

Support Vector Machines (1/2)

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Confident predictions

- Consider logistic regression where the probability $p(y = 1|x; \theta)$ is modeled by $h_{\theta}(x) = g(\theta^{\top}x)$.

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- Consider a positive training example ($y = 1$), the larger the $\theta^{\top}x$ is, the larger also is $h_{\theta}(x) = p(y = 1|x; w, b)$, and thus also the higher our degree of confidence that the label is 1.

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- Thus, informally we can think of our prediction as being a very confident one that $y = 1$ if $\theta^{\top}x \gg 0$.

Confident predictions

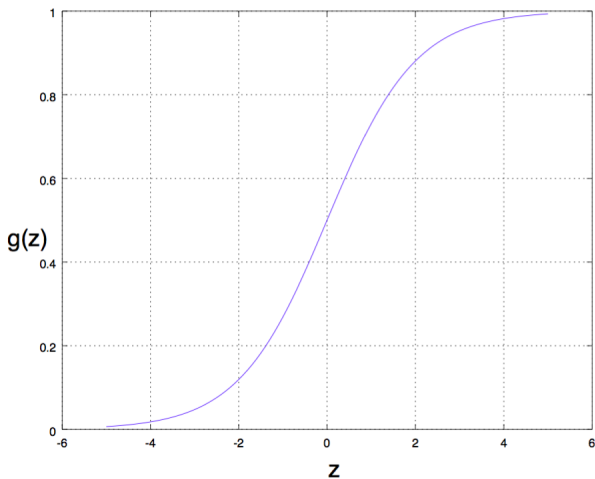


Figure: Sigmoid function (where $z = \theta^\top x$).

Confident predictions

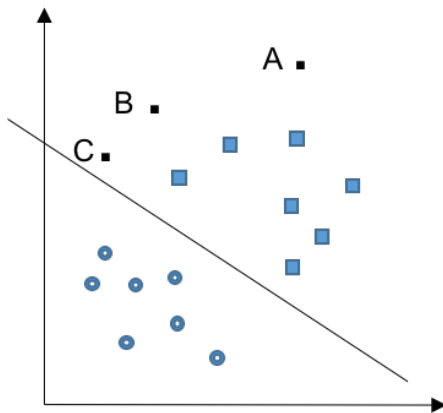


Figure: Separating hyperplane, this is the line given by the equation $\theta^T \mathbf{x} = 0$.

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- Similarly, we think of logistic regression as making a very confident prediction of $y = 0$, if $\theta^\top x \ll 0$.
- Given a training set, again informally it seems that we'd have found a good fit to the training data if we can find θ so that:

$$\theta^\top x \gg 0 \text{ whenever } y^{(i)} = 1$$

and

$$\theta^\top x \ll 0 \text{ whenever } y^{(i)} = 0$$

since this would reflect a very confident (and correct) set of classifications for all the training examples.

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- We will use $y \in \{-1, 1\}$ and instead of the vector θ , we will use parameters w, b .
- So our classifier can be written as $h_{w,b}(x) = g(w^\top x + b)$.
- Here, $g(z) = 1$ if $z \geq 0$, and $g(z) = -1$ otherwise.

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- Conversely, if $y^{(i)} = -1$, then for the functional margin to be large, then we need $w^\top x + b$ to be a large negative number.
- Moreover, if $y^{(i)}(w^\top x + b) > 0$, then our prediction on this example is correct. Hence, a large functional margin represents a confident and a correct prediction.

Functional Margin

- For a linear classifier with the choice of $h_{w,b}(x) = g(w^\top x + b)$, note that if we replace w with $2w$ and b with $2b$, then $g(w^\top x + b) = g(2w^\top x + 2b)$ and this would not change $h_{w,b}(x)$.

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- Hence $h_{w,b}(x)$ depends only on the sign and not on the magnitude of $w^\top x + b$.
- However, replacing (w, b) with $(2w, 2b)$ also results in multiplying our functional margin by a factor of 2.
- Thus, it seems that by exploiting our freedom to scale w and b , we can make the functional margin arbitrarily large without really changing anything meaningful.

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- We might replace (w, b) with $(w/\|w\|_2, b/\|w\|_2)$ and instead consider the functional margin of $(w/\|w\|_2, b/\|w\|_2)$.

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- Intuitively, it might therefore make sense to impose some sort of normalization condition such as that $\|w\|_2 = 1$.
- We might replace (w, b) with $(w/\|w\|_2, b/\|w\|_2)$ and instead consider the functional margin of $(w/\|w\|_2, b/\|w\|_2)$.
- Given a training set $S = \{(x^{(i)}, y^{(i)}); i = 1, \dots, m\}$, we define the functional margin of (w, b) with respect to S as the smallest of the functional margins of the individual training examples, denoted by $\hat{\gamma}$:

$$\hat{\gamma} = \min_{i=1, \dots, m} \hat{\gamma}^{(i)}.$$

Geometric Margin

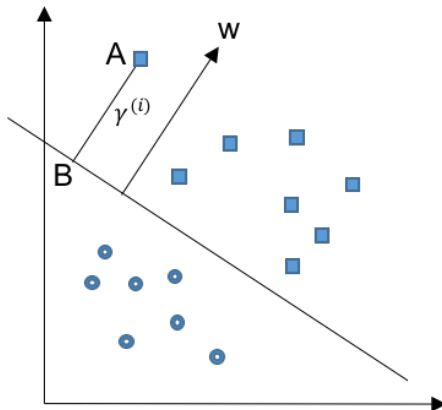
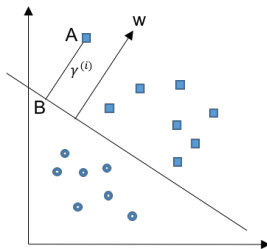


Figure: The decision boundary corresponding to (w, b) is shown, along with the vector w . Note that w is orthogonal (at 90°) to the separating hyperplane.

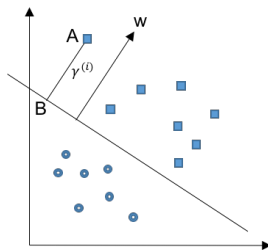
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- How can we find $\gamma^{(i)}$?



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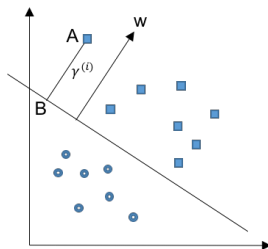
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Geometric Margin

- How can we find $\gamma^{(i)}$?



- Since A represents example $x^{(i)}$, point B is given by $x^{(i)} - \gamma^{(i)} \cdot \frac{w}{\|w\|}$.
- But this point lies on the decision boundary and satisfies $w^T x + b = 0$.

Geometric Margin

- Hence

$$w^{\top} \left(x^{(i)} - \gamma^{(i)} \cdot \frac{w}{\|w\|} \right) + b = 0.$$

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- Hence

$$w^T \left(x^{(i)} - \gamma^{(i)} \cdot \frac{w}{\|w\|} \right) + b = 0.$$

- Solving for $\gamma^{(i)}$

$$\gamma^{(i)} = \frac{w^T x^{(i)} + b}{\|w\|} = \left(\frac{w}{\|w\|} \right)^T x^{(i)} + \frac{b}{\|w\|}.$$

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$$\gamma^{(i)} = \frac{w^T x^{(i)} + b}{\|w\|} = \left(\frac{w}{\|w\|} \right)^T x^{(i)} + \frac{b}{\|w\|}.$$

- More generally we define the geometric margin for (w, b) with respect to a training example $(x^{(i)}, y^{(i)})$ to be

$$\gamma^{(i)} = y^{(i)} \left(\left(\frac{w}{\|w\|} \right)^T x^{(i)} + \frac{b}{\|w\|} \right).$$

Geometric Margin

- Given a training set $S = \{(x^{(i)}, y^{(i)}); i = 1, \dots, m\}$, we also define the geometric margin of (w, b) with respect to S to be the smallest of the geometric margins on the individual training examples:

$$\gamma = \min_{i=1, \dots, m} \gamma^{(i)}.$$

Functional and Geometric Margins

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$$\gamma^{(i)} = y^{(i)} \left(\left(\frac{w}{\|w\|} \right)^\top x^{(i)} + \frac{b}{\|w\|} \right).$$

- Note that if $\|w\| = 1$, then the functional margin equals the geometric margin. This thus gives us a way of relating these two different notions of margin.

Optimal Margin Classifier

- Given a training set, it seems natural to try to find a decision boundary that maximizes the geometric margin, since this would reflect a very confident set of predictions on the training set and a good “fit” to the training data.

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- Given a training set, it seems natural to try to find a decision boundary that maximizes the geometric margin, since this would reflect a very confident set of predictions on the training set and a good “fit” to the training data.
- Specifically, this will result in a classifier that separates the positive and the negative training examples with a “gap” (geometric margin).
- We will assume that we are given a training set that is linearly separable; i.e., that it is possible to separate the positive and negative examples using some separating hyperplane. How can we find the one that achieves the maximum geometric margin?

Optimal Margin Classifier

- We can pose the following optimization problem:

$$\max_{\gamma, w, b} \quad \gamma$$

$$\text{s.t.} \quad y^{(i)}(w^\top x^{(i)} + b) \geq \gamma, i = 1, \dots, m$$

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- The $\|w\| = 1$ constraint ensures that the functional margin equals to the geometric margin, so we are also guaranteed that all the geometric margins are at least γ .
- Thus, solving this problem will result in (w, b) with the largest possible geometric margin with respect to the training set.

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- Lets transform the problem into a nicer one. Consider:

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- Moreover, we've gotten rid of the constraint $\|w\| = 1$ that we didn't like.

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- Since maximizing $\hat{\gamma}/||w|| = 1/||w||$ is the same as minimizing $||w||^2$, we can solve the following optimization problem:

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- This optimization problem can be solved using commercial quadratic programming (QP) code.

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- The β_i 's called the Lagrange multipliers.

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and solve for w and β .

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$$g_i(w^*) \leq 0, i = 1, \dots, k$$

$$\alpha^* \geq 0, i = 1, \dots, k$$

Optimal Margin using Lagrange Method

Previously we posed the following optimization problem for finding the optimal margin classifier:

$$\begin{aligned} \min_{w,b} \quad & \frac{1}{2} ||w||^2 \\ \text{s.t.} \quad & y^{(i)}(w^\top x^{(i)} + b) \geq 1, i = 1, \dots, m \end{aligned}$$

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We can write the constraints as

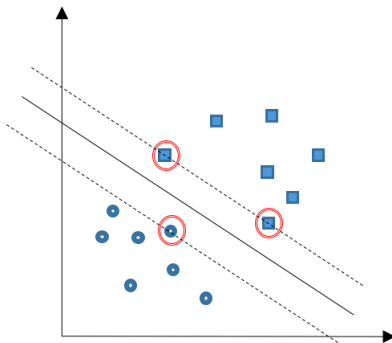
$$g_i(w) = -y^{(i)}(w^\top x^{(i)} + b) + 1 \leq 0.$$

Optimal Margin using Lagrange Method

From the KKT condition $\alpha_i g_i(w) = 0$ we have that $\alpha_i > 0$ only for the training examples that have a functional margin equal to one: the ones corresponding to constraints that hold with equality $g_i(w) = 0$.

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Optimal Margin using Lagrange Method

Then, we can construct the Lagrangian as:

$$\mathcal{L}(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i \left[y^{(i)} (w^\top x^{(i)} + b) - 1 \right].$$

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To solve this Lagrangian first we set the derivatives of \mathcal{L} with respect to w and b to zero:

$$\nabla_w \mathcal{L}(w, b, \alpha) = w - \sum_{i=1}^m \alpha_i y^{(i)} x^{(i)} = 0$$

Optimal Margin using Lagrange Method

Then, we can construct the Lagrangian as:

$$\mathcal{L}(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i \left[y^{(i)} (w^\top x^{(i)} + b) - 1 \right].$$

To solve this Lagrangian first we set the derivatives of \mathcal{L} with respect to w and b to zero:

$$\nabla_w \mathcal{L}(w, b, \alpha) = w - \sum_{i=1}^m \alpha_i y^{(i)} x^{(i)} = 0$$

which implies

$$w = \sum_{i=1}^m \alpha_i y^{(i)} x^{(i)}.$$

Optimal Margin using Lagrange Method

As for the derivative of \mathcal{L}

$$\mathcal{L}(\mathbf{w}, b, \alpha) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^m \alpha_i \left[y^{(i)} (\mathbf{w}^\top \mathbf{x}^{(i)} + b) - 1 \right].$$

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with respect to b we obtain:

$$\frac{\partial}{\partial b} \mathcal{L}(\mathbf{w}, b, \alpha) = \sum_{i=1}^m \alpha_i y^{(i)} = 0.$$

Optimal Margin using Lagrange Method

Now, replacing

$$\mathbf{w} = \sum_{i=1}^m \alpha_i y^{(i)} \mathbf{x}^{(i)}$$

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$$\mathcal{L}(\mathbf{w}, b, \alpha) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^m \alpha_i \left[y^{(i)} (\mathbf{w}^\top \mathbf{x}^{(i)} + b) - 1 \right].$$

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and simplifying it, we get

$$\mathcal{L}(\mathbf{w}, b, \alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m y^{(i)} y^{(j)} \alpha_i \alpha_j (\mathbf{x}^{(i)})^\top \mathbf{x}^{(j)} - b \sum_{i=1}^m \alpha_i y^{(i)}.$$

Optimal Margin using Lagrange Method

And considering that

$$\frac{\partial}{\partial b} \mathcal{L}(w, b, \alpha) = \sum_{i=1}^m \alpha_i y^{(i)} = 0.$$

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Optimal Margin using Lagrange Method

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Optimal Margin using Lagrange Method

So, by minimizing $\mathcal{L}(w, b, \alpha)$ with respect to w and b we have:

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which is now a just function of α :

$$\mathcal{W}(\alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m y^{(i)} y^{(j)} \alpha_i \alpha_j \langle x^{(i)}, x^{(j)} \rangle.$$

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where

$$\langle x^{(i)}, x^{(j)} \rangle$$

is a dot product.

Optimal Margin using Lagrange Method

Now we need to maximize $\mathcal{W}(\alpha)$ subject to some constraints:

$$\max_{\alpha} \mathcal{W}(\alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m y^{(i)} y^{(j)} \alpha_i \alpha_j \langle \mathbf{x}^{(i)}, \mathbf{x}^{(j)} \rangle.$$

$$\text{s.t. } \alpha_i \geq 0, \quad i = 1, \dots, m$$

$$\sum_{i=1}^m \alpha_i y^{(i)} = 0$$

Optimal Margin using Lagrange Method

Once, we have found the optimal w, b, α values, we can predict a new input x to be 1 if

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$$\begin{aligned} w^T x + b &= \left(\sum_{i=1}^m \alpha_i y^{(i)} x^{(i)} \right)^T x + b \\ &= \sum_{i=1}^m \alpha_i y^{(i)} \langle x^{(i)}, x \rangle + b. \end{aligned}$$

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Thank You!

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