# MA1140: Lecture 8 Eigenvalues and Eigenvectors

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January 28, 2020

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  - An eigenvalue can be positive, negative or zero.

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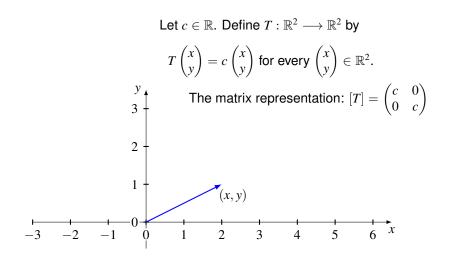
Let 
$$c \in \mathbb{R}$$
. Define  $T : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$  by

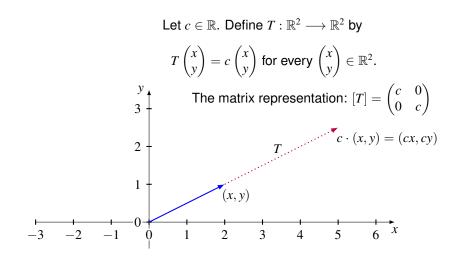
$$T \begin{pmatrix} x \\ y \end{pmatrix} = c \begin{pmatrix} x \\ y \end{pmatrix}$$
 for every  $\begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2$ .

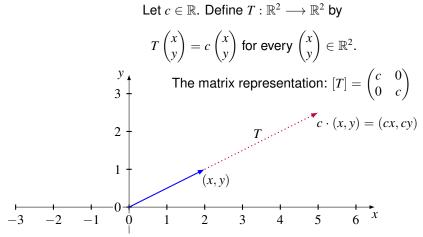
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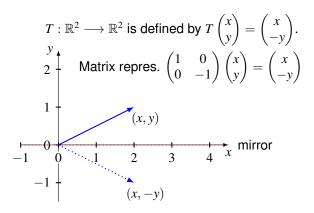
The matrix representation: 
$$[T] = \begin{pmatrix} c & 0 \\ 0 & c \end{pmatrix}$$

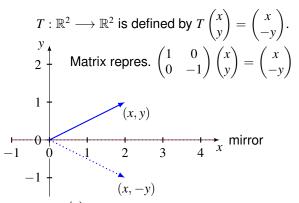






Every  $v \neq 0 \in \mathbb{R}^2$  is an eigenvector of T with the eigenvalue c.





For  $x \neq 0$ ,  $\begin{pmatrix} x \\ 0 \end{pmatrix}$  is an eigenvector of T with eigenvalue 1.

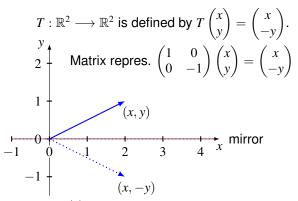
$$T: \mathbb{R}^2 \longrightarrow \mathbb{R}^2 \text{ is defined by } T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ -y \end{pmatrix}.$$

$$2 \qquad \text{Matrix repres. } \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ -y \end{pmatrix}.$$

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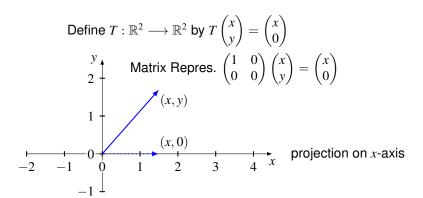
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These are ALL the eigenvectors of T. (Verify it!)



Define 
$$T: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$$
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These are ALL the eigenvectors of T. (Verify it!)

# Example 4: A may not have eigenvalues and eigenvectors over a particular field

• Consider the matrix  $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$  over  $\mathbb{R}$ .

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$$\Rightarrow \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

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- Consider the matrix  $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$  over  $\mathbb{R}$ .
- Does A have eigenvalues and eigenvectors over  $\mathbb{R}$ ?
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• So A does not have eigenvalues and eigenvectors over  $\mathbb{R}$ .

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• Conclusion: The matrix A has eigenvalues and eigenvectors over  $\mathbb{C}$ , but not over  $\mathbb{R}$ .

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# Characteristic polynomial of a matrix

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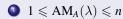
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Let *A* be an  $n \times n$  matrix over  $\mathbb{C}$ . For every eigenvalue  $\lambda$  of *A*, we have

- $0 \quad 1 \leqslant AM_A(\lambda) \leqslant n \quad \text{ and } \quad 1 \leqslant GM_A(\lambda) \leqslant n.$
- ②  $\sum_{i=1}^{r} AM_A(\lambda_i) = n$ , the sum varies over all the eigenvalues of A.

### Proof.

- Note that  $\deg(p_A(x)) = n$  and  $p_A(x) = (x \lambda)^{\mathrm{AM}_A(\lambda)} f(x)$  for some f. Since  $\mathrm{GM}_A(\lambda) = \dim (\mathrm{Null}(A - \lambda I_n))$ , we have  $1 \leqslant \mathrm{GM}_A(\lambda) \leqslant n$ .
- ② It follows from  $p_A(x) = \prod_{i=1}^r (x \lambda_i)^{\text{AM}_A(\lambda_i)}$  and  $\deg(p_A(x)) = n$ .
- We will skip it.



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- The algebraic multiplicities of both  $\lambda_1$  and  $\lambda_2$  are 1.

## How to compute eigenvalues and eigenvectors

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 Recall that in order to solve a linear system, you may apply elementary row operations to make it into a system with row reduced echelon coefficient matrix.

### Definition

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Some statements (without proof) about importance of similarity of matrices:

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  - Jordan canonical forms of A and B are same. (???)

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The set of eigenvectors helps us to test whether a matrix is diagonalizable or not.

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Hence left multiply by P from the left side.

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Note that  $\det(xI_n - A) = \det(xI_n - B) = (x - \lambda_1) \cdots (x - \lambda_n)$ . By induction on n, one can verify that

$$(B-\lambda_1I_n)(B-\lambda_2I_n)\cdots(B-\lambda_nI_n)=0.$$

Hence, multiplying P on left and  $P^{-1}$  on right, we get

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#### Remark

It can be observed from the proof that if A is diagonalizable, then A satisfies a polynomial having distinct roots.

### Applications of Eigenvalues and Eigenvectors

Some real life applications of the use of eigenvalues and eigenvectors in science, engineering and computer science can be found here:

```
https://www.intmath.com/matrices-determinants/8-applications-eigenvalues-eigenvectors.php
```

## Thank You!