

Hierarchy

All

Visuals

Collisions

left\_hand\_camera

left\_hand\_camera\_axis

left\_hand\_range

left\_hand\_accelerometer

FT\_bottom\_plate\_left

Visuals

Collisions

FT\_left

Visuals

unnamed

Collisions

FT\_Top\_Plate\_left

Visuals

Collisions

left\_gripper\_base

Visuals

unnamed

Collisions

left\_gripper

Lgripper\_l\_finger

Lgripper\_r\_finger

left\_upper\_forearm\_visual

left\_upper\_elbow\_visual

pedestal

agentCam

agentCam2

Scene

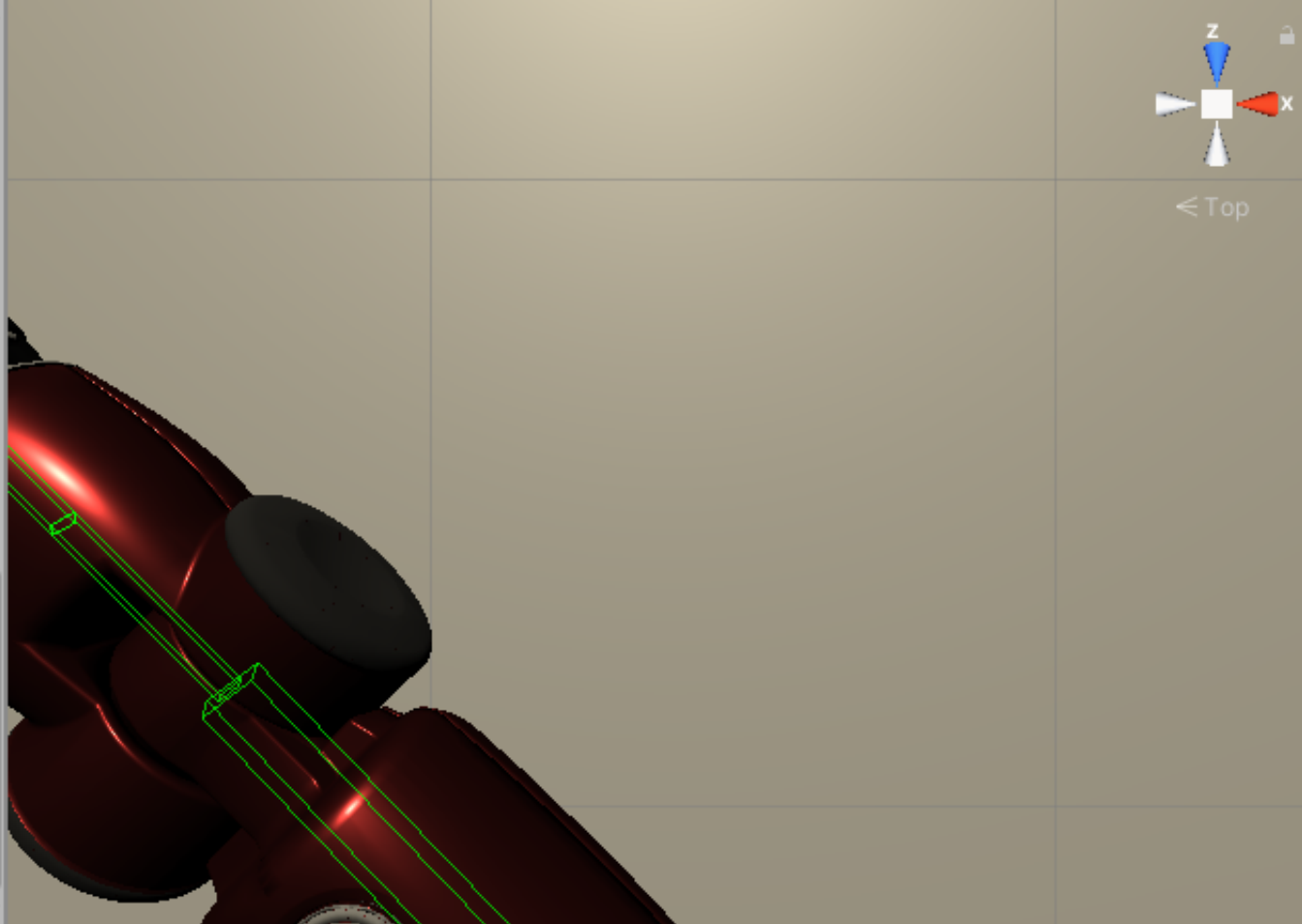
Shaded

2D

0

Gizmos

All



Inspector

left\_gripper

Static

Tag Untagged

Layer Default

Transform

Position

X -1.117409e-01

Y 0.0950008

Z -1.604491e-01

Rotation

X 0

Y 0

Z 0

Scale

X 1.000003

Y 0.9999947

Z 1.000003

Fast IK Fabric (Script)

Script

FastIKFabric

Chain Length

11

Target

TargetLeft (Transform)

Pole

PoleLeft (Transform)

Solver Parameters

Iterations

10

Delta

0.001

Snap Back Strength

1

Robot Control Left (Script)

Script

RobotControlLeft

Guide

TargetLeft (Transform)

Urdf Link (Script)

Is Base Link

Child Joint Type

Fixed

Add child link (with joint)

Rigidbody

Mass

0.0001

Drag

0

Angular Drag

0.05

Use Gravity

Is Kinematic

Interpolate

None

Collision Detection

Discrete

Center Of Mass

X 0

Y 0

Z 0

Inertia Tensor

X 1

Y 1

Z 1

Project

Console

11

Favorites

All Materi

All Model

All Prefab

Assets

Materials

ML-Agen

Prefav

Robot

RosSharp

Scenes

Scripts

Agents

Assets > Scripts > AgentsScripts

#

#

#

#

#

AgentRobo...

AreaRobot

FoldControl

LeftFoldC...

RightFoldC...