# Numerical Implementation of Fourier Galerkin Method

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### 1 Introduction

The Fourier-Galerkin Method is to solve the differential equations with periodic boundary conditions. We project the solutions from infinite dimensional space into finite dimensional space  $\hat{B_N} = span\{e^{inx}|n \leq N/2\}$ .

The numerical solution  $u_h = \sum_{n=-N/2}^{N/2} \hat{u}_n e^{inx_h}$ , where  $x_j = \frac{2\pi j}{N}$ ,  $j = 0, 1, \dots, N-1$  are the nodes of the domain and  $\hat{u}_n$  are the Fourier coefficients given by

$$\hat{u}_n = \frac{1}{2\pi} \int_0^{2\pi} u(x)e^{-inx} dx \tag{1}$$

In discrete cases, it can be rewritten by

$$\hat{u}_n = \frac{1}{N} \sum_{j=0}^{N-1} u(x_j) e^{-inx_j}$$
(2)

For the differential equations

$$u_t = \mathcal{L}u + \mathcal{N}u \tag{3}$$

the numerical problem using semi-implicit scheme can be rewritten by

$$\frac{u^{n+1} - u^n}{\delta t} = \mathcal{L}u^{n+1} + \mathcal{N}u^n. \tag{4}$$

Then we calculate the problem in spectral space

$$\frac{\hat{u}_k^{n+1} - \hat{u}_k^n}{\delta t} = f(k)\hat{u}_k^{n+1} + (\hat{\mathcal{N}}u^n)_k.$$
 (5)

The matrix is diagonal.

# 2 Matching with Matlab FFT

In matlab the ifft function is

$$X(k) = \frac{1}{2N+1} \sum_{j=1}^{2N+1} x(j)e^{\frac{2\pi i(j-1)(k-1)}{2N+1}}, \quad k = 1:2N+1.$$
 (6)

For matching

$$\hat{u}_n = \frac{1}{2N+1} \sum_{i=0}^{2N} u_j e^{\frac{2\pi i j n}{2N+1}}, \quad n = -N : N,$$
(7)

we shift k = n + N + 1, thus

$$\hat{u}_n = \frac{1}{2N+1} \sum_{j=1}^{2N+1} u_{j-1} e^{\frac{2\pi i(j-1)(k-N-1)}{2N+1}} = \frac{1}{2N+1} \sum_{j=1}^{2N+1} u_{j-1} e^{\frac{-2N\pi i(j-1)}{2N+1}} e^{\frac{2\pi i(j-1)(k-1)}{2N+1}}$$
(8)

So we can obtain  $\hat{u} = ifft(\{u_{j-1}e^{\frac{-2N\pi i(j-1)}{2N+1}}\}_j).$ 

Similarly, we can obtain  $u = \{e^{\frac{-2N\pi i(j-1)}{2N+1}}\}_j \cdot *fft(\hat{u}).$ 

## 3 Numerical Examples

#### 3.1 Diffusion Equation

The equation is

$$-u_{xx} = f. (9)$$

Using Fourier galerkin method with periodic boundary condition, the equation can rewritten as

$$-\sum_{n=-\frac{N}{2}}^{\frac{N}{2}} \hat{u}_n(e^{inx})_{xx} = \sum_{n=-\frac{N}{2}}^{\frac{N}{2}} \hat{f}_n e^{inx};$$

$$i.e. \qquad n^2 \hat{u}_n = \hat{f}_n, \qquad n = -\frac{N}{2} : \frac{N}{2}.$$
(10)

Notice that when n=0, we have  $\hat{f}_0=\frac{1}{N}\sum_j f(x_j)=0$  which is called compatibility condition. And

the numerical solution is  $u_h = \sum_{n=-\frac{N}{2}, n \neq 0}^{\frac{N}{2}} \hat{u}_n e^{inx} + \hat{u}_0$ , where  $\hat{u}_0 = \frac{1}{N} \sum_j u(x_j)$  called stability condition should be given.

Firstly we calculate  $u = \sin 2x$  to test.  $u = \sin 2x$  shall be exact for any N since it is a base of  $B_N$ . When N = 10, the residual is less than 1e - 15. This test can show whether your codes have grammar error.

Secondly we calculate  $u = \frac{3}{5-4cosx}$  and observe how the residual changes with N changing.

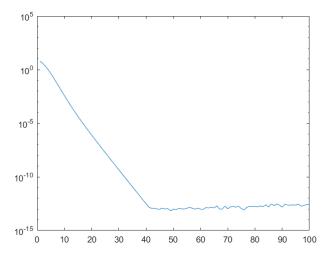


Figure 1: The x-axis is  $\frac{N-1}{2}$  where N is the number of nodes and the y-axis is  $\ln(error)$  where the error is  $||u-u_h||_{L^{\infty}}$ .

In figure (1) it follows  $||u - u_h|| = e^{-N}$  unit the error attains machine epsilon.

After these two tests finished, your program is much possible to be right and we shall use the method to solve problem now.

### 3.2 Allen Cahn Equation

The equation is

$$u_t = \epsilon u_{xx} + u - u^3. \tag{11}$$

Using Fourier galerkin method and semi-implicit scheme, the iteration takes the form as

$$\frac{\hat{u}_k^{n+1} - \hat{u}_k^n}{\delta t} = -\epsilon k^2 \hat{u}_k^{n+1} - (u^n - (u^n)^3)_k.$$
 (12)

where  $\delta t$  depends on  $\epsilon$  and h.

Here is a numerical experiment. Set  $\Omega = [0, 2\pi], N = 40, \delta = \frac{1}{N^2}, T = 1, \epsilon = 0.01$  and u(x, 0) = sin(x). Figure (2) shows the numerical solution.

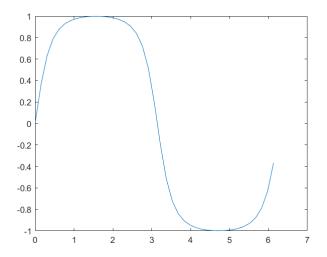


Figure 2: The Allen-Cahn equation's solution when T=1 and  $\Omega=[0,2\pi], N=40, \delta=\frac{1}{N^2}, \epsilon=0.01, u(x,0)=sin(x).$