Null space of a matrix

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 5 & 4 & 9 \\ 2 & 4 & 6 \end{bmatrix}$$

then
$$\begin{bmatrix} 1 & 0 & 1 \\ 9 & 4 & 9 \\ 2 & 4 & 6 \end{bmatrix} \begin{bmatrix} 4 \\ v \\ w \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

y=c, w=-c guies u=c, for any CER.

c.e.,
$$N(A) = \left\{c \cdot \begin{bmatrix} 1 \\ -1 \end{bmatrix} : ceR \right\}$$

Describe the column space and Exercise:

rull space of me matrices

$$A = \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}, B = \begin{bmatrix} 0 & 0 & 3 \\ 1 & 2 & 3 \end{bmatrix}$$

$$b = \begin{bmatrix} 1 & 3 & 4 \\ 2 & 1 & 5 \end{bmatrix}$$

From the definition of column epace,

$$C(A) = \left\{ c_1 \begin{bmatrix} i \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 0 \end{bmatrix} : c_1, c_2 \in \mathbb{R} \right\}$$

Can you see that his simplifies to:

Notice Mart $c_1[0] + c_2[0] = (c_1-c_2)[0]$

and c,, c, are just scalar, so we can denote it using 'c'.)

$$C(B) = \begin{cases} c_1 \begin{cases} 0 \\ 1 \end{cases} + c_2 \begin{cases} 0 \\ 2 \end{cases} + c_3 \begin{cases} 3 \\ 3 \end{cases} : c_1, c_2, c_3 \end{cases}$$

(what does this simplify to?)

$$C(D) = \left\{ \begin{array}{l} C_1 \left[\frac{1}{2} \right] + C_2 \left[\frac{3}{1} \right] + \frac{1}{3} \left[\frac{4}{5} \right] : C_1, C_2, C_3 \in \mathbb{R} \right\} \\ C Does Kris Set simplify further?) \end{array}$$

The "simplification" we are doing is just removing extra/redundant elements.

We would like to study subsets that span a vector space) subspace as "efficiently' on parible. In order to do so, we need the concept of "Linear Independence":

Definition: A set of vectors $\{v_1, v_2, ..., v_p\}$ in a vector space V is said to be linearly independent if the vector equation independent if the vector equation $c_1v_1 + c_2v_2 + ... + c_pv_p = \bar{0} - \bar{0}$

has only the trivial solution $C_1=0$ $C_2=0$ $C_3=0$

If not, that is, suppose there is a

solution to eyn 1 with some ci's non-zero,

then the vectors $V_1, ..., V_p$ are said to be linearly dependent.

Example

1) $V = \mathbb{R}^2$ The set $\{v_1 = (1_1 2), v_2 = (2_1 0), v_3 = (0,1)\}$ is linearly dependent because $1 \cdot (1,2) - \frac{1}{2}(2_1 0) - 2(0_1 1) = (0_1 0).$ $\frac{1}{2} \quad \frac{1}{2} \quad$

On the other hand, the set $\{w_1=(2_10), w_2=(0_11)\}$ is linearly independent because

if we tay to solve:

$$c_1W_1 + c_2W_2 = \overline{0}$$

i.e., $c_1(2_10) + c_2(0_11) = (0_10)$
we get the equations equations
 $c_1 \cdot 2 + c_2 \cdot 0 = 0 \rightarrow \text{ptr component}$
 $c_1 \cdot 0 + c_2 \cdot 1 = 0$

C1.0 + C2.1 = 0 Le equating and components on both sides

and we see $2C_1 = 0$ $=> C_1 = C_2 = 0$.

So $C_1 = C_2 = 0$ is the DNLY solution, thus, the set $\{(2,0), (0,1)\}$ is linearly independent.

2). $V = \mathbb{P}$ (Set of polynomials with coefficients in \mathbb{R}) $v_1 = 1 \quad \text{(constant polynomial)}$

 $V_2 = t V_3 = 4-t$

Then $\{v_1, v_2, v_3\}$ is linearly dependent because $4v_1 + (-1)v_2 - v_3 = 0$.

How to we check if a given set of vectors are linearly dependent or independent?

Example: Determine whether the vectors $v_1 = (1,2)$ $v_2 = (2,1)$ $v_3 = (3,0)$ are linearly independent or not.

Solution: We want to see whether there are Scalars C_1 , C_2 , C_3 $\in \mathbb{R}$ not all zero, so that $C_1V_1 + C_2V_2 + C_3V_3 = \overline{0}$.

i.e., $C_1(1,2) + C_2(2,1) + C_3(3,0) = (0,0)$ This leads to the linear system:

$$C_1 + 2C_2 + 3C_3 = 0$$

 $2C_1 + C_2 + 0C_3 = 0$

This gives $2C_1 = -C_2$ and $C_1 = 4C_1 + 3C_3 = 0$ So $C_3 = C_1$.

:. This has infinitely many colutions.

In particular, Eaking $C_1=1$, $C_2=-2$, $C_3=1$, (1,2)-2(2,1)+(3,0)=(0,0). Therefore, the vectors V_1,V_2,V_3 are linearly dependent.

NOTE: The intuitive idea for linear dependence is to see if one vector is "dependent" on the hemaining, i.e., "dependent" on the hemaining, i.e., given {v₁,..., v_m}, whether v₁ (or any other years in the set) can be expressed as a linear combination of the remaining vectors.

Some properties that hold for any vector space:

1) If a set contains only ONE vector. Is it always binearly independent?

Ans: We want to see if one set is $\{v\}$,
then $c \cdot v = 0 \Rightarrow c = 0$?

Notice: C·V=O forces C=O only y V is not the zerovedor.

Therefore we infer:

- 1) EVE where v≠ō is ALWRYS linearly independent.
- 2) { $\bar{0}$ } is ALWAYS linearly dependent. Ly in fact, any set with $\bar{0}$ in it is always linearly dependent!

(2) Consider a set of two vectors: { v1, V2}. If these are linearly dependent, this would mean

CIV1 + C2 V2 = 0

with one (and hence both) constants C1 & C2 to be non-zero.

Therefore, $C_1V_1 = -C_2V_2$ $V_1 = -\frac{C_2}{C_1}V_2$

In other words, vi is a scalar) multiple

Similarly, $V_2 := -\frac{C_1}{C_2}v_1$, so v_2 is a scalar multiple $\Im V_1$.

If either c, or c2 is zero, it poaces both c, kc2 to be zero, so me conclude:

Ev., v23 is lin. dependent if and only if v, and v2 are scalar multiples of each other.

Example 4) The columns of the matrix

$$A = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 5 \\ -1 & -3 & 3 & 0 \end{bmatrix}$$

are linearly dependent, since $C_z = 3C_1$.

Alternatively,

$$-3 \cdot \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} + 1 \cdot \begin{pmatrix} 3 \\ 6 \\ -3 \end{pmatrix} + 0 \cdot \begin{pmatrix} 3 \\ 4 \\ 3 \end{pmatrix} + 0 \cdot \begin{pmatrix} 2 \\ 5 \\ 0 \end{pmatrix} = 0$$

is a linear combination involving nonzero scalare that is equal to zero.

The rows are also linearly dependent: $2R_2 - 5R_1 = R_3$

Example 5) The columns of
$$\begin{bmatrix} 3 & 4 & 2 \\ 0 & 1 & 5 \\ 0 & 0 & 2 \end{bmatrix}$$

are linearly independent.

If. We need to show that if
$$c_1\begin{pmatrix} 3\\0\\0\end{pmatrix} + c_2\begin{pmatrix} 4\\1\\0\end{pmatrix} + c_3\begin{pmatrix} 2\\5\\2\end{pmatrix} = 0$$

Then $C_1 = 0$, $C_2 = 0$, $C_3 = 0$.

Let us express the above equation as a system of linear equations.

$$3c_1 + 4c_2 + 2c_3 = 0$$

$$c_2 + 5c_3 = 0 - 6$$

$$2c_3 = 0 - 6$$

© \Rightarrow $C_3=0$, then b \Rightarrow $C_2=0$ and using $C_2=C_3=0$ in a we get $C_4=0$.

Observe that we have shown that the system $A \bar{c} = 0$ has the only colution $\bar{c} = 0$, But solutions to $A \bar{c} = \bar{0}$ as we saw earlier form the <u>null space</u> of A.

This indicates (and the above reasoning can be shown to hold for any matrix)

The columns of A ove linearly independent if and only if we have N(A) = {0}.

Example: The non-zero rows of a matrix in echelon form are linearly independent.

Further, if we pick out the columns that contoin the pivots, they are also linearly independent.

eq i
$$U = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 0 & 0 & 3 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
 is the REF of $A = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 5 \\ -1 & -3 & 3 & 0 \end{bmatrix}$ then $\left\{ \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 9 \\ 3 \end{pmatrix} \right\}$ is a linearly independent set.

by The rank of a matrix A is the no. of linearly independent rows (or columns) of the matrix.

It can be found by countries he no. I non. zero rows in the row-echelon form of the matrix.

Example:
$$A = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 7 \\ -1 & -3 & 3 & 4 \end{bmatrix}$$

has the now echelon form $U = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

Then, the work of A is 2, since the REF has two non-zero hows.

(We will see more about rank of a matrix later in the course)

we now check our understanding of some key concepts covered in the following example:

Example (
$$\star$$
)

Let $A = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 3 & 1 \\ 1 & 1 & 0 \end{bmatrix}$

- 1. What is C (A)?
- a. What is N(A)?
- 3. Determine whether the vectors (1,2,1), (1,3,1) and (0,1,0) are linearly independent in \mathbb{R}^3 .
- 4. What is the name of A?