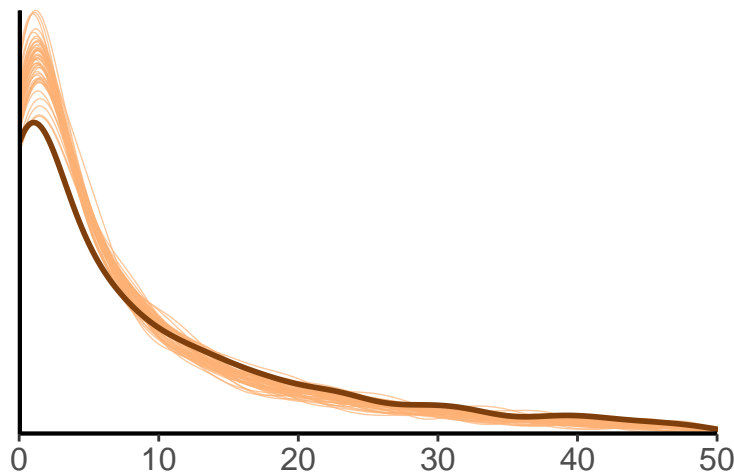
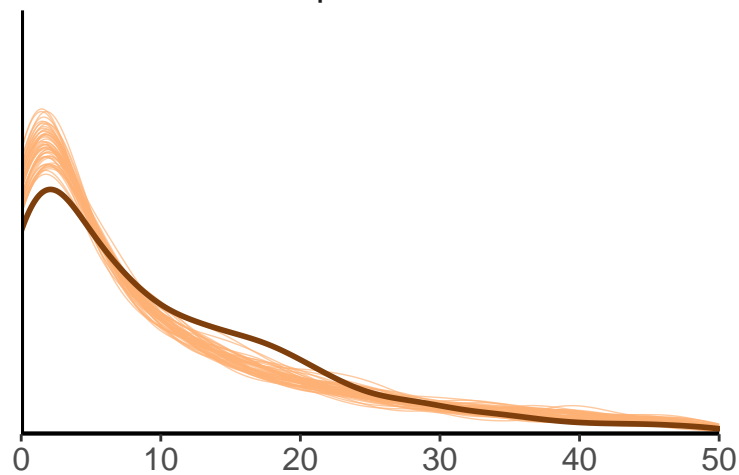


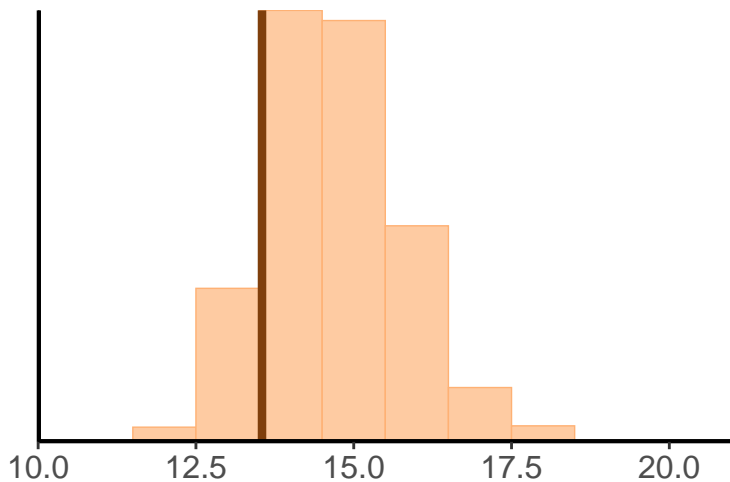
control



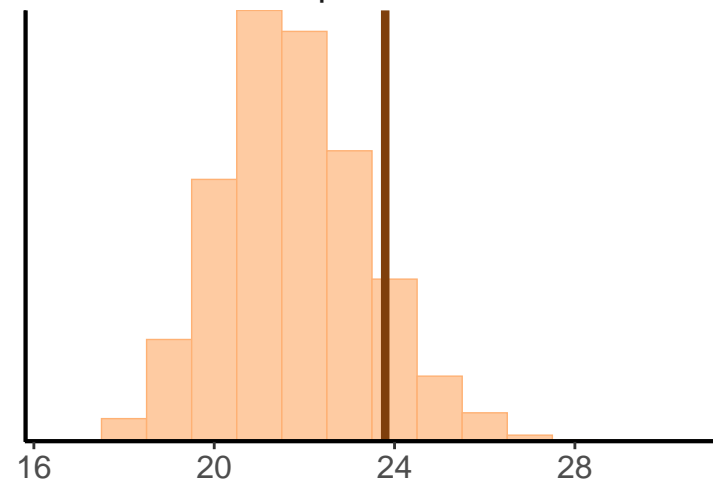
experiment

 c_5 distribution (posterior)

control



experiment

 c_5 mean