



Inspector

☒ **right_gripper** ☐ Static

Tag: Untagged Layer: Default

Transform

Position	X	-1.492956e-1	Y	0.1327012	Z	-8.041247e-
Rotation	X	0	Y	0	Z	0
Scale	X	1.000002	Y	0.9999955	Z	1.000002

Fast IK Fabric (Script)

Script: FastIKFabric

Chain Length: 11

Target: TargetRight (Transform)

Pole: PoleRight (Transform)

Solver Parameters

Iterations: 10

Delta: 0.001

Snap Back Strength: 1

Robot Control Right (Script)

Script: RobotControlRight

Guide: TargetRight (Transform)

Urdf Link (Script)

Is Base Link: ☐

Child Joint Type: Fixed

Add child link (with joint)

Rigidbody

Mass: 0.0001

Drag: 0

Angular Drag: 0.05

Use Gravity: ☒

Is Kinematic: ☒

Interpolate: None

Collision Detection: Discrete

Center Of Mass: X 0 Y 0 Z 0

Inertia Tensor: X 1 Y 1 Z 1

Project

Console

Assets > Scripts > AgentsScripts

AgentRobo... AreaRobot FoldControl LeftFoldC... RightFoldC...

Favorites

- All Materi
- All Model
- All Prefab

Assets

- Materials
- ML-Agen
- Prefav
- Robot
- RosSharp
- Scenes
- Scripts
- Agents