

## Mixing Quantum Circuits with Classical Vector Dynamics

- **Classical Vectors:** In vector dynamics, we describe motion using position  $\vec{r}=(x,y,z)\vec{r} = (x, y, z)$ , velocity  $\vec{v}=\frac{d\vec{r}}{dt}\vec{v} = \frac{d\vec{r}}{dt}$ , and acceleration  $\vec{a}=\frac{d\vec{v}}{dt}\vec{a} = \frac{d\vec{v}}{dt}$ . These quantities are essential for modeling objects like an airplane in motion.
  - **Quantum Circuits:** Quantum circuits are composed of quantum gates (e.g., Hadamard or Pauli gates) and algorithms that transform qubits. For example:
    - A quantum rotation applies transformations akin to classical rotation matrices.
    - Superposition states created by Hadamard gates introduce bifurcations or reflections in quantum space.
  - **Combining Both:** Using quantum transformation matrices, we can modify classical vectors in three-dimensional or tetrahedral (4D) space. For example:
    - An airplane's trajectory can be mapped to a quantum state  $|\psi\rangle=\alpha|0\rangle+\beta|1\rangle|\psi\rangle = \alpha|0\rangle + \beta|1\rangle$ , where the amplitudes  $\alpha, \beta$  relate to probabilities associated with positions or velocities.
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## 4. Python

```
import numpy as np
import matplotlib.pyplot as plt

# 1. Classical vectors for airplane dynamics
position = np.array([3, 1, 0]) # Initial position (x, y, z)
velocity = np.array([2, 3, 0]) # Initial velocity
acceleration = np.array([0, 0, -9.8]) # Gravitational acceleration

# 2. Time simulation
t = np.linspace(0, 10, 100) # Time from 0 to 10 seconds
positions = position + np.outer(t, velocity) + 0.5 * np.outer(t**2,
acceleration)

# 3. Quantum transformation with rotation gate
theta = np.pi / 4 # Rotation angle
rotation_matrix = np.array([
    [np.cos(theta), -np.sin(theta), 0],
    [np.sin(theta), np.cos(theta), 0],
    [0, 0, 1]
```

```
)
```

```
quantum_transformed_positions = positions @ rotation_matrix.T
```

```
# 4. Plot results
```

```
fig = plt.figure()
```

```
ax = fig.add_subplot(111, projection='3d')
```

```
ax.plot(positions[:, 0], positions[:, 1], positions[:, 2],  
label='Classical Trajectory')
```

```
ax.plot(quantum_transformed_positions[:, 0],  
quantum_transformed_positions[:, 1],
```

```
quantum_transformed_positions[:, 2], '--', label='Quantum  
Transformed Trajectory')
```

```
ax.set_xlabel('X')
```

```
ax.set_ylabel('Y')
```

```
ax.set_zlabel('Z')
```

```
ax.legend()
```

```
plt.title('Airplane Dynamics with Quantum Transformations')
```

```
plt.show()
```