

Section 4.2: Null Spaces, Column Spaces, & Linear Transformations

Note: Subspaces of \mathbb{R}^n usually arise 1 of 2 ways:

- ① As a set of all solutions to a system of Homogeneous Linear Eq.
- ② As the set of all linear combinations of certain specified vectors.

*In this section, we compare & contrast these↑ 2 descriptions, quickly realizing that we have been working w/ subspaces since Day 1 *

The Null Space of a Matrix

Consider the following system of homogeneous eq:

$$\begin{cases} x_1 + 2x_2 = 0 \\ 3x_1 + 4x_2 = 0 \end{cases} \iff \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$A \quad \vec{x} \quad = \quad \vec{0}$

Recall: The set of all \vec{x} that satisfy ↑ is called : "The Solution Set" of the system.

We will now call the set of \vec{x} that satisfy $A\vec{x} = \vec{0}$ the "Null Space" of the Matrix A.

*Definition: The Null Space of an $m \times n$ matrix A, written as "Nul(A)", is the set of all solutions of the homogeneous equation $A\vec{x} = \vec{0}$.

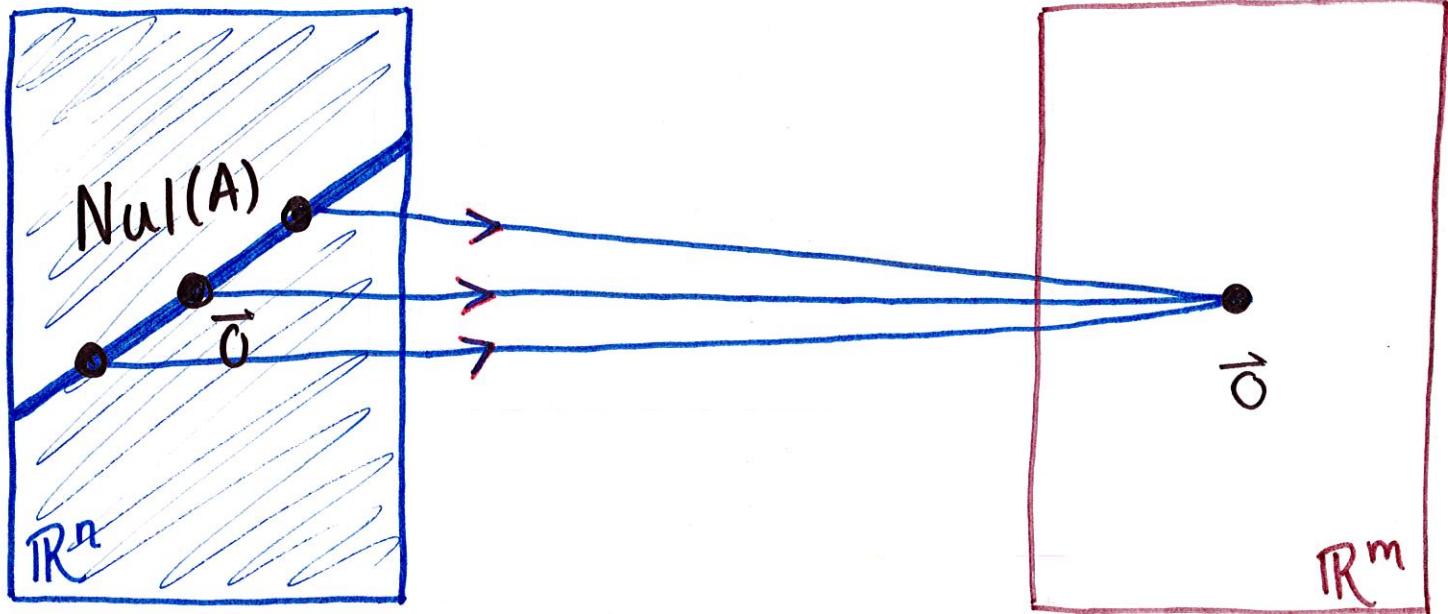
In Set Notation:

$$\text{Nul}(A) = \left\{ \vec{x} : \vec{x} \in \mathbb{R}^n \text{ & } A\vec{x} = \vec{0} \right\}$$

The Null Space as a Linear Transformation

A more dynamic description of the $\text{Nul}(A)$ is the set of all $\vec{x} \in \mathbb{R}^n$ that are mapped onto $\vec{0} \in \mathbb{R}^m$ via the Linear Transformation $\vec{x} \mapsto A\vec{x}$

Graphical Interpretation:



Example (Null Space): Determine if \vec{u} belongs to the null space of A :

$$A = \begin{bmatrix} 1 & -3 & -2 \\ -5 & 9 & 1 \end{bmatrix} \quad \& \quad \vec{u} = \begin{bmatrix} 5 \\ 3 \\ -2 \end{bmatrix}$$

Answer:

*Note: To test if \vec{u} satisfies $A\vec{u} = \vec{0}$, simply compute " $A\vec{u}$ ".

* Compute the Matrix Equation, $A\vec{u}$:

$$\begin{aligned} A\vec{u} &= \begin{bmatrix} 1 & -3 & -2 \\ -5 & 9 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 3 \\ -2 \end{bmatrix} = 5 \begin{bmatrix} 1 \\ -5 \end{bmatrix} + 3 \begin{bmatrix} -3 \\ 9 \end{bmatrix} - 2 \begin{bmatrix} -2 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 5 \\ -25 \end{bmatrix} + \begin{bmatrix} -9 \\ 27 \end{bmatrix} + \begin{bmatrix} 4 \\ -2 \end{bmatrix} = \begin{bmatrix} 5 - 9 + 4 \\ -25 + 27 - 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \checkmark \end{aligned}$$

∴ Since $A\vec{u} = \vec{0}$, $\vec{u} = \begin{bmatrix} 5 \\ 3 \\ -2 \end{bmatrix}$ is in the Null Space of A .

Answer

Example: Determine if \vec{w} is in the $\text{Nul}(A)$:

$$\vec{w} = \begin{bmatrix} 5 \\ 1 \\ 2 \end{bmatrix}, \quad A = \begin{bmatrix} 5 & -5 & -10 \\ 4 & -2 & -9 \\ -2 & 2 & 4 \end{bmatrix}$$

Answer:

*Recall: To determine if \vec{w} is in the $\text{Nul}(A)$, compute: $A\vec{w}$

*Compute $A\vec{w}$:

$$\begin{bmatrix} 5 & -5 & -10 \\ 4 & -2 & -9 \\ -2 & 2 & 4 \end{bmatrix} \begin{bmatrix} 5 \\ 1 \\ 2 \end{bmatrix} = 5 \begin{bmatrix} 5 \\ 4 \\ -2 \end{bmatrix} + 1 \begin{bmatrix} -5 \\ -2 \\ 2 \end{bmatrix} + 2 \begin{bmatrix} -10 \\ -9 \\ 4 \end{bmatrix}$$

$$= \begin{bmatrix} 25 & -5 & -20 \\ 20 & -2 & -18 \\ -10 & +2 & +8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \checkmark$$

\therefore Since $A\vec{w} = \vec{0}$, $\vec{w} \in \text{Nul}(A)$

Answer.

Theorem 2:

* The Null Space of an $m \times n$ matrix A is a subspace of \mathbb{R}^n .

-Equivalently-

* The set of all solutions to a system $A\vec{x} = \vec{0}$ of m -homogeneous Linear Equations in n -unknowns is a subspace of \mathbb{R}^n .

Note: The Null Space of A is certainly a subset of \mathbb{R}^n (b/c A has n -Col.)
BUT we must still show that the $\text{Nul}(A)$ satisfies the 3 properties of a subset ::

Proof:

• Let A be an $m \times n$ matrix.

① Show that $\vec{0} \in \mathbb{R}^n$ is in $\text{Nul}(A)$:

Of course $\vec{0} \in \text{Nul}(A) \checkmark$

② Show that the $\text{Nul}(A)$ is closed under addition:

Goal: To show $\vec{u} + \vec{v} \in \text{Nul}(A)$, we must show: $A(\vec{u} + \vec{v}) = \vec{0}$.

• Let \vec{u} & \vec{v} be vectors in $\text{Nul}(A)$, $\vec{u}, \vec{v} \in \text{Nul}(A)$.

• Then by Def: $A\vec{u} = \vec{0}$ & $A\vec{v} = \vec{0}$.

• By Prop. of Matrix Multiplication: $A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v} = \vec{0} + \vec{0} = \vec{0}$

∴ Since $A(\vec{u} + \vec{v}) = \vec{0}$, then $\vec{u} + \vec{v} \in \text{Nul}(A)$ & so $\text{Nul}(A)$ is closed under addition.

③ Show that the $\text{Nul}(A)$ is closed under scalar multiplication:

Goal: To show $c\vec{u} \in \text{Nul}(A)$, we must show: $A(c\vec{u}) = \vec{0}$.

• Let c be any scalar.

• By Prop. of Matrix Multiplication: $A(c\vec{u}) = c(A\vec{u}) = c(\vec{0}) = \vec{0} \checkmark$

∴ Since $A(c\vec{u}) = \vec{0}$, then $c\vec{u} \in \text{Nul}(A)$ & so $\text{Nul}(A)$ is closed under scalar-multiplication.

∴ Therefore: $\text{Nul}(A)$ is a subspace of \mathbb{R}^n

Example: ($\text{Nul}(A)$ as a subspace of \mathbb{R}^n):

Let H be the set of all vectors in \mathbb{R}^4 whose coordinates a, b, c, d satisfy the equations $a - 2b + 5c = d$ & $c - a = b$. Show that H is a subspace of \mathbb{R}^4 .

Answer:

*Note: It is important that the Linear Equations defining the set H are homogeneous ($A\vec{x} = \vec{0}$)

→ Otherwise, the set of solutions will NOT be a subspace
($b/c \vec{0}$ is NOT a solution of a nonhomogeneous system)

*Also, in some cases, the set of solution could be empty.

*Rearrange the equations that describe the elements of H :

$$\left\{ \begin{array}{l} a - 2b + 5c - d = 0 \\ -a - b + c = 0 \end{array} \right. \quad \Leftrightarrow \quad A \cdot \vec{x} = \vec{0}$$

$$\left[\begin{array}{cccc} 1 & -2 & 5 & -1 \\ -1 & -1 & 1 & 0 \end{array} \right] \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

So, H is the set of all solutions that satisfy the system $A\vec{x} = \vec{0}$ of $m=2$ Homogeneous Linear Equations, in $n=4$ unknowns.

⇒ ∵ (By Theorem #2): H is a subspace of \mathbb{R}^4

Answer

*An Explicit Description of $\text{Nul}(A)$ *

- There is NO obvious relation btw $\text{Nul}(A)$ & the entries of A .
⇒ $\text{Nul}(A)$ is defined implicitly b/c it is defined by a condition that must be checked.
⇒ NO explicit list/description of the elements in $\text{Nul}(A)$ is provided/given.

* To produce an explicit description of $\text{Nul}(A)$, we solve $A\vec{x} = \vec{0}$:

- ① Find a General Solution of $A\vec{x} = \vec{0}$ in terms of any free variables
* Row-reduce $[A : \vec{0}]$ to rref & write the basic variable(s) in terms of the free variable(s).
- ② Decompose the vector giving the General Solution into a Linear Combination of vectors
* The free variable(s) are the weights.

* Important Notes: (When $\text{Nul}(A)$ contains nonzero vectors) *

- ① The spanning set produced by solving $A\vec{x} = \vec{0}$ is automatically Linearly Independent b/c the Free Variables are the weights of the spanning set. (By Def.)
- ② The number of vectors in the spanning set for $\text{Nul}(A)$ equals the number of free variables in the equation $A\vec{x} = \vec{0}$.

Example (Explicit Descriptions of $\text{Nul}(A)$):

Find a spanning set for the null space of the matrix:

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$$

Answer:

Note: Here we need to find a general solution of $A\vec{x} = \vec{b}$::

* Row-Reduce $[A : \vec{b}]$ to rref:

$$\left[\begin{array}{ccccc|c} -3 & 6 & -1 & 1 & -7 & 0 \\ 1 & -2 & 2 & 3 & -1 & 0 \\ 2 & -4 & 5 & 8 & -4 & 0 \end{array} \right] \xrightarrow{R_1 \leftrightarrow R_2} \sim \left[\begin{array}{ccccc|c} 1 & -2 & 2 & 3 & -1 & 0 \\ -3 & 6 & -1 & 1 & -7 & 0 \\ 2 & -4 & 5 & 8 & -4 & 0 \end{array} \right] \xrightarrow{\frac{3R_1 + R_2}{N.R_2}} \sim$$

$$\left[\begin{array}{ccccc|c} 1 & -2 & 2 & 3 & -1 & 0 \\ 0 & 0 & 5 & 10 & -10 & 0 \\ 2 & -4 & 5 & 8 & -4 & 0 \end{array} \right] \xrightarrow{\frac{1}{5}R_2} \sim \left[\begin{array}{ccccc|c} 1 & -2 & 2 & 3 & -1 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \\ 2 & -4 & 5 & 8 & -4 & 0 \end{array} \right] \xrightarrow{\frac{-2R_1 + R_3}{N.R_3}} \sim \left[\begin{array}{ccccc|c} 1 & -2 & 2 & 3 & -1 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \end{array} \right]$$

$$\xrightarrow{\frac{-R_2 + R_3}{N.R_3}} \sim \left[\begin{array}{ccccc|c} 1 & -2 & 2 & 3 & -1 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{\frac{-2R_2 + R_1}{N.R_1}} \sim \left[\begin{array}{ccccc|c} 1 & -2 & 0 & -1 & 3 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Echelon Form

$$\Rightarrow \left\{ \begin{array}{l} x_1 - 2x_2 - x_4 + 3x_5 = 0 \\ x_3 + 2x_4 - 2x_5 = 0 \\ 0 = 0 \end{array} \right. \quad \Leftrightarrow \quad \left\{ \begin{array}{l} x_1 = 2x_2 + x_4 - 3x_5 \\ x_2 \text{ is free} \\ x_3 = -2x_4 + 2x_5 \\ x_4 \text{ is free} \\ x_5 \text{ is free} \end{array} \right.$$

Notes:

- Basic Variables: x_1 & x_3
- Free Variables: x_2, x_4 , & x_5

Example (Explicit Description) Continued...

*Decompose the General Solution Vector into a Linear Combination of Vectors (st 'Weights' = Free Variables):

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_2 + x_4 - 3x_5 \\ x_2 \\ -2x_4 + 2x_5 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_2 \\ x_2 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} x_4 \\ 0 \\ -2x_4 \\ x_4 \\ 0 \end{bmatrix} + \begin{bmatrix} -3x_5 \\ 0 \\ 2x_5 \\ 0 \\ x_5 \end{bmatrix}$$

$$\Rightarrow \vec{x} = x_2 \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix} \quad \text{Ans.}$$

So, every Linear Combination of $\vec{u}, \vec{v}, \text{ & } \vec{w}$ is an element of $\text{Nul}(A)$ (& vice versa).

$\therefore \{\vec{u}, \vec{v}, \vec{w}\}$ is a spanning set of $\text{Nul}(A)$. Ans.

*Additional Notes/ Observations: Since $\text{Nul}(A)$ contains nonzero vectors

① The set of vectors $\{\vec{u}, \vec{v}, \vec{w}\}$ is Linearly Independent!

$\Rightarrow \vec{x} = x_2 \vec{u} + x_4 \vec{v} + x_5 \vec{w}$ has only the trivial sol., $\vec{x} = \vec{0}$, when

$$x_2 = x_4 = x_5 = 0$$

② (# of vectors in the Spanning Set) = (# of free variables in $A\vec{x} = \vec{0}$)
of $\text{Nul}(A)$

$$\boxed{3 = 3}$$

Example: Find an explicit description of $\text{Nul}(A)$ by listing vectors that span the null space:

$$A = \begin{bmatrix} 1 & -5 & -2 & 0 \\ 0 & 0 & 3 & 0 \end{bmatrix}$$

Answer:

* Row-reduce the augmented matrix $[A : \vec{0}]$ to rref to write the basic variables in terms of the free variables:

$$[A : \vec{0}] = \left[\begin{array}{cccc|c} 1 & -5 & -2 & 0 & 0 \\ 0 & 0 & 3 & 0 & 0 \end{array} \right] \xrightarrow{\frac{1}{3}R_2} \left[\begin{array}{cccc|c} 1 & -5 & -2 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{array} \right]$$

$$\xrightarrow[\substack{2R_2 \\ + R_1 \\ N.R.}]{} \left[\begin{array}{cccc|c} 1 & -5 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{array} \right] \Rightarrow \begin{cases} x_1 - 5x_2 = 0 \\ x_3 = 0 \end{cases}$$

$$\Rightarrow \begin{cases} x_1 = 5x_2 \\ x_2 \text{ is free} \\ x_3 = 0 \\ x_4 \text{ is free} \end{cases}$$

$$\therefore \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 5x_2 \\ x_2 \\ 0 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} 5 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

where $x_2 \neq x_4$ are any scalar.

∴ Every Linear Combination of \vec{u} & \vec{v} is an element of $\text{Nul}(A)$:

So, $\left\{ \begin{bmatrix} 5 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is a spanning set for $\text{Nul}(A)$

Ans.

Example: Find an explicit description of $\text{Nul}(A)$ by listing vectors that span the null space:

$$A = \begin{bmatrix} 1 & 4 & 0 & -2 & 0 \\ 0 & 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 0 & -5 \end{bmatrix}$$

Answer:

*Row-reduce the Augmented Matrix $[A : \vec{0}]$ to rref to write the basic variables in terms of the free-variables:

$$[A : \vec{0}] = \left[\begin{array}{ccccc|c} 1 & 4 & 0 & -2 & 0 & 0 \\ 0 & 0 & 1 & -3 & 0 & 0 \\ 0 & 0 & 0 & 0 & -5 & 0 \end{array} \right] \xrightarrow{-\frac{1}{5}R_3} \left[\begin{array}{ccccc|c} 1 & 4 & 0 & -2 & 0 & 0 \\ 0 & 0 & 1 & -3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right]$$

$$\Rightarrow \begin{cases} x_1 + 4x_2 - 2x_4 = 0 \\ x_3 - 3x_4 = 0 \\ x_5 = 0 \end{cases} \Leftrightarrow \begin{cases} x_1 = -4x_2 + 2x_4 \\ x_2 \text{ is free} \\ x_3 = 3x_4 \\ x_4 \text{ is free} \\ x_5 = 0 \end{cases}$$

General Solution:

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -4x_2 + 2x_4 \\ x_2 \\ 3x_4 \\ x_4 \\ 0 \end{bmatrix} = x_2 \begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ 0 \\ 3 \\ 1 \\ 0 \end{bmatrix}$$

where x_2 & x_4 are any scalar

Example Continued...

Note: Every Linear Combination of the vectors

$\begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ & $\begin{bmatrix} 2 \\ 0 \\ 3 \\ -1 \\ 0 \end{bmatrix}$ is an element of $\text{Nul}(A)$ \therefore

\therefore A Spanning Set for the $\text{Nul}(A)$:

$$\left\{ \begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 3 \\ -1 \\ 0 \end{bmatrix} \right\}$$

Answer ✓

Example: Either use an appropriate theorem to show that the given set, W , is a vector space - OR - Find a specific example to the contrary:

$$W = \left\{ \begin{bmatrix} p \\ q \\ r \\ s \end{bmatrix}, \quad \begin{array}{l} -p+q=2s \\ -2p=-s+3r \end{array} \right\}$$

Answer:

* Recall (Thm #2): The null space of an $m \times n$ matrix A is a subspace of \mathbb{R}^n . Equivalently, the set of all solutions to a system $A\vec{x} = \vec{0}$ of m -homogeneous linear eq. in n -unknowns is a subspace of \mathbb{R}^n .

* Rearrange the terms that define "W" st $A\vec{x} = 0$:

$$W = \left\{ \begin{array}{l} -p+q-2s=0 \\ -2p-3r+s=0 \end{array} \right.$$

$$\Leftrightarrow \boxed{\begin{bmatrix} -1 & 1 & 0 & -2 \\ -2 & 0 & -3 & 1 \end{bmatrix} \begin{bmatrix} p \\ q \\ r \\ s \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}} \quad A \quad \vec{x} = \vec{0}$$

"W" is the set of all solutions of the system \uparrow of Homogeneous Eq., $A\vec{x} = \vec{0}$

∴ By Theorem 2,
 $W = \text{Null}(A)$ is a subspace of \mathbb{R}^4

Note: W must be a vector space b/c a subspace IS a vector space ∵

Example: Either use an appropriate theorem to show that the given set, W , is a vector space, or find a specific example to the contrary:

$$W = \left\{ \begin{bmatrix} s - 2t \\ 3 + 3s \\ 3s + t \\ 3s \end{bmatrix} : s, t \in \mathbb{R} \right\}$$

Answer:

* Recall (Thm #2): The null space of an $m \times n$ matrix A is a subspace of \mathbb{R}^n . Equivalently, the set of all solutions to a system $A\vec{x} = \vec{0}$ of m homogeneous linear equations in n unknowns is a subspace of \mathbb{R}^n .

* Rearrange the terms that define "W" so $A\vec{x} = \vec{0}$

$$W = \left\{ \begin{bmatrix} 0 \\ 3 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} 1 \\ 3 \\ 3 \\ 3 \end{bmatrix} + t \begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -2 \\ 3 & 0 \\ 3 & 1 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} s \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \\ 0 \\ 0 \end{bmatrix} \right. \quad \rightarrow \leftarrow$$

* The zero vector $\vec{0} \in \mathbb{R}^4$ is NOT in W

∴ W is NOT a subspace of \mathbb{R}^4 & so
 W is NOT a vectorspace

Ans.

*The Column Space of a Matrix *

*Definition: The Column Space of an $m \times n$ matrix A , written as " $\text{Col}(A)$ ", is the set of all linear combinations of the columns of A .

• If $A = [\vec{a}_1, \dots, \vec{a}_n]$, then: $\text{Col}(A) = \text{Span} \{ \vec{a}_1, \dots, \vec{a}_n \}$

• In Set Notation: $\text{Col}(A) = \left\{ \vec{b} : \vec{b} = A\vec{x} \text{ for some } \vec{x} \in \mathbb{R}^n \right\}$

*Notes:

- " $A\vec{x}$ " stands for a Linear Combination of the Columns of A .
- " $A\vec{x}$ " also shows that $\text{Col}(A)$ is in the range of the Linear Transformation $\vec{x} \mapsto A\vec{x}$.

• Since $\text{Span} \{ \vec{a}_1, \dots, \vec{a}_n \}$ is a subspace (by Thm 1, sect. 4.1), the next theorem is a direct result of the Def. of $\text{Col}(A)$ - AND - the fact that the columns of A are in \mathbb{R}^m .

*Theorem 3:

The Column Space of an $m \times n$ matrix A is a subspace of \mathbb{R}^m

*Important Note/Connection w/ previous section:

The Column Space of an $m \times n$ matrix A is all of \mathbb{R}^m IFF the equation $A\vec{x} = \vec{b}$ has a solution $\forall \vec{b} \in \mathbb{R}^m$.
(*Same Equivalence Prop. seen in chapter 1 ::)

Example (Column Space): Find a matrix A st $W = \text{Col}(A)$.

$$W = \left\{ \begin{bmatrix} 6a-b \\ a+b \\ -7a \end{bmatrix} : a, b \in \mathbb{R} \right\}$$

Answer:

* First we must rewrite W as a Linear Combination: $\text{Span} \{ \vec{a}_1, \dots, \vec{a}_n \}$

* Iow: Decompose W :

$$W = \left\{ \begin{bmatrix} 6a \\ a \\ -7a \end{bmatrix} + \begin{bmatrix} -b \\ b \\ 0 \end{bmatrix} = a \begin{bmatrix} 6 \\ 1 \\ -7 \end{bmatrix} + b \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} : a, b \in \mathbb{R} \right\}$$

$$\text{So, } W = \text{Span} \left\{ \begin{bmatrix} 6 \\ 1 \\ -7 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \right\}$$

* Next, use the vectors of the spanning set to define the columns of matrix A :

$$A = [\vec{a}_1 \ \vec{a}_2] = \begin{bmatrix} 6 & -1 \\ 1 & 1 \\ -7 & 0 \end{bmatrix}$$

* Therefore: (By Def.)

$$\text{Since } A = \begin{bmatrix} 6 & -1 \\ 1 & 1 \\ -7 & 0 \end{bmatrix}, \text{ then } W = \text{Col}(A) = \text{Span} \left\{ \begin{bmatrix} 6 & -1 \\ 1 & 1 \\ -7 & 0 \end{bmatrix} \right\}$$

Ans.

Example: Find A st the given set is $\text{Col}(A)$:

$$\left\{ \begin{bmatrix} 2r+3s+t \\ -r-2s-3t \\ -2r+s+2t \\ -s+3t \end{bmatrix} : r,s,t \in \mathbb{R} \right\}$$

Answer:

* Write as a set of Linear Combinations:

$$\left\{ r \begin{bmatrix} 2 \\ -1 \\ -2 \\ 0 \end{bmatrix} + s \begin{bmatrix} 3 \\ -2 \\ 1 \\ -1 \end{bmatrix} + t \begin{bmatrix} 1 \\ -3 \\ 2 \\ 3 \end{bmatrix} : r,s,t \in \mathbb{R} \right\} = \text{Span} \left\{ \begin{bmatrix} 2 \\ -1 \\ -2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -2 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \\ 2 \\ 3 \end{bmatrix} \right\}$$

* Use the vectors in the spanning set as the columns of A:

$$A = \boxed{\begin{bmatrix} 2 & 3 & 1 \\ -1 & -2 & -3 \\ -2 & 1 & 2 \\ 0 & -1 & 3 \end{bmatrix}}$$

Ans ✓

The Contrast Btw Nul(A) & Col(A)

Nul(A):

vs.

Col(A):

① Nul(A) is a subspace of \mathbb{R}^n .

② Nul(A) is implicitly defined;
*IOW: we are only given a condition ($A\vec{x} = \vec{0}$) that vectors in Nul(A) must satisfy.

③ It takes time to find vectors in Nul(A):

\Rightarrow row-reduce: $[A : \vec{0}]$

④ NO obvious relation btw Nul(A) & the entries in A.

⑤ A typical vector \vec{v} in Nul(A) has the prop: $A\vec{v} = \vec{0}$

⑥ Given a specific vector \vec{v} , it is easy to tell if $\vec{v} \in \text{Nul}(A)$
 \Rightarrow Compute $A\vec{v}$

⑦ $\text{Nul}(A) = \{\vec{0}\}$ IFF $A\vec{x} = \vec{0}$ has ONLY the Trivial Solution.

⑧ $\text{Nul}(A) = \{\vec{0}\}$ IFF the Linear Transformation $\vec{x} \mapsto A\vec{x}$ is one-to-one

① Col(A) is a subspace of \mathbb{R}^m .

② Col(A) is explicitly defined.
*IOW: We are told how to build vectors in Col(A).

③ It is easy/quick to find vectors in Col(A)
 \Rightarrow Columns of A are displayed; others can be formed from them.

④ Obvious relation btw Col(A) & entries in A
 \Rightarrow Each Column of A is in Col(A)

⑤ A typical vector \vec{v} in Col(A) has the prop: $A\vec{x} = \vec{v}$ is consistent

⑥ Given a specific vector \vec{v} , it may take time to tell if $\vec{v} \in \text{Col}(A)$
 \Rightarrow Row-Reduce $[A : \vec{v}]$

⑦ $\text{Col}(A) = \mathbb{R}^m$ IFF $A\vec{x} = \vec{b}$ has a solution $\forall \vec{b} \in \mathbb{R}^m$.

⑧ $\text{Col}(A) = \mathbb{R}^m$ IFF the Linear Transformation $\vec{x} \mapsto A\vec{x}$ maps \mathbb{R}^n onto \mathbb{R}^m .

Example (Contrast #1): Let $A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}$

(a) IF the Column Space of A is a subspace of \mathbb{R}^K , what is K ?

(b) IF the Null Space of A is a subspace of \mathbb{R}^K , what is K ?

Answer:

* Part (a): \$ Col(A)\$ is a subspace of \mathbb{R}^K , find K :

• Recall (Theorem³): The Column Space of an $m \times n$ matrix A is a subspace of $\underline{\mathbb{R}^m}$

• Given: 3×4 matrix $A \Rightarrow \begin{cases} \cdot 3\text{-Rows (Eq.)} \\ \cdot 4\text{-Columns (Unknowns)} \end{cases}$

* The Columns of A each have 3 entries.

∴ Since A has $m=3$ rows, then the Column Space of A is a subspace of $\underline{\mathbb{R}^3} \Rightarrow K=3$

* Part (b): \$ Nul(A)\$ is a subspace of \mathbb{R}^K , find K :

• Recall (Th^m #2): The Null Space of an $m \times n$ matrix A is a subspace of $\underline{\mathbb{R}^n}$.

* The vector \vec{x} or $A\vec{x}$ must have 4 entries.

∴ Since A has $n=4$ columns, then the Null Space of A is a subspace of $\underline{\mathbb{R}^4} \Rightarrow K=4$

Example (Contrast #2): Find a nonzero vector in $\text{Col}(A)$ and find a nonzero vector in $\text{Nul}(A)$:

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}$$

Answer:

* Find a nonzero vector in $\text{Col}(A)$:

Note: Each column of A is a vector in $\text{Col}(A)$::
 ⇒ Any one of the 4 columns will suffice.

∴ $\vec{a}_4 = \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix}$ is a nonzero vector s.t. $\vec{a}_4 \in \text{Col}(A)$

Ans ✓

* Find a nonzero vector in $\text{Nul}(A)$:

Note: Here we must row-reduce $[A : \vec{0}]$ to find a nonzero vector in $\text{Nul}(A)$.

$$[A : \vec{0}] = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix} \xrightarrow[\text{N.R.}_2]{\frac{R_1 + R_2}{N.R.}} \begin{bmatrix} 2 & 4 & -2 & 1 \\ 0 & -1 & 5 & 4 \\ 3 & 7 & -8 & 6 \end{bmatrix} \xrightarrow{\begin{array}{l} \frac{1}{2}R_1 \\ -R_2 \end{array}} \begin{bmatrix} 1 & 2 & -1 & \frac{1}{2} \\ 0 & 1 & -5 & -4 \\ 3 & 7 & -8 & 6 \end{bmatrix}$$

$$\xrightarrow[\text{N.R.}_3]{\begin{array}{l} -3R_1 \\ +R_3 \end{array}} \begin{bmatrix} 1 & 2 & -1 & \frac{1}{2} \\ 0 & 1 & -5 & -4 \\ 0 & 1 & -5 & \frac{17}{2} \end{bmatrix} \xrightarrow[\text{N.R.}_3]{\begin{array}{l} -R_2 \\ +R_3 \end{array}} \begin{bmatrix} 1 & 2 & -1 & \frac{1}{2} \\ 0 & 1 & -5 & -4 \\ 0 & 0 & 0 & \frac{17}{2} \end{bmatrix} \xrightarrow[\text{N.R.}_1]{\begin{array}{l} -2R_2 \\ +R_1 \end{array}} \begin{bmatrix} 1 & 0 & 9 & \frac{17}{2} \\ 0 & 1 & -5 & -4 \\ 0 & 0 & 0 & \frac{17}{2} \end{bmatrix}$$

Example (Contrast #2) Continued...

$$\left[\begin{array}{cccc} 1 & 0 & 9 & \frac{17}{2} \\ 0 & 1 & -5 & -4 \\ 0 & 0 & 0 & \frac{17}{2} \end{array} \right] \xrightarrow{\substack{-R_3 \\ +R_1 \\ N.R.}} \sim \left[\begin{array}{cccc} 1 & 0 & 9 & 0 \\ 0 & 1 & -5 & -4 \\ 0 & 0 & 0 & \frac{17}{2} \end{array} \right] \xrightarrow{\frac{2}{17}R_3} \sim \left[\begin{array}{cccc} 1 & 0 & 9 & 0 \\ 0 & 1 & -5 & -4 \\ 0 & 0 & 0 & 1 \end{array} \right]$$

$$\xrightarrow{\substack{4R_3 \\ +R_2 \\ N.R_2}} \sim \left[\begin{array}{cccc} 1 & 0 & 9 & 0 \\ 0 & 1 & -5 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] \Leftrightarrow \left\{ \begin{array}{l} x_1 + 9x_3 = 0 \\ x_2 - 5x_3 = 0 \\ x_4 = 0 \end{array} \right. \Rightarrow \boxed{\begin{array}{l} x_1 = -9x_3 \\ x_2 = 5x_3 \\ x_3 \text{ is free} \\ x_4 = 0 \end{array}}$$

A nonzero vector in $\text{Nul}(A)$:

$$\therefore \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -9x_3 \\ 5x_3 \\ x_3 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} -9 \\ 5 \\ 1 \\ 0 \end{bmatrix}$$

where x_3 is any scalar

Ans.

Example (Contrasts³): Let

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}, \quad \vec{u} = \begin{bmatrix} 3 \\ -2 \\ -1 \\ 0 \end{bmatrix}, \quad \text{and} \quad \vec{v} = \begin{bmatrix} 3 \\ -1 \\ 3 \end{bmatrix}$$

- (a) Determine if \vec{u} is in $\text{Nul}(A)$. Could \vec{u} be in $\text{Gl}(A)$?
(b) Determine if \vec{v} is in $\text{Col}(A)$. Could \vec{v} be in $\text{Nul}(A)$?

Answer:

* Part(a): To determine if $\vec{u} \in \text{Nul}(A)$, compute $A\vec{u}$.

$$\begin{aligned} A\vec{u} &= \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix} \begin{bmatrix} 3 \\ -2 \\ -1 \\ 0 \end{bmatrix} = 3 \begin{bmatrix} 2 \\ -2 \\ 3 \end{bmatrix} - 2 \begin{bmatrix} 4 \\ -5 \\ 7 \end{bmatrix} - \begin{bmatrix} -2 \\ 7 \\ -8 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix} \\ &= \begin{bmatrix} 6 & -8 + 2 + 0 \\ -6 + 10 - 7 + 0 \\ 9 - 14 + 8 + 0 \end{bmatrix} = \begin{bmatrix} 0 \\ -3 \\ 3 \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \therefore \boxed{\vec{u} \text{ is NOT in } \text{Nul}(A)} \end{aligned}$$

* Since \vec{u} is NOT a solution of $A\vec{x} = \vec{0}$, $\vec{u} \notin \text{Nul}(A)$.

* Since $\text{Gl}(A)$ is a subspace of \mathbb{R}^3 & $\vec{u} \in \mathbb{R}^4$
 $\Rightarrow \vec{u} \notin \text{Gl}(A)$.

Similarly:

* Since $\text{Nul}(A)$ is a subspace of \mathbb{R}^4 & $\vec{v} \in \mathbb{R}^3$
 $\Rightarrow \vec{v} \notin \text{Nul}(A)$.



Example (Contrasts³) continued... *Note: Stopping once you reach echelon form is sufficient :)

*Part (b): To Determine if $\vec{v} \in \text{Col}(A)$, row-reduce $[A; \vec{v}]$

$$\left[\begin{array}{cccc|c} 2 & 4 & -2 & 1 & 3 \\ -2 & -5 & 7 & 3 & -1 \\ 3 & 7 & -8 & 6 & 3 \end{array} \right] \xrightarrow{\begin{array}{l} R_1 + R_2 \\ N \cdot R_2 \end{array}} \sim \left[\begin{array}{cccc|c} 2 & 4 & -2 & 1 & 3 \\ 0 & -1 & 5 & 4 & 2 \\ 3 & 7 & -8 & 6 & 3 \end{array} \right] \xrightarrow{\frac{1}{2}R_1} \sim$$

$$\left[\begin{array}{cccc|c} 1 & 2 & -1 & y_2 & 3/2 \\ 0 & -1 & 5 & 4 & 2 \\ 3 & 7 & -8 & 6 & 3 \end{array} \right] \xrightarrow{\begin{array}{l} -3R_1 \\ N \cdot R_3 \\ R_2 + R_3 \end{array}} \sim \left[\begin{array}{cccc|c} 1 & 2 & -1 & y_2 & 3/2 \\ 0 & -1 & 5 & 4 & 2 \\ 0 & 1 & -5 & 9/2 & -3/2 \end{array} \right] \xrightarrow{\frac{R_2}{N \cdot R_3}} \sim$$

$$\left[\begin{array}{cccc|c} 1 & 2 & -1 & y_2 & 3/2 \\ 0 & -1 & 5 & 4 & 2 \\ 0 & 0 & 0 & 17/2 & 1/2 \end{array} \right] \xrightarrow{\begin{array}{l} 2R_2 \\ R_1 + R_2 \\ N \cdot R_1 \end{array}} \sim \left[\begin{array}{cccc|c} 1 & 0 & 9 & 17/2 & 1/y_2 \\ 0 & -1 & 5 & 4 & 2 \\ 0 & 0 & 0 & 17/2 & 1/y_2 \end{array} \right] \xrightarrow{-R_2}$$

*We can stop here ↑ echelon-form shows us system is consistent.

$$\left[\begin{array}{cccc|c} 1 & 0 & 9 & 17/2 & 1/y_2 \\ 0 & 1 & -5 & -4 & -2 \\ 0 & 0 & 0 & 17/2 & 1/y_2 \end{array} \right] \xrightarrow{\begin{array}{l} -R_3 \\ R_1 + R_3 \\ N \cdot R_1 \end{array}} \sim \left[\begin{array}{cccc|c} 1 & 0 & 9 & 0 & 5 \\ 0 & 1 & -5 & -4 & -2 \\ 0 & 0 & 0 & 17/2 & 1/y_2 \end{array} \right] \xrightarrow{\frac{2}{17}R_3}$$

$$\left[\begin{array}{cccc|c} 1 & 0 & 9 & 0 & 5 \\ 0 & 1 & -5 & -4 & -2 \\ 0 & 0 & 0 & 1 & 1/y_{17} \end{array} \right] \xrightarrow{\begin{array}{l} 4R_3 \\ R_2 + R_3 \\ N \cdot R_2 \end{array}} \sim \left[\begin{array}{cccc|c} 1 & 0 & 9 & 0 & 5 \\ 0 & 1 & -5 & 0 & -30/17 \\ 0 & 0 & 0 & 1 & 1/y_2 \end{array} \right]$$

rref

Ans: Since $A\vec{x} = \vec{v}$ is consistent (@ least one solution \exists)
 $\Rightarrow \vec{v} \in \text{Col}(A)$.

Example: Find the following for the provided matrix:

$$A = \begin{bmatrix} 0 & 9 \\ 5 & -3 \\ -7 & -8 \\ -7 & -5 \end{bmatrix}$$

(a) Find K st $\text{Nul}(A)$ is a subspace for \mathbb{R}^K .

(b) Find K st $\text{Col}(A)$ is a subspace for \mathbb{R}^K .

Answer:

* Recall: For an $m \times n$ matrix A :

- $\text{Nul}(A)$ is a subspace of \mathbb{R}^n
- $\text{Col}(A)$ is a subspace of \mathbb{R}^m

* Given: $m \times n = 4 \times 2$ matrix A

(a) A vector \vec{x} st $A\vec{x}$ is defined must have 2 entries:

$\therefore \text{Nul}(A)$ is a subspace of $\mathbb{R}^2 \Rightarrow \boxed{K=2}$

Ans.

(b) The columns of A each have 4 entries:

$\therefore \text{Col}(A)$ is a subspace of $\mathbb{R}^4 \Rightarrow \boxed{K=4}$

Ans.

Example: Find the following for the provided matrix

$$A = \begin{bmatrix} 5 & -2 & 9 & 6 \\ 4 & 6 & 6 & 0 \\ -5 & 1 & -1 & -6 \\ -8 & 2 & 4 & 5 \\ 6 & -2 & 5 & -5 \end{bmatrix}$$

(a) Find K st $\text{Nul}(A)$ is a subspace of \mathbb{R}^K .

(b) Find K st $\text{Col}(A)$ is a subspace of \mathbb{R}^K .

Answer:

* Recall: For some $m \times n$ matrix A

- $\text{Nul}(A)$ is a subspace of \mathbb{R}^n .
(# of entries in \vec{x} st $A\vec{x} = \vec{0}$)
- $\text{Col}(A)$ is a subspace of \mathbb{R}^m .
(# of entries per column)

* Given: $m \times n = 5 \times 4$ matrix A

(a) A vector \vec{x} (st $A\vec{x}$ is defined) must have 4 entries:

∴ $\text{Nul}(A)$ is a subspace of \mathbb{R}^4
 $\Rightarrow K = 4$

(b) The columns of A each have 5 entries:

∴ $\text{Col}(A)$ is a subspace of \mathbb{R}^5
 $\rightarrow K = 5$

Example: For the matrix A below, find the following:

$$A = \begin{bmatrix} 6 & 8 \\ 3 & 4 \\ -12 & -16 \\ 9 & 12 \end{bmatrix}$$

(a) Find a nonzero vector for $\text{Nul}(A)$.

(b) Find a nonzero vector for $\text{Col}(A)$.

Answer:

Recall: To find a nonzero vector in:

$\text{Nul}(A) \rightarrow$ row-reduce $[A : \vec{0}]$
 $\text{Col}(A) \rightarrow$ choose any column-vector

* Part(a): Find a nonzero vector in $\text{Nul}(A)$:

$$[A : \vec{0}] = \left[\begin{array}{cc|c} 6 & 8 & 0 \\ 3 & 4 & 0 \\ -12 & -16 & 0 \\ 9 & 12 & 0 \end{array} \right] \xrightarrow{\frac{1}{2}R_1} \sim \left[\begin{array}{cc|c} 3 & 4 & 0 \\ 3 & 4 & 0 \\ 3 & 4 & 0 \\ 3 & 4 & 0 \end{array} \right] \xrightarrow{-\frac{1}{4}R_3} \sim \left[\begin{array}{cc|c} 3 & 4 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Whoa ::
 $\frac{1}{2}R_1$, $\frac{-R_3}{N.R_3}$, $\frac{-R_1}{N.R_1}$, $\frac{+R_2}{N.R_2}$, $\frac{+R_3}{N.R_3}$, $\frac{+R_4}{N.R_4}$

$$\left[\begin{array}{cc|c} 3 & 4 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 4/3 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] \Rightarrow$$

\therefore IF \vec{x} satisfies $A\vec{x} = \vec{0}$, then:

$$\begin{cases} x_1 = -\frac{4}{3}x_2 \\ x_2 \text{ is free} \end{cases} \Rightarrow \vec{x} = x_2 \begin{bmatrix} -\frac{4}{3} \\ 1 \end{bmatrix}$$

where $x_2 \in \mathbb{R}$

* Part(b): Find a nonzero vector in $\text{Col}(A)$:

$$A = [\vec{a}_1 \ \vec{a}_2] \Rightarrow \vec{a}_1, \vec{a}_2 \in \text{Col}(A)$$

$$\therefore \boxed{\begin{bmatrix} 6 \\ 3 \\ -12 \\ 9 \end{bmatrix} \in \text{Col}(A)}$$

Ans.

Kernel & Range of a Linear Transformation

Note: Subspaces of vector spaces other than \mathbb{R}^n are often described in terms of a Linear Transformation instead of a matrix.

*Definition: A Linear Transformation, T , from a vector space V into a vector space W is a rule that assigns to each vector $\vec{x} \in V$ a unique vector $T(\vec{x}) \in W$ s.t:

$$(i) T(\vec{u} + \vec{v}) = T(\vec{u}) + T(\vec{v}), \quad \forall \vec{u}, \vec{v} \in V.$$

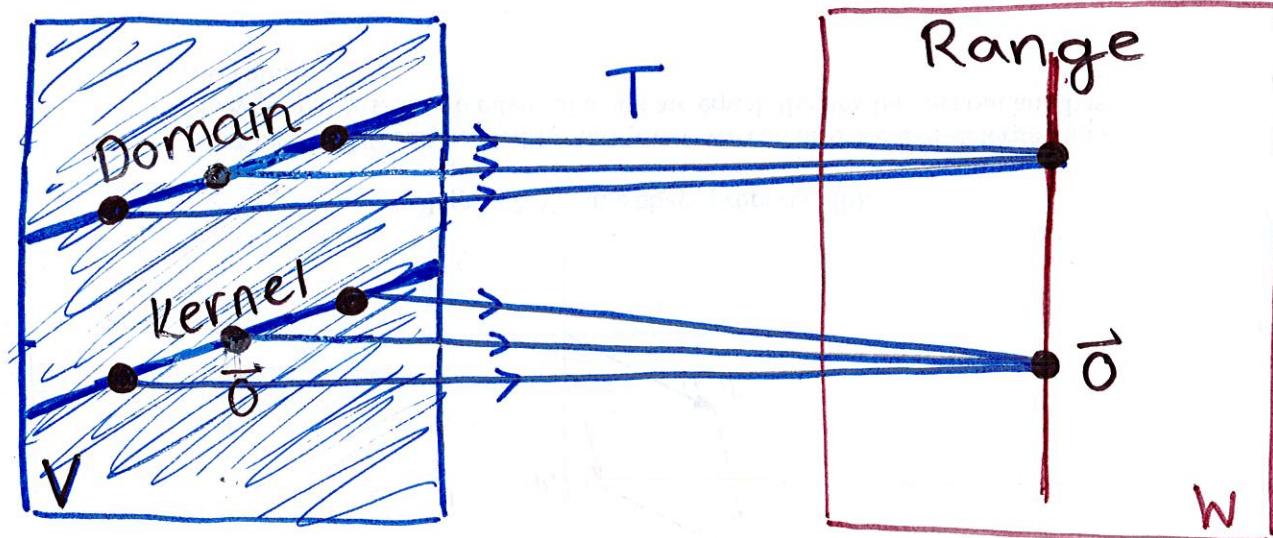
- AND -

$$(ii) T(c\vec{u}) = cT(\vec{u}), \quad \forall \vec{u} \in V \text{ & } \forall \text{ scalars } c.$$

- The Kernel (or Null Space) of such a T is the set of all $\vec{u} \in V$ s.t $T(\vec{u}) = \vec{0}$ (the zero vector in W).
- The range of T is the set of all vectors in W of the form $T(\vec{x})$ for some $\vec{x} \in V$.

Note:
* IF T happens to arise as a matrix transformation (i.e. $T(\vec{x}) = A\vec{x}$), then the kernel & the range of T are just the Null Space & Column Space of A ::

Subspaces Associated with a Linear Transformation



*The Kernel is a
Subspace of V .

*The range is
a Subspace of W

*Proofs on next page ::

Property: Let $T: V \rightarrow W$ be a Linear Transformation from a vector space V into a vector space W . Prove that the range of T is a subspace of W .

*Hint: Typical elements in the range have the form $T(\vec{x}) \& T(\vec{w})$ for some $\vec{x}, \vec{w} \in V$.

Proof:

Let $T: V \rightarrow W$ be a Linear Transformation from a vector space V into a vector space W .

Then by Definition: T is a rule that assigns each $\vec{x} \in V$ to a unique vector $T(\vec{x}) \in W$ ST: $\begin{cases} \cdot T(\vec{u} + \vec{v}) = T(\vec{u}) + T(\vec{v}) \\ \cdot T(c\vec{u}) = cT(\vec{u}) \end{cases}$ $\forall \vec{u}, \vec{v} \in V \&$ scalars c .

*Goal: Show that the range of T is a subspace of W

i) Show that the $\vec{0}_W \in W$ is in W ($\vec{0}_W \in W$):

Let $\vec{x} = \vec{0} \in V \Rightarrow$ Then $T(\vec{0}) = \vec{0}_W$

\Rightarrow \therefore The $\vec{0}_W$ of W is in the Range of T .

*Let $T(\vec{x}) \& T(\vec{w})$ be typical elements in the range of T .

ii) Show that the Range of T is closed under addition:

Since $T(\vec{x}) + T(\vec{w}) = T(\vec{x} + \vec{w})$ by definition

\Rightarrow $T(\vec{x}) + T(\vec{w})$ is in the Range of T

- AND -

The Range of T is closed under addition.

Proof. Continued...

iii) Show that the Range of T is closed under scalar multiplication:

* Let c be any scalar.

* Since $cT(\vec{x}) = T(c\vec{x})$ By Definition,

$\Rightarrow cT(\vec{x})$ is in the Range of T

- AND -

The Range of T is closed under scalar mult.



Therefore:

Since all 3 conditions are met, the Range of T is a subspace of W.



Ex/Property: Let V & W be vector spaces.

Let $T: V \rightarrow W$ be a Linear Transformation.

Given a subspace U of V , let $T(U)$ denote the set of all images of the form $T(\vec{x})$, where $\vec{x} \in U$.

*Show that $T(U)$ is a subspace of W *

Proof:

*Recall: A subspace of a Vector Space V is a subset H st

i) The zero vector of V is in H : $\vec{0}_v \in H$

ii) H is closed under addition: $\forall \vec{u}, \vec{v} \in H, \vec{u} + \vec{v} \in H$

iii) H is closed under scalar multiplication: $\forall \vec{u} \in H, c\vec{u} \in H$
+ scalars c

Prop 1:

• Since U is a subspace of V , then by definition:

$$\vec{0}_v \in U.$$

• Since T is a Linear Transformation, then by definition:

$$T(\vec{0}_v) = \vec{0}_w. \Rightarrow \boxed{\text{So } \vec{0}_w \in T(U)} * \text{The zero vector of } W \text{ is in } T(U) \checkmark$$

Prop 2

• Let $T(\vec{x})$ & $T(\vec{y})$ be typical elements in $T(U)$:

$$\Rightarrow \text{Then } \vec{x}, \vec{y} \in U$$

*Since U is a subspace of V : $\vec{x} + \vec{y} \in U$

*Since T is a Linear Transformation: $T(\vec{x}) + T(\vec{y}) = T(\vec{x} + \vec{y})$

$\therefore \boxed{T(\vec{x}) + T(\vec{y}) \in T(U) \text{ & so } T(U) \text{ is closed}} \checkmark$
under addition

Proof. Continued...

Prop³:

- Let $T(\vec{x})$ be a Typical Element in $T(U)$ & let c be any scalar:

\Rightarrow Then $\vec{x} \in U$.

* Since U is a subspace of V : $c\vec{u} \in U$

* Since T is a Linear Transformation: $cT(\vec{u}) = T(c\vec{u})$

$\therefore cT(\vec{u}) \in T(U) \text{ & so } T(U) \text{ is closed}$

under scalar multiplication.

✓

* Therefore: Since all 3 conditions are met,

$T(U)$ is a subspace of W .