1 Force model

So far we have only considered the gravitational force acting between point masses. In reality, the Earth is not a point mass, neither a spherically symmetric mass distribution. In this section we will deep into the details of a more realistic model of the Earth's gravitational field.

1.1 Geopotential model

1.1.1 Continuous distribution of mass

In ?? we have seen that the motion of a body orbiting another one can be described by a conic section. However, we have not been concerned about the mass distribution of the large body, in our case the Earth. In this section we will see that the motion of the smaller body, the satellite, is slightly perturbed by the mass distribution of the Earth as well as the precense of other forces such as atmospheric drag, solar radiation pressure, and the gravitational pull of the Moon and Sun, which we wil talk later on. Even though, the perturbations are relatively small and the orbits of the satellites are still approximating ellipses.

Consider a body confined in a compact region $\Omega \subseteq \mathbb{R}$ with a continuous density of mass $\rho: \Omega \to \mathbb{R}$. We would like to know the gravitational pull on a point mass m located at position \mathbf{r} from the center of mass of the body. To do this we can discretize the body Ω in a set of cubes $m_{i,j,k}$ each of volume $\frac{1}{n_x n_y n_z}$ and density $\rho(\frac{i}{n_x}, \frac{j}{n_y}, \frac{k}{n_z}) =: \rho_{i,j,k}$, where n_x , n_y , and n_z are the number of cubes in the x, y, and z directions, respectively. The total gravitational acceleration \mathbf{g} exerted on m is the sum of the contributions of all the forces exected by the cubes (considered as point masses) and it is given by:

$$\mathbf{g} = -\sum_{i=0}^{n_x} \sum_{j=0}^{n_y} \sum_{k=0}^{n_z} \frac{m_{i,j,k}}{\|\mathbf{r} - \mathbf{s}_{i,j,k}\|^3} (\mathbf{r} - \mathbf{s}_{i,j,k}) = -\sum_{i=0}^{n_x} \sum_{j=0}^{n_y} \sum_{k=0}^{n_z} \frac{\rho_{i,j,k}}{\|\mathbf{r} - \mathbf{s}_{i,j,k}\|^3} (\mathbf{r} - \mathbf{s}_{i,j,k}) \frac{1}{n_x n_y n_z}$$
(1)

where $\mathbf{s}_{i,j,k}=(\frac{i}{n_x},\frac{j}{n_y},\frac{k}{n_z})$ (in cartesian coordinates). Note that Eq. (1) is a Riemann sum and so letting $n_x,n_y,n_z\to\infty$ we get:

$$\mathbf{g} = -\int_{\Omega} \frac{\rho(\mathbf{s})}{\|\mathbf{r} - \mathbf{s}\|^3} (\mathbf{r} - \mathbf{s}) d^3 \mathbf{s}$$
 (2)

where $d^3\mathbf{s} := dx' dy' dz'$, if $\mathbf{s} = (x', y', z')$.

Theorem 1. Let Ω be a compact region in \mathbb{R}^3 with a continuous density of mass $\rho: \Omega \to \mathbb{R}$. Then, the gravitational acceleration field \mathbf{g} is conservative. That is, there exists a function $f: \mathbb{R}^3 \to \mathbb{R}$ such that $\mathbf{g} = \nabla f$.

Proof. An easy computation shows that fixed $\mathbf{s} \in \mathbb{R}^3$ we have:

$$\nabla \left(\frac{1}{\|\mathbf{r} - \mathbf{s}\|} \right) = -\frac{1}{\|\mathbf{r} - \mathbf{s}\|^3} (\mathbf{r} - \mathbf{s})$$
(3)

So we need to justify if the following exchange of the gradient and the integral is correct:

$$\mathbf{g} = -\int_{\Omega} \frac{\rho(\mathbf{s})}{\|\mathbf{r} - \mathbf{s}\|^3} (\mathbf{r} - \mathbf{s}) d^3 \mathbf{s} = \int_{\Omega} \rho(\mathbf{s}) \nabla \left(\frac{1}{\|\mathbf{r} - \mathbf{s}\|} \right) d^3 \mathbf{s} = \nabla \int_{\Omega} \frac{\rho(\mathbf{s})}{\|\mathbf{r} - \mathbf{s}\|} d^3 \mathbf{s}$$
(4)

Without loss of generality it suffices to justify that

$$\frac{\partial}{\partial x} \int_{\Omega} \frac{\rho(\mathbf{s})}{\|\mathbf{r} - \mathbf{s}\|} d^3 \mathbf{s} = \int_{\Omega} \frac{\partial}{\partial x} \left(\frac{\rho(\mathbf{s})}{\|\mathbf{r} - \mathbf{s}\|} \right) d^3 \mathbf{s}$$
 (5)

assuming $\mathbf{r}=(x,y,z)$ and $\mathbf{s}=(x',y',z')$. In order to apply the theorem of derivation under the integral sign we need to control $\frac{\partial}{\partial x}\left(\frac{\rho(\mathbf{s})}{\|\mathbf{r}-\mathbf{s}\|}\right)=-\rho(\mathbf{s})\frac{x-x'}{\|\mathbf{r}-\mathbf{s}\|^3}$ by an integrable function $h(\mathbf{s})$. Using spherical coordinates centered at \mathbf{r} and writing $(\mathbf{r}-\mathbf{s})_{\mathrm{sph}}=(\rho_{\mathbf{r}},\theta,\phi)$, the integrand to bound becomes (in spherical coordinates):

$$\left| -\rho(\mathbf{s}) \frac{x - x'}{\|\mathbf{r} - \mathbf{s}\|^3} \rho_{\mathbf{r}}^2 \sin \phi \right| = |\rho(\mathbf{s})| \left| \frac{\rho_{\mathbf{r}} \cos \theta \sin \phi}{\rho_{\mathbf{r}}^3} \rho_{\mathbf{r}}^2 \sin \phi \right| \le |\rho(\mathbf{s})| \le K$$
 (6)

where the last inequality follows for certain $K \in \mathbb{R}$ by Weierstraß theorem (ρ is continuous and Ω is compact). Thus, since $h(\mathbf{s}) = K$ is integrable, because Ω is bounded, the equality of Eq. (5) is licit. \square

Physically speaking, the gravitational force \mathbf{F} being conservative means that the work W done by the force along a path C

$$W = \int_{C} \mathbf{F} \cdot d\mathbf{s} \tag{7}$$

depends only on the initial and final positions of it. Moreover, due to historical reasons, we will write $\mathbf{g} = -\nabla V$ (with the minus sign) and call V the gravitational potential. The minus sign is chosen according the convention that work done by gravitational forces decreases the potential.

1.1.2 Laplace equation for V

Theorem 2. Consider a distribution of matter of density ρ in a compact region Ω . Then, the gravitational potential V satisfies the Laplace equation

$$\Delta V = 0 \tag{8}$$

for all points outside Ω^1 .

Proof. Recall that $\Delta V = \operatorname{\mathbf{div}}(\nabla V)$. So since $\mathbf{g} = -\nabla V$ it suffices to prove that $\operatorname{\mathbf{div}}(\mathbf{g}) = 0$. Note that if $\mathbf{r} \in \Omega^c$ and $\mathbf{s} \in \Omega$ then $\|\mathbf{r} - \mathbf{s}\| \ge \delta > 0$, so $\frac{\mathbf{r} - \mathbf{s}}{\|\mathbf{r} - \mathbf{s}\|^3}$ is differentiable and:

$$\mathbf{div}\left(\frac{\mathbf{r} - \mathbf{s}}{\|\mathbf{r} - \mathbf{s}\|^{3}}\right) = \frac{\partial}{\partial x}\left(\frac{x - x'}{\|\mathbf{r} - \mathbf{s}\|^{3}}\right) + \frac{\partial}{\partial y}\left(\frac{y - y'}{\|\mathbf{r} - \mathbf{s}\|^{3}}\right) + \frac{\partial}{\partial z}\left(\frac{z - z'}{\|\mathbf{r} - \mathbf{s}\|^{3}}\right) =$$

$$= \frac{\|\mathbf{r} - \mathbf{s}\|^{2} - 3(x - x')^{2}}{\|\mathbf{r} - \mathbf{s}\|^{5}} + \frac{\|\mathbf{r} - \mathbf{s}\|^{2} - 3(y - y')^{2}}{\|\mathbf{r} - \mathbf{s}\|^{5}} + \frac{\|\mathbf{r} - \mathbf{s}\|^{2} - 3(z - z')^{2}}{\|\mathbf{r} - \mathbf{s}\|^{5}} = 0$$

Hence, as in Theorem 1, we have that for each $\mathbf{r} \in \Omega^c \exists \varepsilon, \delta > 0$ such that $\forall \tilde{\mathbf{r}} \in B(\mathbf{r}, \varepsilon) \subset \Omega^c$ we have:

$$\left| \rho(\mathbf{s}) \frac{\|\tilde{\mathbf{r}} - \mathbf{s}\|^2 - 3(\tilde{x} - x')^2}{\|\tilde{\mathbf{r}} - \mathbf{s}\|^5} \right| \le \frac{4|\rho(\mathbf{s})|}{\|\tilde{\mathbf{r}} - \mathbf{s}\|^3} \le \frac{4|\rho(\mathbf{s})|}{\delta^3}$$

which is integrable by Weierstraß theorem. Thus, by the theorem of derivation under the integral sign:

$$\mathbf{div}(\mathbf{g}) = -\mathbf{div} \int_{\Omega} \frac{\rho(\mathbf{s})}{\|\mathbf{r} - \mathbf{s}\|^3} (\mathbf{r} - \mathbf{s}) d^3 \mathbf{s} = -\int_{\Omega} \rho(\mathbf{s}) \, \mathbf{div} \left(\frac{\mathbf{r} - \mathbf{s}}{\|\mathbf{r} - \mathbf{s}\|^3} \right) d^3 \mathbf{s} = 0$$
 (9)

So far we have seen that the gravitational potential V satisfies the Laplace equation. If moreover we choose the origin of potential to be at the infinity, that is, if we impose $\lim_{\|\mathbf{r}\|\to\infty}V=0$, then the gravitational

potential created by a distribution of mass in a compact region Ω is a solution of the following exterior Dirichlet problem:

$$\begin{cases} \Delta V = 0 & \text{in } \Omega^c \\ V = f & \text{on } \partial \Omega \\ \lim_{\|\mathbf{r}\| \to \infty} V = 0 \end{cases}$$
 (10)

If Ω represents the Earth, then $f = f(\theta, \phi)$ is the boundary condition concerning the gravitational potential at the surface of the Earth as a function of the longitude θ and colatitude ϕ .

We will see now that Eq. (10) has a unique solution. To do that we invoke the maximum principle, which we will not prove (see [Eva10] for more details).

Theorem 3 (Maximum principle). Let $U \subset \mathbb{R}^n$ be open and bounded and $u \in \mathcal{C}^2(U) \cap \mathcal{C}(\overline{U})$. Suppose that u is harmonic within U, that is, $\Delta u = 0$ in U. Then, $\max_{\overline{U}} u = \max_{\partial U} u$.

Corollary 4. The Dirichlet problem of Eq. (10) has a unique solution.

Proof. Suppose we have two solutions V_1 , V_2 of Eq. (10). Then, $W := V_1 - V_2$ is harmonic in Ω^c and W = 0 on $\partial \Omega$. Moreover, $\lim_{\|\mathbf{r}\| \to \infty} W = 0$. So $\forall \varepsilon > 0$, $\exists n \in \mathbb{N}$ large enough such that $|W| \le \varepsilon$ on $\partial B(0, n)$.

Thus, by the maximum principle, $|W| \leq \varepsilon$ on $\overline{B(0,n)} \cap \Omega^c$. Since the ε is arbitrary, we must have W = 0 on Ω^c , that is, $V_1 = V_2$.

¹It can be seen that V satisfies in fact the Poisson equation $\Delta V = 4\pi G\rho$ for any point $\mathbf{r} \in \mathbb{R}^3$, which reduced to Laplace equation when $\mathbf{r} \in \Omega^c$, because there we have $\rho(\mathbf{r}) = 0$.

1.1.3 Expansion in spherical harmonics

We have just seen that V satisfies the exterior Dirichlet problem for the Laplace equation. In $\ref{laplace}$ we saw that a solution to the Laplace equation can be expressed as:

$$V(r,\theta,\phi) = \sum_{n=0}^{\infty} \sum_{m=0}^{n} (a_n r^n + b_n r^{-n-1}) (\tilde{c}_{n,m} Y_{n,m}^{c}(\theta,\phi) + \tilde{s}_{n,m} Y_{n,m}^{s}(\theta,\phi))$$
(11)

where $a_n, b_n, \tilde{c}_{n,m}, \tilde{s}_{n,m} \in \mathbb{R}$. If we impose V to satisfy the third condition of Eq. (10), we must have $a_n = 0$. Finally, if we choose R_{\oplus} as a reference radius for a spherical model of the Earth, using the boundary condition on $\partial \Omega$

$$f(\theta,\phi) = \sum_{n=0}^{\infty} \sum_{m=-n}^{n} \frac{b_n}{R_{\oplus}^{n+1}} (\tilde{c}_{n,m} Y_{n,m}^{c}(\theta,\phi) + \tilde{s}_{n,m} Y_{n,m}^{s}(\theta,\phi))$$
 (12)

and the orthogonality of the spherical harmonics, we can deduce that the coefficients $b_n \tilde{c}_{n,m}$ and $b_n \tilde{s}_{n,m}$ are given by:

$$b_n \tilde{c}_{n,m} = \frac{R_{\oplus}^{n+1}}{4\pi} \int_0^{2\pi} \int_0^{\pi} f(\theta, \phi) Y_{n,m}^{c}(\theta, \phi) \sin \phi \, d\phi \, d\theta$$
 (13)

$$b_n \tilde{s}_{n,m} = \frac{R_{\oplus}^{n+1}}{4\pi} \int_0^{2\pi} \int_0^{\pi} f(\theta, \phi) Y_{n,m}^{\mathbf{s}}(\theta, \phi) \sin \phi \, d\phi \, d\theta$$
 (14)

Hence introducing the gravitational constant G and the Earth's mass M_{\oplus} into the equation, our final expression for the gravitational potential is

$$V(r,\theta,\phi) = \frac{GM_{\oplus}}{R_{\oplus}} \sum_{n=0}^{\infty} \sum_{m=0}^{n} \left(\frac{R_{\oplus}}{r}\right)^{n+1} (\bar{C}_{n,m} Y_{n,m}^{c}(\theta,\phi) + \bar{S}_{n,m} Y_{n,m}^{s}(\theta,\phi))$$
(15)

where the coefficients $\bar{C}_{n,m}, \bar{S}_{n,m} \in \mathbb{R}$ are given by the formulas:

$$\bar{C}_{n,m} = \frac{1}{4\pi} \frac{R_{\oplus}}{GM_{\oplus}} \int_{0}^{2\pi} \int_{0}^{\pi} f(\theta, \phi) Y_{n,m}^{c}(\theta, \phi) \sin \phi \, d\phi \, d\theta$$
 (16)

$$\bar{S}_{n,m} = \frac{1}{4\pi} \frac{R_{\oplus}}{GM_{\oplus}} \int_{0}^{2\pi} \int_{0}^{\pi} f(\theta, \phi) Y_{n,m}^{s}(\theta, \phi) \sin \phi \, d\phi \, d\theta$$
 (17)

The coefficients $\bar{C}_{n,m}$, $\bar{S}_{n,m}$ are called geopotential coefficients and they describe the dependence on the Earth's internal structure. They are obtained from observation of the perturbations seen in the orbits of other satellites [MG05]. Other methods for obtaining such data are through surface gravimetry, which provides precise local and regional information about the gravity field, or through altimeter data, which can be used to provide a model for the geoid of the Earth, that is the shape that the ocean surface would take under the influence of the gravity of Earth, which in turn can be used to obtain the geopotential coefficients.

1.1.4 Numerical computation of the gravity acceleration

Up to this point, we have only studied the gravitational potential exerted by the non-homogeneous Earth on a satellite. But, in order to integrate the equations of motion of the satellite, we need to compute the gravitational acceleration $\mathbf{g} = -\nabla V$ instead. In order to do this in an efficient way, we will make use of the following formulas given in [MG05; Cun70]. First, let

$$V_{n,m}(\theta,\phi) = \left(\frac{R_{\oplus}}{r}\right)^{n+1} P_{n,m}(\cos\phi)\cos(m\theta) \qquad W_{n,m}(\theta,\phi) = \left(\frac{R_{\oplus}}{r}\right)^{n+1} P_{n,m}(\cos\phi)\sin(m\theta)$$
 (18)

Thus, we can write:

$$V = \sum_{n=0}^{\infty} \sum_{m=0}^{n} \bar{C}_{n,m} N_{n,m} V_{n,m} + \bar{S}_{n,m} N_{n,m} W_{n,m}$$
(19)

Let $C_{n,m}:=\bar{C}_{n,m}N_{n,m}$ and $S_{n,m}:=\bar{S}_{n,m}N_{n,m}$. If $\mathbf{g}=(\ddot{x},\ddot{y},\ddot{z})$, then:

$$\ddot{x} = \sum_{n=0}^{\infty} \sum_{m=0}^{n} \ddot{x}_{n,m} \qquad \ddot{y} = \sum_{n=0}^{\infty} \sum_{m=0}^{n} \ddot{y}_{n,m} \qquad \ddot{z} = \sum_{n=0}^{\infty} \sum_{m=0}^{n} \ddot{z}_{n,m}$$
(20)

where the partial accelerations $x_{n,m}$, $y_{n,m}$, $z_{n,m}$ are given by:

$$\ddot{x}_{n,m} = \begin{cases} -\frac{GM}{R_{\oplus}^{2}} C_{n,0} V_{n+1,1} & \text{if } m = 0\\ -\frac{GM}{R_{\oplus}^{2}} \left[C_{n,m} V_{n+1,m+1} + S_{n,m} W_{n+1,m+1} - \frac{(n-m+2)!}{(n-m)!} \left(C_{n,m} V_{n+1,m-1} + S_{n,m} W_{n+1,m-1} \right) \right] & \text{if } m > 0 \end{cases}$$

$$\left\{ -\frac{GM}{R_{\oplus}^{2}} C_{n,0} W_{n+1,1} & \text{if } m = 0 \end{cases}$$

$$\left\{ -\frac{GM}{R_{\oplus}^{2}} C_{n,0} W_{n+1,1} & \text{if } m = 0 \end{cases}$$

$$\ddot{y}_{n,m} = \begin{cases}
-\frac{GM}{R_{\oplus}^{2}} C_{n,0} W_{n+1,1} & \text{if } m = 0 \\
-\frac{GM}{R_{\oplus}^{2}} \left[C_{n,m} W_{n+1,m+1} - S_{n,m} V_{n+1,m+1} - \frac{(n-m+2)!}{(n-m)!} \left(C_{n,m} W_{n+1,m-1} - S_{n,m} V_{n+1,m-1} \right) \right] & \text{if } m > 0 \end{cases}$$

$$\ddot{g}_{n,m} = \begin{cases}
GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1}) - S_{n,m} V_{n+1,m-1} \right) \\
\ddot{g}_{n,m} = \frac{GM}{(n-m+1)!} \left(C_{n-1} V_{n-1} + C_{n-1} W_{n-1} - S_{n-1} V_{n-1,m-1} \right)$$

$$\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1}) - S_{n-1} V_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \frac{GM}{(n-m+1)!} \left(C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} V_{n-1,m-1} \right)$$

$$\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} V_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} V_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1} W_{n-1,m-1} \right) \\
\ddot{g}_{n,m} = \begin{pmatrix} GM \left((n-m+1) \cdot (C_{n-1} V_{n-1} + C_{n-1} W_{n-1,m-1} - S_{n-1$$

$$\ddot{z}_{n,m} = -\frac{GM}{R_{\odot}^2} (n - m + 1) \left(C_{n,m} V_{n+1,m} + S_{n,m} W_{n+1,m} \right)$$
(23)

and the functions $V_{n,m},\,W_{n,m}$ are calculated using the following recurrence relations:

$$\begin{cases} V_{n,m} = \frac{2n-1}{n-m} \frac{R_{\oplus}}{r} \cos \phi V_{n-1,m} - \frac{n+m-1}{n-m} \frac{R_{\oplus}^2}{r^2} V_{n-2,m} \\ W_{n,m} = \frac{2n-1}{n-m} \frac{R_{\oplus}}{r} \cos \phi W_{n-1,m} - \frac{n+m-1}{n-m} \frac{R_{\oplus}^2}{r^2} W_{n-2,m} \end{cases} & \text{if } 0 \le m \le n-2 \\ \begin{cases} V_{n,n-1} = (2n-1) \frac{R_{\oplus}}{r} \cos \phi V_{n-1,n-1} \\ W_{n,n-1} = (2n-1) \frac{R_{\oplus}}{r} \cos \phi W_{n-1,n-1} \end{cases} & \text{if } m = n-1 \\ \end{cases} \\ V_{n,n} = (2m-1) \frac{R_{\oplus}}{r} \sin \phi [\cos \theta V_{n-1,n-1} - \sin \theta W_{n-1,n-1}] \\ W_{n,n} = (2m-1) \frac{R_{\oplus}}{r} \sin \phi [\cos \theta W_{n-1,n-1} + \sin \theta V_{n-1,n-1}] \end{cases} & \text{if } m = n \end{cases}$$

starting from the initial quantities $V_{00} = \frac{R_{\oplus}}{r}$ and $W_{00} = 0$.

1.1.5 Other perturbations

atmospheric drag, solar radiation pressure, and the gravitational pull of the Moon and Sun, POSAR-HO SI AL FINAL FAIG SIMULACIO AMB AIXO, SI NO, NOOOO.