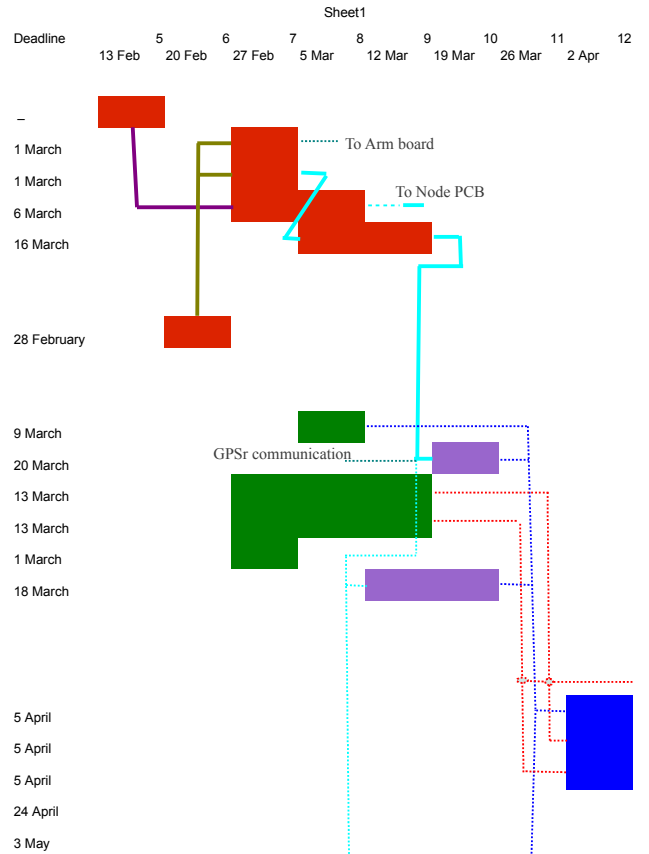


Sheet1		
Tasks	Validation	Assignee
<b>Communication Primitives</b>		
I2C Communication	Milestone 1	Via, Justin
GPSr UART communication	travelling over the UART. Then using a bus master device, request position data over I2C	Via
PIC to MiWi communication	Successful read & write to MiWi registers (e.g. set Tx power, then read to verify setting)	Via
Long Distance I2C Communication	Successful reliable communications along 75'+ of cabling	Mitch
MiWi <> MiWi communication	Sending predetermined bytestrings over MiWi with confirmed reception	Via, Mitch
<b>PIC Software</b>		
Adapt existing 2680 code to 45J10	Using a bus sniffer, verify I2C read/write operations are successful to all 45J10 devices	Via
<b>Arm Board Software</b>		
Test Position Data to Web Server	the webpage (even if the 'changing' data is just hardcoded at this time)	Andrew, Justin
GPS Data to ARM board	GPS position is displayed on ARM	Via, Justin
Filesystem	Successful text file creation on a computer-readable filesystem	Via
Fancy Display	The fancy display looks nice, and has spots for pertinent information to go	Andrew
Web Server	Custom content is displayed on the webpage	Andrew
Position Calculation on ARM	Position calculator output is fed to ARM display and other interfaces	Mitch, Justin
<b>Integration</b>		
Actual Position Data to Web Server	GPSr position data, and calculated position is displayed on the webpage	ALL the people
Position Data to Filesystem	GPSr position data, and calculated position is written to a flat text file	ALL the people
Position Data to Display	GPSr position data, and calculated position is displayed on the 'fancy display'	ALL the people
Final Project Demonstration	Project completed, demonstrated	ALL the people
Final Report	Report completed, submitted.	ALL the people

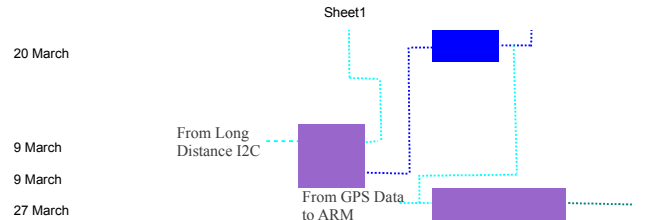
Page 1

Sheet1		
Board Assembly	It works	ALL the people
<b>Design Dependencies</b>		
Position Calculation Algorithm	calculator provides some reasonable position output	Mitch, Andrew
Node PCB design	It exists	Andrew
Calibration Sequence	ARM Display or Web page displays GPS position of all three receiver nodes	Andrew

Page 2



Page 3



Page 4

