

TEST 2 Solutions

1. Use the formula for T to get images of basis vectors in \mathbb{R}^4 :

$$T(1, 0, 0, 0) = (1, 0, 0) = 1 \cdot e_1 + 0 \cdot e_2 + 0 \cdot e_3$$

$$T(0, 1, 0, 0) = (1, 1, 0) = e_1 + e_2 + 0 \cdot e_3$$

$$T(0, 0, 1, 0) = (0, 1, 0) = 0 \cdot e_1 + e_2 + 0 \cdot e_3$$

$$T(0, 0, 0, 1) = (0, 0, 2) = 0 \cdot e_1 + 0 \cdot e_2 + 2 \cdot e_3$$

\therefore The matrix is
$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

2. $N(T) = \{ v \in V : T(v) = \bar{0} \}$

- a) It consists of vectors in V that map to the zero vector in W , under the linear transformation T .

- b) Verify that $Av_1 \neq \bar{0}$, while $A\bar{v}_2 = \bar{0}$.

So $v_1 \notin N(A)$, $v_2 \in N(A)$.

3. See this solved in Lecture 17. The given set is an orthogonal basis, so there is a simple formula for the coefficients!

4. a) Check that the properties of W being a subspace are satisfied, by taking arbitrary vectors in W .
eg. to show W is closed under addition,

$$\text{let } u = (x_1, x_2, x_3) \in W \Rightarrow x_1 = 2x_2$$

$$v = (y_1, y_2, y_3) \in W \Rightarrow y_1 = 2y_2$$

$$\text{Then, } u+v = (x_1+y_1, x_2+y_2, x_3+y_3)$$

$$\begin{aligned} \text{Observe: } x_1 + y_1 &= 2x_2 + 2y_2 \\ &= 2(x_2 + y_2) \end{aligned}$$

$$\therefore u+v \in W.$$

b) Since $x_1 = 2x_2$ for a vector $(x_1, x_2, x_3) \in W$,
an arbitrary vector in W is
of the form $(2x_2, x_2, x_3) : x_2, x_3 \in \mathbb{R}$.

$$= x_2 (2, 1, 0) + x_3 (0, 0, 1).$$

$$W = \text{span}\{(2, 1, 0), (0, 0, 1)\}$$

Further, these vectors are linearly independent.

\therefore a basis of W is $\{(2, 1, 0), (0, 0, 1)\}$.

5. a) You can take any matrix or (finite) set of matrices in $M_2(\mathbb{R})$ and take the span of these.

$$\text{eg. } \text{span}\left\{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right\} \text{ or } \text{span}\left\{\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}\right\}$$

$$\text{or } \text{span}\left\{\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}\right\}$$

But the word "span" is important.

Many of you wrote one or two matrices in $M_2(\mathbb{R})$ as an example.

This is incorrect! A non-zero subspace has infinitely many vectors, not just one or two.

Other examples are : • trace 0 matrices in $M_2(\mathbb{R})$

• upper triangular matrices in $M_2(\mathbb{R})$

• diagonal matrices in $M_2(\mathbb{R})$

b) Using rank-nullity theorem,

$$\begin{aligned} \text{(i)} \quad \dim \text{Range}(T) &= 3 - \dim \ker T \\ &= 3 - 0 \\ &= 3. \end{aligned}$$

(ii) The co-domain is \mathbb{R}^4 , which has dimension 4. Since $\text{Range}(T)$ is not of dimension 4, the map T is not surjective.

c) Many examples can be given.

eg. $(1, 1, -1)$, $(0, -3, 2)$

$$\|v\| = \sqrt{1^2 + 2^2 + 3^2} = \sqrt{14}.$$

d) \mathbb{R}^2 .