

复旦大学力学与工程科学系

2008~2009学年第二学期期末考试试卷答案

A卷 B卷

课程名称: 数学分析 (II)

课程代码: MATH120009.09

开课院系: 力学与工程科学系

考试形式: 开卷/闭卷/课程论文

姓名: _____ 学号: _____ 专业: _____

题号	1/(1)	1/(2)	1/(3)	1/(4)	2	3/(1)	3/(2)	4/(1)	4/(2)
得分									
题号	5/(1)	5/(2)	6/(1)	6/(2)	7/(1)	7/(2)	8/(1)	8/(2)	总分
得分									

Problem 1 (向量值映照基本概念) 现有向量值映照:

$$\Phi(x, y) : \mathbb{R}^2 \ni (x, y) \mapsto \Phi(x, y) \triangleq \begin{bmatrix} f(x, y) \\ g(x, y) \end{bmatrix} \in \mathbb{R}^2,$$

其中:

$$f(x, y) \triangleq \begin{cases} xy \cdot \frac{x^2-y^2}{x^2+y^2} & (x, y) \neq (0, 0) \\ 0 & (x, y) = (0, 0) \end{cases}; \quad g(x, y) \triangleq x \cdot \sin y \quad \forall (x, y) \in \mathbb{R}^2$$

1. (10%) 计算: $\lim_{(x,y) \rightarrow (0,0)} \Phi(x, y)$
2. (10%) 计算: $\frac{\partial f}{\partial x}(0, 0), \frac{\partial f}{\partial y}(0, 0)$
3. (05%) 研究: $\Phi(x, y) \in \mathbb{R}^2$ 在 $(0, 0)$ 点的可微性 (要求明确写出该点的Jacobian矩阵)
4. (05%) 计算:
$$\frac{\partial \Phi}{\partial \mathbf{e}} \triangleq \lim_{\lambda \rightarrow 0 \in \mathbb{R}} \frac{\Phi(\mathbf{0} + \lambda \cdot \mathbf{e}) - \Phi(\mathbf{0})}{\lambda}$$

此处: $\mathbf{e} = (1, 1)/\sqrt{2} \in \mathbb{R}^2, \Phi(\mathbf{0}) = \Phi(0, 0)$ 。

1/(1):

$$\lim_{(x,y) \rightarrow 0 \in \mathbb{R}^2} f(x, y) = \lim_{(x,y) \rightarrow 0 \in \mathbb{R}^2} xy \frac{x^2 - y^2}{x^2 + y^2} = 0$$

$$\lim_{(x,y) \rightarrow 0 \in \mathbb{R}^2} g(x, y) = \lim_{(x,y) \rightarrow 0 \in \mathbb{R}^2} x \sin y = 0$$

$$\text{故 } \lim_{(x,y) \rightarrow 0 \in \mathbb{R}^2} \Phi(x, y) = \lim_{(x,y) \rightarrow 0 \in \mathbb{R}^2} \begin{bmatrix} f(x, y) \\ g(x, y) \end{bmatrix} = 0 \in \mathbb{R}^2$$

1/(2):

$$\frac{\partial f}{\partial x}(0, 0) \triangleq \lim_{\Delta x \rightarrow 0} \frac{f(0 + \Delta x, 0) - f(0, 0)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{0 - 0}{\Delta x} = 0$$

$$\frac{\partial f}{\partial y}(0, 0) \triangleq \lim_{\Delta y \rightarrow 0} \frac{f(0, 0 + \Delta y) - f(0, 0)}{\Delta y} = \lim_{\Delta y \rightarrow 0} \frac{0 - 0}{\Delta y} = 0$$

1/(3): 对于 $\Phi(x, y) \in \mathbb{R}^2$ 在 $(0, 0)$ 点的可微性，考虑 $f(x, y), g(x, y)$ 在 $(0, 0)$ 点的可微性
显然 $g(x, y) \triangleq x \sin y$ 在 $(0, 0)$ 点可微

$$\frac{\left| f(x, y) - f(0, 0) - \left[\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right] (0, 0) \begin{bmatrix} x \\ y \end{bmatrix} \right|}{\sqrt{x^2 + y^2}} = \frac{\left| xy \frac{x^2 - y^2}{x^2 + y^2} \right|}{\sqrt{x^2 + y^2}} \leq \frac{|x|}{\sqrt{x^2 + y^2}} |y| \leq \sqrt{x^2 + y^2}$$

故 $f(x, y)$ 在 $(0, 0)$ 点可微，由此 $\Phi(x, y)$ 在 $(0, 0)$ 点可微。另外 $\frac{\partial g}{\partial x}(0, 0) = 0, \frac{\partial g}{\partial y}(0, 0) = 0$

故

$$D\Phi(0, 0) = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \in \mathbb{R}^{2 \times 2}$$

1/(4): 由于 $\Phi(x, y)$ 在 $(0, 0) \in \mathbb{R}^2$ 点可微，故

$$\frac{\partial \Phi}{\partial e}(0, 0) = D\Phi(0, 0)e = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}e = 0$$

Problem 2 (导数计算) (10%) 求函数 $u(x, y) = f(xy, y/x)$ 的二阶偏导数 $\frac{\partial^2 u}{\partial x \partial y}(x, y)$ 。此处认为 $f(\xi, \eta)$ 具有足够的光滑性。

2:

$$u(x, y) = f(xy, \frac{y}{x})$$

则 $\frac{\partial u}{\partial y}(x, y) = f_1 \cdot x + f_2 \cdot \frac{1}{x}$

$$\begin{aligned} \frac{\partial^2 u}{\partial x \partial y}(x, y) &= \left(f_{11} \cdot y + f_{12} \cdot \left(-\frac{y}{x^2}\right) \right) x + f_1 + \left(f_{21} \cdot y + f_{22} \left(-\frac{y}{x^2}\right) \right) \frac{1}{x} + f_2 \left(-\frac{1}{x^2}\right) \\ &= xyf_{11} - 2xyf_{12} - \frac{y}{x^3}f_{22} + f_1 - \frac{1}{x^2}f_2 \end{aligned}$$

此处 $f_{12}(xy, \frac{y}{x}) = \frac{\partial^2 f}{\partial x \partial y}(xy, \frac{y}{x}) = \frac{\partial^2 f}{\partial y \partial x}(xy, \frac{y}{x})$ 等。

Problem 3 (Fourier 级数基本概念) 现有有限区间上定义的分段函数:

$$f(x) \triangleq \begin{cases} 0 & x \in [0, 1) \\ 1 & x \in [1, 2] \\ x - 2 & x \in (2, 3] \end{cases}$$

1. (10%) 按点收敛的概念, 将 $f(x), x \in [0, 3]$ 表示成 Fourier 级数的形式。要求写出具体的表达形式, 但相关系数仅需给出具体计算式。
2. (05%) 示意性绘出 Fourier 级数对应的和函数 (极限函数) 的图像。

3/(1):

$$\frac{f(x+0) + f(x-0)}{2} = \frac{a_0}{2} + \sum_{n=1}^{+\infty} \left(a_n \cos \frac{n\pi x}{l} + b_n \sin \frac{n\pi x}{l} \right)$$

此处 $l = \frac{3}{2}$

$$\begin{cases} a_n \triangleq \frac{1}{l} \int_0^3 f(x) \cos \frac{n\pi x}{\frac{3}{2}} dx, n \in \mathbb{N} \cup \{0\} \\ b_n \triangleq \frac{1}{l} \int_0^3 f(x) \sin \frac{n\pi x}{\frac{3}{2}} dx, n \in \mathbb{N} \end{cases}$$

3/(2): 略

Problem 4 (条件极值问题) 在椭球面 $x^2/a^2 + y^2/b^2 + z^2/c^2 = 1$ 的内积长方体中, 求体积为最大的那个长方体。

1. (10%) 按 Lagrange 方法进行有约束目标函数极值点的寻找
2. (05%) 从极值到最值的有关说明 (需先计算 Hasse 矩阵)

4/(1): 利用Lagrange乘子法求条件极值

$$L(x, y, z) \triangleq xyz - \lambda\left(\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} - 1\right)$$

$$\begin{cases} \frac{\partial L}{\partial x}(x, y, z) = yz - \frac{2\lambda}{a^2}x = 0 \\ \frac{\partial L}{\partial y}(x, y, z) = xz - \frac{2\lambda}{b^2}y = 0 \\ \frac{\partial L}{\partial z}(x, y, z) = xy - \frac{2\lambda}{c^2}z = 0 \end{cases}, \text{ 即为临界点所满足的条件}$$

$$\begin{cases} 3xyz = 2\lambda\left(\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2}\right) = 2\lambda \\ \frac{x^2}{a^2} = \frac{y^2}{b^2} = \frac{z^2}{c^2} = \frac{xyz}{2\lambda} = \frac{1}{3} \end{cases}$$

$$\begin{cases} x = \frac{a}{\sqrt{3}} \\ y = \frac{b}{\sqrt{3}} \\ z = \frac{c}{\sqrt{3}} \end{cases}$$

$$\lambda = \frac{3}{2}xyz = \frac{3}{2} \frac{abc}{3\sqrt{3}} = \frac{abc}{2\sqrt{3}}$$

4/(2):

$$H_L(xyz) = \begin{bmatrix} -\frac{2\lambda}{a^2} & z & y \\ z & -\frac{2\lambda}{b^2} & x \\ y & x & -\frac{2\lambda}{c^2} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{bc}{a\sqrt{3}} & \frac{c}{\sqrt{3}} & \frac{b}{\sqrt{3}} \\ \frac{c}{\sqrt{3}} & -\frac{ac}{b\sqrt{3}} & \frac{a}{\sqrt{3}} \\ \frac{b}{\sqrt{3}} & \frac{a}{\sqrt{3}} & -\frac{ab}{c\sqrt{3}} \end{bmatrix} = \frac{1}{\sqrt{3}} \begin{bmatrix} -\frac{bc}{a} & c & b \\ c & -\frac{ac}{b} & a \\ b & a & -\frac{ab}{c} \end{bmatrix}$$

对此可基于问题的实际情况，说明最大值的存在性。

Problem 5 (曲面积分计算) 设有螺旋面，其向量值映照表示为：

$$\Sigma(u, v) : \mathcal{D}_{uv} \ni \begin{bmatrix} u \\ v \end{bmatrix} \mapsto \Sigma(u, v) \triangleq \begin{bmatrix} u \cos v \\ u \sin v \\ v \end{bmatrix} \in \mathbb{R}^3$$

此处， $\mathcal{D}_{uv} \triangleq \{[u, v]^T \in \mathbb{R}^2 \mid u \subset [0, a], v \subset [0, 2\pi]\}$ 。

1. (10%) 计算： $\int_{\Sigma} z^2 d\sigma$

2. (10%) 计算： $\int_{\Sigma} (y\mathbf{i} + x\mathbf{j} + z^2\mathbf{k}) \cdot \mathbf{n} d\sigma \equiv \int_{\Sigma} y dy dz + x dz dx + z^2 dx dy$

5/(1):

$$\int_{\Sigma} z^2 d\sigma = \int_{\mathcal{D}_{u,v}} z^2(u, v) \left| \frac{\partial \Sigma}{\partial u} \times \frac{\partial \Sigma}{\partial v} \right|_{\mathbb{R}^3} (u, v) d\sigma$$

$$\frac{\partial \Sigma}{\partial u} \times \frac{\partial \Sigma}{\partial v} (u, v) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos v & \sin v & 0 \\ -u \sin v & u \cos v & 1 \end{vmatrix} = \begin{bmatrix} \sin v \\ -\cos v \\ u \end{bmatrix}$$

$$\int_{\Sigma} z^2 d\sigma = \int_{\mathcal{D}_{uv}} v^2 \sqrt{1+u^2} d\sigma = \int_0^{2\pi} v^2 dv \int_0^a \sqrt{1+u^2} du = \frac{8\pi^3}{3} \int_0^a \sqrt{1+u^2} du$$

$$\begin{aligned} \int \sqrt{1+u^2} du &= u\sqrt{1+u^2} - \int u \frac{u}{\sqrt{1+u^2}} du = u\sqrt{1+u^2} - \int \frac{1+u^2-1}{\sqrt{1+u^2}} du \\ &= u\sqrt{1+u^2} - \int \sqrt{1+u^2} du + \int \frac{du}{\sqrt{1+u^2}} =: I \\ 2I &= u\sqrt{1+u^2} + \int \frac{du}{\sqrt{1+u^2}} \end{aligned}$$

对于 $\int \frac{du}{\sqrt{1+u^2}}$ 令 $u(\theta) = \tan \theta$, $\theta \in (-\frac{\pi}{2}, \frac{\pi}{2})$, $u(\theta)$ 在 $(-\frac{\pi}{2}, \frac{\pi}{2})$ 严格单调且连续, 满足 $u(-\frac{\pi}{2}, \frac{\pi}{2}) = \mathbb{R}$
且存在 $u'(\theta) = \sec^2 \theta$, $\forall \theta \in (-\frac{\pi}{2}, \frac{\pi}{2})$

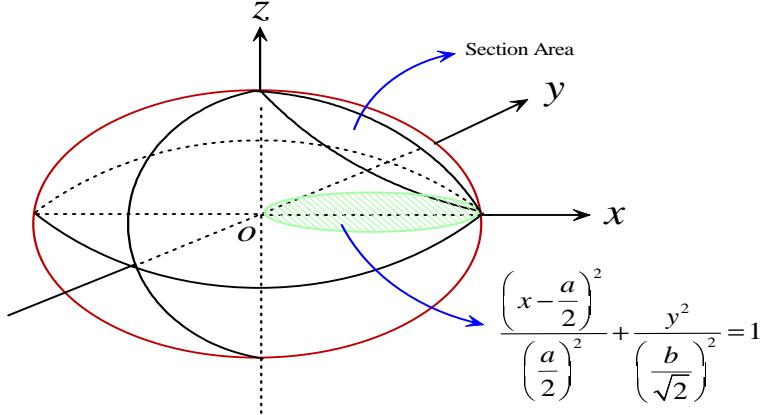
$$\begin{aligned} \text{故 } \int \frac{du}{\sqrt{1+u^2}} &= \int \frac{\sec^2 \theta d\theta}{\sec \theta} = \int \frac{d\theta}{\cos \theta} \\ &= \int \frac{d \sin \theta}{(1 - \sin^2 \theta)} = \int \left(\frac{1}{1 + \sin \theta} + \frac{1}{1 - \sin \theta} \right) d \sin \theta \\ &= \ln \frac{1 + \sin \theta}{1 - \sin \theta} + c = \ln \frac{1 + \frac{u}{\sqrt{1+u^2}}}{1 - \frac{u}{\sqrt{1+u^2}}} + c = \ln \frac{\sqrt{1+u^2} + u}{\sqrt{1+u^2} - u} + c \\ &= 2 \ln(u + \sqrt{1+u^2}) + c \end{aligned}$$

故 $I = \frac{1}{2} u \sqrt{1+u^2} + \ln(u + \sqrt{1+u^2}) + c$ 为 $\sqrt{1+u^2}$ 在 $[0, a]$ 上的原函数

$$\text{故 } \int_{\Sigma} z^2 d\sigma = \frac{8\pi^3}{3} \left(\frac{1}{2} a \sqrt{1+a^2} + \ln(a + \sqrt{1+a^2}) \right)$$

5/(2):

$$\begin{aligned}
& \int_{\Sigma} (\vec{y}i + \vec{x}j + z^2\vec{k}) \cdot \vec{n} d\sigma \\
&= \int_{\mathcal{D}_{uv}} (\vec{y}i + \vec{x}j + z^2\vec{k})(u, v) \cdot \left(\frac{\partial \Sigma}{\partial u} \times \frac{\partial \Sigma}{\partial v} \right)(u, v) d\sigma \\
&= \int_{\mathcal{D}_{uv}} \begin{bmatrix} u \sin v & u \cos v & v^2 \end{bmatrix} \begin{bmatrix} \sin v \\ -\cos v \\ u \end{bmatrix} d\sigma \\
&= \int_{\mathcal{D}_{uv}} [u^2(\sin^2 v - \cos^2 v) + uv^2] d\sigma \\
&= \int_{\mathcal{D}_{uv}} (uv^2 - u^2 \cos 2v) d\sigma \\
\int_{\mathcal{D}_{uv}} uv^2 d\sigma &= \int_0^a u du \int_0^{2\pi} v^2 dv = \frac{8\pi^3}{3} \cdot \frac{a^2}{2} = \frac{4\pi a^2}{3} \\
\int_{\mathcal{D}_{uv}} u^2 \cos 2v d\sigma &= \int_0^a u^2 du \int_0^{2\pi} \cos 2v dv = 0 \\
\text{故 } \int_{\Sigma} (\vec{y}i + \vec{x}j + z^2\vec{k}) \cdot \vec{n} d\sigma &= \frac{4\pi a^2}{3}
\end{aligned}$$



Problem 6 (曲线积分计算) 如上图所示，计算曲线积分：

$$\int_L [(y^2 + z^2)\mathbf{i} + (z^2 + x^2)\mathbf{j} + (x^2 + y^2)\mathbf{k}] \cdot \tau dl \equiv \int_L (y^2 + z^2) dx + (z^2 + x^2) dy + (x^2 + y^2) dz$$

此处曲线 L 为

$$\begin{cases} \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1 \\ \frac{x}{a} + \frac{z}{c} = 1 \end{cases}, \quad x \geq 0, y \geq 0, z \geq 0$$

($a > 0, b > 0, c > 0$) 的交线；积分指向面对于 x 轴为逆时针方向。消去 z ，易得交线 L 在 xy 平面的投影为：

$$\frac{(x - \frac{a}{2})^2}{(\frac{a}{2})^2} + \frac{y^2}{(\frac{b}{\sqrt{2}})^2} = 1$$

藉此可构造 L 的参数表示（向量值映照）。本问题可有以下两种解法：

1. (15%) 基于 Stokes 公式计算上述积分。
2. (10%) 构造 L 的向量值映照表示，并写出上述积分计算的表达式（无需完成全部计算）。

6/(1):

$$\begin{aligned}
 & \int_L [(y^2 + z^2)\vec{i} + (z^2 + x^2)\vec{j} + (x^2 + y^2)\vec{k}] \cdot \vec{\tau} dl \\
 &= \int_{\Sigma} \operatorname{rot} \vec{a} \cdot \vec{n} d\sigma \\
 \operatorname{rot} \vec{a} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^2 + z^2 & z^2 + x^2 & x^2 + y^2 \end{vmatrix} = \begin{bmatrix} 2y - 2z \\ 2z - 2x \\ 2x - 2y \end{bmatrix} = 2 \begin{bmatrix} y - z \\ z - x \\ x - y \end{bmatrix}
 \end{aligned}$$

对于所截平面，利用Monge型表示，即为：

$$\Sigma(x, y) : \mathcal{D}_{xy} \ni \begin{bmatrix} x \\ y \end{bmatrix} \longmapsto \Sigma(x, y) \triangleq \begin{bmatrix} x \\ y \\ c(1 - \frac{x}{a}) \end{bmatrix}$$

$$\begin{aligned}
\frac{\partial \Sigma}{\partial x} \times \frac{\partial \Sigma}{\partial y} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & -\frac{c}{a} \\ 0 & 1 & 0 \end{vmatrix} = \begin{bmatrix} \frac{c}{a} \\ 0 \\ 1 \end{bmatrix} \\
\text{故 } I &= \int_{\Sigma} \operatorname{rot} \vec{a} \cdot \vec{n} d\sigma = \int_{\mathcal{D}_{xy}} 2[y-z, z-x, x-y](x, y) \cdot \begin{bmatrix} \frac{c}{a} \\ 0 \\ 1 \end{bmatrix} d\sigma \\
&= \frac{2c}{a} \int_{\mathcal{D}_{xy}} [y - c(1 - \frac{x}{a})] d\sigma \\
&= \frac{2c^2}{a^2} \int_{\mathcal{D}_{xy}} (\frac{x}{a} - 1) d\sigma \\
&= \frac{2c^2}{a^2} \left(\int_{\mathcal{D}_{xy}} \frac{x}{a} d\sigma - \pi \frac{ab}{2\sqrt{2}} \right) \\
\text{此处 } \mathcal{D}_{xy} &\triangleq \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2 \mid \frac{(x - \frac{a}{2})^2}{(\frac{a}{2})^2} + \frac{y^2}{(\frac{b}{\sqrt{2}})^2} \leq 1 \right\} \\
\int_{\mathcal{D}_{xy}} \frac{x}{a} d\sigma &= \frac{1}{a} \int_{\mathcal{D}_{xy}} x d\sigma \\
&\text{作 } \begin{cases} x = \frac{a}{2} + \frac{a}{2}r \cos \theta \\ y = \frac{b}{\sqrt{2}}r \sin \theta \end{cases} \quad \begin{cases} r \in [0, 1] \\ \theta \in [0, 2\pi] \end{cases} \\
\frac{D(x, y)}{D(r, \theta)}(r, \theta) &= \begin{vmatrix} \frac{a}{2} \cos \theta & -\frac{a}{2}r \sin \theta \\ \frac{b}{\sqrt{2}} \sin \theta & \frac{b}{\sqrt{2}}r \cos \theta \end{vmatrix} = \frac{ab}{2\sqrt{2}}r
\end{aligned}$$

$$\begin{aligned}
\text{故 } \frac{1}{a} \int_{\mathcal{D}_{xy}} x d\sigma &= \frac{1}{a} \int_{\mathcal{D}_{xy}} \left(\frac{a}{2} + \frac{a}{2}r \cos \theta \right) \frac{ab}{2\sqrt{2}} r d\sigma = \frac{ab}{4\sqrt{2}} \int_{\mathcal{D}_{xy}} r d\sigma = \frac{\pi ab}{4\sqrt{2}} \\
\text{综上 } I &= \frac{2c^2}{a^2} \left(\frac{\pi ab}{4\sqrt{2}} - \frac{\pi ab}{2\sqrt{2}} \right) = -\frac{\pi bc^2}{2\sqrt{2}a}
\end{aligned}$$

6/(2): 对于L的向量值映照

$$\begin{cases} x = \frac{a}{2} + \frac{a}{2} \cos \theta \\ y = \frac{b}{\sqrt{2}} \sin \theta \\ z = c(1 - \frac{x}{a}) = c(\frac{1}{2} - \frac{1}{2} \cos \theta) = \frac{c}{2}(1 - \cos \theta) \end{cases}$$

$$\theta \in [0, \frac{\pi}{2}]$$

由此 $\int_L [(y^2 + z^2)\vec{i} + (z^2 + x^2)\vec{j} + (x^2 + y^2)\vec{k}] \cdot \vec{r} dl$

$$= \int_0^{2\pi} [(y^2 + z^2)\vec{i} + (z^2 + x^2)\vec{j} + (x^2 + y^2)\vec{k}] (\theta) \cdot \frac{d\vec{r}}{d\theta} (\theta) d\theta$$

此处 $\frac{d\vec{r}}{d\theta} (\theta) = D\vec{r}(\theta) = \begin{bmatrix} -\frac{a}{2} \sin \theta \\ \frac{b}{\sqrt{2}} \cos \theta \\ \frac{c}{2} \sin \theta \end{bmatrix} \in \mathbb{R}^3$

Problem 7 (幂级数基本性质) 已知幂级数

$$S(x) = \sum_{n=1}^{\infty} \frac{x^n}{n \cdot 2^n}$$

1. (10%) 计算: $S(x)$ 的收敛半径及收敛域。

2. (10%) 计算: $S(x)$ 的解析表达式。

7/(1):

$$S(x) = \sum_{n=1}^{\infty} \frac{x^n}{n \cdot 2^n}$$

则, 考虑 $\frac{|x|^{n+1}}{(n+1) \cdot 2^{n+1}} \cdot \frac{n \cdot 2^n}{|x|^n} = |x| \cdot \frac{n}{n+1} \cdot \frac{1}{2} \longrightarrow \frac{|x|}{2} < 1$

故收敛半径为2, 再考虑 $a_n = \frac{2^n}{n \cdot 2^n} = \frac{1}{n}$

$$a_n = \frac{(-1)^n 2^n}{n \cdot 2^n} = \frac{(-1)^n}{n}$$

故 $S(x), x \in [-2, 2)$ 为收敛域。

7/(2):

$$S(x) = \sum_{n=1}^{+\infty} \frac{x^n}{n \cdot 2^n}$$

$$= \frac{x}{2} + \sum_{n=2}^{+\infty} \frac{x^n}{n \cdot 2^n} \quad x \in [-2, 2)$$

$$\text{考慮 } \frac{1}{2} + \sum_{n=2}^{+\infty} \frac{nx^{n-1}}{n \cdot 2^n} = \frac{1}{2} + \sum_{n=2}^{+\infty} \frac{x^{n-1}}{2 \cdot 2^{n-1}}$$

$$= \frac{1}{2} + \sum_{n=1}^{+\infty} \frac{x^n}{2 \cdot 2^n} \quad \text{收敛域为} (-2, 2).$$

$$\text{故有 } \frac{dS}{dx}(x) = \frac{1}{2} \left(1 + \sum_{n=1}^{+\infty} \left(\frac{x}{2} \right)^n \right) \quad \forall x \in (-2, 2)$$

$$= \frac{1}{2} \frac{1}{1 - \frac{x}{2}} = \frac{1}{2 - x}$$

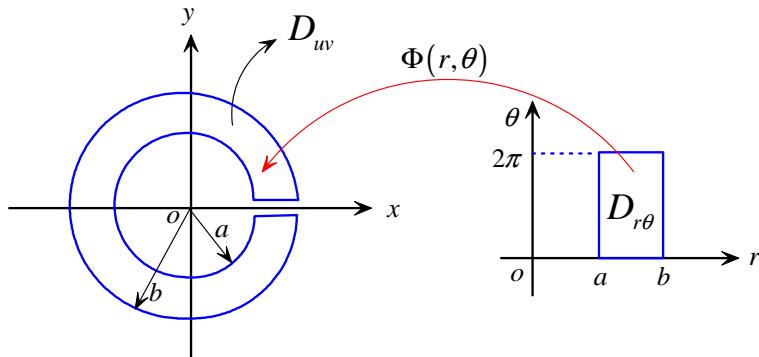
$$S(x) = S(0) + \int_0^x \frac{1}{2 - \xi} d\xi \quad \forall x \in (-2, 2)$$

$$= - \int_0^x \frac{1}{2 - \xi} d(2 - \xi) = - \ln \frac{2 - x}{2} = - \ln \left(1 - \frac{x}{2} \right)$$

$$\text{即 } S(x) = - \ln \left(1 - \frac{x}{2} \right) \quad \forall x \in (-2, 2)$$

$$\lim_{x \rightarrow -2+0} - \ln \left(1 - \frac{x}{2} \right) = - \ln 2 = S(-2)$$

$$\text{故 } S(x) = - \ln \left(1 - \frac{x}{2} \right) \quad \forall x \in [-2, 2)$$



Problem 8 (区域变换) $f(x, y)$ 在环型区域 $\mathcal{D}_{xy} \triangleq \{(x, y) \mid a^2 \leq x^2 + y^2 \leq b^2, \text{ 且在 } x \text{ 轴正部有割缝}\}$ (a, b 均为正数) 上有定义, 且满足 Laplace 方程, 即有

$$\frac{\partial^2 f}{\partial x^2}(x, y) + \frac{\partial^2 f}{\partial y^2}(x, y) = 0$$

考虑极坐标变换:

$$\Phi(r, \theta) : \mathcal{D}_{r\theta} \ni \begin{bmatrix} r \\ \theta \end{bmatrix} \mapsto \Phi(r, \theta) \triangleq \begin{bmatrix} r \cos \theta \\ r \sin \theta \end{bmatrix} \in \mathbb{R}^2$$

此处 $\mathcal{D}_{r\theta} \triangleq \{(r, \theta) \mid r \in (a, b), \theta \in (0, 2\pi)\}$, 则实现环形区域 \mathcal{D}_{xy} 同矩形区域 $\mathcal{D}_{r\theta}$ 间的一一对应的变换。如上图所示。

1. (10%) 计算: Φ 逆映照的 Jacobian 矩阵。

2. (10%) 计算: $\hat{f}(r, \theta) \triangleq f(x(r, \theta), y(r, \theta))$ 所满足的方程。提示: $f(x, y) = \hat{f}(r(x, y), \theta(x, y))$ 。

8/(1):

$$D\Phi(r, \theta) = \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix}$$

8/(2):

$$\begin{aligned} D\Phi(r, \theta) &= \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{bmatrix} = \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix} \quad \det D\Phi(r, \theta) = r \\ \text{则 } \begin{bmatrix} \frac{\partial r}{\partial x} & \frac{\partial r}{\partial y} \\ \frac{\partial \theta}{\partial x} & \frac{\partial \theta}{\partial y} \end{bmatrix} &= \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix}^{-1} = \frac{1}{r} \begin{bmatrix} r \cos \theta & -\sin \theta \\ r \sin \theta & \cos \theta \end{bmatrix}^T \\ &= \frac{1}{r} \begin{bmatrix} r \cos \theta & r \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\frac{\sin \theta}{r} & \frac{\cos \theta}{r} \end{bmatrix} \end{aligned}$$

由 $f(x, y) = \hat{f}(r(x, y), \theta(x, y))$

$$\begin{aligned}
\frac{\partial f}{\partial x} &= \frac{\partial \hat{f}}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial \hat{f}}{\partial \theta} \frac{\partial \theta}{\partial x} = \frac{\partial \hat{f}}{\partial r} \cos \theta - \frac{\partial \hat{f}}{\partial \theta} \frac{\sin \theta}{r} \\
\frac{\partial^2 f}{\partial x^2} &= \left(\frac{\partial^2 \hat{f}}{\partial r^2} \frac{\partial r}{\partial x} + \frac{\partial^2 \hat{f}}{\partial \theta \partial r} \frac{\partial \theta}{\partial x} \right) \cos \theta + \frac{\partial \hat{f}}{\partial r} (-\sin \theta) \frac{\partial \theta}{\partial x} \\
&\quad - \left(\frac{\partial \hat{f}}{\partial r \partial \theta} \frac{\partial r}{\partial x} + \frac{\partial^2 \hat{f}}{\partial \theta^2} \frac{\partial \theta}{\partial x} \right) \frac{\sin \theta}{r} - \frac{\partial \hat{f}}{\partial \theta} \left(-\frac{\sin \theta}{r^2} \frac{\partial r}{\partial x} + \frac{\cos \theta}{r} \frac{\partial \theta}{\partial x} \right) \\
&= \left(\frac{\partial^2 \hat{f}}{\partial r^2} \cos \theta - \frac{\partial^2 \hat{f}}{\partial \theta \partial r} \frac{\sin \theta}{r} \right) \cos \theta + \frac{\partial \hat{f}}{\partial r} (-\sin \theta) \left(-\frac{\sin \theta}{r} \right) \\
&\quad - \left(\frac{\partial^2 \hat{f}}{\partial r \partial \theta} \cos \theta - \frac{\partial^2 \hat{f}}{\partial \theta^2} \frac{\sin \theta}{r} \right) \frac{\sin \theta}{r} - \frac{\partial \hat{f}}{\partial \theta} \left(-\frac{\sin \theta}{r^2} \cos \theta - \frac{\cos \theta \sin \theta}{r} \right) \\
&= \frac{\partial^2 \hat{f}}{\partial r^2} \cos^2 \theta + \frac{\partial^2 \hat{f}}{\partial \theta^2} \frac{\sin^2 \theta}{r^2} - \frac{2 \sin \theta \cos \theta}{r} \frac{\partial^2 \hat{f}}{\partial r \partial \theta} \\
&\quad + \frac{\sin^2 \theta}{r} \frac{\partial \hat{f}}{\partial r} + \frac{2 \sin \theta \cos \theta}{r^2} \frac{\partial \hat{f}}{\partial \theta} \\
\frac{\partial f}{\partial y} &= \frac{\partial \hat{f}}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial \hat{f}}{\partial \theta} \frac{\partial \theta}{\partial y} = \frac{\partial \hat{f}}{\partial r} \sin \theta + \frac{\partial \hat{f}}{\partial \theta} \frac{\cos \theta}{r} \\
\frac{\partial^2 f}{\partial y^2} &= \left[\frac{\partial^2 \hat{f}}{\partial r^2} \frac{\partial r}{\partial y} + \frac{\partial^2 \hat{f}}{\partial \theta \partial r} \frac{\partial \theta}{\partial y} \right] \sin \theta + \frac{\partial \hat{f}}{\partial r} \cos \theta \frac{\partial \theta}{\partial y} \\
&\quad + \left[\frac{\partial^2 \hat{f}}{\partial r \partial \theta} \frac{\partial r}{\partial y} + \frac{\partial^2 \hat{f}}{\partial \theta^2} \frac{\partial \theta}{\partial y} \right] \frac{\cos \theta}{r} + \frac{\partial \hat{f}}{\partial \theta} \left(-\frac{\cos \theta}{r^2} \frac{\partial r}{\partial y} - \frac{\sin \theta}{r} \frac{\partial \theta}{\partial y} \right) \\
&= \left[\frac{\partial^2 \hat{f}}{\partial r^2} \sin \theta + \frac{\partial^2 \hat{f}}{\partial \theta \partial r} \frac{\cos \theta}{r} \right] \sin \theta + \frac{\partial \hat{f}}{\partial r} \cos \theta \frac{\cos \theta}{r} \\
&\quad + \left[\frac{\partial^2 \hat{f}}{\partial r \partial \theta} \sin \theta + \frac{\partial^2 \hat{f}}{\partial \theta^2} \frac{\cos \theta}{r} \right] \frac{\cos \theta}{r} + \frac{\partial \hat{f}}{\partial \theta} \left(-\frac{\cos \theta}{r^2} \sin \theta - \frac{\sin \theta \cos \theta}{r} \right) \\
&= \sin^2 \theta \frac{\partial^2 \hat{f}}{\partial r^2} + \frac{2 \sin \theta \cos \theta}{r} \frac{\partial^2 \hat{f}}{\partial r \partial \theta} + \frac{\cos^2 \theta}{r^2} \frac{\partial^2 \hat{f}}{\partial \theta^2} \\
&\quad + \frac{\cos^2 \theta}{r} \frac{\partial \hat{f}}{\partial r} - \frac{2 \sin \theta \cos \theta}{r^2} \frac{\partial \hat{f}}{\partial \theta} \\
\text{综上 } \left(\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} \right) (x, y) &= \frac{\partial^2 \hat{f}}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 \hat{f}}{\partial \theta^2} + \frac{1}{r} \frac{\partial \hat{f}}{\partial r}
\end{aligned}$$