

## EIGEN VALUES AND EIGEN VECTORS — 14.21

Ans.  $\begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$

8.  $Q = (x_1 + x_2 + x_3)^2$

Ans.  $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

9.  $Q = 4x_1x_3 + 2x_2x_3 + x_3^2$

Ans.  $\begin{bmatrix} 0 & 0 & 2 \\ 0 & 0 & 1 \\ 2 & 1 & 1 \end{bmatrix}$

Verify that the following matrices are orthogonal:

10.  $\frac{1}{3} \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & -2 \\ 2 & -2 & 1 \end{bmatrix}$

**Hint:** Show that  $AA^T = I$ .

11.  $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

12. Prove that the product  $AB$  of two symmetric matrices  $A$  and  $B$  is symmetric if  $AB = BA$ .

**Hint:**  $(AB)^T = B^T A^T = BA$  since  $A = A^T, B = B^T$ , so  $(AB)^T = BA = AB$  then  $AB$  is symmetric. Provided  $AB = BA$ .

### 14.7 CANONICAL FORM: or SUM OF THE SQUARES FORM

Of a real quadratic form  $Q = X^T A X$  is  $Y^T D Y$  or

$$\lambda_1 y_1^2 + \lambda_2 y_2^2 + \cdots + \lambda_n y_n^2 \quad (1)$$

which is obtained by an orthogonal transformation  $X = P Y$ . Here  $P$  is known as **modal** matrix.  $D$  is known as **spectral** matrix.  $D$  is a diagonal matrix with the eigen values of  $A$  as the diagonal elements.

Let  $r$  be the rank of  $A$  and  $n$  be the number of variables  $x_1, x_2, \dots, x_n$  in the quadratic form. Then:

**Index**  $S$  of a quadratic form is the number of positive square terms in the canonical form.

**Signature** of a quadratic form is the difference between the number of positive and negative square terms in the canonical form.

**Definiteness** A real nonsingular quadratic form  $Q = X^T A X$  (with  $|A| \neq 0$ ) is said to be

**Positive definite:** If rank and index are equal i.e.,  $r = n, s = n$  or if all the eigen values of  $A$  are positive

**Negative definite:** If index equals to zero i.e.,  $r = n, s = 0$  or if all the eigen values of  $A$  are negative.

**Positive semi-definite:** If rank and index are equal but less than  $n$

i.e.,  $s = r < n, (|A| = 0)$

or all eigen values of  $A$  are non-negative ( $\geq 0$ ) and at least one eigen value is zero.

**Negative semi definite:** If index zero

i.e.,  $s = 0, r < n, (|A| = 0)$

or all eigen values of  $A$  are non-positive ( $\leq 0$ ) and at least one eigen value is zero.

**Indefinite:** Quadratic form is said to be indefinite in any other case or some eigen values are positive and some eigen values are negative.

**Note:** If  $Q$  is negative definite (semi-definite) then  $-Q$  is positive definite (semi-definite).

### WORKED OUT EXAMPLES

**Example 1:** Determine the nature, index and signature of the quadratic form  $2x_1^2 + 2x_2^2 + 3x_3^2 + 2x_1x_2 - 4x_1x_3 - 4x_2x_3$ .

**Solution:** The real symmetric matrix  $A$  associated with the Q.F. is

$$A = \begin{bmatrix} 2 & 1 & -2 \\ 1 & 2 & -2 \\ -2 & -2 & 3 \end{bmatrix}$$

Its characteristic equation is

$$\begin{vmatrix} 2-\lambda & 1 & -2 \\ 1 & 2-\lambda & -2 \\ -2 & -2 & 3-\lambda \end{vmatrix}$$

$$= \lambda^3 - 7\lambda^2 + 7\lambda - 1 = 0$$

$$= (\lambda - 1)(\lambda - (3 + \sqrt{8}))(\lambda - (3 - \sqrt{8})) = 0$$

## 14.22 — HIGHER ENGINEERING MATHEMATICS—IV

The eigen values are  $\lambda = 1, 0.1715, 3.1715$  which are all positive. So Q.F. is positive definite.

Index: 3, Signature :  $3 - 0 = 3$ .

**Example 2:** Find the nature, index and signature of Q.F.

$$2x_1x_2 + 2x_1x_3 + 2x_2x_3$$

**Solution:**  $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$

Characteristic equation is

$$\begin{vmatrix} -\lambda & 1 & 1 \\ 1 & -\lambda & 1 \\ 1 & 1 & -\lambda \end{vmatrix} = 0$$

$$\lambda^3 - 3\lambda - 2 = 0 \quad \text{or} \quad (\lambda + 1)^2(\lambda - 2) = 0$$

The eigen values are 2, -1, -1, some are positive and some are negative. So the Q.F. is indefinite.

Index: 1, Signature:  $1 - 2 = -1$ .

**Example 3:** Identify the nature, index and signature of the Q.F.

$$x_1^2 + 4x_2^2 + x_3^2 - 4x_1x_2 + 2x_3x_1 - 4x_2x_3$$

**Solution:**  $A = \begin{bmatrix} 1 & -2 & 1 \\ -2 & 4 & -2 \\ 1 & -2 & 1 \end{bmatrix}$

Characteristic equation is

$$|A - \lambda I| = \begin{vmatrix} 1-\lambda & -2 & 1 \\ -2 & 4-\lambda & -2 \\ 1 & -2 & 1-\lambda \end{vmatrix} = \lambda^2(\lambda - 6) = 0$$

Eigen values are  $\lambda = 0, 0, 6$ . So Q.F. is positive semi definite.

Index: 3, Signature: 3.

**Example 4:** Classify the Q.F. and find the index and signature of

$$-3x_1^2 - 3x_2^2 - 3x_3^2 - 2x_1x_2 - 2x_1x_3 + 2x_2x_3$$

**Solution:**  $A = \begin{bmatrix} -3 & -1 & -1 \\ -1 & -3 & 1 \\ -1 & 1 & -3 \end{bmatrix}$

Characteristic equation is

$$\begin{vmatrix} -3-\lambda & -1 & -1 \\ -1 & -3-\lambda & 1 \\ -1 & 1 & -3-\lambda \end{vmatrix} = 0$$

$$\lambda^3 + 9\lambda^2 + 24\lambda + 16 = (\lambda + 1)(\lambda + 4)^2 = 0$$

All the eigen values -1, -4, -4, are negative. Q.F. is negative definite.

Index: 0, Signature:  $0 - 3 = -3$ .

**Note:**

$$Q = 3x_1^2 + 3x_2^2 + 3x_3^2 + 2x_1x_2 + 2x_1x_3 - 2x_2x_3$$

is positive definite.

### EXERCISE

Determine the nature, index and signature of the quadratic form:

1.  $x_1^2 + 2x_2^2 + 3x_3^2 + 2x_2x_3 - 2x_3x_1 + 2x_1x_2$

Ans. indefinite (eigen value: 1, 1, -2), index: 2, signature: 1

2.  $5x_1^2 + 26x_2^2 + 10x_3^2 + 4x_2x_3 + 14x_3x_1 + 6x_1x_2$

Ans. positive semi definite (eigen value: 5, 0, 5), index: 3, signature: 3

3.  $x_1^2 + 5x_2^2 + x_3^2 + 2x_1x_2 + 2x_2x_3 + 6x_3x_1$

Ans. indefinite (eigen value: -2, 3, 6), index: 2, signature: 1

4.  $3x_1^2 + 5x_2^2 + 3x_3^2 - 2x_2x_3 + 2x_3x_1 - 2x_1x_2$

Ans. positive definite (eigen value: 2, 3, 6), index: 3, signature: 3

5.  $8x_1^2 + 7x_2^2 + 3x_3^2 - 12x_1x_2 - 8x_2x_3 + 4x_3x_1$

Ans. positive semi definite (eigen value: 3, 0, 1), index: 3, signature: 3

6.  $6x_1^2 + 3x_2^2 + 3x_3^2 - 4x_1x_2 - 2x_2x_3 + 4x_1x_3$

Ans. positive definite (eigen value: 8, 2, 2), index: 3, signature: 3

7.  $-4x_1^2 - 2x_2^2 - 13x_3^2 - 4x_1x_2 - 8x_2x_3 - 4x_1x_3$

Ans. negative definite, index: 0, signature: -3

8.  $-3x_1^2 - 3x_2^2 - 7x_3^2 - 6x_1x_2 - 6x_2x_3 - 6x_1x_3$

Ans. negative definite, index: 0, signature: -3

### 14.8 TRANSFORMATION (REDUCTION) OF QUADRATIC FORM TO CANONICAL FORM

Let  $Q$  be the quadratic form given by

$$Q = X^T A X = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j \quad (1)$$

The coefficient matrix  $A$  is real symmetric therefore has  $n$  linearly independent orthonormal set of eigen vectors corresponding  $n$  eigen values (which need not necessarily be distinct). Let  $\hat{P}$  be normalized modal matrix of  $A$ . Then  $\hat{P}$  is an orthogonal matrix.

Thus the transformation

$$X = \hat{P} Y \quad (2)$$

is an orthogonal transformation. This transfers the quadratic form  $Q$  to canonical form, as follows:

We know that  $P$  diagonalizes  $A$ . Thus

$$\begin{aligned} \hat{P}^{-1} A \hat{P} &= D \\ A &= \hat{P} D \hat{P}^{-1} = \hat{P} D \hat{P}^T \end{aligned} \quad (3)$$

since  $\hat{P}^{-1} = \hat{P}^T$  by virtue of orthogonality  
Substituting (3) in (1)

$$Q = X^T A X = X^T \hat{P} D \hat{P}^T X = (X^T \hat{P})(D)(\hat{P}^T X) \quad (4)$$

Pre-multiplying (2) by  $\hat{P}^{-1}$ , we get

$$\hat{P}^{-1} X = \hat{P}^{-1} \hat{P} Y = Y$$

$$\text{So } Y = \hat{P}^{-1} X = \hat{P}^T X \quad (5)$$

since  $\hat{P}^{-1} = \hat{P}^T$

Taking transpose of this equation

$$Y^T = (\hat{P}^T X)^T = X^T \hat{P} \quad (6)$$

Using (5) and (6) in (4), we have

$$\begin{aligned} Q &= X^T A X = Y^T D Y \\ &= [y_1, y_2, \dots, y_n] \begin{bmatrix} \lambda_1 & 0 & 0 & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \lambda_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \\ Q &= \lambda_1 y_1^2 + \lambda_2 y_2^2 + \dots + \lambda_n y_n^2 \end{aligned} \quad (7)$$

(7) is known as the *canonical form* or "*sum of the squares form*" or "*principal axes form*".

### Procedure to Reduce Quadratic Form to Canonical Form

1. Identify the real symmetric matrix associated with the quadratic form  $Q$ .
2. Determine the eigen values of  $A$ .
3. The required canonical form is given by (7)
4. Form the modal matrix containing the  $n$  eigen vectors of  $A$  as  $n$  column vectors. Normalize. Then

$$X = \hat{P} Y$$

is the required orthogonal transformation which reduces Q.F. to C.F.

### WORKED OUT EXAMPLES

**Example 1:** Find the orthogonal transformation which transforms the quadratic form

$$x_1^2 + 3x_2^2 + 3x_3^2 - 2x_2x_3$$

to canonical form (or "sum of squares form" or "principal axes form"). Determine the index, signature and nature of the quadratic form.

**Solution:** Let  $X = [x_1 x_2 x_3]^T$ ,  $Y = [y_1 y_2 y_3]^T$ . Let  $P$  be the non-singular orthogonal matrix, containing the (three) eigen vectors of the coefficient matrix  $A$  of the given quadratic form. Then  $X = \hat{P} Y$  is the required non-singular linear transformation that transforms (reduces) the given quadratics form to canonical form. Here  $\hat{P}$  is the normalized modal matrix  $P$ . The coefficient matrix  $A$  of the given quadratic form is

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix}$$

The characteristic equation of  $A$  is

$$\begin{aligned} |A - \lambda I| &= \begin{vmatrix} 1-\lambda & 0 & 0 \\ 0 & 3-\lambda & -1 \\ 0 & -1 & 3-\lambda \end{vmatrix} = \lambda^3 - 7\lambda^2 + 14\lambda - 8 \\ &= (\lambda - 1)(\lambda - 2)(\lambda - 4) = 0 \end{aligned}$$

So there are three distinct real eigen values  $\lambda = 1, 2, 4$  of  $A$ .

## 14.24 — HIGHER ENGINEERING MATHEMATICS—IV

For  $\lambda = 1$ ,

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \sim \begin{cases} 2x_2 = x_3 \\ x_2 = 2x_3 \end{cases}$$

$\therefore x_2 = x_3 = 0, x_1 = \text{arbitrary}$ ,

The eigen vector  $X_1$  associated with  $\lambda = 1$  is

$$X_1 = [1 \ 0 \ 0]^T$$

For  $\lambda = 2$ ,

$$\begin{aligned} -x_1 + 0 + 0 &= 0 \\ x_2 - x_3 &= 0 \\ -x_2 + x_3 &= 0 \end{aligned} \quad \therefore \begin{cases} x_1 = 0 \\ x_2 = x_3 \\ x_2 = -x_3 \end{cases}$$

$$X_2 = [0 \ 1 \ 1]^T$$

For  $\lambda = 3$ ,

$$\begin{bmatrix} -3 & 0 & 0 \\ 0 & -1 & -1 \\ 0 & -1 & -1 \end{bmatrix} \sim \begin{cases} x_1 = 0 \\ x_2 = -x_3 \end{cases}$$

$$X_3 = [0 \ 1 \ -1]^T$$

Thus the modal matrix  $P$  is

$$P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix}$$

The norm of the eigen vector  $X_1$  is

$$\|X_1\| = \sqrt{1^2 + 0 + 0} = 1,$$

$$\|X_2\| = \sqrt{0 + 1^2 + 1^2} = \sqrt{2},$$

$$\|X_3\| = \sqrt{1^2 + 1^2} = \sqrt{2}.$$

Then the normalized modal matrix  $\hat{P}$  is

$$\hat{P} = \begin{bmatrix} \frac{1}{1} & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix}$$

To find inverse of  $P$ :

$$\begin{aligned} &\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & 0 & 0 & 1 \end{array} \right] \\ &\sim \begin{matrix} R_{32}(-1) \\ R_{3(-\frac{1}{2})} \\ R_{23}(-1) \end{matrix} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 1 & 0 & \frac{1}{2} & -\frac{1}{2} \end{array} \right] \end{aligned}$$

Thus

$$P^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$

and the normalized  $P^{-1}$  is

$$\hat{P}^{-1} = \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix}$$

Diagonalization:

$$\begin{aligned} \hat{P}^{-1} A \hat{P} &= \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix} \\ &\times \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \\ &= \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 4 & -4 \end{bmatrix} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \\ &= \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 8 \end{bmatrix} \end{aligned}$$

Then

$$\hat{P}^{-1} A \hat{P} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix} = D = \text{diagonal matrix}$$

with the eigen values of  $A$  as the diagonal elements  
Transformation (reduction) to canonical form:

Quadratic form (Q.F.)

$$Q = x_1^2 + 3x_2^2 + 3x_3^2 - 2x_2x_3$$

$$= [x_1 \ x_2 \ x_3] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = X^T A X$$

Put  $X = \hat{P}Y$  and  $X^T = (\hat{P}Y)^T = Y^T \hat{P}^T$ .  
So  $Q = X^T A X = Y^T \hat{P}^T A \hat{P} Y = Y^T (\hat{P}^T A \hat{P}) Y$   
But we know that  $\hat{P}$  is an orthogonal matrix  
because

$$\begin{aligned} \hat{P} \hat{P}^T &= \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \\ &= \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I \end{aligned}$$

Thus

$$\hat{P}^T = \hat{P}^{-1}$$

So

$$Q.F. = X^T A X = Y^T (\hat{P}^{-1} A \hat{P}) Y$$

But through diagonalization

$$\hat{P}^{-1} A \hat{P} = D$$

Therefore

$$\begin{aligned} Q &= X^T A X = Y^T D Y \\ &= [y_1 \ y_2 \ y_3] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \\ &= [y_1 \ 2 \cdot y_2 \ 4y_3] \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \\ &= y_1^2 + 2y_2^2 + 4y_3^2 \end{aligned}$$

This is the required canonical form (or sum of squares form).

Orthogonal transformation:

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \hat{P} Y = \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

so  $x_1 = y_1$ ;  $x_2 = \frac{1}{\sqrt{2}}(y_2 + y_3)$ ,  $x_3 = \frac{1}{\sqrt{2}}(y_2 - y_3)$  is the orthogonal transformation which reduces the Q.F. to canonical form.

Index is 3 for the Q.F. since the number of positive terms in the canonical form is 3. i.e.,  $S = 3$ , rank  $r$  is 3. The number of variables is  $n = 3$ .

Signature of Q.F. is  $2s - r = 6 - 3 = 3$  (difference between number of positive and negative terms in C.F.).

The given Q.F. is *positive definite* because  $r = 3 = n$  and  $s = 3 = n$ .

**Example 2:** By Lagrange's reduction transform the quadratic form  $X^T A X$  to sum of the squares form for

$$A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & -2 \\ 4 & -2 & 18 \end{bmatrix}$$

Solution:

$$Q.F. = X^T A X = [x_1 \ x_2 \ x_3] \begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & -2 \\ 4 & -2 & 18 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$Q.F. = [x_1 + 2x_2 + 4x_3 \ 2x_1 + 6x_2 - 2x_3 \ 4x_1 - 2x_2 + 18x_3] \times \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= x_1^2 + 6x_2^2 + 18x_3^2 + 4x_1x_2 + 8x_1x_3 - 4x_2x_3$$

$$= [x_1^2 + 4x_1(x_2 + 2x_3)] + 6x_2^2 + 18x_3^2 - 4x_2x_3$$

$$= [x_1^2 + 4x_1(x_2 + 2x_3) + 2^2(x_2 + 2x_3)^2]$$

$$- 2^2(x_2 + 2x_3)^2 + 6x_2^2 + 18x_3^2 - 4x_2x_3$$

$$= [x_1 + 2(x_2 + 2x_3)]^2 + 2x_2^2 + 2x_3^2 - 20x_2x_3$$

$$= [x_1 + 2(x_2 + 2x_3)]^2 + 2[x_2^2 - 10x_2x_3] + 2x_3^2$$

$$= [x_1 + 2(x_2 + 2x_3)]^2$$

$$+ 2[x_2^2 - 10x_2x_3 + 5^2x_3^2] - 2 \cdot 5^2x_3^2 + 2x_3^2$$

$$= [x_1 + 2(x_2 + 2x_3)]^2 + 2[x_2 - 5x_3]^2 - 48x_3^2$$

$$Q.F. = y_1^2 + 2y_2^2 - 48y_3^2$$

where

$$y_1 = x_1 + 2(x_2 + 2x_3),$$

$$y_2 = x_2 - 5x_3,$$

$$y_3 = x_3.$$

Index:  $S = 2$ , ( $n = 3$ ,  $r = 3$ ),

Signature:  $2s - r = 2 \cdot 2 - 3 = 1$  (or  $2 - 1 = 1$ ).

### EXERCISE

**Transform (reduce) the quadratic form to canonical form** (or "sum of squares form" or "principal axes form") by orthogonal transformation.

State matrix for transformation (i.e., modal matrix).

$$1. \ 17x_1^2 - 30x_1x_2 + 17x_2^2$$

$$\text{Ans. } A = \begin{bmatrix} 17 & -15 \\ -15 & 17 \end{bmatrix}, \lambda = 2, 32,$$

$$P = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \frac{1}{\sqrt{2}}, \text{ C.F.: } 2y_1^2 + 32y_2^2$$

## 14.26 — HIGHER ENGINEERING MATHEMATICS—IV

2.  $3x_1^2 + 5x_2^2 + 3x_3^2 - 2x_2x_3 + 2x_1x_3 - 2x_1x_2$

Ans.  $A = \begin{bmatrix} 3 & -1 & 1 \\ -1 & 5 & -1 \\ 1 & -1 & 3 \end{bmatrix}, \lambda = 2, 3, 6,$

$P = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{3}} & -\frac{2}{\sqrt{6}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} \end{bmatrix}, \text{C.F.: } 2y_1^2 + 3y_2^2 + 6y_3^2$

3.  $5x_1^2 + 26x_2^2 + 10x_3^2 + 4x_2x_3 + 6x_1x_2 + 14x_1x_3$

Ans.  $A = \begin{bmatrix} 5 & 3 & 7 \\ 3 & 26 & 2 \\ 7 & 2 & 10 \end{bmatrix}, \lambda = 5, \frac{121}{3}, 0,$

$P = \begin{bmatrix} 1 & -\frac{3}{5} & -\frac{16}{11} \\ 0 & 1 & \frac{1}{11} \\ 0 & 0 & 1 \end{bmatrix}, \text{C.F.: } 5y_1^2 + \frac{121}{3}y_2^2$

4.  $2(x_1x_2 + x_2x_3 + x_3x_1)$ ; nature of Q.F.

Ans.  $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & +1 \\ 1 & +1 & 0 \end{bmatrix}, \lambda = 2, -1, -1,$

$P = \begin{bmatrix} \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{bmatrix},$

C.F.:  $2y_1^2 - y_2^2 - y_3^2$

Nature: Indefinite

5.  $2(x_1^2 + x_1x_2 + x_2^2)$

Ans.  $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}, \lambda = 1, 3,$

$P = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}, \text{C.F.: } y_1^2 + 3y_2^2$

6.  $2x_1^2 + x_2^2 - 3x_3^2 - 8x_2x_3 - 4x_3x_1 + 12x_1x_2$ , find index

Ans.  $A = \begin{bmatrix} 2 & 6 & -2 \\ 6 & 1 & -4 \\ -2 & -4 & -3 \end{bmatrix}, \lambda = 1, -1, -1,$

$P = \begin{bmatrix} a & -3b & \frac{11c}{17} \\ 0 & b & \frac{2b}{17} \\ 0 & 0 & c \end{bmatrix}$

where  $a = 1/\sqrt{2}, b = 1/\sqrt{17}, c = \sqrt{(17/81)},$

C.F.:  $y_1^2 - y_2^2 - y_3^2$ , Index = 1

7.  $3x_1^2 - 2x_2^2 - x_3^2 - 4x_1x_2 + 12x_2x_3 + 8x_1x_3$

Ans.  $A = \begin{bmatrix} 3 & -2 & 4 \\ -2 & -2 & 6 \\ 4 & 6 & -1 \end{bmatrix}, \lambda = 3, 6, -9,$

$P = \frac{1}{3} \begin{bmatrix} 2 & 2 & 1 \\ -2 & 1 & 2 \\ -1 & 2 & 2 \end{bmatrix}, \text{C.F.: } 3y_1^2 + 6y_2^2 - 9y_3^2$

8.  $8x_1^2 + 7x_2^2 + 3x_3^2 + 12x_1x_2 + 4x_1x_3 - 8x_2x_3$   
find the rank, index, signature and nature.

Ans.  $A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}, \lambda = 3, 0, 15,$

$P = \frac{1}{3} \begin{bmatrix} 2 & 1 & 2 \\ 1 & 2 & -2 \\ -2 & 2 & 1 \end{bmatrix}, \text{C.F.: } 3y_1^2 + 15y_2^2$

rank of Q.F.: 2, index: 2, signature 2, positive definite.

### Lagrange's reduction

9.  $x_1^2 + 2x_2^2 - 7x_3^2 - 4x_1x_2 + 8x_1x_3$

Ans.  $(x_1 - 2x_2 + 4x_3)^2 - 2(x_2 - 4x_3)^2 + 9x_3^2$

10.  $2x_1^2 + 5x_2^2 + 19x_3^2 - 24x_4^2 + 8x_1x_2 + 12x_1x_3 + 8x_1x_4 + 18x_2x_3 - 8x_2x_4 - 16x_3x_4$

Ans.  $2(x_1 + 2x_2 + 3x_3 + 2x_4)^2 - 3(x_2 + x_3 + 4x_4)^2 + 4(x_3 - 2x_4)^2$

11.  $2x_1^2 + 7x_2^2 + 5x_3^2 - 8x_1x_2 - 10x_2x_3 + 4x_1x_3$

Ans.  $2(x_1 - 2x_2 - x_3)^2 - (x_2 + x_3)^2 + 4x_3^2$

12. Coefficient matrix  $A = \begin{bmatrix} 1 & -1 & 0 & 2 \\ -1 & 4 & 6 & 4 \\ 0 & 6 & 11 & 8 \\ 2 & 4 & 8 & 8 \end{bmatrix}$

Hint: QF:  $x_1^2 + 4x_2^2 + 11x_3^2 + 8x_4^2 - 2x_1x_2 + 4x_1x_4 + 12x_2x_3 + 8x_2x_4 + 16x_3x_4$

Ans.  $(x_1 - x_2 + 2x_3)^2 + 3(x_2 + 2x_3 + 2x_4)^2 - (x_3 + 4x_4)^2 + 8x_4^2$