Part 2 Explanation

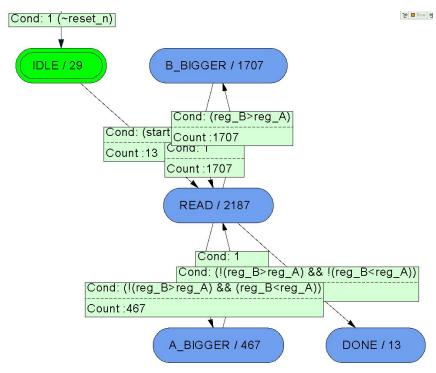


Figure 1: Generated State Machine

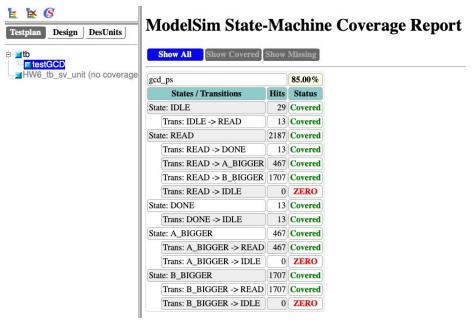


Figure 2: Transition Coverage

My design does NOT reach 100% coverage due to transitions not taking place. The common denominator of these two is that the destination is IDLE. One case we go to IDLE is when we have completed a computation at the state DONE. The other, and causing issue, is when the

system is reset. Whenever we reset, we have to go back to IDLE regardless of which state the system is in. The state DONE already has a path to IDLE that's executed every time; it can be seen in my code. So that's why A_BIGGER, B_BIGGER, and READ don't get transitioned to IDLE, because we don't reset when we're in these states.

NOTE: The difference between pre-coverage and post-coverage is that I changed my design to incorporate flip-flops and remove the latches I had.