Lectures 6 and 7 Linear Transformation and Rank-Nullity Theorem

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A 'Linear Transformation' is nothing but a map between vector spaces.

$$T: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$$

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$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto c \begin{pmatrix} x \\ y \end{pmatrix}$$

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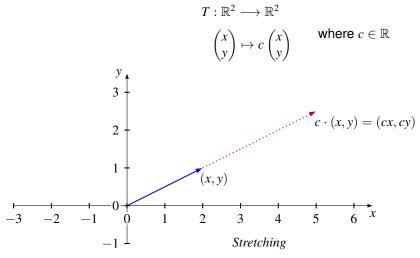
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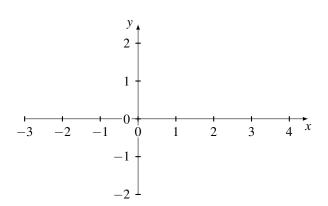
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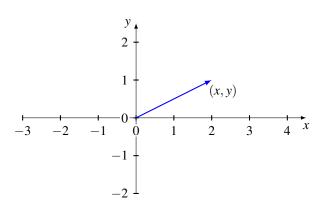
$$(x, y)$$

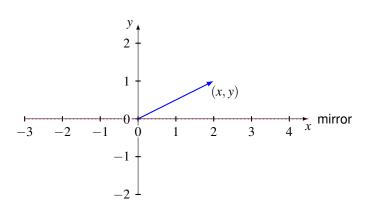
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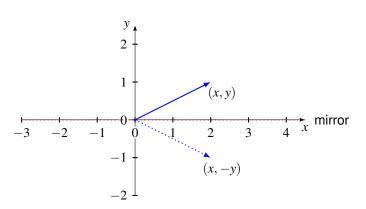
$$-3 \quad -2 \quad -1$$

$$Stretching$$

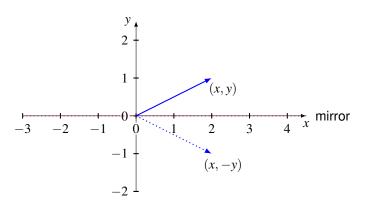


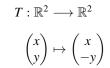


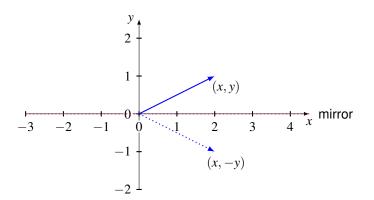




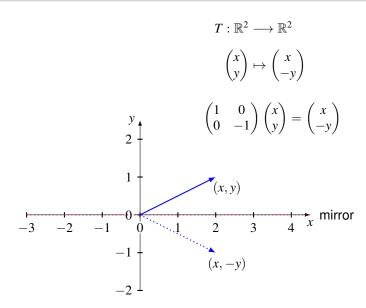
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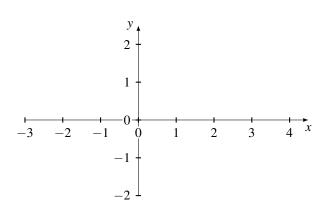


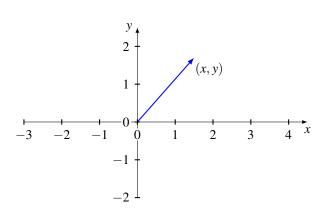


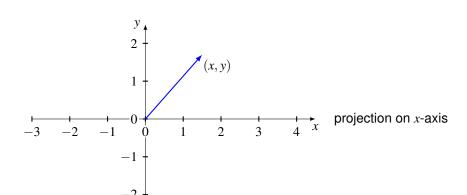


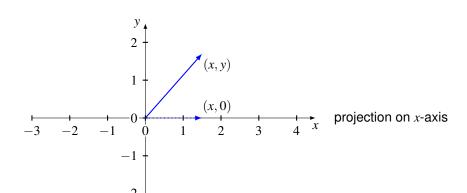
Reflection with \overline{x} -axis as mirror



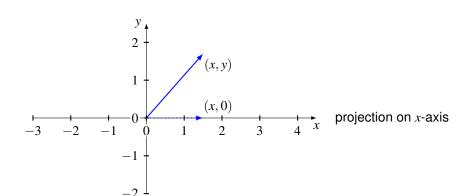




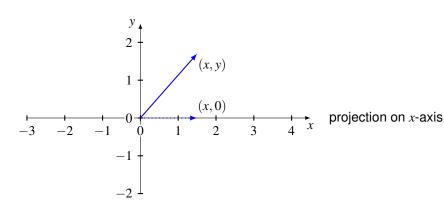


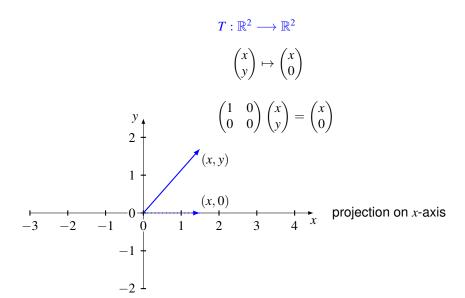


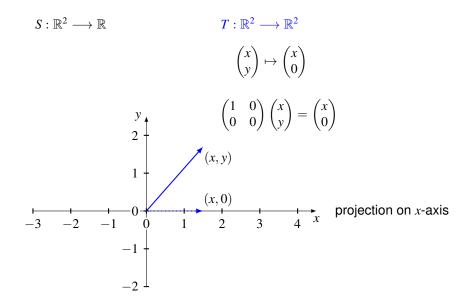
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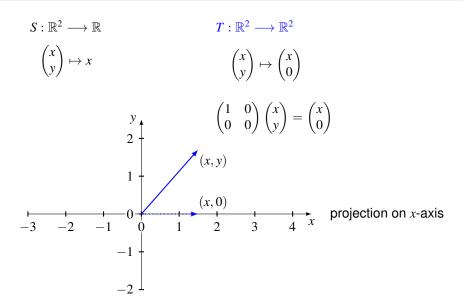


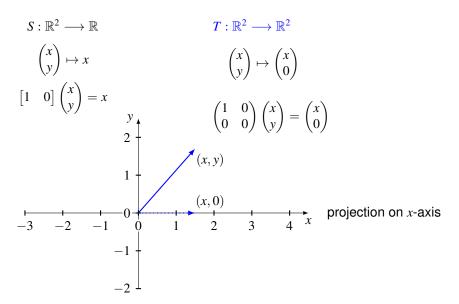
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$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x \\ 0 \end{pmatrix}$$











$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \cos \theta - y \sin \theta \\ x \sin \theta + y \cos \theta \end{pmatrix}.$$

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Counterclockwise rotation by an angle θ

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where $C_1, \ldots, C_n \in \mathbb{R}^m$.



Matrix representation of a linear map $T: \mathbb{R}^n \to \mathbb{R}^m$

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Remark. A linear map $T : \mathbb{R}^n \to \mathbb{R}^m$ is uniquely determined by its action on $\{e_1, \dots, e_n\}$, i.e., by $T(e_i)$ for all $1 \le i \le n$.



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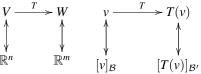
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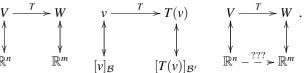
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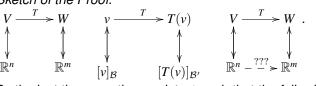
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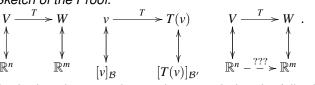
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Lin. Independence: Let $b_1T(v_1) + \cdots + b_rT(v_r) = 0$.

This implies that $b_1v_1 + \cdots + b_rv_r \in \text{Null}(T)$.

So $b_1v_1 + \cdots + b_rv_r = a_1u_1 + \cdots + a_nu_n$ for some $a_i \in \mathbb{R}$.

Thus $b_1v_1 + \cdots + b_rv_r - a_1u_1 - \cdots - a_nu_n = 0$.



Theorem

Let $T: V \to W$ be a linear transformation, where $\dim(V)$ is finite. Then $\operatorname{rank}(T) + \operatorname{nullity}(T) = \dim(V)$.

Proof. Start with a basis $\{u_1, \ldots, u_n\}$ of Null(T). Extend this to a basis $\{u_1, \ldots, u_n, v_1, \ldots, v_r\}$ of V. It is enough to prove that

$$\{T(v_1),\ldots,T(v_r)\}$$
 is a basis of $Image(T)$.

Spanning: Any vector of Image(T) looks like T(v) for some $v \in V$.

Write
$$v = c_1 u_1 + \dots + c_n u_n + d_1 v_1 + \dots + d_r v_r$$
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Therefore $b_1 = \cdots = b_r = 0$.



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Examples: Row and column spaces

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As a consequence of Rank-Nullity Theorem, we will prove that for an arbitrary matrix D, row rank(D) = column rank(D).



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So it is enough to show that

$$row rank(A) = n - nullity(A)$$
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Proof. Note that *A* and *B* have the same order (say, $m \times n$). Let $R_1, \ldots, R_m \in \mathbb{R}^n$ be the row vectors of *A*.

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We will study some examples to observe this inequality. But I will leave it as an exercise to verify this inequality in the general situation.

Consider a row-reduced echelon matrix
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Theorem

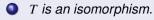
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Proof. We already proved $(1) \Leftrightarrow (2) \Leftrightarrow (3) \Leftrightarrow (4)$.

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(4) \Leftrightarrow (5) and (6) \Leftrightarrow (7): Since $\dim(\mathbb{R}^n) = n$, any collection of n vectors in \mathbb{R}^n is linearly independent if and only if it spans \mathbb{R}^n .



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- (4) \Leftrightarrow (6): It follows from the above equivalences "(4) \Leftrightarrow (5) and (6) \Leftrightarrow
- (7)" and the fact that column $rank(A) = row \ rank(A)$.



Thank You!