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### Low-Power, Slew-Rate-Limited RS-485/RS-422 Transceivers

#### **General Description**

The MAX481, MAX483, MAX485, MAX487-MAX491, and MAX1487 are low-power transceivers for RS-485 and RS-422 communication. Each part contains one driver and one receiver. The MAX483, MAX487, MAX488, and MAX489 feature reduced slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, thus allowing error-free data transmission up to 250kbps. The driver slew rates of the MAX481, MAX485, MAX490, MAX491, and MAX1487 are not limited, allowing them to transmit up to 2.5Mbps.

These transceivers draw between 120µA and 500µA of supply current when unloaded or fully loaded with disabled drivers. Additionally, the MAX481, MAX483, and MAX487 have a low-current shutdown mode in which they consume only 0.1µA. All parts operate from a single 5V supply.

Drivers are short-circuit current limited and are protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high-impedance state. The receiver input has a fail-safe feature that guarantees a logic-high output if the input is open circuit.

The MAX487 and MAX1487 feature quarter-unit-load receiver input impedance, allowing up to 128 MAX487/ MAX1487 transceivers on the bus. Full-duplex communications are obtained using the MAX488-MAX491, while the MAX481, MAX483, MAX485, MAX487, and MAX1487 are designed for half-duplex applications.

#### **Applications**

Low-Power RS-422 Transceivers Level Translators Transceivers for EMI-Sensitive Applications Industrial-Control Local Area Networks

Low-Power RS-485 Transceivers

#### Features

- ♦ In µMAX Package: Smallest 8-Pin SO
- ♦ Slew-Rate Limited for Error-Free Data Transmission (MAX483/487/488/489)
- ♦ 0.1µALow-Current Shutdown Mode (MAX481/483/487)
- **♦ Low Quiescent Current:** 120µA (MAX483/487/488/489) 230µA (MAX1487) 300µA (MAX481/485/490/491)
- ◆ -7V to +12V Common-Mode Input Voltage Range
- **♦ Three-State Outputs**
- ♦ 30ns Propagation Delays, 5ns Skew (MAX481/485/490/491/1487)
- ♦ Full-Duplex and Half-Duplex Versions Available
- ♦ Operate from a Single 5V Supply
- ♦ Allows up to 128 Transceivers on the Bus (MAX487/MAX1487)
- ♦ Current-Limiting and Thermal Shutdown for **Driver Overload Protection**

### **Ordering Information**

PART	TEMP. RANGE	PIN-PACKAGE
MAX481CPA	0°C to +70°C	8 Plastic DIP
MAX481CSA	0°C to +70°C	8 SO
MAX481CUA	0°C to +70°C	8 µMAX
MAX481C/D	0°C to +70°C	Dice*

Ordering Information continued at end of data sheet.

#### **Selection Table**

PART NUMBER	HALF/FULL DUPLEX	DATA RATE (Mbps)	SLEW-RATE LIMITED	LOW-POWER SHUTDOWN	RECEIVER/ DRIVER ENABLE	QUIESCENT CURRENT (μA)	NUMBER OF TRANSMITTERS ON BUS	PIN COUNT
MAX481	Half	2.5	No	Yes	Yes	300	32	8
MAX483	Half	0.25	Yes	Yes	Yes	120	32	8
MAX485	Half	2.5	No	No	Yes	300	32	8
MAX487	Half	0.25	Yes	Yes	Yes	120	128	8
MAX488	Full	0.25	Yes	No	No	120	32	8
MAX489	Full	0.25	Yes	No	Yes	120	32	14
MAX490	Full	2.5	No	No	No	300	32	8
MAX491	Full	2.5	No	No	Yes	300	32	14
MAX1487	Half	2.5	No	No	Yes	230	128	8

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<sup>\*</sup>Contact factory for dice specifications.

#### **ABSOLUTE MAXIMUM RATINGS**

14-Pin SO (derate 8.33mW/°C above +70	°C)667mW
8-Pin µMAX (derate 4.1mW/°C above +70	)°C)830mW
8-Pin CERDIP (derate 8.00mW/°C above	+70°C)640mW
14-Pin CERDIP (derate 9.09mW/°C above	+70°C)727mW
Operating Temperature Ranges	
MAX4C/MAX1487C_ A	0°C to +70°C
MAX4E/MAX1487E_ A	40°C to +85°C
MAX4MJ_/MAX1487MJA	55°C to +125°C
Storage Temperature Range	65°C to +160°C
Lead Temperature (soldering, 10sec)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### DC ELECTRICAL CHARACTERISTICS

( $V_{CC}$  = 5V ±5%,  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Differential Driver Output (no load)	V <sub>OD1</sub>					5	V
Differential Driver Output	Vone	$R = 50\Omega (RS-422)$	$R = 50\Omega (RS-422)$				V
(with load)	V <sub>OD2</sub>	$R = 27\Omega$ (RS-485), Figure 4		1.5		5	v
Change in Magnitude of Driver Differential Output Voltage for Complementary Output States	ΔV <sub>OD</sub>	R = $27\Omega$ or $50\Omega$ , Figure 4				0.2	V
Driver Common-Mode Output Voltage	Voc	$R=27\Omega$ or $50\Omega$ , Figure 4				3	V
Change in Magnitude of Driver Common-Mode Output Voltage for Complementary Output States	ΔV <sub>OD</sub>	R = $27\Omega$ or $50\Omega$ , Figure 4				0.2	V
Input High Voltage	VIH	DE, DI, RE		2.0			V
Input Low Voltage	V <sub>IL</sub>	DE, DI, RE				0.8	V
Input Current	I <sub>IN1</sub>	DE, DI, RE				±2	μΑ
	l <sub>IN2</sub>	DE = 0V; V <sub>CC</sub> = 0V or 5.25V,	V <sub>IN</sub> = 12V			1.0	mA
Input Current (A, B)		all devices except MAX487/MAX1487	V <sub>IN</sub> = -7V			-0.8	1117 (
		MAX487/MAX1487,	VIN = 12V			0.25	mA
		DE = 0V, $V_{CC} = 0V \text{ or } 5.25V$	V <sub>IN</sub> = -7V			-0.2	IIIA
Receiver Differential Threshold Voltage	V <sub>T</sub> H	-7V ≤ V <sub>CM</sub> ≤ 12V		-0.2		0.2	V
Receiver Input Hysteresis	ΔVτΗ	VCM = 0V			70		mV
Receiver Output High Voltage	Voh	$I_{O} = -4mA, V_{ID} = 200mV$		3.5			V
Receiver Output Low Voltage	Vol	$I_{O} = 4mA, V_{ID} = -200mV$				0.4	V
Three-State (high impedance) Output Current at Receiver	lozr	$0.4V \le V_{O} \le 2.4V$				±1	μΑ
Receiver Input Resistance	RIN	-7V ≤ V <sub>CM</sub> ≤ 12V, all devices except MAX487/MAX1487		12			kΩ
Trooper input registance	THIN	-7V ≤ V <sub>CM</sub> ≤ 12V, MAX487/MA	AX1487	48			kΩ

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### **DC ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{CC} = 5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.})$  (Notes 1, 2)

PARAMETER	SYMBOL	COND	ITIONS		MIN	TYP	MAX	UNITS
		MAX488/MAX489, DE, DI, $\overline{\text{RE}}$ = 0V or V <sub>CC</sub>				120	250	
		MAX490/MAX491, DE, DI, $\overline{RE}$ = 0V or V <sub>C</sub> (	0			300	500	
No Load Cupply Current		MAX481/MAX485,	DE = Vcc			500	900	
No-Load Supply Current (Note 3)	Icc	RE = 0V or V <sub>CC</sub>	DE = 0V			300	500	μΑ
(**************************************		MAX1487, RE = 0V or V <sub>CC</sub>	DE = Vcc			300	500	
			DE = 0V			230	400	
		MAX483/MAX487, RE = 0V or VCC	DE = 5V	MAX483		350	650	
			DL = 3V	MAX487		250	400	
			DE = 0V			120	250	
Supply Current in Shutdown	ISHDN	MAX481/483/487, DE	$= 0V, \overline{RE} = V$	CC		0.1	10	μΑ
Driver Short-Circuit Current, V <sub>O</sub> = High	losp1	-7V ≤ V <sub>O</sub> ≤12V (Note 4	35		250	mA		
Driver Short-Circuit Current, V <sub>O</sub> = Low	los <sub>D2</sub>	-7V ≤ V <sub>O</sub> ≤12V (Note 4)			35		250	mA
Receiver Short-Circuit Current	Iosr	$0V \le V_O \le V_{CC}$			7		95	mA

#### SWITCHING CHARACTERISTICS—MAX481/MAX485, MAX490/MAX491, MAX1487

 $(V_{CC} = 5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.})$  (Notes 1, 2)

PARAMETER	SYMBOL	CC	CONDITIONS		TYP	MAX	UNITS
Driver Input to Output	tplH	Figures 6 and 8, R	DIFF = $54\Omega$ ,	10	30	60	ns
Driver input to Output	tphL	$C_{L1} = C_{L2} = 100pF$	=	10	30	60	1115
Driver Output Skew to Output	tskew	Figures 6 and 8, RD	$_{IFF} = 54Ω$ , $C_{L1} = C_{L2} = 100pF$		5	10	ns
		Figures 6 and 8,	MAX481, MAX485, MAX1487	3	15	40	
Driver Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>		MAX490C/E, MAX491C/E	5	15	25	ns
		$C_{L1} = C_{L2} = 100pF$	MAX490M, MAX491M	3	15	40	
Driver Enable to Output High	tzH	Figures 7 and 9, C	L = 100pF, S2 closed		40	70	ns
Driver Enable to Output Low	tzL	Figures 7 and 9, C	L = 100pF, S1 closed		40	70	ns
Driver Disable Time from Low	tLZ	Figures 7 and 9, C	L = 15pF, S1 closed		40	70	ns
Driver Disable Time from High	tHZ	,	L = 15pF, S2 closed		40	70	ns
	tplh, tphl	Figures 6 and 10,	MAX481, MAX485, MAX1487	20	90	200	
Receiver Input to Output			MAX490C/E, MAX491C/E	20	90	150	ns
			MAX490M, MAX491M	20	90	200	
I t <sub>PLH</sub> - t <sub>PHL</sub> I Differential Receiver Skew	tskd	Figures 6 and 10, $R_{L1} = C_{L2} = 100 pF$			13		ns
Receiver Enable to Output Low	tzL	Figures 5 and 11, 0	C <sub>RL</sub> = 15pF, S1 closed		20	50	ns
Receiver Enable to Output High	tzH	Figures 5 and 11, 0	C <sub>RL</sub> = 15pF, S2 closed		20	50	ns
Receiver Disable Time from Low	t <sub>LZ</sub>	Figures 5 and 11, C <sub>RL</sub> = 15pF, S1 closed			20	50	ns
Receiver Disable Time from High	tHZ	Figures 5 and 11, C <sub>RL</sub> = 15pF, S2 closed			20	50	ns
Maximum Data Rate	fMAX			2.5			Mbps
Time to Shutdown	tshdn	MAX481 (Note 5)		50	200	600	ns

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#### SWITCHING CHARACTERISTICS—MAX481/MAX485, MAX490/MAX491, MAX1487 (continued)

( $V_{CC} = 5V \pm 5\%$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Enable from Shutdown to Output High (MAX481)	tzh(SHDN)	Figures 7 and 9, C <sub>L</sub> = 100pF, S2 closed		40	100	ns
Driver Enable from Shutdown to Output Low (MAX481)	tzL(SHDN)	Figures 7 and 9, C <sub>L</sub> = 100pF, S1 closed		40	100	ns
Receiver Enable from Shutdown to Output High (MAX481)	tzh(SHDN)	Figures 5 and 11, C <sub>L</sub> = 15pF, S2 closed, A - B = 2V		300	1000	ns
Receiver Enable from Shutdown to Output Low (MAX481)	tzL(SHDN)	Figures 5 and 11, C <sub>L</sub> = 15pF, S1 closed, B - A = 2V		300	1000	ns

#### SWITCHING CHARACTERISTICS—MAX483, MAX487/MAX488/MAX489

 $(V_{CC} = 5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.})$  (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Input to Output	tplh	Figures 6 and 8, RDIFF = $54\Omega$ ,	250	800	2000	no
Driver input to Output	tphl	$C_{L1} = C_{L2} = 100pF$	250	800	2000	ns
Driver Output Skew to Output	tskew	Figures 6 and 8, R <sub>DIFF</sub> = $54\Omega$ , CL1 = CL2 = $100$ pF		100	800	ns
Driver Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>	Figures 6 and 8, RDIFF = $54\Omega$ , $C_{L1} = C_{L2} = 100 pF$	250		2000	ns
Driver Enable to Output High	tzH	Figures 7 and 9, C <sub>L</sub> = 100pF, S2 closed	250		2000	ns
Driver Enable to Output Low	tzL	Figures 7 and 9, C <sub>L</sub> = 100pF, S1 closed	250		2000	ns
Driver Disable Time from Low	tLZ	Figures 7 and 9, C <sub>L</sub> = 15pF, S1 closed	300		3000	ns
Driver Disable Time from High	tHZ	Figures 7 and 9, C <sub>L</sub> = 15pF, S2 closed	300		3000	ns
December of the Control	tpLH	Figures 6 and 10, $R_{DIFF} = 54\Omega$ ,	250		2000	
Receiver Input to Output	tphL	$C_{L1} = C_{L2} = 100pF$	250		2000	ns
I t <sub>PLH</sub> - t <sub>PHL</sub> I Differential Receiver Skew	tskD	Figures 6 and 10, $R_{DIFF}$ = $54\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF		100		ns
Receiver Enable to Output Low	tzL	Figures 5 and 11, C <sub>RL</sub> = 15pF, S1 closed		20	50	ns
Receiver Enable to Output High	tzH	Figures 5 and 11, C <sub>RL</sub> = 15pF, S2 closed		20	50	ns
Receiver Disable Time from Low	t <sub>LZ</sub>	Figures 5 and 11, C <sub>RL</sub> = 15pF, S1 closed		20	50	ns
Receiver Disable Time from High	tHZ	Figures 5 and 11, C <sub>RL</sub> = 15pF, S2 closed		20	50	ns
Maximum Data Rate	f <sub>MAX</sub>	tplh, tphl < 50% of data period	250			kbps
Time to Shutdown	tshdn	MAX483/MAX487 (Note 5)	50	200	600	ns
Driver Enable from Shutdown to Output High	tzh(SHDN)	MAX483/MAX487, Figures 7 and 9, C <sub>L</sub> = 100pF, S2 closed			2000	ns
Driver Enable from Shutdown to Output Low	tZL(SHDN)	MAX483/MAX487, Figures 7 and 9, C <sub>L</sub> = 100pF, S1 closed			2000	ns
Receiver Enable from Shutdown to Output High	tzh(SHDN)	MAX483/MAX487, Figures 5 and 11, C <sub>L</sub> = 15pF, S2 closed			2500	ns
Receiver Enable from Shutdown to Output Low	tzL(SHDN)	MAX483/MAX487, Figures 5 and 11, C <sub>L</sub> = 15pF, S1 closed			2500	ns

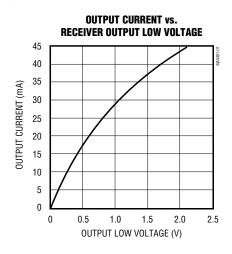
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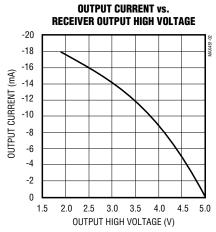
#### NOTES FOR ELECTRICAL/SWITCHING CHARACTERISTICS

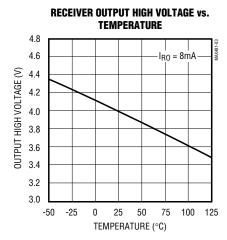
- Note 1: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.
- **Note 2:** All typical specifications are given for  $V_{CC} = 5V$  and  $T_A = +25$ °C.
- **Note 3:** Supply current specification is valid for loaded transmitters when DE = 0V.
- Note 4: Applies to peak current. See Typical Operating Characteristics.
- Note 5: The MAX481/MAX483/MAX487 are put into shutdown by bringing RE high and DE low. If the inputs are in this state for less than 50ns, the parts are guaranteed not to enter shutdown. If the inputs are in this state for at least 600ns, the parts are guaranteed to have entered shutdown. See Low-Power Shutdown Mode section.

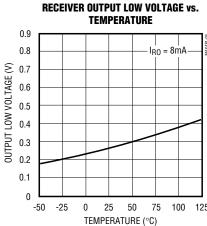
### \_Typical Operating Characteristics

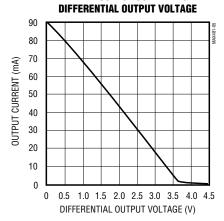
 $(V_{CC} = 5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 



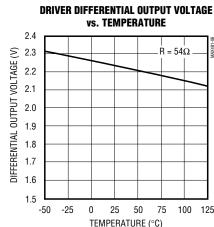






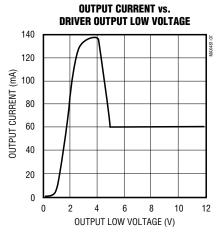


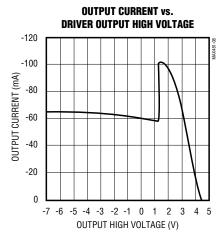
DRIVER OUTPUT CURRENT vs.

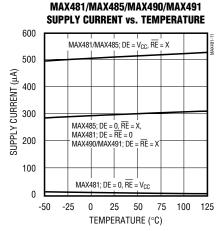


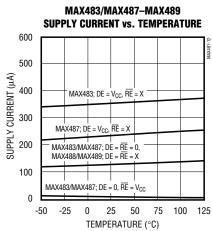
### **Typical Operating Characteristics (continued)**

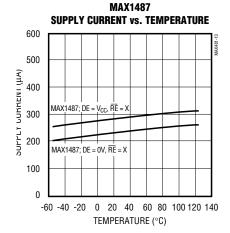
 $(V_{CC} = 5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 











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### **Pin Description**

		PIN				
MAX481/ MAX485/ MAX	MAX487/		(488/ (490	MAX489/ MAX491	NAME	FUNCTION
DIP/SO	μМΑХ	DIP/SO	μМΑХ	DIP/SO		
1	3	2	4	2	RO	Receiver Output: If A > B by 200mV, RO will be high; If A < B by 200mV, RO will be low.
2	4	_		3	RE	Receiver Output Enable. RO is enabled when RE is low; RO is high impedance when RE is high.
З	5	_	_	4	DE	Driver Output Enable. The driver outputs, Y and Z, are enabled by bringing DE high. They are high impedance when DE is low. If the driver outputs are enabled, the parts function as line drivers. While they are high impedance, they function as line receivers if RE is low.
4	6	3	5	5	DI	Driver Input. A low on DI forces output Y low and output Z high. Similarly, a high on DI forces output Y high and output Z low.
5	7	4	6	6, 7	GND	Ground
_	_	5	7	9	Υ	Noninverting Driver Output
_	_	6	8	10	Z	Inverting Driver Output
6	8	_	_	_	Α	Noninverting Receiver Input and Noninverting Driver Output
_	_	8	2	12	А	Noninverting Receiver Input
7	1	_	_	_	В	Inverting Receiver Input and Inverting Driver Output
_	_	7	1	11	В	Inverting Receiver Input
8	2	1	3	14	Vcc	Positive Supply: 4.75V ≤ V <sub>CC</sub> ≤ 5.25V
_	_	_	_	1, 8, 13	N.C.	No Connect—not internally connected

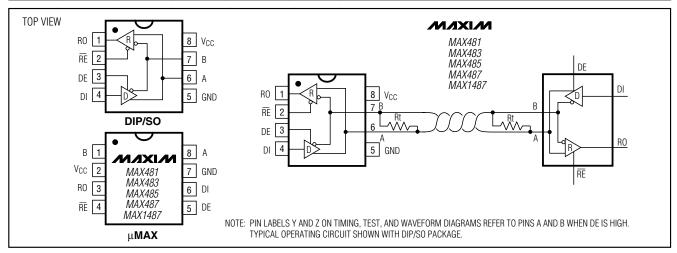


Figure 1. MAX481/MAX483/MAX485/MAX487/MAX1487 Pin Configuration and Typical Operating Circuit

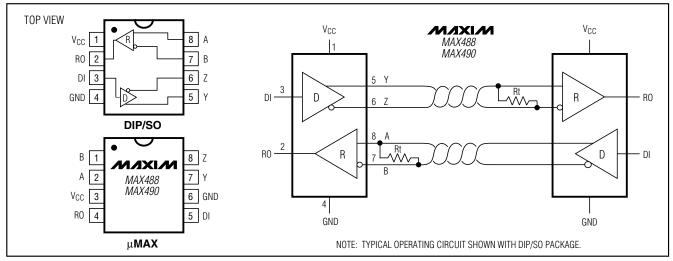


Figure 2. MAX488/MAX490 Pin Configuration and Typical Operating Circuit

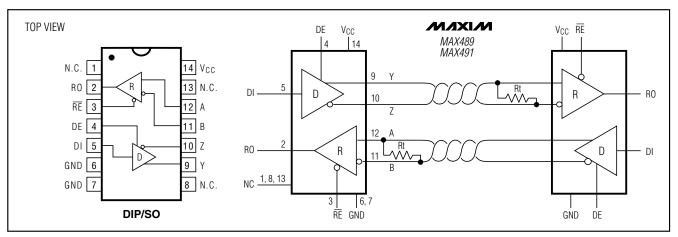


Figure 3. MAX489/MAX491 Pin Configuration and Typical Operating Circuit

### **Applications Information**

The MAX481/MAX483/MAX485/MAX487–MAX491 and MAX1487 are low-power transceivers for RS-485 and RS-422 communications. The MAX481, MAX485, MAX490, MAX491, and MAX1487 can transmit and receive at data rates up to 2.5Mbps, while the MAX483, MAX487, MAX488, and MAX489 are specified for data rates up to 250kbps. The MAX488–MAX491 are full-duplex transceivers while the MAX481, MAX483, MAX485, MAX487, and MAX1487 are half-duplex. In addition, Driver Enable (DE) and Receiver Enable (RE) pins are included on the MAX481, MAX483, MAX485, MAX487, MAX489, MAX491, and MAX1487. When disabled, the driver and receiver outputs are high impedance.

## MAX487/MAX1487: 128 Transceivers on the Bus

The  $48k\Omega$ , 1/4-unit-load receiver input impedance of the MAX487 and MAX1487 allows up to 128 transceivers on a bus, compared to the 1-unit load ( $12k\Omega$  input impedance) of standard RS-485 drivers (32 transceivers maximum). Any combination of MAX487/MAX1487 and other RS-485 transceivers with a total of 32 unit loads or less can be put on the bus. The MAX481/MAX483/MAX485 and MAX488–MAX491 have standard  $12k\Omega$  Receiver Input impedance.

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#### **Test Circuits**

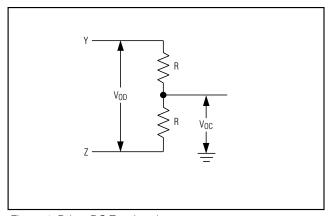


Figure 4. Driver DC Test Load

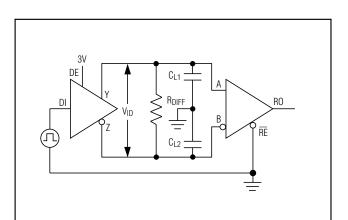


Figure 6. Driver/Receiver Timing Test Circuit

#### MAX483/MAX487/MAX488/MAX489: Reduced EMI and Reflections

The MAX483 and MAX487–MAX489 are slew-rate limited, minimizing EMI and reducing reflections caused by improperly terminated cables. Figure 12 shows the driver output waveform and its Fourier analysis of a 150kHz signal transmitted by a MAX481, MAX485, MAX490, MAX491, or MAX1487. High-frequency har-

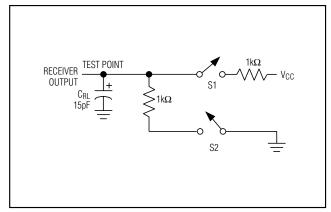


Figure 5. Receiver Timing Test Load

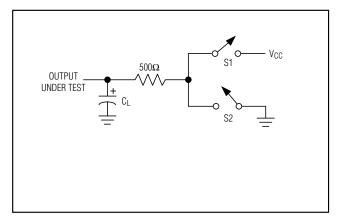


Figure 7. Driver Timing Test Load

monics with large amplitudes are evident. Figure 13 shows the same information displayed for a MAX483, MAX487, MAX488, or MAX489 transmitting under the same conditions. Figure 13's high-frequency harmonics have much lower amplitudes, and the potential for EMI is significantly reduced.

### Switching Waveforms

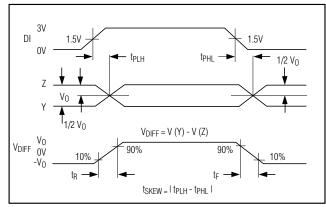


Figure 8. Driver Propagation Delays

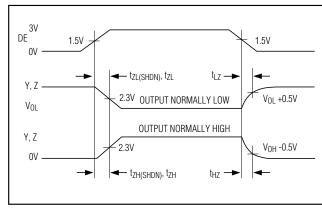


Figure 9. Driver Enable and Disable Times (except MAX488 and MAX490)

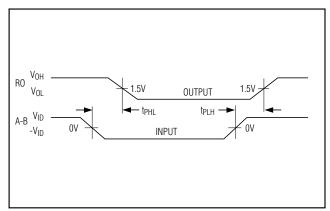


Figure 10. Receiver Propagation Delays

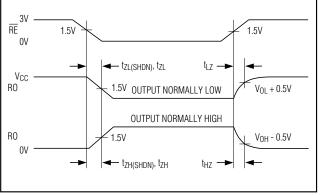


Figure 11. Receiver Enable and Disable Times (except MAX488 and MAX490)

### Function Tables (MAX481/MAX483/MAX485/MAX487/MAX1487)

#### **Table 1. Transmitting**

	INPUTS	OUTPUTS			
RE	DE	DI	z	Υ	
Χ	1	1	0	1	
Х	1	0	1	0	
0	0	Х	High-Z	High-Z	
1	0	Х	High-Z*	High-Z*	

X = Don't care

High-Z = High impedance

#### Table 2. Receiving

	OUTPUT		
RE	DE	A-B	RO
0	0	≥ +0.2V	1
0	0	≤ -0.2V	0
0	0	Inputs open	1
1	0	X	High-Z*

X = Don't care

High-Z = High impedance

<sup>\*</sup> Shutdown mode for MAX481/MAX483/MAX487

<sup>\*</sup> Shutdown mode for MAX481/MAX483/MAX487

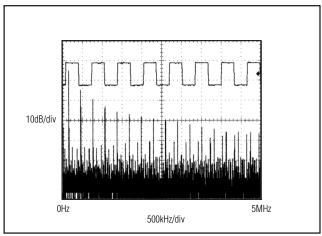


Figure 12. Driver Output Waveform and FFT Plot of MAX481/ MAX485/MAX490/MAX491/MAX1487 Transmitting a 150kHz Signal

### Low-Power Shutdown Mode (MAX481/MAX483/MAX487)

A low-power shutdown mode is initiated by bringing both  $\overline{RE}$  high and DE low. The devices will not shut down unless both the driver and receiver are disabled. In shutdown, the devices typically draw only  $0.1\mu A$  of supply current.

RE and DE may be driven simultaneously; the parts are guaranteed not to enter shutdown if RE is high and DE is low for less than 50ns. If the inputs are in this state for at least 600ns, the parts are guaranteed to enter shutdown.

For the MAX481, MAX483, and MAX487, the tzH and tzL enable times assume the part was not in the low-power shutdown state (the MAX485/MAX488–MAX491 and MAX1487 can not be shut down). The tzH(SHDN) and tzL(SHDN) enable times assume the parts were shut down (see *Electrical Characteristics*).

It takes the drivers and receivers longer to become enabled from the low-power shutdown state (tzh(Shdn)), tzl(Shdn)) than from the operating mode (tzh, tzl). (The parts are in operating mode if the  $\overline{\text{RE}}$ , DE inputs equal a logical 0,1 or 1,1 or 0, 0.)

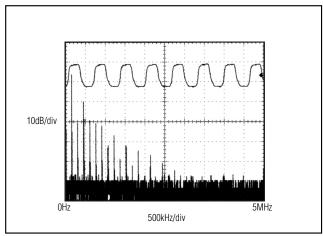


Figure 13. Driver Output Waveform and FFT Plot of MAX483/ MAX487–MAX489 Transmitting a 150kHz Signal

#### **Driver Output Protection**

Excessive output current and power dissipation caused by faults or by bus contention are prevented by two mechanisms. A foldback current limit on the output stage provides immediate protection against short circuits over the whole common-mode voltage range (see *Typical Operating Characteristics*). In addition, a thermal shutdown circuit forces the driver outputs into a high-impedance state if the die temperature rises excessively.

#### **Propagation Delay**

Many digital encoding schemes depend on the difference between the driver and receiver propagation delay times. Typical propagation delays are shown in Figures 15–18 using Figure 14's test circuit.

The difference in receiver delay times, I tplh - tphl I, is typically under 13ns for the MAX481, MAX485, MAX490, MAX491, and MAX1487 and is typically less than 100ns for the MAX483 and MAX487–MAX489.

The driver skew times are typically 5ns (10ns max) for the MAX481, MAX485, MAX490, MAX491, and MAX1487, and are typically 100ns (800ns max) for the MAX483 and MAX487–MAX489.

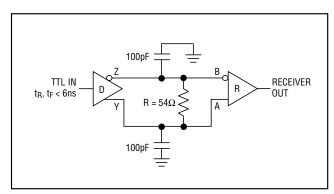


Figure 14. Receiver Propagation Delay Test Circuit

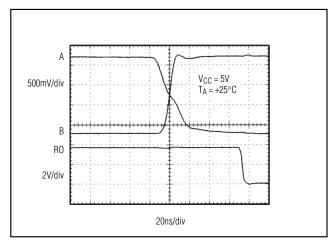


Figure 15. MAX481/MAX485/MAX490/MAX491/MAX1487 Receiver t<sub>PHL</sub>

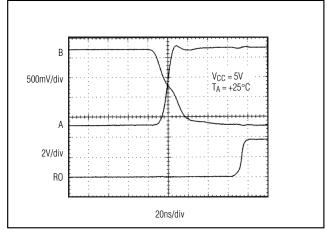


Figure 16. MAX481/MAX485/MAX490/MAX491/MAX1487 Receiver tp\_H

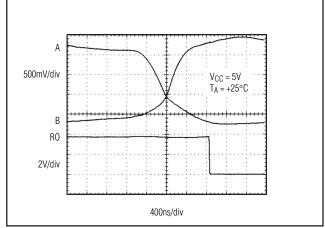


Figure 17. MAX483, MAX487-MAX489 Receiver tphL

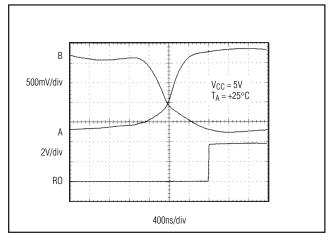


Figure 18. MAX483, MAX487-MAX489 Receiver tplh

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#### Line Length vs. Data Rate

The RS-485/RS-422 standard covers line lengths up to 4000 feet. For line lengths greater than 4000 feet, see Figure 23.

Figures 19 and 20 show the system differential voltage for the parts driving 4000 feet of 26AWG twisted-pair wire at 110kHz into  $120\Omega$  loads.

#### **Typical Applications**

The MAX481, MAX483, MAX485, MAX487–MAX491, and MAX1487 transceivers are designed for bidirectional data communications on multipoint bus transmission lines.

Figures 21 and 22 show typical network applications circuits. These parts can also be used as line repeaters, with cable lengths longer than 4000 feet, as shown in Figure 23.

To minimize reflections, the line should be terminated at both ends in its characteristic impedance, and stub lengths off the main line should be kept as short as possible. The slew-rate-limited MAX483 and MAX487–MAX489 are more tolerant of imperfect termination.

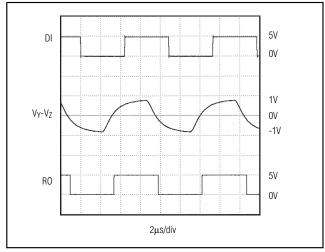


Figure 19. MAX481/MAX485/MAX490/MAX491/MAX1487 System Differential Voltage at 110kHz Driving 4000ft of Cable

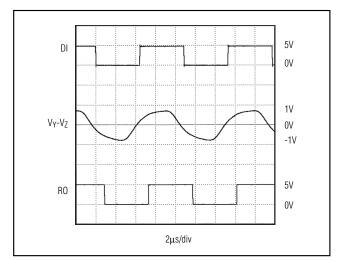


Figure 20. MAX483, MAX487–MAX489 System Differential Voltage at 110kHz Driving 4000ft of Cable

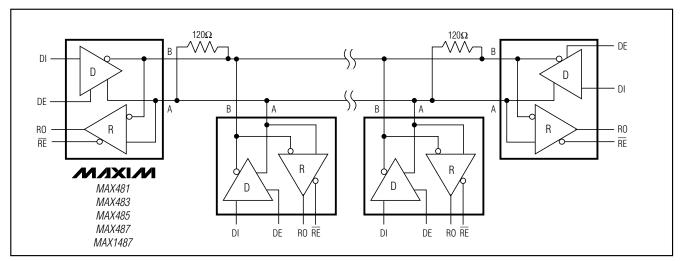


Figure 21. MAX481/MAX483/MAX485/MAX487/MAX1487 Typical Half-Duplex RS-485 Network

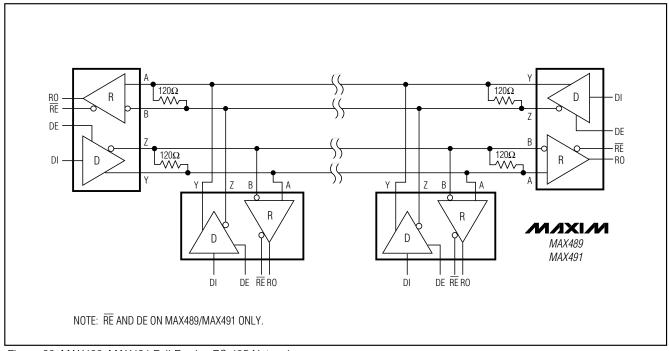


Figure 22. MAX488–MAX491 Full-Duplex RS-485 Network

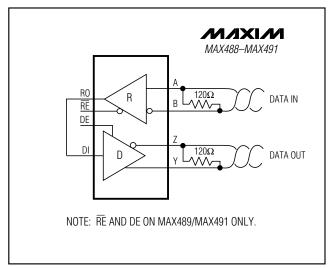


Figure 23. Line Repeater for MAX488-MAX491

#### **Isolated RS-485**

For isolated RS-485 applications, see the MAX253 and MAX1480 data sheets.

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### Ordering Information (continued)

PART	TEMP. RANGE	PIN-PACKAGE
MAX481EPA	-40°C to +85°C	8 Plastic DIP
MAX481ESA	-40°C to +85°C	8 SO
MAX481MJA	-55°C to +125°C	8 CERDIP
MAX483CPA	0°C to +70°C	8 Plastic DIP
MAX483CSA	0°C to +70°C	8 SO
MAX483CUA	0°C to +70°C	8 μMAX
MAX483C/D	0°C to +70°C	Dice*
MAX483EPA	-40°C to +85°C	8 Plastic DIP
MAX483ESA	-40°C to +85°C	8 SO
MAX483MJA	-55°C to +125°C	8 CERDIP
MAX485CPA	0°C to +70°C	8 Plastic DIP
MAX485CSA	0°C to +70°C	8 SO
MAX485CUA	0°C to +70°C	8 μMAX
MAX485C/D	0°C to +70°C	Dice*
MAX485EPA	-40°C to +85°C	8 Plastic DIP
MAX485ESA	-40°C to +85°C	8 SO
MAX485MJA	-55°C to +125°C	8 CERDIP
MAX487CPA	0°C to +70°C	8 Plastic DIP
MAX487CSA	0°C to +70°C	8 SO
MAX487CUA	0°C to +70°C	8 µMAX
MAX487C/D	0°C to +70°C	Dice*
MAX487EPA	-40°C to +85°C	8 Plastic DIP
MAX487ESA	-40°C to +85°C	8 SO
MAX487MJA	-55°C to +125°C	8 CERDIP
MAX488CPA	0°C to +70°C	8 Plastic DIP
MAX488CSA	0°C to +70°C	8 SO
MAX488CUA	0°C to +70°C	8 μMAX
MAX488C/D	0°C to +70°C	Dice*
MAX488EPA	-40°C to +85°C	8 Plastic DIP
MAX488ESA	-40°C to +85°C	8 SO
MAX488MJA	-55°C to +125°C	8 CERDIP
MAX489CPD	0°C to +70°C	14 Plastic DIP
MAX489CSD	0°C to +70°C	14 SO
MAX489C/D	0°C to +70°C	Dice*
MAX489EPD	-40°C to +85°C	14 Plastic DIP
MAX489ESD	-40°C to +85°C	14 SO
MAX489MJD	-55°C to +125°C	14 CERDIP

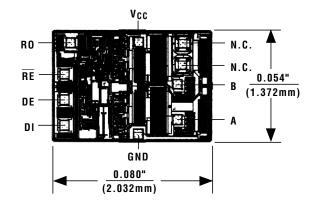
### \_\_Ordering Information (continued)

PART	TEMP. RANGE	PIN-PACKAGE
MAX490CPA	0°C to +70°C	8 Plastic DIP
MAX490CSA	0°C to +70°C	8 SO
MAX490CUA	0°C to +70°C	8 µMAX
MAX490C/D	0°C to +70°C	Dice*
MAX490EPA	-40°C to +85°C	8 Plastic DIP
MAX490ESA	-40°C to +85°C	8 SO
MAX490MJA	-55°C to +125°C	8 CERDIP
MAX491CPD	0°C to +70°C	14 Plastic DIP
MAX491CSD	0°C to +70°C	14 SO
MAX491C/D	0°C to +70°C	Dice*
MAX491EPD	-40°C to +85°C	14 Plastic DIP
MAX491ESD	-40°C to +85°C	14 SO
MAX491MJD	-55°C to +125°C	14 CERDIP
MAX1487CPA	0°C to +70°C	8 Plastic DIP
MAX1487CSA	0°C to +70°C	8 SO
MAX1487CUA	0°C to +70°C	8 µMAX
MAX1487C/D	0°C to +70°C	Dice*
MAX1487EPA	-40°C to +85°C	8 Plastic DIP
MAX1487ESA	-40°C to +85°C	8 SO
MAX1487MJA	-55°C to +125°C	8 CERDIP

<sup>\*</sup> Contact factory for dice specifications.

### **Chip Topographies**

#### MAX481/MAX483/MAX485/MAX487/MAX1487

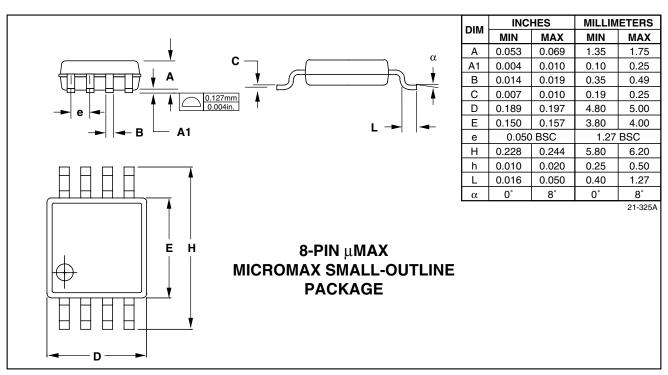


#### **Chip Topographies (continued)**

#### MAX489/MAX491 MAX488/MAX490 Vcc Vcc R0 RE 0.054" N.C. 0.054" (1.372mm)(1.372mm)DF N.C. DI GND GND 0.080" 0.080" (2.032mm)(2.032mm)

TRANSISTOR COUNT: 248
SUBSTRATE CONNECTED TO GND

### Package Information



Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

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