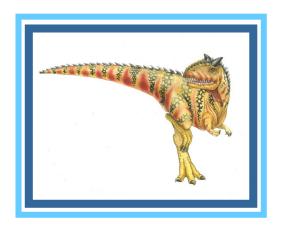
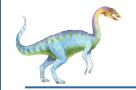
Chapter 5a: CPU Scheduling





Outline

- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms





Objectives

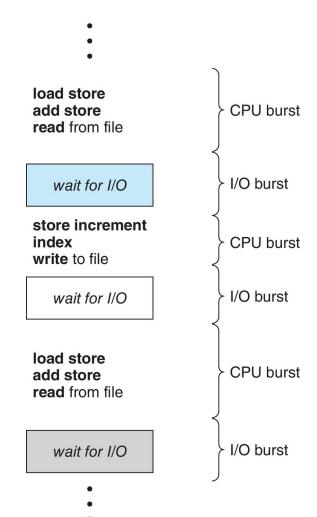
- Describe various CPU scheduling algorithms
- Assess CPU scheduling algorithms based on scheduling criteria
- Explain the issues related to multiprocessor and multicore scheduling
- Describe various real-time scheduling algorithms
- Describe the scheduling algorithms used in the Windows, Linux, and Solaris operating systems
- Apply modeling and simulations to evaluate CPU scheduling algorithms



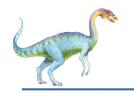


Basic Concepts

- Maximum CPU utilization obtained with multiprogramming
- CPU-I/O Burst Cycle Process execution consists of a cycle of CPU execution and I/O wait
- CPU burst followed by I/O burst
- CPU burst distribution is of main concern



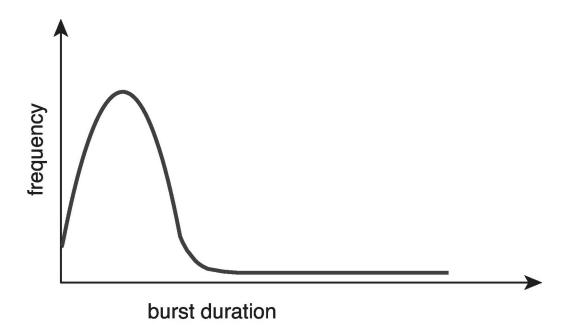




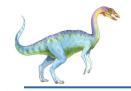
Histogram of CPU-burst Times

Large number of short bursts

Small number of longer bursts







CPU Scheduler

- The CPU scheduler selects from among the processes in ready queue, and allocates a CPU core to one of them
 - Queue may be ordered in various ways
- CPU scheduling decisions may take place when a process:
 - 1. Switches from running to waiting state
 - 2. Switches from running to ready state
 - 3. Switches from waiting to ready
 - 4. Terminates
- For situations 1 and 4, there is no choice in terms of scheduling. A new process (if one exists in the ready queue) must be selected for execution.
- For situations 2 and 3, however, there is a choice.





Preemptive and Nonpreemptive Scheduling

- When scheduling takes place only under circumstances 1 and 4, the scheduling scheme is nonpreemptive.
- Otherwise, it is preemptive.
- Under Nonpreemptive scheduling, once the CPU has been allocated to a process, the process keeps the CPU until it releases it either by terminating or by switching to the waiting state.
- Virtually all modern operating systems including Windows, MacOS, Linux, and UNIX use preemptive scheduling algorithms.

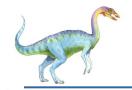




Preemptive Scheduling and Race Conditions

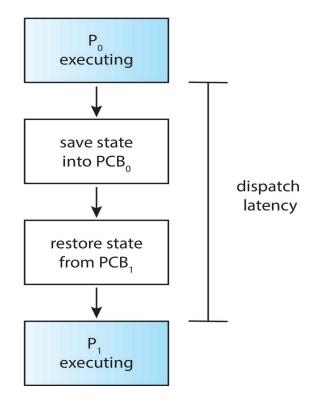
- Preemptive scheduling can result in race conditions when data are shared among several processes.
- Consider the case of two processes that share data. While one process is updating the data, it is preempted so that the second process can run. The second process then tries to read the data, which are in an inconsistent state.
- This issue will be explored in detail in Chapter 6.





Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the CPU scheduler; this involves:
 - Switching context
 - Switching to user mode
 - Jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running







Scheduling Criteria

- CPU utilization keep the CPU as busy as possible
- Throughput # of processes that complete their execution per time unit
- Turnaround time amount of time to execute a particular process
- Waiting time amount of time a process has been waiting in the ready queue
- Response time amount of time it takes from when a request was submitted until the first response is produced.





Scheduling Algorithm Optimization Criteria

- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time





First-Come, First-Served (FCFS) Scheduling

Process Burst Time

- P₁ 24
- P_2 3
- P_3 3
- Suppose that the processes arrive in the order: P_1 , P_2 , P_3 The Gantt Chart for the schedule is:



- Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
- Average waiting time: (0 + 24 + 27)/3 = 17





FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order:

$$P_2$$
, P_3 , P_1

The Gantt chart for the schedule is:



- Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
- Average waiting time: (6 + 0 + 3)/3 = 3
- Much better than previous case
- Convoy effect short process behind long process
 - Consider one CPU-bound and many I/O-bound processes





Shortest-Job-First (SJF) Scheduling

- Associate with each process the length of its next CPU burst
 - Use these lengths to schedule the process with the shortest time
- SJF is optimal gives minimum average waiting time for a given set of processes
 - The difficulty is knowing the length of the next CPU request
 - Could ask the user





Shortest-Job-First (SJF) Scheduling

- Associate with each process the length of its next CPU burst
 - Use these lengths to schedule the process with the shortest time
- SJF is optimal gives minimum average waiting time for a given set of processes
- Preemptive version called shortest-remaining-time-first
- How do we determine the length of the next CPU burst?
 - Could ask the user
 - Estimate





Example of SJF

Process

Burst Time

- P_1 6 8 8
- P_{4} 3
- SJF scheduling chart



• Average waiting time = (3 + 16 + 9 + 0) / 4 = 7





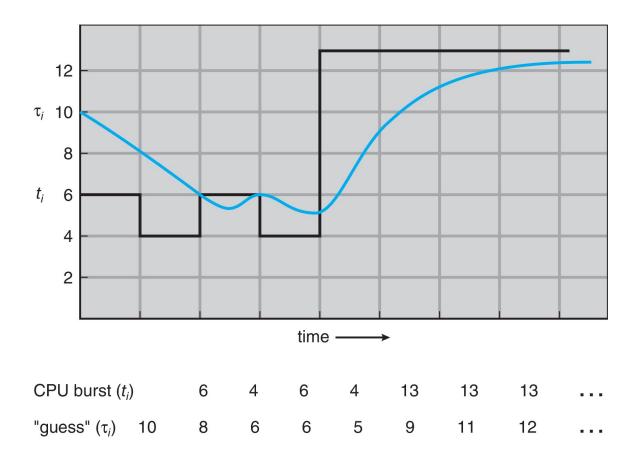
Determining Length of Next CPU Burst

- Can only estimate the length should be similar to the previous one
 - Then pick process with shortest predicted next CPU burst
- Can be done by using the length of previous CPU bursts, using exponential averaging
 - 1. t_n =actual length of n^{th} CPU burst
 - 2. τ_{n+1} =predicted value for the next CPU burst
 - 3. α , $0 \le \alpha \le 1$
 - 4. Define:
- Commonly, α set $\tau_{n+1} = \alpha t_n + (1 \alpha)\tau_n$.

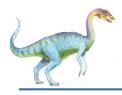




Prediction of the Length of the Next CPU Burst







Examples of Exponential Averaging

- =0
 - $_{n+1} = _{n}$
 - Recent history does not count
- **=** =1
 - $_{\text{n+1}} = t_{\text{n}}$
 - Only the actual last CPU burst counts
- If we expand the formula, we get:

$$t_{n+1} = t_n + (1 -) t_{n-1} + \dots$$

$$+ (1 -)^j t_{n-j} + \dots$$

$$+ (1 -)^{n+1} 0$$

 Since both and (1 -) are less than or equal to 1, each successive term has less weight than its predecessor



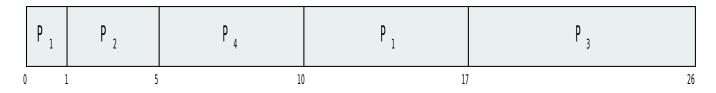


Example of Shortest-remaining-time-first

 Now we add the concepts of varying arrival times and preemption to the analysis

<u>Process</u>			<u>Arrival Time</u>	Burst Time
$P_{\scriptscriptstyle 1}$	0	8		
P_2	1	4		
P_3	2	9		
P_{4}	3	5		

Preemptive SJF Gantt Chart



• Average waiting time = [(10-1)+(1-1)+(17-2)+(5-3)]/4 = 26/4 = 6.5





Round Robin (RR)

- Each process gets a small unit of CPU time (time quantum q), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are n processes in the ready queue and the time quantum is q, then each process gets 1/n of the CPU time in chunks of at most q time units at once. No process waits more than (n-1)q time units.
- Timer interrupts every quantum to schedule next process
- Performance
 - q large FIFO
 - q small q must be large with respect to context switch, otherwise overhead is too high

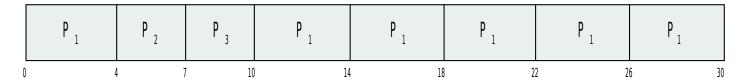




Example of RR with Time Quantum = 4

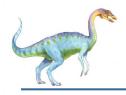
Process Burst Time

- P_{1} 24
- P_{2} 3
- P_3 3
- The Gantt chart is:

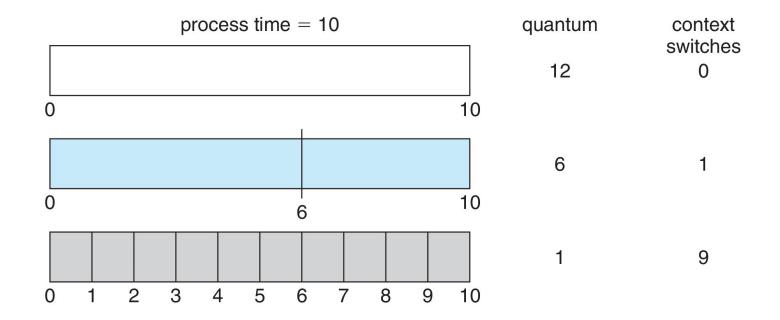


- Typically, higher average turnaround than SJF, but better response
- q should be large compared to context switch time
 - q usually 10 milliseconds to 100 milliseconds,
 - Context switch < 10 microseconds





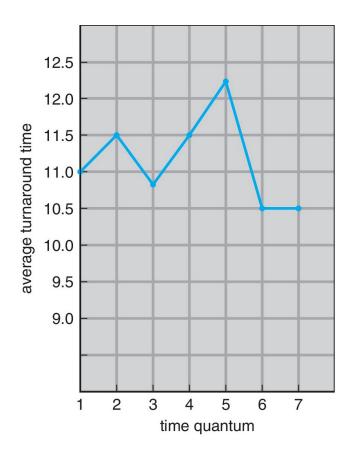
Time Quantum and Context Switch Time







Turnaround Time Varies With The Time Quantum



process	time
P ₁	6
P_2	3
P_3	1
P_4	7

80% of CPU bursts should be shorter than q



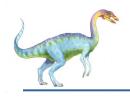


Priority Scheduling

- A priority number (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer highest priority)
 - Preemptive
 - Nonpreemptive
- SJF is priority scheduling where priority is the inverse of predicted next
 CPU burst time
- Problem Starvation low priority processes may never execute
- Solution Aging as time progresses increase the priority of the process



Silberschatz, Galvin and Gagne ©2018



Example of Priority Scheduling

P	rocess

Burst Time Priority

P₁ 10 3

 P_{2} 1 1

 P_3 2 4

 P_4 1 5

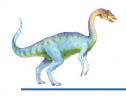
 P_{5} 5 2

Priority scheduling Gantt Chart

P_2	P_{5}	P_{1}	P ₃	P_{4}
0	1	6 16	5 1	8 19

Average waiting time = 8.2





Priority Scheduling w/ Round-Robin

	<u>Pr</u>	<u>ocess</u>	Burst Time	<u>Priority</u>
$P_{\scriptscriptstyle 1}$	4	3		
P_2	5	2		
P_3	8	2		
P_4	7	1		
$P_{\scriptscriptstyle 5}$	3	3		

- Run the process with the highest priority. Processes with the same priority run round-robin
- Gantt Chart with time quantum = 2

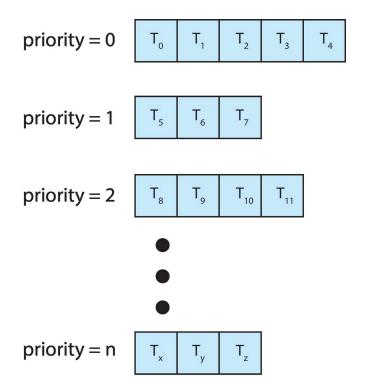
	P ₄	P ₂	P ₃	P ₂	P ₃	P ₂	P ₃	P ₁	P ₅	P ₁	P ₅
0		7 9) 11	1 1	3 1.	5 16	5 2	0 22	2 2	4 2	6 27





Multilevel Queue

- With priority scheduling, have separate queues for each priority.
- Schedule the process in the highest-priority queue!

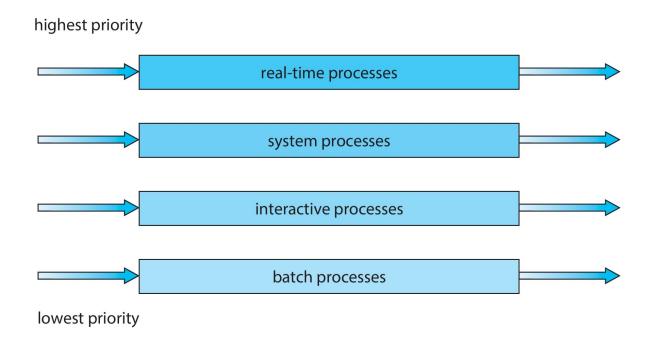






Multilevel Queue

Prioritization based upon process type







Multilevel Feedback Queue

- A process can move between the various queues.
- Multilevel-feedback-queue scheduler defined by the following parameters:
 - Number of queues
 - Scheduling algorithms for each queue
 - Method used to determine when to upgrade a process
 - Method used to determine when to demote a process
 - Method used to determine which queue a process will enter when that process needs service
- Aging can be implemented using multilevel feedback queue





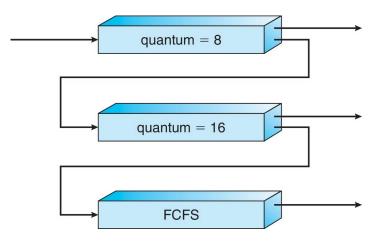
Example of Multilevel Feedback Queue

Three queues:

- Q_0 RR with time quantum 8 milliseconds
- Q_1 RR time quantum 16 milliseconds
- Q₂ FCFS

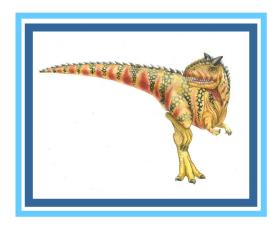
Scheduling

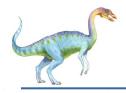
- A new process enters queue Q₀ which is served in RR
 - When it gains CPU, the process receives 8 milliseconds
 - If it does not finish in 8 milliseconds, the process is moved to queue Q_1
- At Q₁ job is again served in RR and receives 16 additional milliseconds
 - If it still does not complete, it is preempted and moved to queue Q_2





End of Chapter 5a





Example of Multilevel Feedback Queue

Three queues:

- Q_0 RR with time quantum 8 milliseconds
- Q_1 RR time quantum 16 milliseconds
- Q₂ FCFS

Scheduling

- A new process enters queue Q_0 which is served RR
 - When it gains CPU, the process receives 8 milliseconds
 - If it does not finish in 8 milliseconds, it is moved to gueue Q_1
- At Q₁ the process is again served RR and receives 16 additional milliseconds
 - If it still does not complete, it is preempted and moved to queue Q_2

