	Sheet1					Sheet1
Tasks	Validation	Assignee	Deadline	5 13 Feb 20 Feb	6 7 27 Feb 5 Ma	8 9 ar 12 Mar 19
Communication Primitives						
I2C Communication	Milestone 1 travelling over the UART. Then using a bus maste	Via, Justin	-			
GPSr UART communication	device, request position data over I2C	Via	1 March			··· To Arm board
PIC to MiWi communication	Successful read & write to MiWi registers (e.g. set Tx power, then read to verify setting) Successful reliable communications along 75'+ of	Via	1 March	-	- 7	To Node
Long Distance I2C Communi	cation cabling	Mitch	6 March		/	
MiWi <> MiWi communicatio	Sending predetermined bytestrings over MiWi with confirmed reception	Via, Mitch	16 March		4	
				- 1		
PIC Software						
Adapt existing 2680 code to	Using a bus sniffer, verify I2C read/write operations 45J10 are successful to all 45J10 devices	Via	28 February			

Adapt existing 2680 code to 45J10	Using a bus sniffer, verify I2C read/write operations are successful to all 45J10 devices	Via
Arm Board Software		
Test Position Data to Web Server	the webpage (even if the 'changing' data is just hardcoded at this time)	Andrew, Justin
	· · · · · · · · · · · · · · · · · · ·	Via,
GPS Data to ARM board	GPS position is displayed on ARM Successful text file creation on a computer-	Justin
Filesystem	readable filesystem	Via
Fancy Display	The fancy display looks nice, and has spots for pertinent information to go	Andrew
Web Server	Custom content is displayed on the webpage	Andrew
Position Calculation on ARM	Position calculator output is fed to ARM display and other interfaces	Mitch, Justin

Integration		
Actual Position Data to Web Server	GPSr position data, and calculated position is displayed on the webpage	ALL the people
Position Data to Filesystem	GPSr position data, and calculated position is written to a flat text file	ALL the people
Position Data to Display	GPSr position data, and calculated position is displayed on the 'fancy display'	ALL the people
Final Project Demonstration	Project completed, demonstrated	ALL the people
Final Report	Report completed, submitted.	ALL the people

Board Assembly

Node PCB design Calibration Sequence

Design Dependencies

Position Calculation Algorithm

Page 1

Sheet1	ALL the			Sheet1
It works	people	20 March		
				
calculator provides some reasonable position output	Mitch	9 March	From Long Distance I2C	
•	Mitch,		Distance 12C	
It exists ARM Display or Web page displays GPS position	Andrew	9 March		From GPS Data
of all three receiever nodes	Andrew	27 March		to ARM

9 March

20 March 13 March 13 March 1 March 18 March

5 April 5 April 5 April 24 April

3 May

8 9 10 11 12 12 Mar 19 Mar 26 Mar 2 Apr

To Node PCB

GPSr communication

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9 Apr 16 Apr 23 Apr 30 Apr 7 May



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Sheet1