# Vidhi Jain

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#### Education

- 2022- PhD Candidate, Carnegie Mellon University.
- 2025 Robotics Institute, Advisor: Yonatan Bisk
- 2019 Masters of Science in Robotics, Carnegie Mellon University.
- 2021 Robotics Institute, GPA 4.0 Advisor: Katia Sycara
- 2014 Bachelor of Engineering (Honors) in Computer Science, BITS Pilani.
- 2018 CGPA 9.06/10.00, Distinction, Advisor (off-campus thesis): Aaron Courville

### Experience

- Sep'24- Stanford, Palo Alto, CA, USA.
- Present Visiting Researcher with Dorsa Sadigh
  - o Developing sim2real active perception policy for in-the-wild visual QA on object geometry and semantics.
- Jun'23- Google DeepMind, Mountain View, CA, USA.
- Feb'24 Student Researcher with Debidatta Dwibedi
  - o Trained video-conditioned robot policies with cross-attention transformers. Vid2Robot (RSS'24)
  - o Extended models for visual grounding with conditional caption generation for QA. FlexCap (NeurIPS'24)
  - Evaluated LLM prompts for low-level motion control for articulated object interaction. PromptBook (ICRA'24)
  - Developed pipelines for zero-shot and fine-tuned task evaluations for single neural network policy trained on aggregated robotics data. Open X-Embodiment (ICRA'24) Best Paper.
- Sep'21- Meta (Facebook), Menlo Park, CA, USA.
- Aug'22 Al resident with Akshara Rai and Yixin Lin
  - o Developed synthetic data for robot demonstrations of loading the simulated dishwasher in Al Habitat. Code
  - o Trained Encoder-decoder Transformer-based high-level policy for learning preferences in loading dishwasher from a single demonstration as prompt. Paper | Website
- Aug'18- Microsoft Research, Bengaluru, India.
- Aug'19 Research Fellow with Amit Deshpande and Navin Goyal
  - o **Divergence minimization in GANs** Investigated the properties of Jensen Shannon and Wasserstein divergences between the given and the generated distributions during training neural network generators, to discuss the learning dynamics like convergence and generalization.
- Jan'18- Montreal Institute for Learning Algorithms (MILA), Montreal, QC, Canada.
- Jun'18 Research Intern with Aaron Courville
  - Out-of-Distribution Detection in Generative Models Experimented on autoregressive generative models and Variational Autoencoders, to detect any 'out-of-distribution (OOD)' sample at deployment. Thesis
- May'17- **Simon Fraser University (SFU)**, Burnaby, BC, Canada.
  - Jul'17 MITACS Globalink Research Intern with Oliver Schulte
    - Learning Bayesian Networks for Relational Databases Remodelled existing codebase for project FactorBase
      to integrate cross-table sufficient statistics or population variables in the contingency tables for learning
      ground-level sufficient statistics. Code | Invited Paper
- May'16- Forschungszentrum Informatik (FZI), Karlsruhe, Germany.
  - Jul'16 Research Intern with York Sure-Vetter and Matthias Frank
    - API annotation platform using Semantic Web Designed and developed a customized Semantic MediaWiki
      for annotation of APIs for dynamic integration of provenance information in the decision support system of
      Project BigGIS; Presented Technical Poster at Grace Hopper Celebration India GHCl'16, Bengaluru, India;
      Extended Abstract | Poster

#### Publications

- Aug 2024 ANAVI: Audio Noise Awareness using Visuals of Indoors for NAVIgation.

  Vidhi Jain, Rishi Veerapanini, Yonatan Bisk. Accepted at Conference of Robot Learning (CoRL) 2024, Munich, Germany. Paper | Website
- Mar 2024 FlexCap: Generating Rich, Localized, and Flexible Captions in Images.

  Debidatta Dwibedi, Vidhi Jain, Jonathan Tompson, Andrew Zisserman, Yusuf Aytar. Accepted at Conference on Neural Information Processing Systems (NeurIPS) 2024, Vancouver, Canada. Paper | Website
- Jan 2024 Vid2Robot: End-to-end Video-conditioned Policy Learning with Cross-Attention Transformers.
  Vidhi Jain, Maria Attarian, Nikhil J Joshi, Ayzaan Wahid, Danny Driess, Quan Vuong, Pannag R Sanketi, Pierre Sermanet, Stefan Welker, Christine Chan, Igor Gilitschenski, Yonatan Bisk, Debidatta Dwibedi, In Proceedings of Robotics: Science and Systems (RSS) 2024, Delft, Netherlands. Paper | Website | Video
- Nov 2023 How to Prompt Your Robot: A PromptBook for Manipulation Skills with Code as Policies.

  Montserrat Gonzalez Arenas, Ted Xiao, Sumeet Singh, Vidhi Jain, Allen Z. Ren, Quan Vuong, Jake Varley, Alexander Herzog, Isabel Leal, Sean Kirmani, Dorsa Sadigh, Vikas Sindhwani, Kanishka Rao, Jacky Liang, Andy Zeng. In Proceedings at International Conference on Robotics and Automation (ICRA) 2024, Yokohama, Japan. Paper
- Nov 2023 Open X-Embodiment: Robotic Learning Datasets and RT-X Models.

  Open X-embodiment collaboration. *In Proceedings at* International Conference on Robotics and Automation (ICRA) 2024, Yokohama, Japan. (Best Paper) Paper | Website
- Jun 2023 SLAP: Spatial-Language Attention Policies.
   Priyam Parasher, Vidhi Jain, Xiaohan Zhang, Jay Vakil, Sam Powers, Yonatan Bisk, Chris Paxton. In Proceedings of Conference on Robot Learning (CoRL) 2023, Atlanta, USA., Paper | Website
- Jun 2023 HomeRobot: Open-Vocabulary Mobile Manipulation.

  Sriram Yenamandra, Arun Ramachandran, Karmesh Yadav, Austin S Wang, Mukul Khanna, Theophile Gervet, Tsung-Yen Yang, Vidhi Jain, Alexander Clegg, John M Turner, Zsolt Kira, Manolis Savva, Angel X Chang, Devendra Singh Chaplot, Dhruv Batra, Roozbeh Mottaghi, Yonatan Bisk, Chris Paxton. In Proceedings of Conference on Robot Learning (CoRL) 2023, Atlanta, USA. Paper | Website | Competition @ NeurIPS 2023
- Dec 2022 **Transformers are Adaptable Task Planners**. **Vidhi Jain**, Yixin Lin, Eric Undersander, Yonatan Bisk, Akshara Rai. *In Proceedings of* Conference on Robot Learning (CoRL) 2022, Auckland, New Zealand. Paper | Website | Video | Code

## Workshop Presentations

- Dec 2022 MAEA: Multimodal Attribution for Embodied AI.

  Vidhi Jain, Jayant Sravan Tamarapalli, Sahiti Yerramilli, Yonatan Bisk. Presented at NeurIPS 2022, 5th Robot Learning Workshop: Trustworthy Robotics (RLW 2022), New Orleans, USA. Short Paper | Website | Video
- Oct 2020 Predicting Strategies in Simulated Search and Rescue.

  Vidhi Jain, Rohit Jena, Huao Li, Tejus Gupta, Dana Hughes, Michael Lewis, Katia Sycara. Presented at NeurlPS AI+HADR 2020, Virtual. Video | Preprint
- Oct 2020 Learning Embeddings that Capture Spatial Semantics for Indoor Navigation.

  Vidhi Jain, Shishir Patil, Prakhar Agarwal, Katia Sycara. Presented at NeurIPS 2020 Object Representations for Learning and Reasoning (ORLR 2020), Virtual. Video | Preprint | Code
- Sep 2020 Learning to Navigate in Unseen Cluttered Structured Environments.

  Vidhi Jain, Ganesh Iyer, Katia Sycara. NeurIPS 2020 Women In Machine Learning (WiML 2020), Virtual. Poster
- Jul 2020 Coping with Sample Inefficiency in Deep Reinforcement Learning (DRL) in embodied AI.
  Vidhi Jain, Simin Liu, Ganesh Iyer. ICML'20 Women In Machine Learning (WiML) Un-Workshop, Virtual.
  Discussion | Presentation
- Aug 2017 Model Selection Scores for Multi-Relational Bayesian Networks.

  Sajjad Gholami, Oliver Schulte, Vidhi Jain, Qiang Zhao. IJCAI 2017 Declarative Learning Based Programming (DeLBP). Invited Paper

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- Dec 2023 **Towards General-Purpose Robots via Foundation Models: A Survey and Meta-Analysis**.

  Yafei Hu\*, Quanting Xie\*, **Vidhi Jain**\*, Jonathan Francis, Jay Patrikar, Nikhil Keetha, Seungchan Kim, Yaqi Xie, Tianyi Zhang, Shibo Zhao, Yu Quan Chong, Chen Wang, Katia Sycara, Matthew Johnson-Roberson, Dhruv Batra, Xiaolong Wang, Sebastian Scherer, Zsolt Kira, Fei Xia, Yonatan Bisk. Paper | Website
- Nov 2019 Towards Zero-Shot Alignment and Retrieval for Forensic Detection.

  Vidhi Jain\*, Amrit Setlur\*, Aditya Pratapa\*. Report

## Tech Reports

- Aug 2021 Towards Explainable Embodied Al. Masters Thesis. Report
- Jun 2018 Investigating the viability of Generative Models for Novelty Detection. Bachelors Thesis. Report

#### Selected Awards and Honors

- Aug 2020 CIFAR Deep Learning Reinforcement Learning Summer School
- Apr 2020 Young Researcher at Heidelberg Laureate Forum (HLF '20) among 224 researchers worldwide.
- Jul 2019 J N Tata Endowment Scholarship for Higher Studies, India
- Jun 2019 K. C. Mahindra Scholarships for Post-Graduate Studies Abroad
- May 2017 ACM-W Scholarship for Attendance at Research Conferences
- Mar 2017 **Citi Women Leader Award (CWLA), Mumbai, India**, Awarded one year of study scholarship covering upto INR 400,000 i.e. USD 6000, among the top 3 out of 1200 applicants
- Jun 2016 **GE Foundation Scholar-Leaders Program (GEFSLP)**, Awarded USD 2000 for two years of study, among top 5 scholars selected in India
- Mar 2016 National Finalists at Microsoft's 'Build the Shield', Hyderabad, India, Ranked  $15^{th}$  nationwide
- 2014–15 Merit Scholarship by Dean, BITS Pilani, Top 1% among the batch of about 900 students
  - 2013 Awarded Kishore Vaigyanik Protsahan Yojna (KVPY) Fellowship by Dept of Science and Tech., Govt.of India
  - 2010 Awarded National Talent Search Exam (NTSE) Scholarship by NCERT, India
  - 2010 Ranked Top 1% in Regional State in National Standard Examination in Junior Science (NSEJS)

#### Talks

Mar 2024 How to think of multimodality in Embodied Al and Robotic Manipulation?.

Guest Lecture in Multimodal Machine Learning course. Lecture Video

Apr 2023 Training vision models in PyTorch.

Hands-on lecture in Computer Vision course. Lecture Video

Oct 2021 Three brushes to paint your research canvas.

SAiDL (Virtual) Video | Event Poster

May 2019 Tutorial on Deep Learning with PyTorch.

 $PyLadies\ Bangalore,\ India.\ Presentation\ |\ Event\ Poster$ 

Jan 2019 The One in Asankhya Project.

by Sukriti Paul and Mansi Goyal (Virtual) Video | Blog

Aug 2018 Invited panelist for 'Research in undergraduate studies'.

IIIT-Bangalore ACM Student Chapter, Bangalore, India Video

Jul 2017 Invited panelist for 'Innovation by Young India'.

telecasted on national news channel NDTV India at New Delhi office. Video

## Professional Service and Leadership

- Sep'23— **Reviewer** at IEEE International Conference on Robotics and Automation (ICRA), International Conference Present on Intelligent Robots and Systems (IROS)
- Jan'20- **Reviewer** at International Conference on Machine Learning (ICML), Neural Information Processing and Present Signal (NeurIPS) and International Conference on Learning Representations (ICLR).
- Jun'20- Workshop Session Organizer | Coping with Sample Inefficiency in Deep Reinforcement Learning (DRL)
- Jul'20 in embodied AI, ICML'20 WiML Un-Workshop, Virtual. Report | Presentation
- Sep'17- Co-Founder and Vice Chair | BITS Pilani Association for Computing Machinery-Women (ACM-W)
- May'18 Chapter, Started with 16 on-campus girls, organized project brainstorming and mentoring sessions
- May'15- Technical Volunteer | ARISE Impact, non-profit organization Developed Android application for
- Aug'15 Audio-based learning for visually challenged

## Teaching Experience

- Jan'24- Teaching Assistant | 11777 Multimodal Machine Learning by Yonatan Bisk. Mentoring 5 teams with
- May'24 3-5 students each for semester-long research projects.
- Jan'23- Teaching Assistant | 16720 Computer Vision by Deva Ramanan. for 106 students enrolled in the course,
- May'23 prepared homework, and graded.
- Jan'17- Teaching Assistant | CS F111 Computer Programming by Vishal Gupta, Mentored 35 students for 4
- May'17 hours per week for Code programming lab sessions.
- Aug'14- Teaching Volunteer | Computer Literacy Programme, National Service Scheme, Tutored 12-15 rural
- May'15 natives for 3 hours per week on computer applications.

#### References

Yonatan Bisk, Assistant Professor, Carnegie Mellon University, ybisk at andrew.cmu.edu

Debidatta Dwibedi, Research Scientist, Google DeepMind, Mountain View, debidatta at google.com

Akshara Rai, Research Scientist, Meta (previously Facebook), Menlo Park, akshararai at meta.com