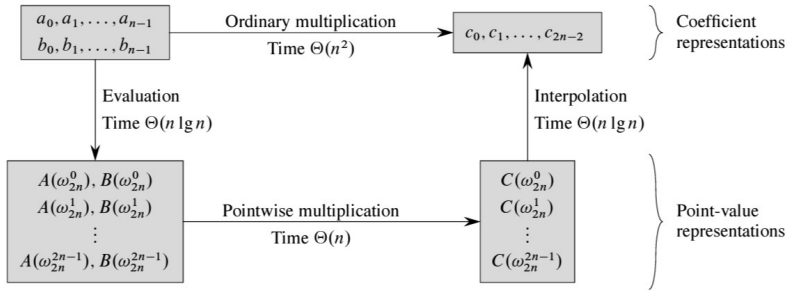


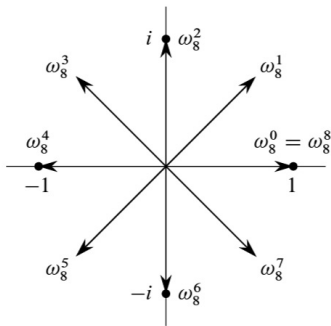
Figure 30.1 A graphical outline of an efficient polynomial-multiplication process. Representations on the top are in coefficient form, while those on the bottom are in point-value form. The arrows from left to right correspond to the multiplication operation. The ω_{2n} terms are complex $(2n)$ th roots of unity.

Discrete and Fast Fourier Transforms (DFT, FFT)

- **Complex root of unity:** Let $\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}$ be complex roots of $\omega^n = 1$, where

$$\omega_n^k = e^{2\pi i k/n}, \quad k = 0, 1, \dots, n-1.$$

- Recall that $e^{iu} = \cos(u) + i \sin(u)$.



- **Lemma 30.3 (Cancellation lemma)**

$$\omega_{dn}^{dk} = \omega_n^k$$

for any integers $n \geq 0$, $k \geq 0$, and $d > 0$.

Proof. $\omega_{dn}^{dk} = (e^{2\pi i/dn})^{dk} = (e^{2\pi i/n})^k = \omega_n^k$.

- **Corollary 30.4.**

$$\omega_n^{n/2} = \omega_2 = -1.$$

- **Lemma 30.5 (Halving lemma)** If $n > 0$ is even, then

$$(\omega_n^{k+n/2})^2 = (\omega_n^k)^2.$$

Proof. By Corollary 30.4 that $\omega_n^{n/2} = \omega_2 = -1$, we have $\omega_n^{k+n/2} = -\omega_n^k$, and so $(\omega_n^{k+n/2})^2 = (\omega_n^k)^2$.

Summation Lemma

- Summation lemma

$$\sum_{j=0}^{n-1} (\omega_n^k)^j = 0$$

for any integer $n > 0$ and any integer $k \neq 0$ with k not divisible by n .

Proof.

$$\sum_{j=0}^{n-1} (\omega_n^k)^j = \frac{(\omega_n^k)^n - 1}{\omega_n^k - 1} = \frac{(\omega_n^n)^k - 1}{\omega_n^k - 1} = \frac{(1)^n - 1}{\omega_n^k - 1} = 0.$$

The DFT

- Let

$$A(x) = \sum_{j=0}^{n-1} a_j x^j,$$

$$y_k = A(\omega_n^k) = \sum_{j=0}^{n-1} a_j \omega_n^{kj}.$$

- $\mathbf{y} = (y_0, y_1, \dots, y_{n-1})$ is the DFT of $\mathbf{a} = (a_0, a_1, \dots, a_{n-1})$, denoted by $\mathbf{y} = \text{DFT}_n(\mathbf{a})$.

The FFT

- Assume that n is a power of 2.
- Divide-and conquer. Rewrite $A(x)$ as

$$\begin{aligned} A(x) &= A^{[0]}(x^2) + xA^{[1]}(x^2), \text{ where} \\ A^{[0]}(x) &= a_0 + a_2x + a_4x^2 + \cdots + a_{n-2}x^{n/2-1}, \\ A^{[1]}(x) &= a_1 + a_3x + a_5x^2 + \cdots + a_{n-1}x^{n/2-1}. \end{aligned}$$

- Only need to evaluate two “half-size” polynomials $A^{[0]}(x)$ and $A^{[1]}(x)$ at

$$(\omega_n^0)^2, (\omega_n^1)^2, \dots, (\omega_n^{n-1})^2,$$

and combine the results.

An Important Observation

By the halving lemma, there are only $n/2$ distinct values in $(\omega_n^0)^2, (\omega_n^1)^2, \dots, (\omega_n^{n-1})^2$, where

$$\begin{aligned}(\omega_n^0)^2 &= (\omega_n^{n/2})^2, \\(\omega_n^1)^2 &= (\omega_n^{1+n/2})^2, \\&\dots, \\(\omega_n^{n/2-1})^2 &= (\omega_n^{n-1})^2.\end{aligned}$$

Recursive FFT

RECURSIVE-FFT(a)

```
1   $n = a.length$                 //  $n$  is a power of 2
2  if  $n == 1$ 
3      return  $a$ 
4   $\omega_n = e^{2\pi i/n}$ 
5   $\omega = 1$ 
6   $a^{[0]} = (a_0, a_2, \dots, a_{n-2})$ 
7   $a^{[1]} = (a_1, a_3, \dots, a_{n-1})$ 
8   $y^{[0]} = \text{RECURSIVE-FFT}(a^{[0]})$ 
9   $y^{[1]} = \text{RECURSIVE-FFT}(a^{[1]})$ 
10 for  $k = 0$  to  $n/2 - 1$ 
11      $y_k = y_k^{[0]} + \omega y_k^{[1]}$ 
12      $y_{k+(n/2)} = y_k^{[0]} - \omega y_k^{[1]}$ 
13      $\omega = \omega \omega_n$ 
14 return  $y$                 //  $y$  is assumed to be a column vector
```

Runtime: $T(n) = 2T(n/2) + \Theta(n) = \Theta(n \log n)$.

For $y_0, y_1, \dots, y_{n/2} - 1$, line 11 yields

$$\begin{aligned} y_k &= y_k^{[0]} + \omega_n^k \cdot y_k^{[1]} \\ &= A^{[0]}(\omega_{n/2}^k) + \omega_n^k \cdot A^{[1]}(\omega_{n/2}^k) \\ &= A^{[0]}(\omega_n^{2k}) + \omega_n^k \cdot A^{[1]}(\omega_n^{2k}) && \text{by the cancellation lemma} \\ &= A(\omega_n^k). \end{aligned}$$

For $y_{n/2}, y_{n/2+1}, \dots, y_{n-1}$, line 12 yields

$$\begin{aligned}
 y_{k+n/2} &= y_k^{[0]} - \omega_n^k \cdot y_k^{[1]} \\
 &= y_k^{[0]} + \omega_n^{k+n/2} \cdot y_k^{[1]} && \text{since } \omega_n^{k+n/2} = -\omega_n^k \\
 &= A^{[0]}(\omega_n^{2k}) + \omega_n^{k+n/2} \cdot A^{[1]}(\omega_n^{2k}) && \text{by the cancellation lemma} \\
 &= A^{[0]}(\omega_n^{2k+n}) + \omega_n^{k+n/2} \cdot A^{[1]}(\omega_n^{2k+n}) && \text{since } \omega_n^{2k+n} = \omega_n^{2k} \\
 &= A(\omega_n^{k+n/2}).
 \end{aligned}$$

Interpolation

- Rewrite $\mathbf{y} = \text{DFT}_n(\mathbf{a})$ as

$$\begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_{n-1} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega_n & \omega_n^2 & \omega_n^3 & \cdots & \omega_n^{n-1} \\ 1 & \omega_n^2 & \omega_n^4 & \omega_n^6 & \cdots & \omega_n^{2(n-1)} \\ 1 & \omega_n^3 & \omega_n^6 & \omega_n^9 & \cdots & \omega_n^{3(n-1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{2(n-1)} & \omega_n^{3(n-1)} & \cdots & \omega_n^{(n-1)(n-1)} \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_{n-1} \end{pmatrix}$$

- The (j, k) entry of the inverse of the Vandermonde matrix V_n is ω_n^{-kj}/n .

Proof.

$$[V_n^{-1}V_n]_{jj'} = \sum_{k=0}^{n-1} (\omega_n^{-kj/n} (\omega_n^{kj'})) = \sum_{k=0}^{n-1} \omega_n^{k(j'-j)}/n = \begin{cases} 1, & \text{if } j = j' \\ 0, & \text{otherwise.} \end{cases}$$

- $\mathbf{a} = \text{DFT}_n^{-1}(\mathbf{y})$.

Coefficients

- For $j = 0, 1, \dots, n-1$,

$$a_j = \frac{1}{n} \sum_{k=0}^{n-1} y_k \omega_n^{-kj}.$$

- Modify recursive FFT to replace \mathbf{a} with \mathbf{y} and ω_n with ω_n^{-1} , we can compute DFT_n^{-1} in $\Theta(n \log n)$ time.
- This means that we can transform the coefficient representation to the point-value representation in $O(n \log n)$ time, and so is the other direction.
- **Theorem 30.8 (Convolution theorem)** For any two vectors \mathbf{a} and \mathbf{b} of length n , where n is a power of 2,

$$\mathbf{a} \otimes \mathbf{b} = \text{DFT}_{2n}^{-1}(\text{DFT}_{2n}(\mathbf{a}) \cdot \text{DFT}_{2n}(\mathbf{b})),$$

where \mathbf{a} and \mathbf{b} are padded with 0s to length $2n$ and \cdot denotes the componentwise product of two $2n$ -element vectors.