

Concurrent Programming

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LDS-1101

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Agenda

- Concurrent programs
- Races
- Synchronization problems:
 - Mutual exclusion
 - Deadlock
 - Starvation and fairness
- Locks





Abstraction of concurrent programs

We use an abstract notation for multithreaded applications using Java syntax:

```
int counter = 0;

thread t

int cnt;

cnt = counter;

counter = cnt + 1;

thread u

int cnt;

cnt = counter;

counter = cnt + 1;
```

Each line of code includes exactly one instruction that can be executed atomically





Traces (1)

A sequence of states gives an execution trace of the concurrent program:

State	t's local	u's local	Shared
1	pc _t : 1, cnt : ⊥	pc _u : 1, cnt : ⊥	counter: 0
2	pc _t : 2, cnt : 0	pc_u : 1, cnt : \perp	counter: 0
3	done	pc_u : 1, cnt : \perp	counter: 1
4	done	pc _u : 2, cnt : 1	counter: 1
5	done	done	counter: 2

The program counter pc points to the atomic instruction that will be executed next





Traces (2)

A sequence of states gives an execution trace of the concurrent program:

State	t's local	u's local	Shared
1	pc _t : 1, cnt : ⊥	pc _u : 1, cnt : ⊥	counter: 0
2	pc _t : 1, cnt : ⊥	pc _u : 2, cnt : 0	counter: 0
3	pc_t : 1, cnt : \perp	done	counter : 1
4	pc _t : 2, cnt : 1	done	counter : 1
5	done	done	counter: 2

The program counter pc points to the atomic instruction that will be executed next





Traces (3)

A sequence of states gives an execution trace of the concurrent program:

State	t's local	u's local	Shared
1	pc _t : 1, cnt : ⊥	pc _u : 1, cnt : ⊥	counter: 0
2	pc _t : 2, cnt : 0	pc _u : 1, cnt : ⊥	counter: 0
3	pc _t : 2, cnt : 0	pc _u : 2, cnt : 0	counter: 0
4	pc _t : 2, cnt : 0	done	counter : 1
5	done	done	counter: 1

The program counter pc points to the atomic instruction that will be executed next









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Race conditions

- Concurrent programs are nondeterministic:
 - Executing multiple times the same concurrent program with the same inputs may lead to different execution traces
 - This is a result of the nondeterministic interleaving of each thread's trace to determine the overall program trace
 - □ In turn, the interleaving is a result of the scheduler's decisions
- A race condition is a situation where the result of a concurrent program depends on the specific execution:
 - The concurrent counter example has a race condition: in some executions the final value of counter is 2, in some executions the final value of counter is 1
 - Race conditions can greatly complicate debugging!





Data races

- Race conditions are typically due lack of synchronization between threads that access shared memory
- A data race occurs when two threads access a shared memory location and:
 - At least one access is a write
 - The relative order of the two accesses is not fixed

```
int counter = 0;

thread t

int cnt;
cnt = counter;
counter = cnt + 1;

int counter = 0;

thread u

int cnt;
cnt = counter;
counter = cnt + 1;
```





Data races vs. race conditions

- Not every race condition is a data race:
 - Race conditions can occur even when there is no shared memory access
 - For example in filesystems or network access

- Not every data race is a race condition:
 - The data race may not affect the result
 - For example if two threads write the same value to shared memory





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Push out the races, bring in the speed

- Concurrent programming introduces:
 - □ The potential for parallel execution (faster, better resource usage)
 - The risk of race conditions (incorrect, unpredictable computations)
- The main challenge of concurrent programming is thus introducing parallelism without introducing race conditions:
 - This requires to restrict the amount of nondeterminism by synchronizing processes/threads that access shared resources





Synchronization

- We will study several synchronization problems that often appear in concurrent programming, together with their solutions:
 - Correctness (that is, avoiding race conditions) is more important than performance: an incorrect result that is computed very quickly is no good!
 - However, we also want to retain as much concurrency as possible, otherwise we might as well stick with sequential programming

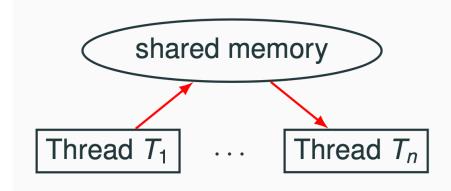


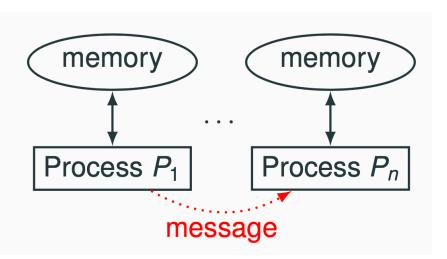


Share memory vs. message passing synchronization (1)

- Shared memory synchronization:
 - Synchronize by writing to and reading from shared memory
 - Natural choice in shared memory systems such as threads

- Message passing synchronization:
 - Synchronize by exchanging messages
 - Natural choice in distributed memory systems such as processes









Share memory vs. message passing synchronization (2)

- The two synchronization models overlap:
 - send a message by writing to and reading from shared memory (example: message board)
 - share information by sending a message (example: order a billboard)
- However, in the first part of the course we will focus on synchronization problems that arise in shared memory concurrency; in the second part we will switch to message passing





The mutual exclusion problem (1)

- The mutual exclusion problem is a fundamental synchronization problem, which arises whenever multiple threads have access to a shared resource:
 - □ Critical section: the part of a program that accesses the shared resource (for example, a shared variable)
 - Mutual exclusion property: no more than one thread is in its critical section at any given time
- The mutual exclusion problem devise a protocol for accessing a shared resource that satisfies the mutual exclusion property





The mutual exclusion problem (2)

- Simplifications to present solutions in a uniform way:
 - The critical section is an arbitrary block of code
 - Threads continuously try to enter the critical section
 - □ Threads spend a finite amount of time in the critical section
 - □ We ignore what the threads do outside their critical sections





The mutual exclusion problem (3)

The mutual exclusion problem devise a protocol for accessing a shared resource that satisfies the mutual exclusion property:

T shared;

thread t_j

```
// continuously
while (true) {
    entry protocol
    critical section {
        // access shared data
    }
    exit protocol
} /* ignore behavior
outside critical section */
```

thread t_k

```
// continuously
while (true) {
    entry protocol
    critical section {
        // access shared data
    }
    exit protocol
} /* ignore behavior
outside critical section */
```





The mutual exclusion problem example: Concurrent counter

Updating a shared variable consistently is an instance of the mutual exclusion problem:

T shared;

thread t

```
int cnt;
while (true) {
  entry protocol
  critical section {
      cnt = counter;
      counter = cnt + 1;
  exit protocol
   return:
```

thread u

```
int cnt;
while (true) {
  entry protocol
  critical section {
      cnt = counter;
      counter = cnt + 1;
  exit protocol
  return.
```





What's a good solution to the mutual exclusion problem?

- A fully satisfactory solution is one that achieves three properties:
 - Mutual exclusion: At most one thread is in its critical section at any given time
 - □ Freedom from deadlock: If some threads tries to enter the critical section, some thread will eventually succeed
 - Freedom from starvation: Every thread that tries to enter the critical section will eventually succeed
- A good solution should also work for an arbitrary number of threads sharing the same memory
- (Note that freedom from starvation implies freedom from deadlock)





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Deadlocks

- A mutual exclusion protocol provides exclusive access to shared resources to one thread at a time
- Threads that try to access the resource when it is not available will have to block and wait
- Mutually dependent waiting conditions may introduce a deadlock

A deadlock is the situation where a group of threads wait forever because each of them is waiting for resources that are held by another thread in the group (circular waiting)





Deadlock: Example

- A deadlock is the situation where a group of threads wait forever because each of them is waiting for resources that are held by another thread in the group (circular waiting)
 - A protocol that achieves mutual exclusion but introduces a deadlock
 - Entry protocol: wait until all other threads have executed their critical section



Via, resti servita Madama brillante – E. Tommasi Ferroni, 2012



The dining philosophers

- The dining philosophers is a classic synchronization problem introduced by Dijkstra: It illustrates the problem of deadlocks using a colorful metaphor (by Tony Hoare):
 - □ Five philosophers are sitting around a dinner table, with a fork in between each pair of adjacent philosophers
 - □ Each philosopher alternates between thinking (non-critical section) and eating (critical section)
 - □ In order to eat, a philosopher needs to pick up the two forks that lie at the philopher's left and right sides
 - Since the forks are shared, there is a synchronization problem between philosophers (threads)







Deadlocking philosophers

An unsuccessful attempt at solving the dining philosophers problem:



This protocol deadlocks if all philosophers get their left forks, and wait forever for their right forks to become available





The Coffman conditions

- Necessary conditions for a deadlock to occur:
 - Mutual exclusion: Threads may have exclusive access to the shared resources
 - Hold and wait: A thread that may request one resource while holding another resource
 - No preemption: Resources cannot forcibly be released from threads that hold them
 - □ Circular wait: Two or more threads form a circular chain where each thread waits for a resource that the next thread in the chain is holding
- Avoiding deadlocks requires to break one or more of these conditions





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Starving philosophers

 A solution to the dining philosophers problem that avoids deadlock by breaking hold and wait (and thus circular wait): Pick up both forks at once (atomic operation)



This protocol avoids deadlocks, but it may introduce starvation: a philosopher may never get a chance to pick up the forks





Starvation

- No deadlocks means that the system makes progress as a whole
- However, some individual thread may still make no progress because it is treated unfairly in terms of access to shared resources

- Starvation is the situation where a thread is perpetually denied access to a resource it requests
- Avoiding starvation requires some assumption on the scheduler, which has to "give a chance to every thread to execute"





Fairness

Weak fairness:

☐ If a thread continuously requests (that is, requests without interruptions) access to a resource, then access is granted infinitely often

Strong fairness:

 If a thread requests access to a resource infinitely often, then access is granted infinitely often

Applied to a scheduler:

- Request = A thread is ready (enabled)
- □ Fairness = Every thread has a chance to execute





Breaking a circular wait

Another solution is to pick up first the fork with the lowest id number:
 This avoids the circular wait because not every philosopher will pick up their left fork first

```
entry protocol ( Pk ) {
    if (left_fork.id() < right_fork.id()) {
        left_fork.acquire();
        right_fork.acquire();
    } else {
        right_fork.acquire();
        left_fork.acquire();
    }
}
critical section { eat(); }
exit protocol ( Pk ) { /* ... */ }</pre>
```



Ordering shared resources and forcing all threads to acquire the resources in order is a common measure to avoid deadlocks





Sequential philosophers

Another solution that avoids deadlock as well as starvation: a (fair) waiter decides which philosopher eats; the waiter gives permission to eat to one philosopher at a time

```
entry protocol ( Pk ) {
    while (!waiter.can_eat(k)) {
        // wait for permission to eat
    }
    left_fork.acquire();
    right_fork.acquire();
}
critical section { eat(); }
exit protocol ( Pk ) { /* ... */ }
```

Having a centralized arbiter avoids deadlocks and starvation, but a waiter who only gives permission to one philosopher a time basically reduces the philosophers to following a sequential order without active concurrency





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Lock objects

A lock is a data structure with interface:

```
interface Lock {
   void lock();  // acquire lock
   void unlock();  // release lock
}
```

- Several threads share the same object lock of type Lock
- Multiple threads calling lock.lock() results in exactly one thread T acquiring the lock:
 - T's call lock.lock() returns: T is holding the lock
 - Other threads block on the call lock.lock(), waiting for the lock to
- Become available
- A thread T that is holding the lock calls lock.unlock() to release the lock:
 - T's call lock.unlock() returns; the lock becomes available
 - Another thread waiting for the lock may succeed in acquiring it
- Locks are also called mutexes; they guarantee mutual exclusion





Using locks

- With lock objects the entry/exit protocols are trivial:
 - ☐ Entry protocol: call lock.lock()
 - Exit protocol: call lock.unlock()

```
int counter = 0; Lock lock = new Lock();

thread t

int cnt;
lock.lock();
cnt = counter;
counter = cnt + 1;
lock.unlock();
Lock lock = new Lock();

thread u

int cnt;
lock.lock();
cnt = counter;
counter = cnt + 1;
lock.unlock();
```

The implementation of the Lock interface should guarantee mutual exclusion, deadlock freedom, and starvation freedom





Using locks in Java

```
// package with lock-related classes
import java.util.concurrent.locks.*;
// shared with other synchronizing threads
Lock lock:
while(true) {
      lock.lock(); // entry protocol
      try {
           // critical section
           // mutual exclusion is guaranteed
           // by the lock protocol
      } finally { // lock released even if
                   // an exception is thrown in the critical section
           lock.unlock(); // exit protocol
```





Counter with mutual exclusion

```
public class LockedCounter extends CCounter
     @Override
     public void run() {
            lock.lock();
            try {
                  // int cnt = counter;
                  // counter = counter + 1;
                  super.run();
            } finally {
                  lock.unlock();
     // shared by all threads working on this object
     private Lock lock = new ReentrantLock();
```





Built-in locks in Java

- Every object in Java has an implicit lock, which can be accessed using the keyword synchronized:
 - Whole method locking (synchronized methods):

```
synchronized T m() {
    // the critical section
    // is the whole method
    // body
}
```

- □ Every call to m implicitly:
 - Acquires the lock
 - Executes m
 - Releases the lock

```
Block locking
(synchronized block):
```

```
synchronized (this) {
    // the critical section
    // is the block's content
}
```

- Every execution of the block implicitly:
 - Acquires the lock
 - Executes m
 - Releases the lock





Counter with mutual exclusion: with synchronized

SyncCounter class:

SyncBlockCounter class:





Lock implementations in Java

The most common implementation of the Lock interface in Java is class ReentrantLock

Mutual exclusion:

ReentrantLock guarantees mutual exclusion

□ Starvation:

- ReentrantLock does not guarantee freedom from starvation by default
- However, calling the constructor with new ReentrantLock(true)
 "favors granting access to the longest-waiting thread"
- This still does not guarantee that thread scheduling is fair

□ Deadlocks:

- One thread will succeed in acquiring the lock
- However, deadlocks may occur in systems that use multiple locks (remember the dining philosophers)





Built-in lock implementations in Java

- The built-in locks used by synchronized methods and blocks have the same behavior as the explicit locks of java.util.concurrent.locks
- Built-in locks, as well as all lock implementations in java.util.concurrent.locks, are re-entrant: A thread holding a lock can lock it again without causing a deadlock



