

Neural-Shadow Quantum State Tomography

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arXiv:2305.01078 (2023)

PIQuIL Seminar Talk, Nov. 10th, 2023



McGill
UNIVERSITY





Phases of matter

Tomography

Ground state properties



Theory

Application

Overview

- 1) Neural network quantum state tomography (NNQST)
- 2) Classical shadow formalism
- 3) Neural-shadow quantum state tomography (NSQST)
- 4) Advantages over NNQST for time-evolved states
- 5) Scalable advantages over direct shadow estimation (*new)
- 6) Noise robustness
- 7) Experimental prospects and future directions

Quantum state tomography

- Quantum state tomography is extremely important for verifying experimentally prepared quantum states.
- Full quantum state tomography requires one to specify $4^n - 1$ independent parameters, therefore exponentially many measurements.
- The exponential scaling makes full quantum state tomography unfeasible for larger quantum systems

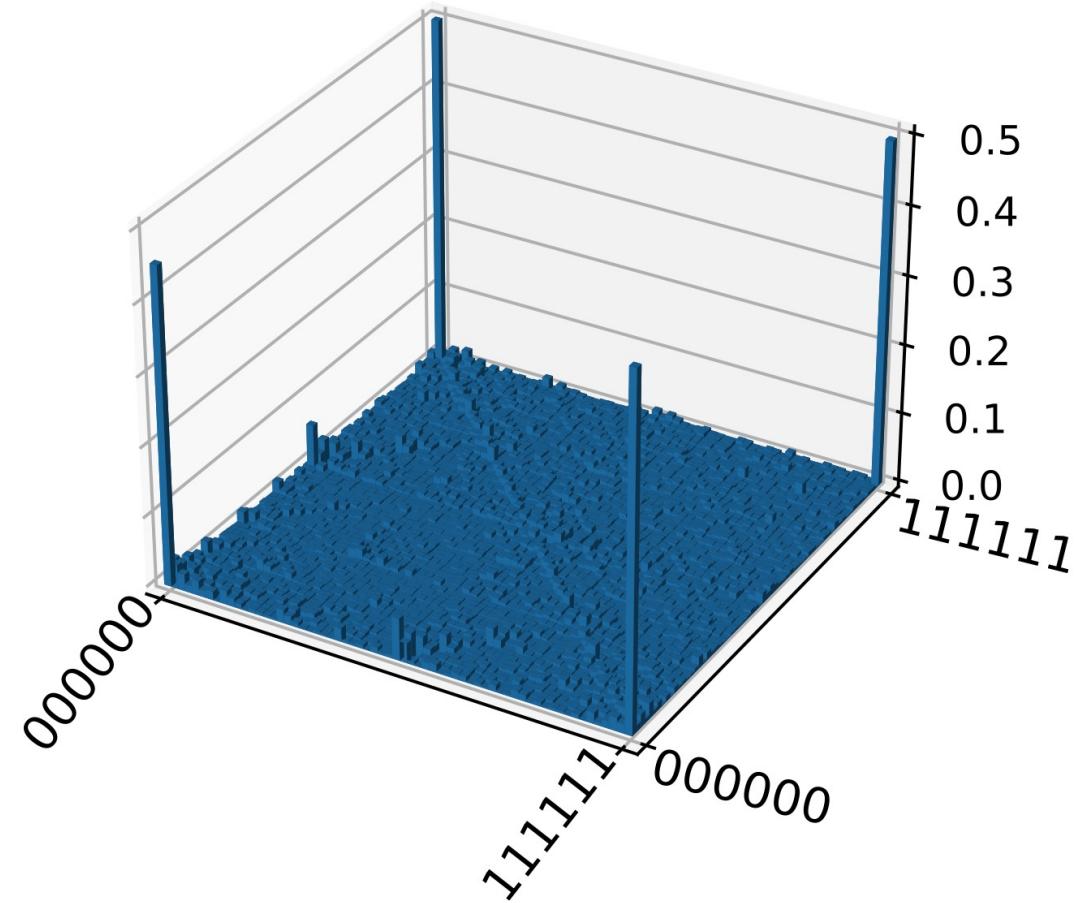


Image credit: Mach. Learn.: Sci. Technol. 3 01LT01

Neural network quantum state tomography (pure state)

Torlai *et al.* *Nature Phys* **14**, 447–450 (2018).

Neural-network quantum state tomography

Giacomo Torlai, Guglielmo Mazzola, Juan Carrasquilla, Matthias Troyer, Roger Melko & Giuseppe Carleo✉

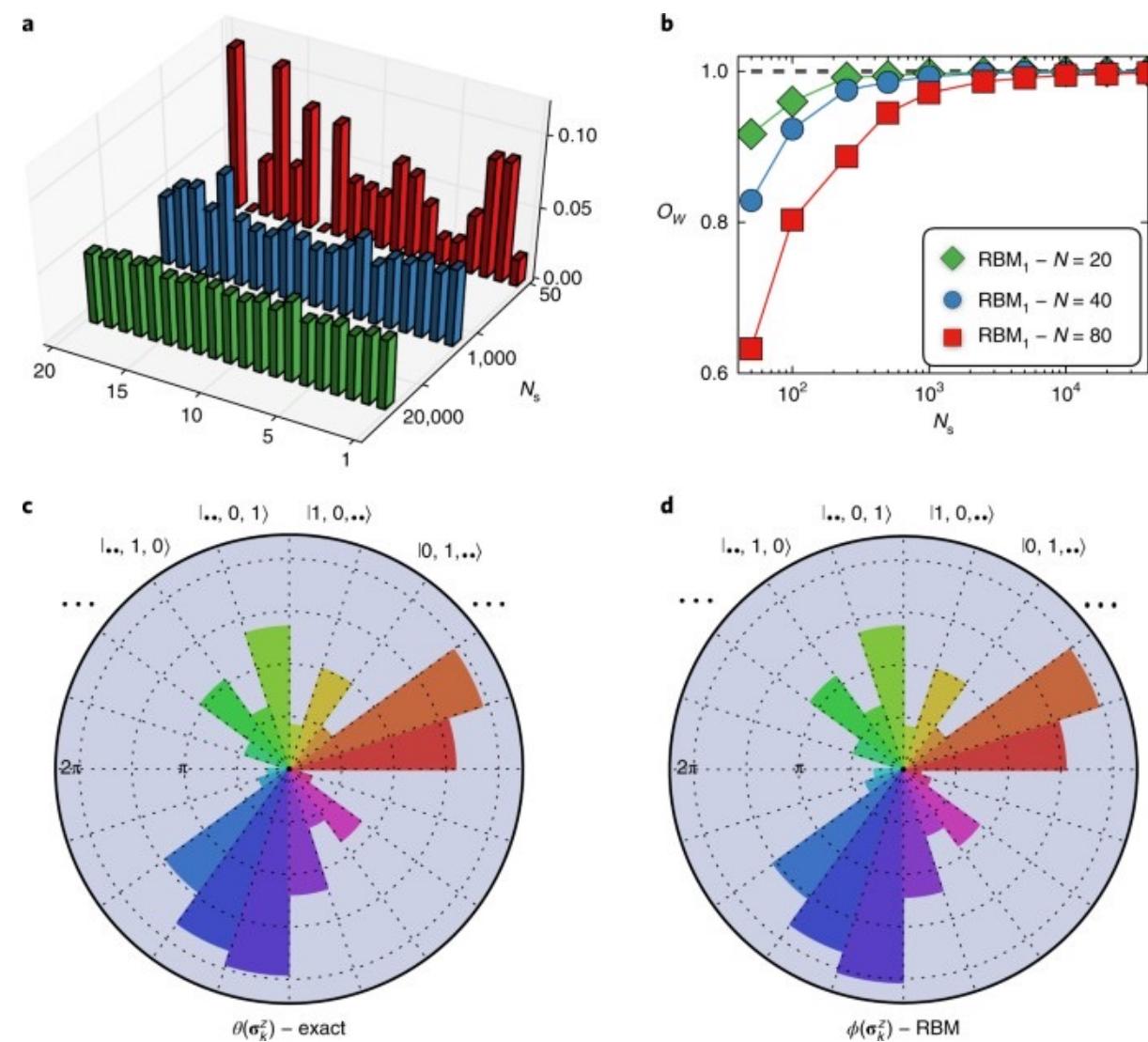
Target state:

$$|\Psi_W\rangle = \frac{1}{\sqrt{N}}(|100\dots\rangle + \dots + |\dots001\rangle)$$

Variational ansatz:

$$\psi_{\lambda,\mu}(\mathbf{x}) = \sqrt{\frac{p_\lambda(\mathbf{x})}{Z_\lambda}} e^{i\phi_\mu(\mathbf{x})/2}$$

relative phases



NNQST training: loss function

The probability distribution can be learnt from direct measurements.

But learning the relative phases requires measurements in rotated bases.

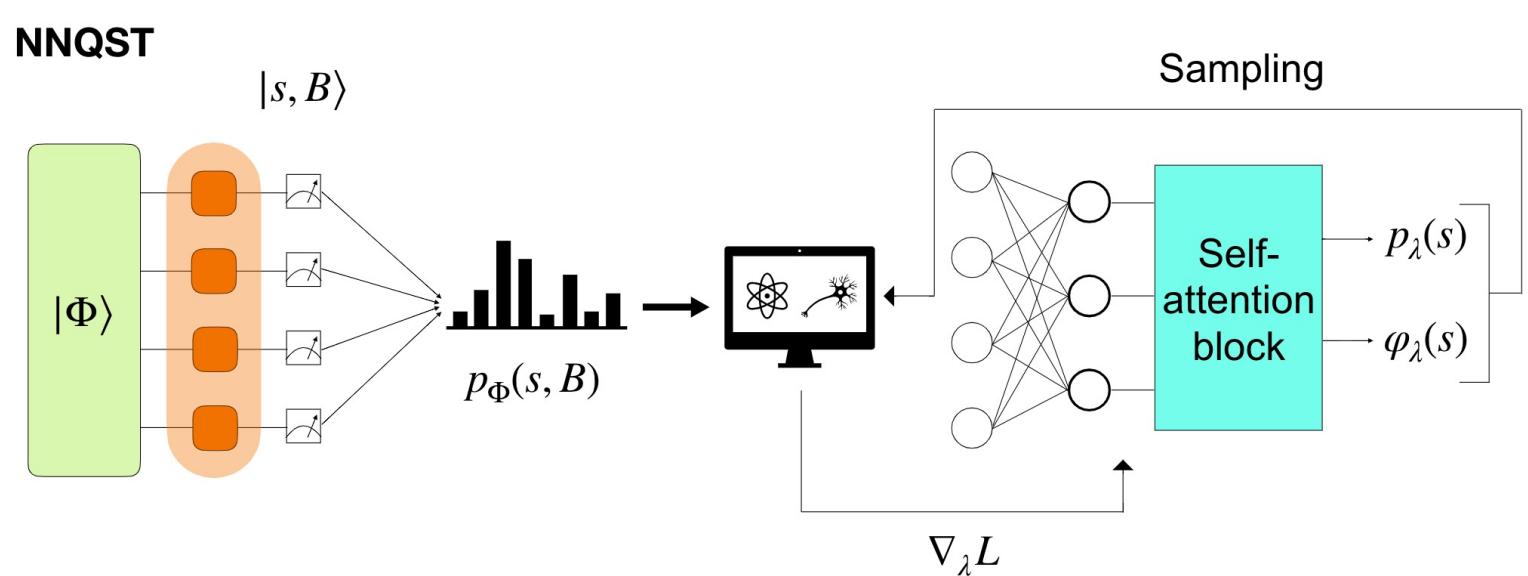
The training dataset consists of measurements over a set of Pauli bases $\{B\}$.



We have exponentially many Pauli bases to choose from, how?

$$L_\lambda \approx -\frac{1}{|\mathcal{D}_T|} \sum_{|s,B\rangle \in \mathcal{D}_T} \ln p_{\psi_\lambda}(s, B)$$

$$p_{\psi_\lambda}(s, B) = \left| \sum_{\substack{t \in \{0,1\}^n \\ \langle s, B | t \rangle \neq 0}} \langle s, B | t \rangle \langle t | \psi_\lambda \rangle \right|^2$$



NNQST training: choosing bases

Two important points:

1. The chosen set of bases should be “informationally complete”.

Ex. If the prepared state is the unique ground state of a known Hamiltonian, choose the Hamiltonian’s Pauli strings as bases.

2. The chosen bases should be “nearly diagonal”.

It means B should have few X or Y elements.

This is necessary for efficient classical post-processing, for evaluating $p_{\psi_\lambda}(s, B) = \left| \sum_{\substack{t \in \{0,1\}^n \\ \langle s, B | t \rangle \neq 0}} \langle s, B | t \rangle \langle t | \psi_\lambda \rangle \right|^2$

Ex. For the W state, Torlai *et al.* chose the following bases:

$$\{X, X, Z, Z, \dots\}, \{Z, X, X, Z, \dots\}, \{Z, Z, X, X, \dots\}$$

$$\{X, Y, Z, Z, \dots\}, \{Z, X, Y, Z, \dots\}, \{Z, Z, X, Y, \dots\}$$

NNQST prediction: Pauli observables and fidelity

1) For Pauli observables, we use the local estimator and collect samples from the neural network ansatz

$$\langle \mathcal{O}^{ND} \rangle = \sum_{\sigma} |\psi_{\lambda}(\sigma)|^2 \mathcal{O}_L(\sigma) \simeq \frac{1}{n} \sum_{k=1}^n \mathcal{O}_L(\sigma_k) \quad \mathcal{O}_L(\sigma) = \sum_{\sigma'} \sqrt{\frac{p_{\lambda}(\sigma')}{p_{\lambda}(\sigma)}} \mathcal{O}_{\sigma\sigma'}$$

The variance of this local estimator is a constant, independent of the system size or the observable weight (“weight” counts non-identity Pauli matrices in \mathcal{O}).

2) For fidelity to another state, we can also define an estimator as fraction of amplitudes, with constant variance.

Detailed proofs can be found in Havlicek, *Quantum* 7, 938 (2023).

NNQST prediction: Rényi-2 entropy

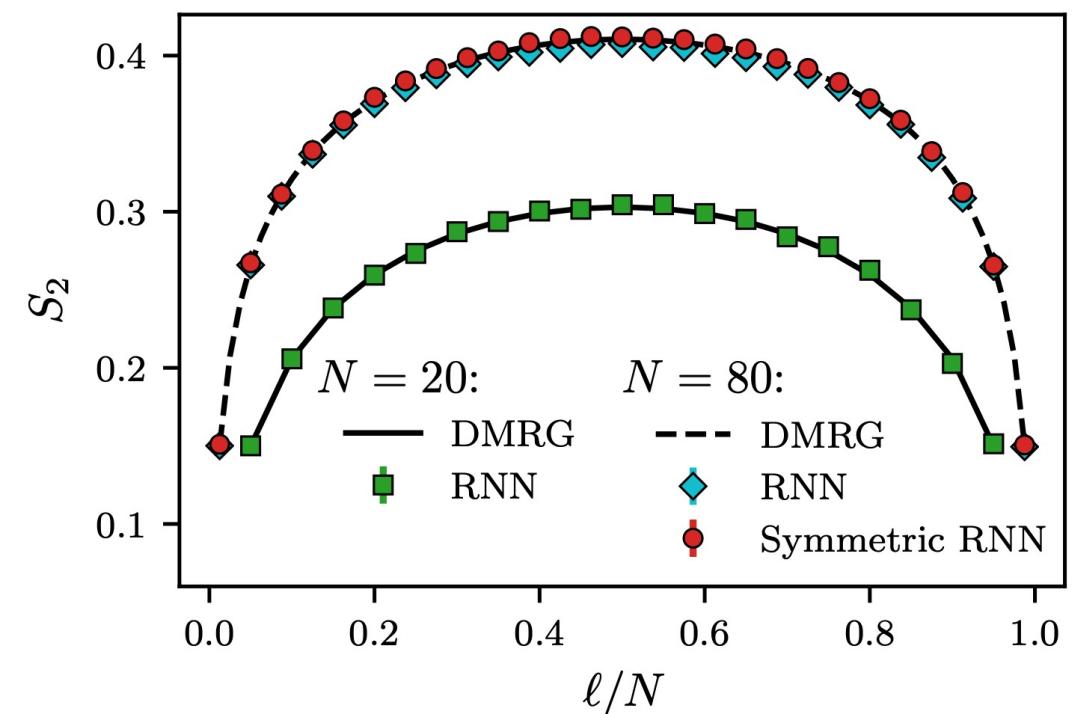
An important non-linear function of interest is Rényi-2 entropy.

$$S_\alpha(A) = \frac{1}{1-\alpha} \log (\mathrm{Tr} \rho_A^\alpha)$$

$$\begin{aligned} \langle \mathrm{Swap}_A \rangle &= \sum_{\sigma, \tilde{\sigma}} \psi_\lambda^*(\sigma_A \sigma_B) \psi_\lambda^*(\tilde{\sigma}_A \tilde{\sigma}_B) \psi_\lambda(\tilde{\sigma}_A \sigma_B) \psi_\lambda(\sigma_A \tilde{\sigma}_B) \\ &= \mathrm{Tr} \rho_A^2 = \exp[-S_2(A)]. \end{aligned}$$

Estimating Swap operator also has a bounded variance, independent of the subsystem size.

Leveraging the sampling advantage of autoregressive models, a figure from Hibat-Allah et al. *Phys. Rev. Research* **2**, 023358 (2020).



From NNQST (mixed state) to classical shadows

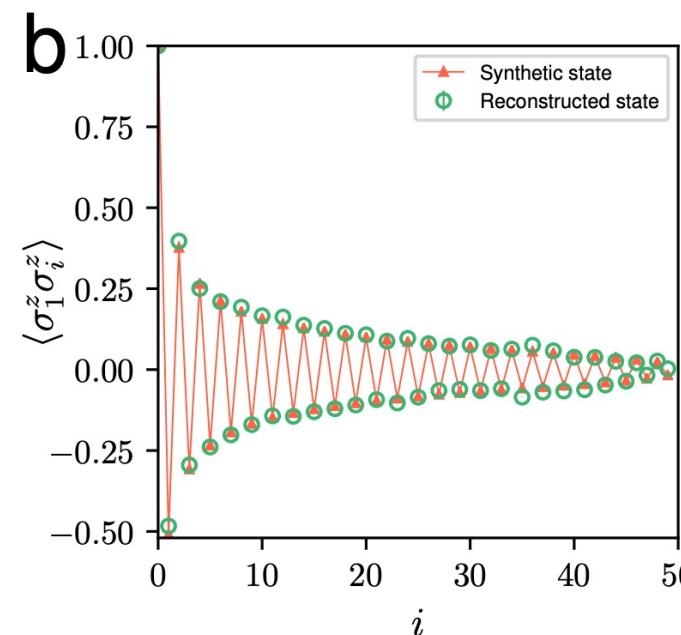
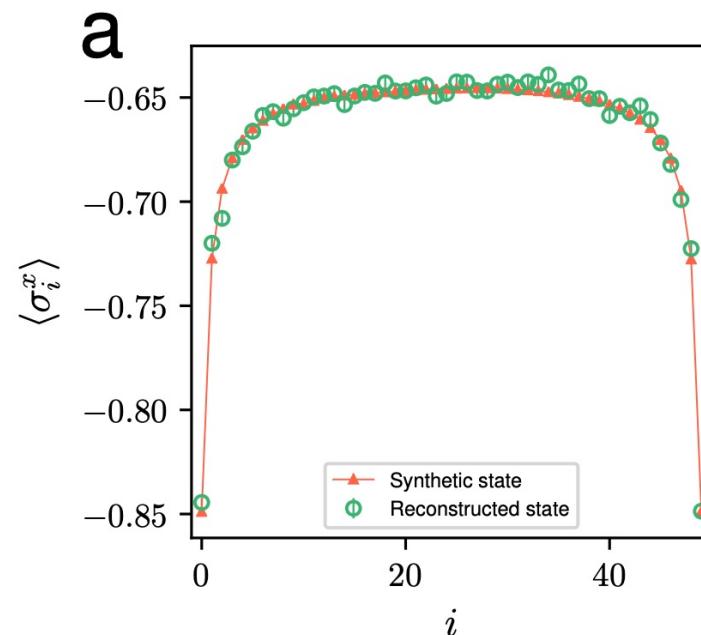
- Motivation: If it is hard to choose a set of informationally-complete bases, can we avoid basis selection by “pushing everything to a single probability distribution”?

Carrasquilla *et al.* *Nature Phys* **14**, 447–450 (2018).

Reconstructing quantum states with generative models

[Juan Carrasquilla](#)✉, [Giacomo Torlai](#), [Roger G. Melko](#) & [Leandro Aolita](#)

Answer is yes! For an informationally-complete POVM with invertible overlap matrix, one can push everything to a typical generative model, and predict observables using the known overlap matrix.

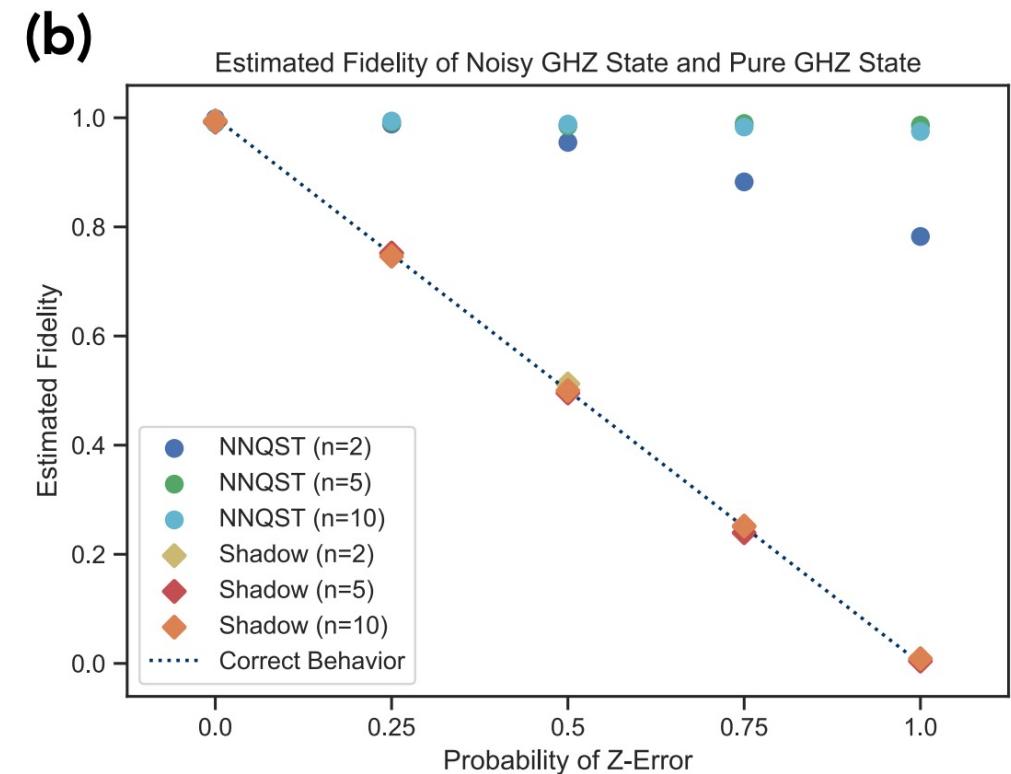


But...

- Unlike pure state ansatz, mixed state NNQST based on informationally-complete POVM has a hard time predicting non-local observables at large system size, such as fidelity to another state.
- Moreover, NNQST's classical fidelity does not reflect phase errors well even at small system sizes.
- To further explore the boundaries of tomography from a theoretical perspective, including the sample efficiency for different observables, classical shadow formalism was introduced.

Predicting many properties of a quantum system from very few measurements

[Hsin-Yuan Huang](#) , [Richard Kueng](#) & [John Preskill](#)



Huang *et al.* *Nature Phys* **16**, 1050–1057 (2020)

Classical shadow formalism

- Unlike **model-based** mixed state NNQST where the **inverse overlap matrix** is only used after a physical probability distribution has been learnt, classical shadow formalism inverts every **randomized** measurement snapshot using an analytically derived **inverted quantum channel**.

Classical shadow expression:

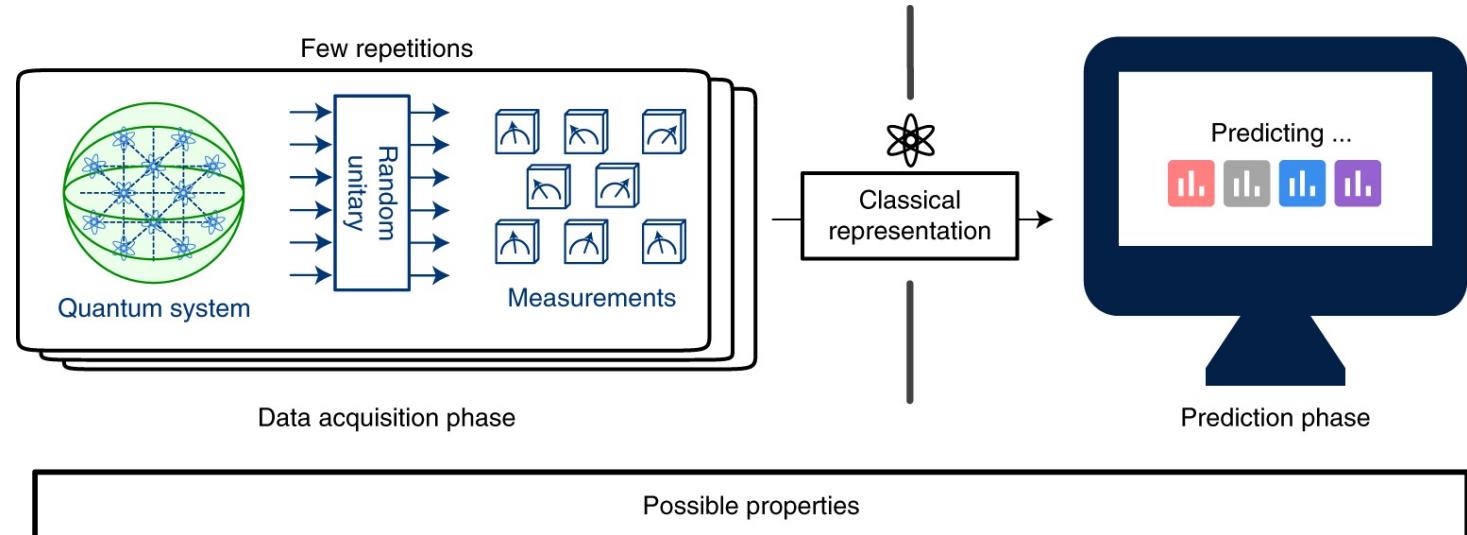
$$\hat{\rho} = \mathcal{M}^{-1} \left(U^\dagger |\hat{b}\rangle\langle\hat{b}|U \right)$$

Prediction:

$$\hat{o}_i = \text{tr} (O_i \hat{\rho}) \quad \text{obeys} \quad \mathbb{E} [\hat{o}] = \text{tr} (O_i \rho)$$

Variance bound (sample efficiency):

$$\text{Var} [\hat{o}] = \mathbb{E} \left[(\hat{o} - \mathbb{E} [\hat{o}])^2 \right] \leq \left\| O - \frac{\text{tr}(O)}{2^n} \mathbb{I} \right\|_{\text{shadow}}^2$$



Quantum fidelity



Entanglement witness



Entanglement entropy



Two-point correlations



Hamiltonian



Local observables

Classical shadow: Pauli and Clifford

- Pauli shadow:
 - 1) measure in randomized Pauli bases with few single qubit gates
 - 2) ideal for local Pauli observables, with variance bound $4^{\text{locality}(O)} \|O\|_\infty^2$
 - 3) efficient classical post-processing with Pauli observable
- Clifford shadow:
 - 1) measure in randomized Clifford bases with $O(n^2)$ entangling gates
 - 2) ideal for low-rank observables such as fidelity, with variance bound $3\text{tr}(O^2)$
 - 3) efficient classical post-processing with **only stabilizer states**

Non-linear functions:

Pauli shadows can be used efficiently predict Rényi-2 entropy with **small subsystem size**

* Neither Pauli or Clifford shadows are guaranteed to efficiently predict high-weight Pauli observables or Rényi-2 entropy of large subsystem size.

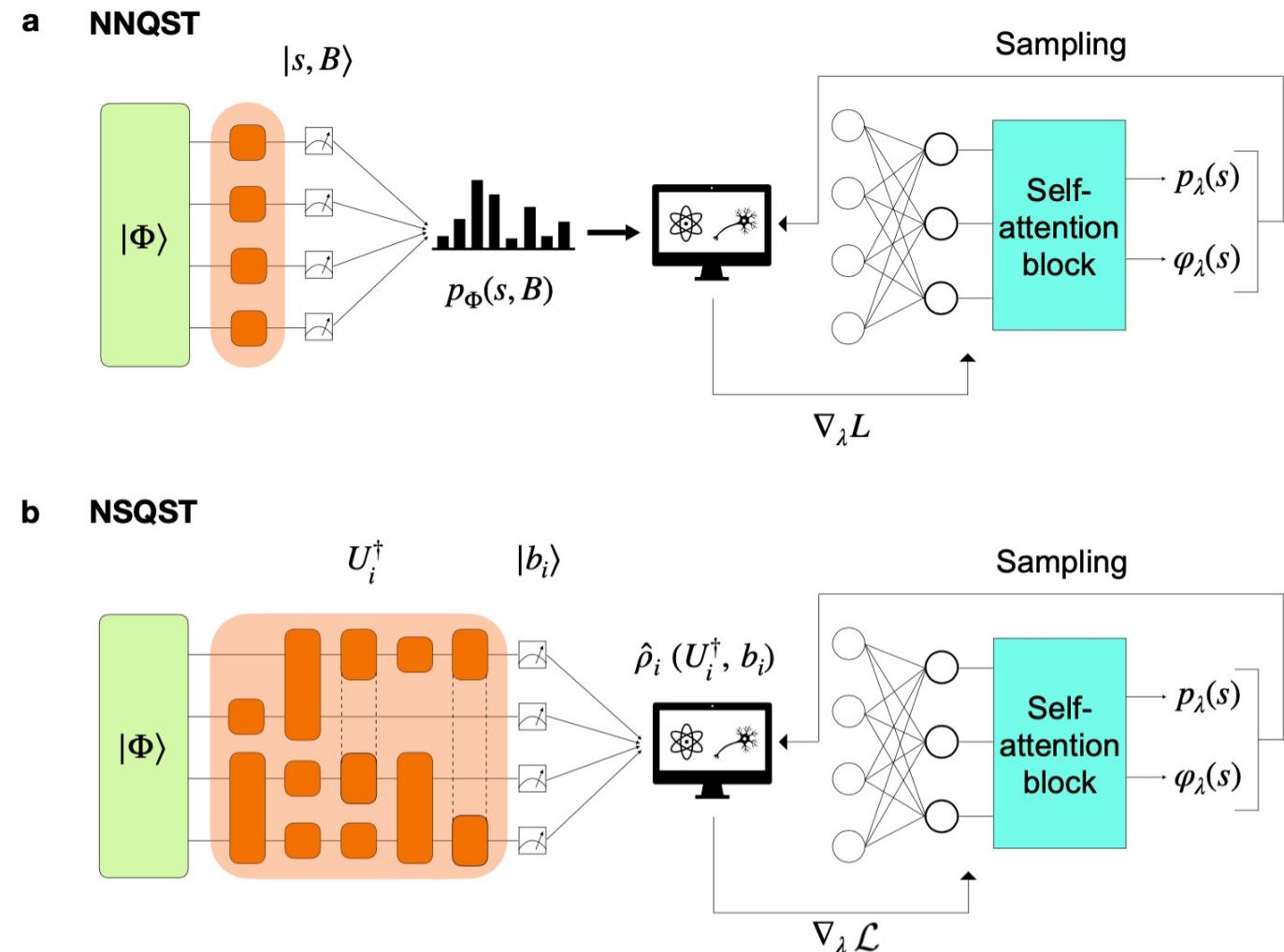
Combine NNQST and classical shadows?

Machine-learning Augmented Shadow Tomography (Part I)

Show affiliations

Cha, Peter ; Skaras, Tim ; Huang, Robert ; Carrasquilla, Juan ; McMahon, Peter ;
Kim, Eun-Ah

- I decided to approach it differently, train neural network quantum state with classical shadows.
- In particular, I used Clifford shadows as training data and an autoregressive model from Bennewitz et al. *Nat Mach Intell* 4, 618–624 (2022).



NSQST loss function

- We use an infidelity-based loss function, where the infidelity is approximated by a set of Clifford shadows.

$$\begin{aligned}\mathcal{L}_\lambda(\mathcal{E}) &:= 1 - |\langle \psi_\lambda | \Phi \rangle|^2 \\ &\approx 1 - \frac{1}{N} \sum_{i=1}^N \text{Tr}(O_\lambda \hat{\rho}_i) \\ &= 1 - \frac{1}{N} \sum_{i=1}^N \langle \psi_\lambda | \hat{\rho}_i(\mathcal{E}, U_i, b_i) | \psi_\lambda \rangle\end{aligned}$$

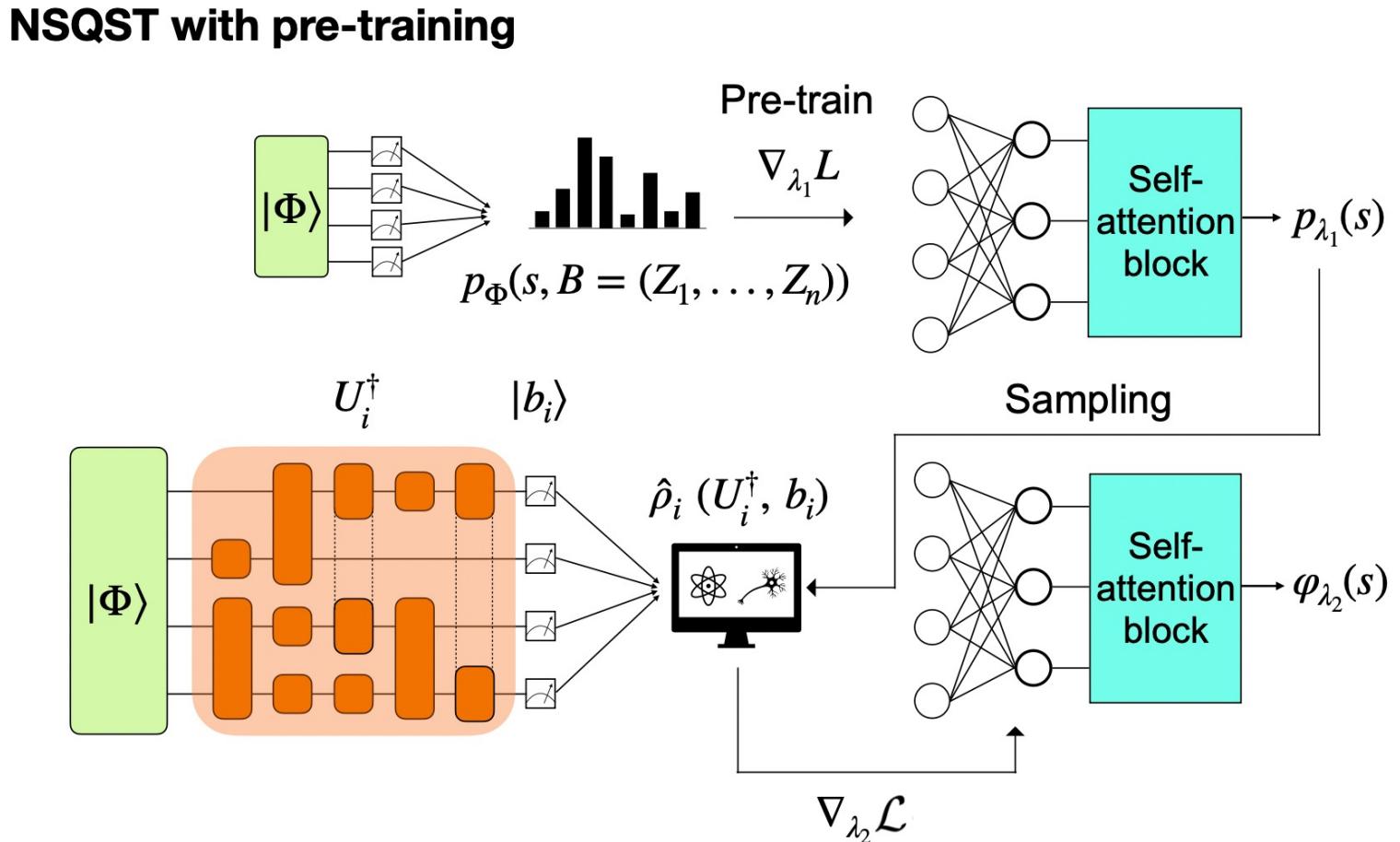
- In the noiseless case, the Clifford shadow takes the expression $\hat{\rho}_i(U_i, b_i) := \mathcal{M}^{-1}(|\phi_i\rangle\langle\phi_i|) = (2^n + 1)|\phi_i\rangle\langle\phi_i| - \mathbb{I}$

$$\mathcal{L}_\lambda(\mathbb{I}) \approx 2 - \frac{2^n + 1}{N} \sum_{i=1}^N |\langle \phi_i | \psi_\lambda \rangle|^2 \quad \longrightarrow \quad \text{Cannot be computed exactly when system size is large, one of Clifford shadow's classical post-processing issue...}$$

- Let's first approximate it using Monte Carlo method and try it on small systems. Just for now, a new set of Clifford shadows are measured in every iteration to avoid overfitting.

NSQST with pre-training

- Pre-train the probability distribution with direct measurements, then learn the relative phases with shadows.
- The pre-training step is about learning a physical probability distribution, beyond the information contained in the unphysical classical shadows.

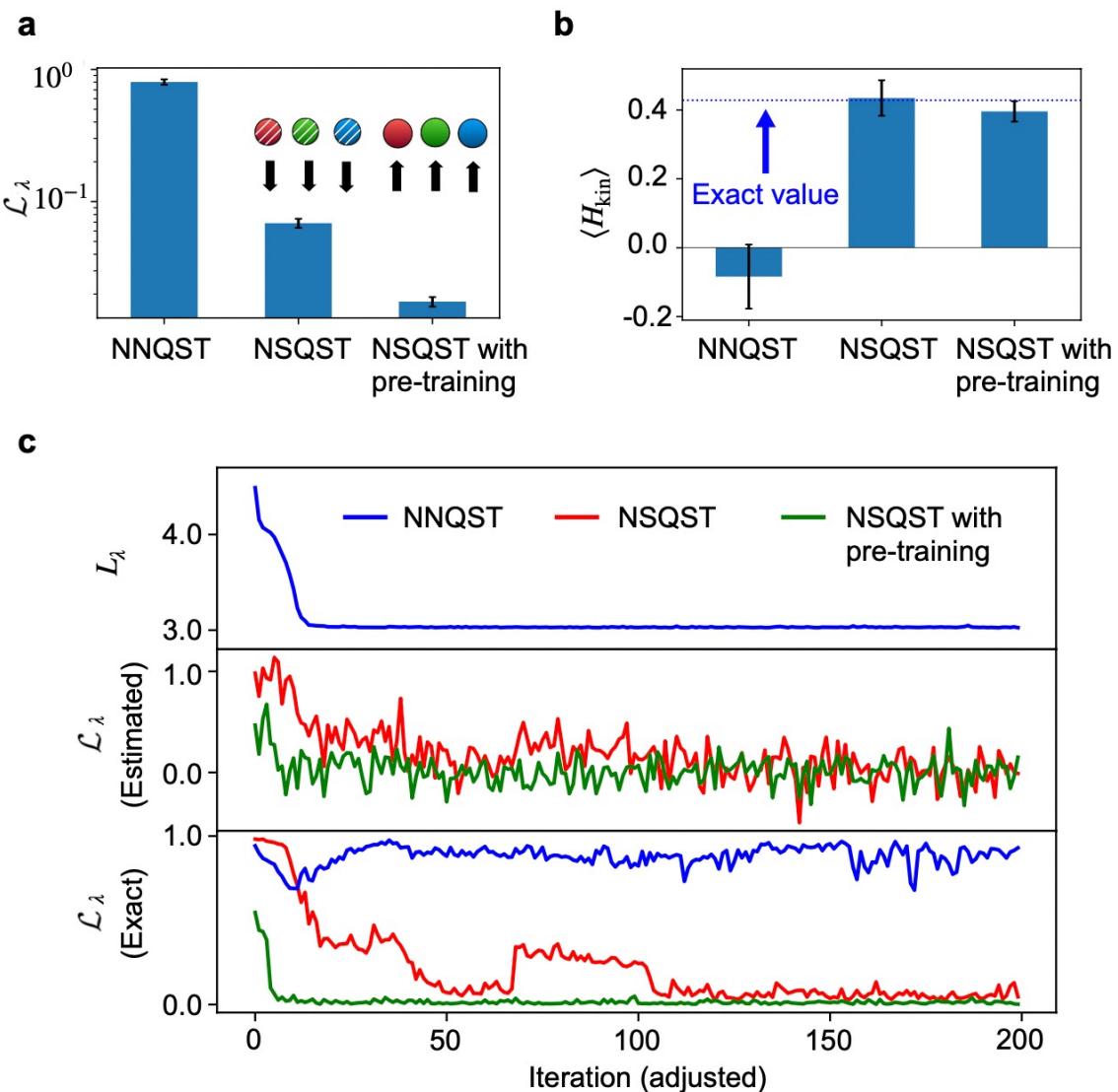


Advantages over NNQST for time-evolved states

- To find interesting examples beyond ground states, we chose a 6-qubit time-evolved state (after Trotterized time evolution).
- NNQST is trained on 21 nearly-diagonal measurement bases (512 shots per base).
- NSQST is trained on using 100 Clifford shadows per iteration.
- NSQST with pre-training, the pre-training stage uses NNQST's measurement resources, then trained using 100 Clifford shadows per iteration.

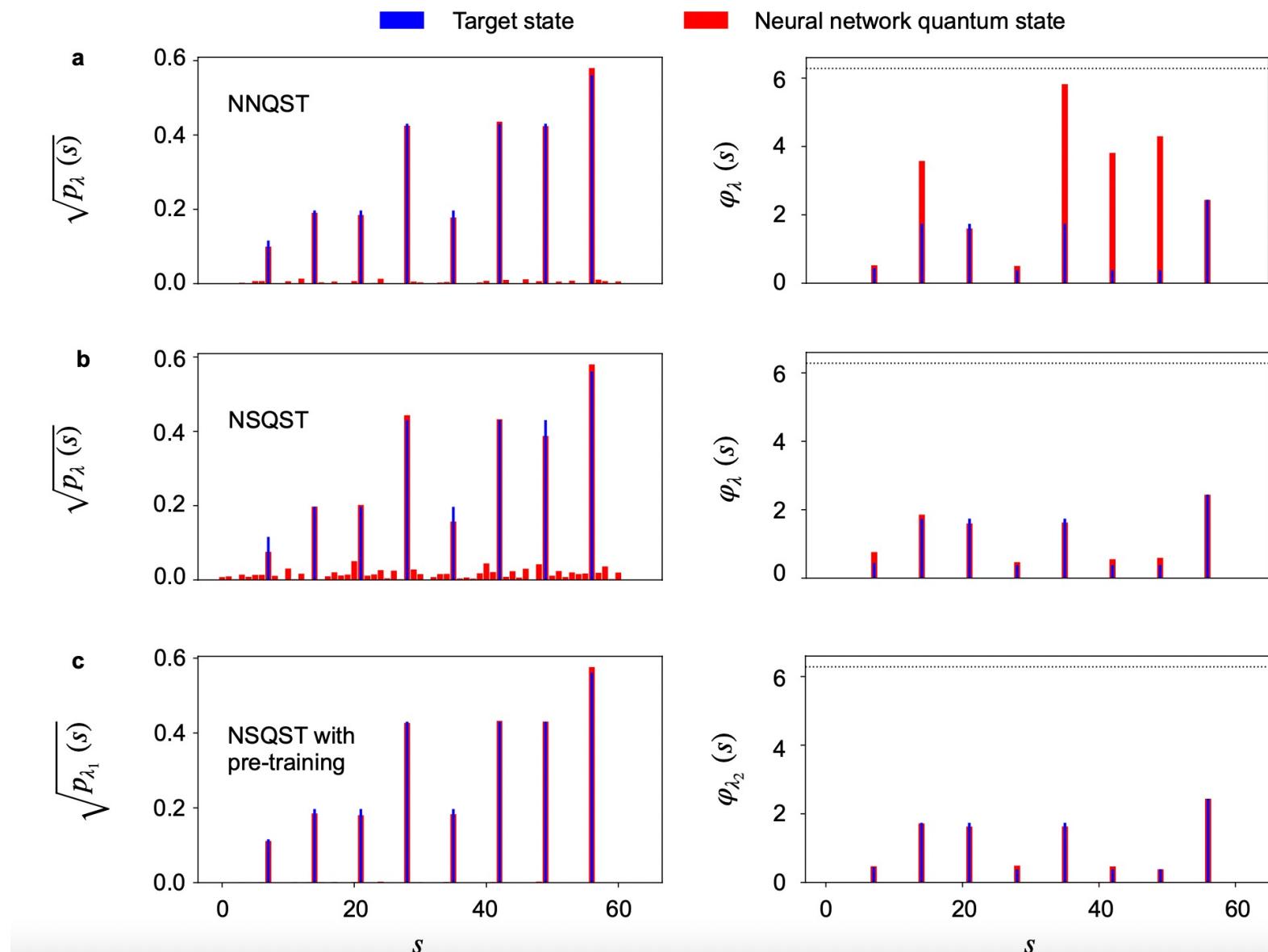
$$H_{kin} = -\frac{1}{2}(\sigma_1^+ \sigma_2^z \sigma_3^z \sigma_4^- - \sigma_2^+ \sigma_3^z \sigma_4^z \sigma_5^- + \sigma_3^+ \sigma_4^z \sigma_5^z \sigma_6^- + \text{H. c.})$$

Atas et al., Phys. Rev. Research 5, 033184 (2023).



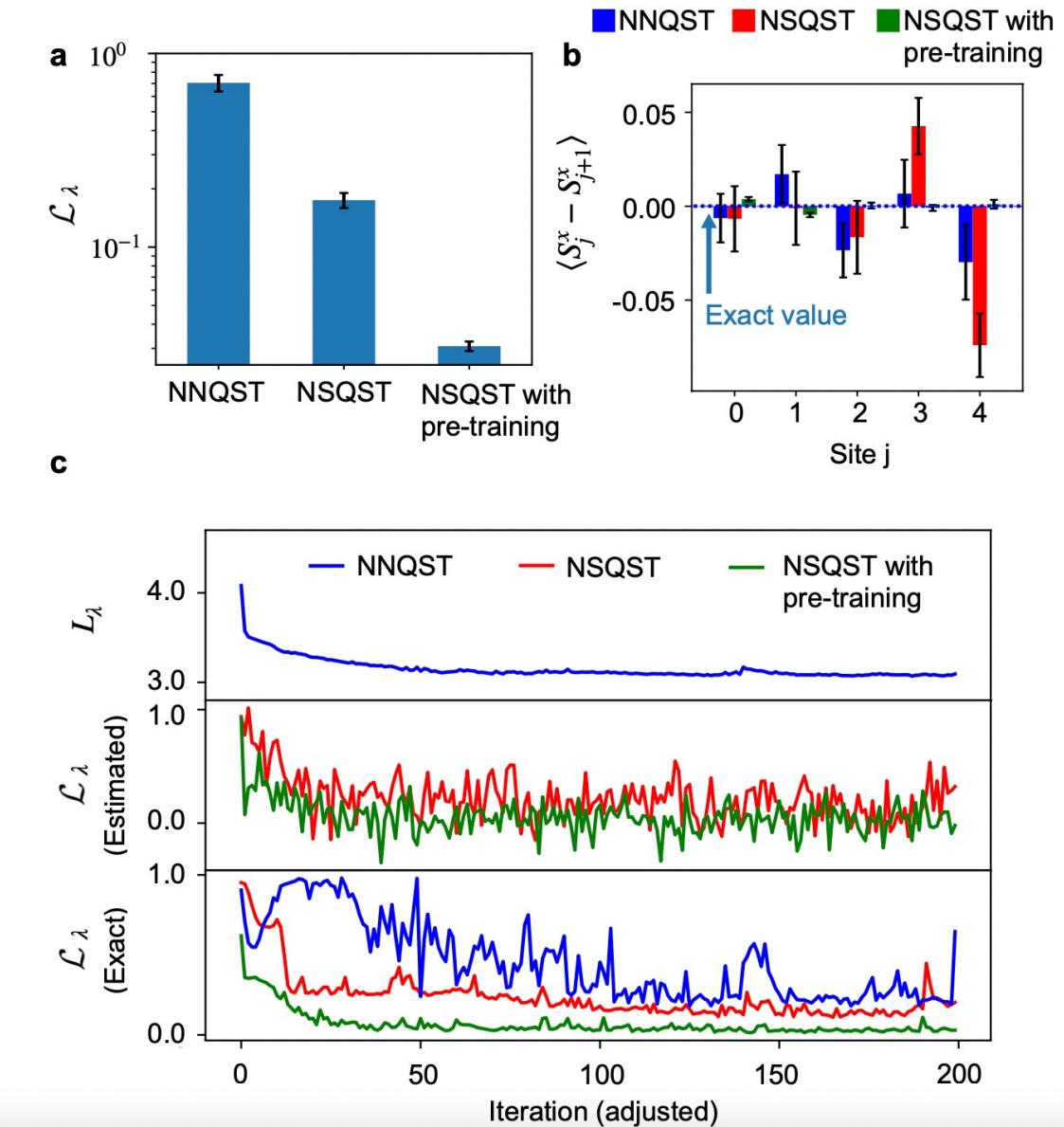
Why did NNQST fail?

- Relative phase are very important for predicting **non-diagonal** observables!
- The kinetic Hamiltonian is clearly non-diagonal, so incorrect relative phases will lead to incorrect observable prediction.



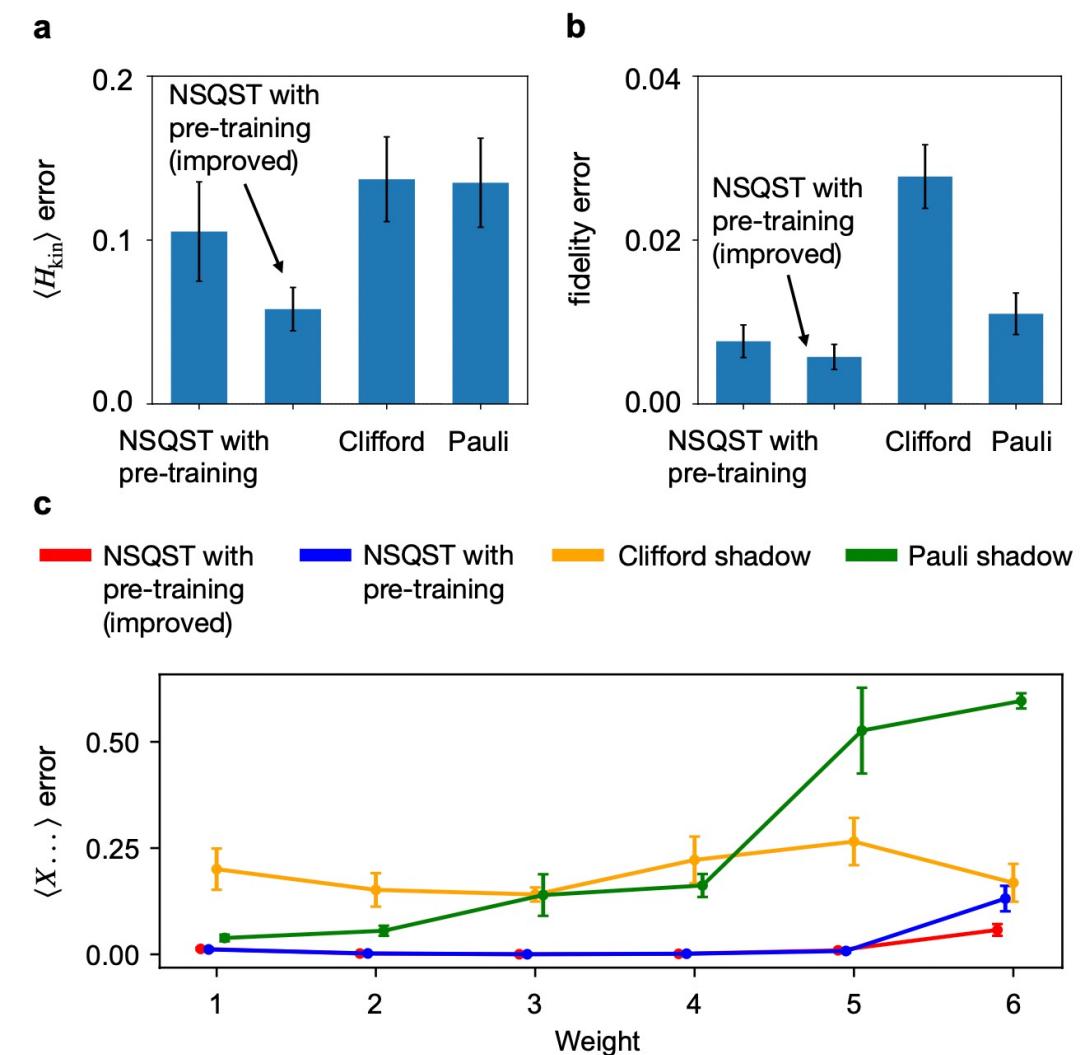
But...it still works for some local observables!

- Trotterized time evolution under one-dimensional antiferromagnetic Heisenberg (AFH) Hamiltonian.
- Despite having a higher final infidelity, NNQST does a good job predicting staggered magnetization, a **local but non-diagonal** observable.
- This is because staggered magnetization is a nearly-diagonal observable, just like NNQST's training data.
- So although NNQST did not reconstruct the target state well, it still does a good job at predicting observables related to the chosen training dataset.



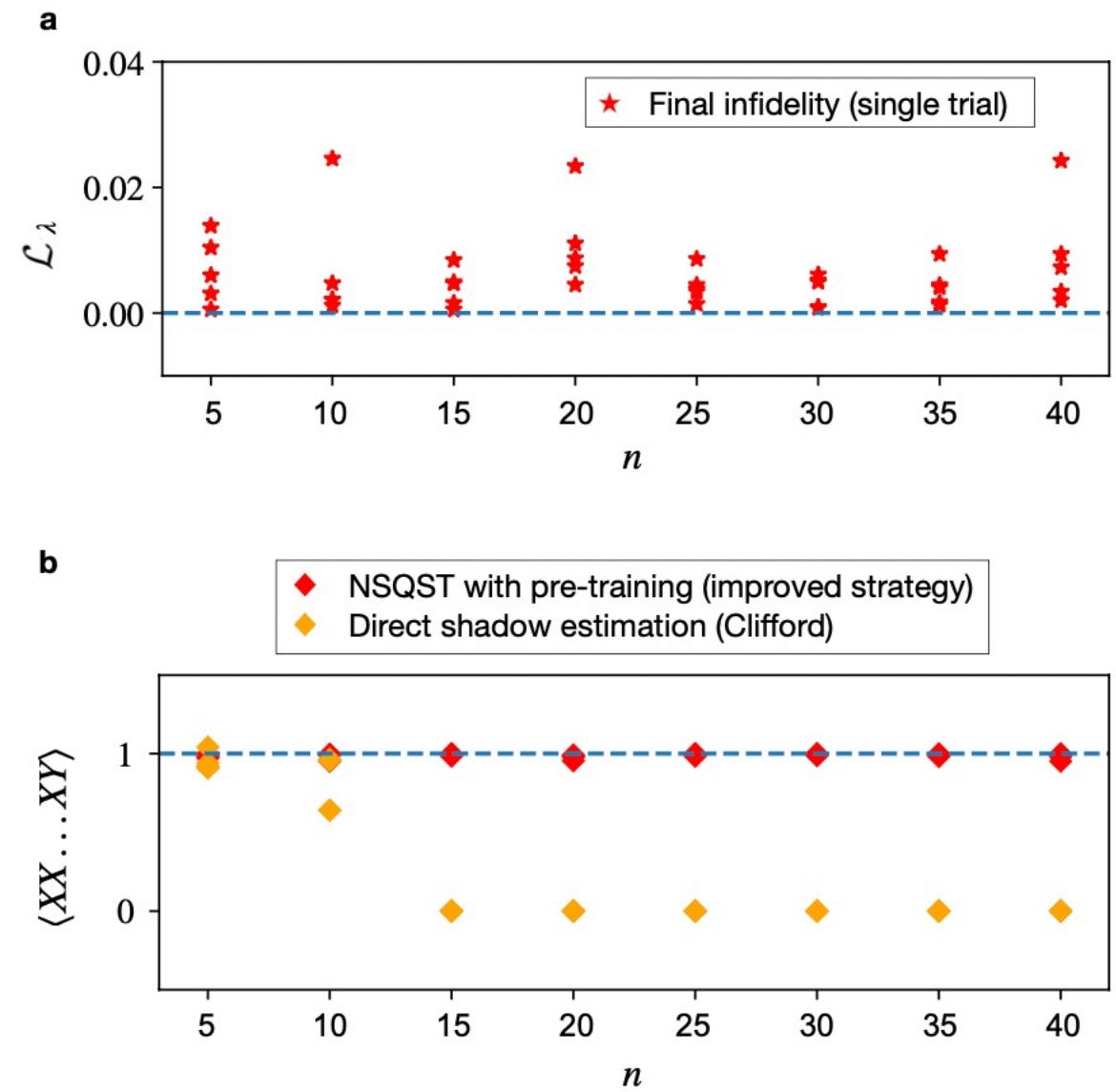
Advantages over direct shadow estimation (*new)

- Does NSQST offer any advantages over direct shadow estimation? In other words, does a model-based approach offer any advantages over using data alone?
- Starting with small system size (6 qubits), we make two changes to reduce the number of measurements for NSQST with pre-training:
 - 1) re-use the Clifford shadows instead of re-measure in every iteration.
 - 2) Although still intractable for general states, we reduce the classical post-processing error in the loss function.
- 1000 direct measurements + 200 Clifford shadows
- 1200 Clifford/Pauli shadows



Scalable advantage?

- For a phase-shifted (by $\pi/2$) GHZ state, we fix the number of measurements and check the final infidelity.
 - We also predict one of the target state's stabilizers, as system size grows.
-
- 3000 direct measurements + 200 Clifford shadows
 - 3200 Clifford shadows



Noise robustness

Going back to NSQST's loss function, if there is a noise channel **after** the Clifford unitary, we can simply modify the shadow expression to account for it. A stronger noise channel leads to larger variance in observable estimate.

The loss function is biased, unless we can estimate the strength of the noise channel with a calibration step.

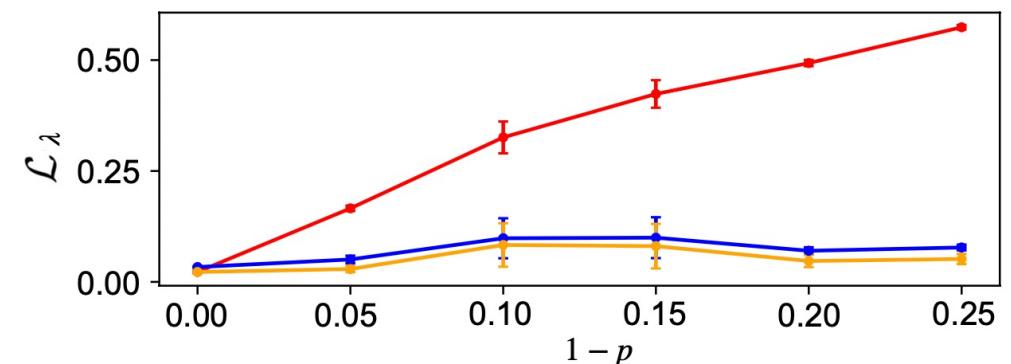
But! The gradient remains unbiased, even if we know nothing about the noise channel!

$$\begin{aligned}
 \mathcal{L}_\lambda(\mathcal{E}) &:= 1 - |\langle \psi_\lambda | \Phi \rangle|^2 \\
 &\approx 1 - \frac{1}{N} \sum_{i=1}^N \text{Tr}(O_\lambda \hat{\rho}_i) \\
 &= 1 - \frac{1}{N} \sum_{i=1}^N \langle \psi_\lambda | \hat{\rho}_i(\mathcal{E}, U_i, b_i) | \psi_\lambda \rangle \\
 &= 1 - \frac{1}{2^n} \left(1 - \frac{1}{f(\mathcal{E})} \right) - \frac{1}{N f(\mathcal{E})} \sum_{i=1}^N |\langle \phi_i | \psi_\lambda \rangle|^2
 \end{aligned}$$

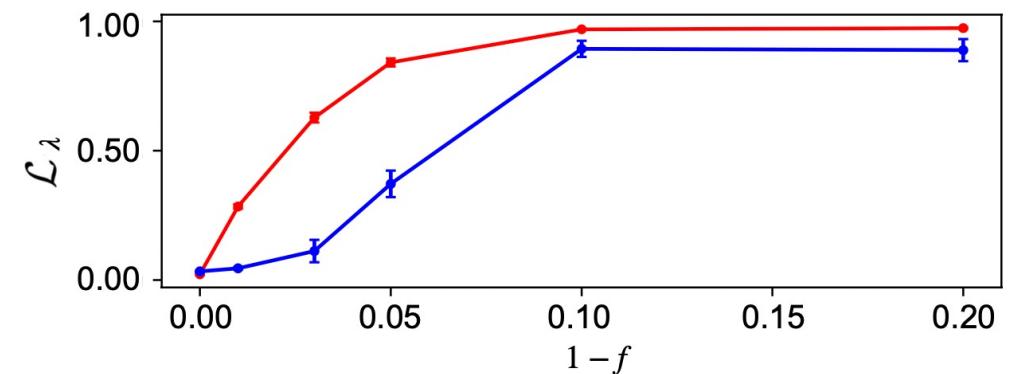
Koh and Grewal. *Quantum* 6:
776 (2022).

— Estimated infidelity
— Exact infidelity
— Transformed loss function

a Amplitude damping channel (applied after U_i)



b Local depolarizing channel (applied after each CNOT within U_i)



Future Prospects

1. Incorporate prior knowledge of the target state into the ansatz, such as symmetries.
2. Reduce classical post-processing problem with more constrained ansatz.
3. Explore new hybrid training strategies with model-based approach.
4. Use other types of randomized measurements.
5. Build a practical tool for experimentalists.
6. More and more...

Experimental feasibility: hardware-efficient shadows

So far, only Pauli shadows have been experimentally demonstrated, as no entangling gates are required.

A recent series of work explores the intermediate regime between Pauli and Clifford shadows.

Matrix product state methods are used to ensure efficient classical post-processing.

Hu et al. *Phys. Rev. Research* 5, 023027 (2023).

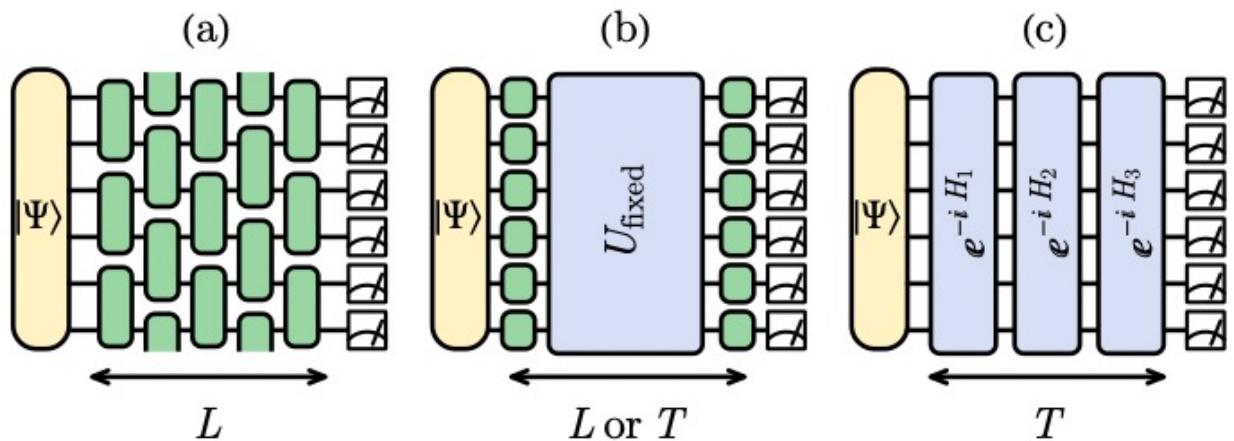
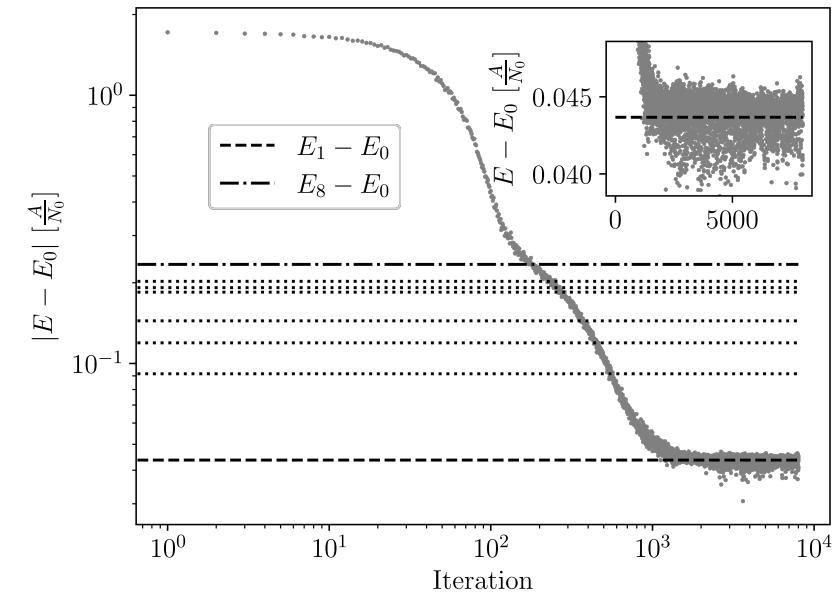
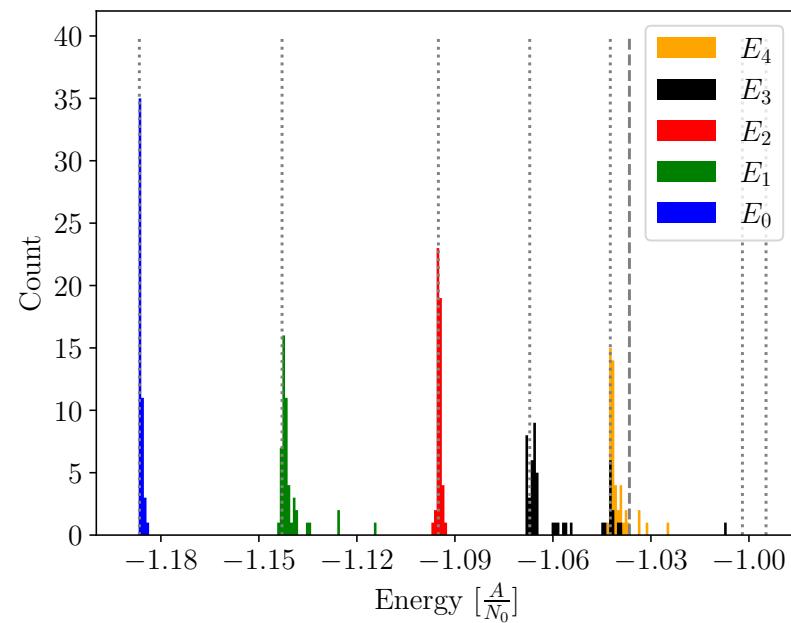


FIG. 3. Classical shadow tomography with (a) finite-depth random unitary/Clifford circuits (of L layers), (b) a fixed unitary twirled by single qubit random Clifford gates, and (c) discrete-time Hamiltonian dynamics (of T steps).

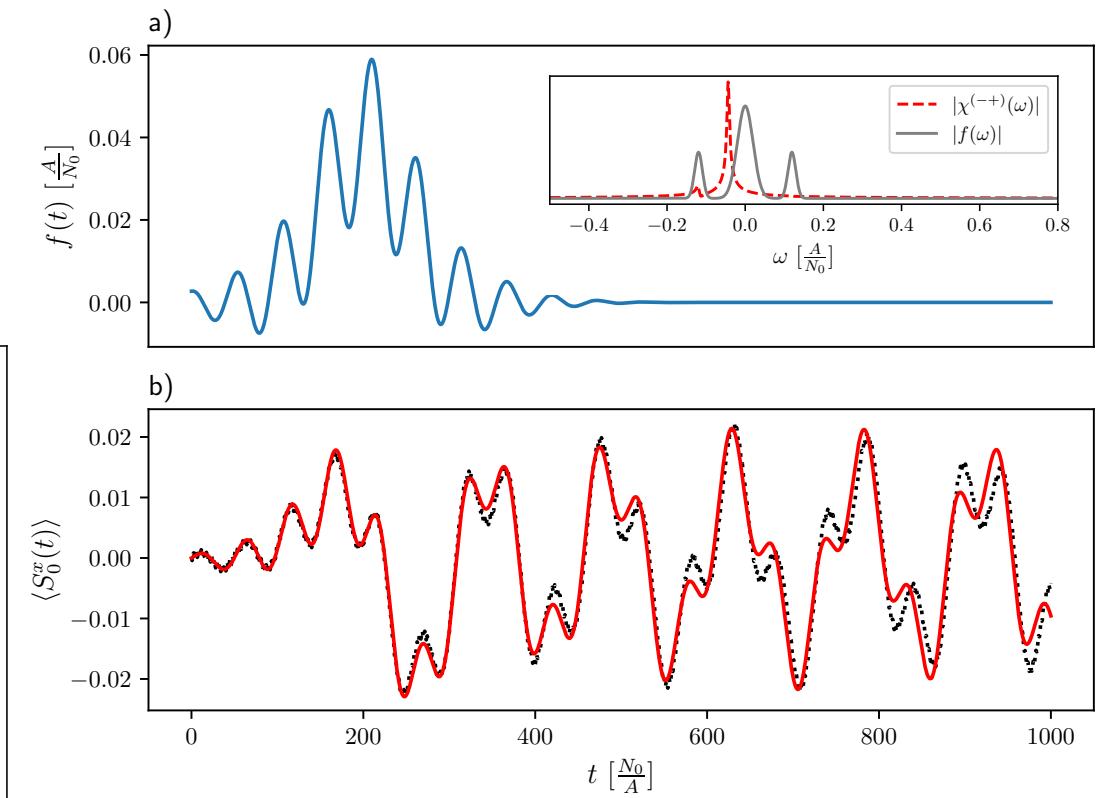
Ads: exploring excited states and low-lying dynamics



Wei et al. *Advanced Phys. Research* 2300078, (2023).



Code available and compatible with Netket utilities.



Acknowledgement



Prof. Bill Coish



Prof. Pooya Ronagh



Prof. Christine Muschik



Conferences

Machine Learning for Quantum Many-Body Systems, Perimeter Institute, Jun. 12th to Jun. 16th, 2023.

Coherent Quantum Dynamics, OIST, Sep. 26th to Oct. 5th, 2023.

