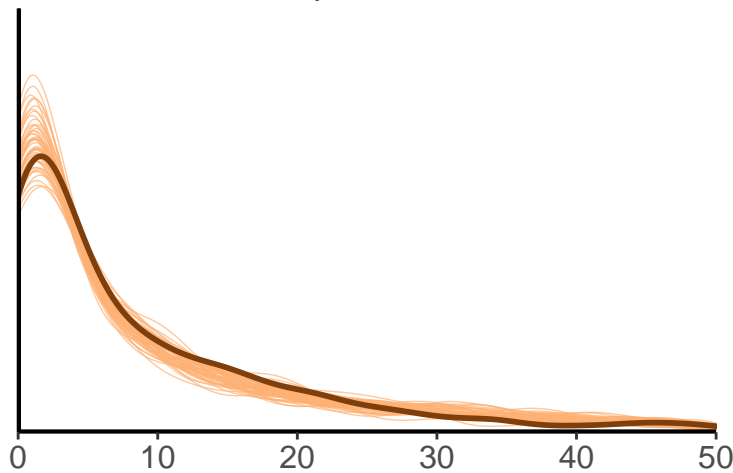
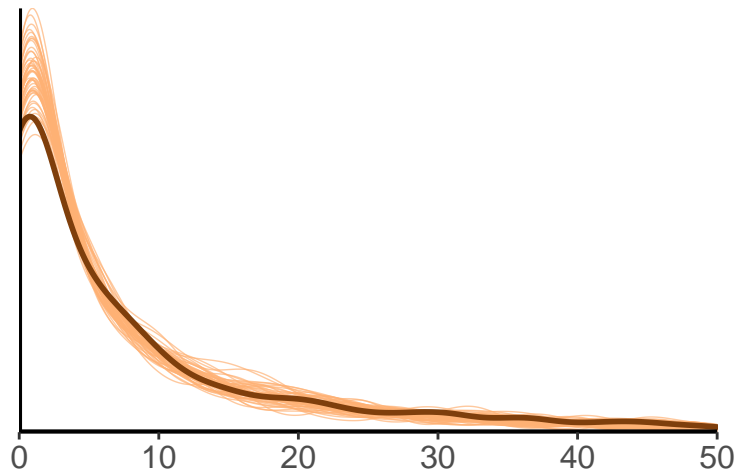


experiment

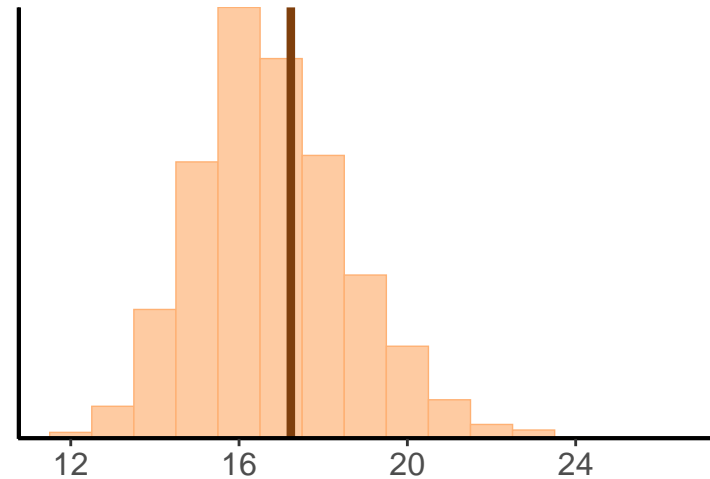


control

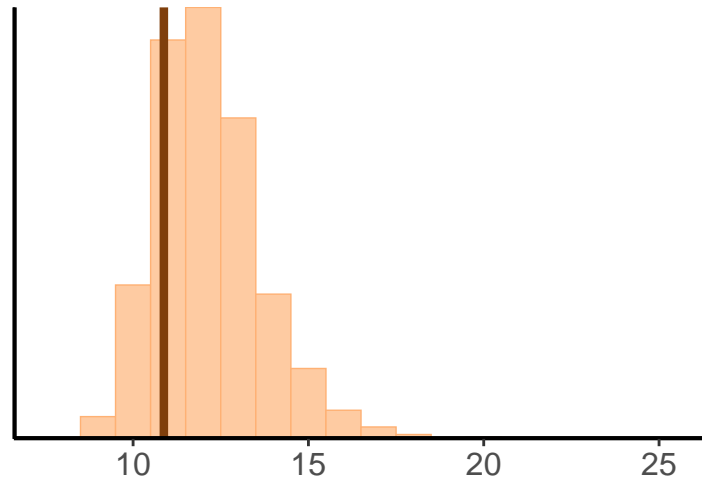


$c_5$  distribution (posterior)

experiment



control



$c_5$  mean