# Victor Aladele

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#### **EDUCATION**

Georgia Institute of Technology

Atlanta GA

PhD in Electrical Engineering

Aug 2016 - Present

Graduated

Dec 2022

Research focus

Robotics and Machine Learning

New Jersey Institute of Technology

 $Newark \,\, NJ$ 

B.S. in Electrical Engineering

May 2016

#### **PUBLICATIONS**

 $\bullet$  IEEE Conference on Decision and Control (CDC)

First author publication (2022)

 $\bullet$  IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)

Two first author publications (2020, 2021).

• International Symposium on Experimental Robotics (ISER)

Co-author publication (2018)

## TECHNICAL SKILLS

**Programming Languages** 

C++, Python

**Tools** 

Robot Operating System (ROS), Pytorch, Pybullet, Tensorflow

OpenAI gym, MATLAB, Gazebo, Blender, CUDA, Autodesk Inventor

#### WORK EXPERIENCE

Fox Robotics Austin TX

Senior Software Engineer

Aug 2022 - Present

· Developing motion planning and control algorithms for self-driving forklifts

Georgia Institute of Technology

 $Atlanta \ GA$ 

Graduate Research Assistant

Aug 2016 - Present

· PhD Advisor: Seth Hutchinson, PhD

 $\cdot \ \ {\rm Dissertation \ Title:} \ \ {\it Cooperative \ manipulation \ strategies \ for \ multi-robot \ and \ human-robot \ collaboration}$ 

## Royal Institute of Technology (KTH)

Stockholm, Sweden

Visiting PhD Student

Aug 2021 - Jan 2022

- · Host Advisor: Danica Kragic Jensfelt, PhD
- · Designed a novel application of residual reinforcement learning to cooperative manipulation. Tools used include: Pybullet, Stable-baselines, OpenAI gym

## Google (Brain/Research)

Remote / Mountain View CA

Research Intern

May 2021 - August 2021

- · Worked on developing reinforcement learning solutions for high-speed robotics.
- · Developed and implemented curriculum learning algorithms to improve robot learning.

Blue River Technology (A John Deere Subsidiary)

Remote / Sunnyvale CA May 2020 - Aug 2020

Software Engineering Intern

- · Worked on a team to develop software for cutting-edge John Deere machinery
- · Tools and frameworks used include: C++17, CUDA, Flatbuffers, Protocol buffers, Google Test, Jira.

# Bosch (Advanced Corporate Research), BSH Home Appliances

 $Sunnyvale\ CA$ 

Robotics Software Intern

May 2019 - Aug 2019

- · Worked on implementing impedance control on a 6 DOF robotic arm for object insertion tasks.
- · Tools used include: C++, Python, ROS, Rigidbody Dynamics Library (RBDL), Gazebo, Kinova arm.

# Massachusetts Institute of Technology

Cambridge MA

Research Intern

June 2015 - Aug 2015

· Advisors: Daniela Rus PhD, Robert MacCurdy, PhD

CSAIL

· Designed and 3D printed gear pumps for hydraulically actuated robots; worked with Autodesk Inventor.

## RESEARCH PROJECTS

## Cooperative Mobile Manipulation

August 2019 - Present

Working both in simulation and on hardware

- · Developing deep reinforcement learning schemes for multi-robot collaboration.
- · Using TrajOpt for motion planning on a single-arm pick-and-place task.
- · Applying adaptive control for dual-arm disturbance rejection.
- · Implementing operational space control on KUKA IIWA7 arms that are mounted on mobile bases.
- · Applying Gaussian Processes as a semi-parametric control approach for a 7DOF manipulator.
- · Working in Gazebo, Pybullet, Matlab/Simulink and Drake.

#### **CLASS PROJECTS**

## Robot Intelligence and Planning

Fall 2020

- · Implemented a version of DeepMind's AlphaZero chess AI. Used Deep Reinforcement Learning in conjunction with Monte-Carlo Tree Search to train a deep neural network to play the game of chess. Tools used include: Python, Pytorch, cuda.
- · Implemented deep reinforcement learning algorithms like: DQN, REINFORCE and A2C.
- · Implemented Rapidly-exploring Random Trees (RRT) to navigate a 2D map. Algorithm implementation included steering dynamics with nonlinear optimization and obstacle detection.

Computer Vision Fall 2020

- · Image classification using deep learning framework; transfer learning with CNNs like Alexnet.
- · Object detection with limited training data; applied transfer learning in Pytorch.

## **Advanced Programming Techniques**

Fall 2019

- · Used OpenGL to simulate bitmapped images and created a distributed MPI program.
- · Designed a UDP server-client program.

## HONORS, AWARDS AND SOCIETIES

· Tau Beta Pi Honors Society, Member

Aug 2014 - Present

· Institute of Electrical and Electronic Engineering, Member

Aug 2013 - Present

**EXTRACURRICULAR ACTIVITIES** 

- · Annually review applications for the undergraduate summer research program at MIT. 2018 present
- · Co-chaired the "Multi-Robot Systems I" session at the IROS 2021 conference. September 2021
- · Reviewed papers for publication at the following conferences: IROS(2020, 2021), ICRA(2021).
- · Worked with Atlanta Public School teachers to develop March 2021 a project-based learning (PBL) component of the Algebra II curriculum.