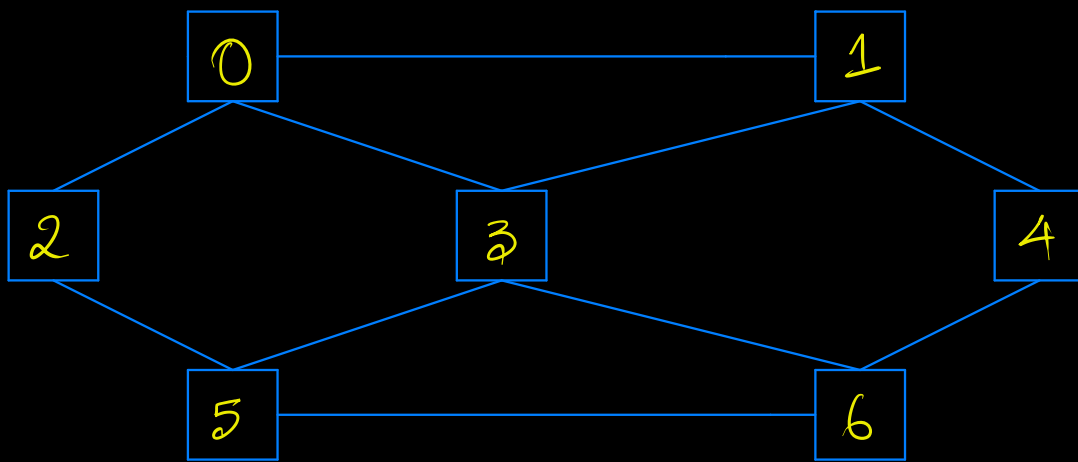


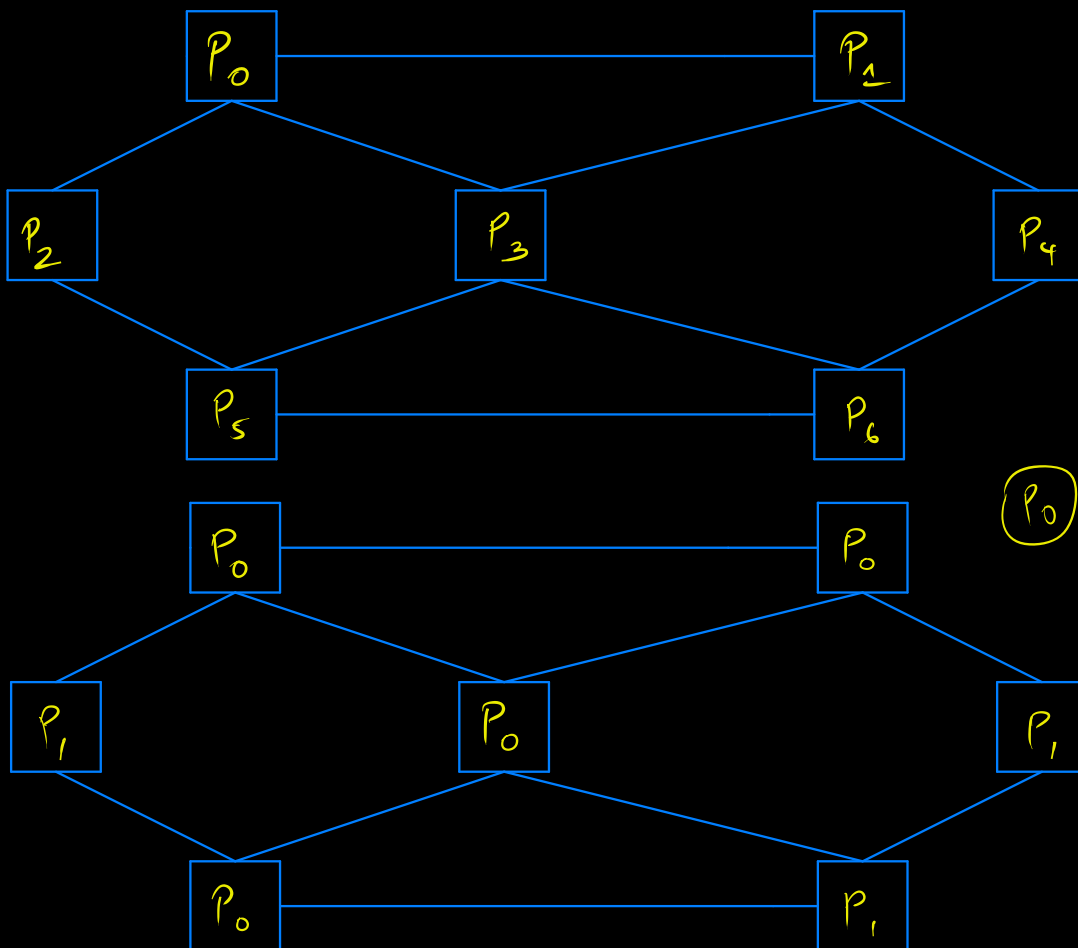
Mapping Techniques for Load Balancing

Two objectives:

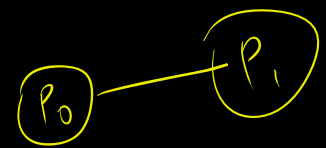
- Reduce amount of time in process interaction
- Reduce total idle time of processes
(while others are engaged in performing tasks)



Task-Interaction Graph
(Assume No Dependency)



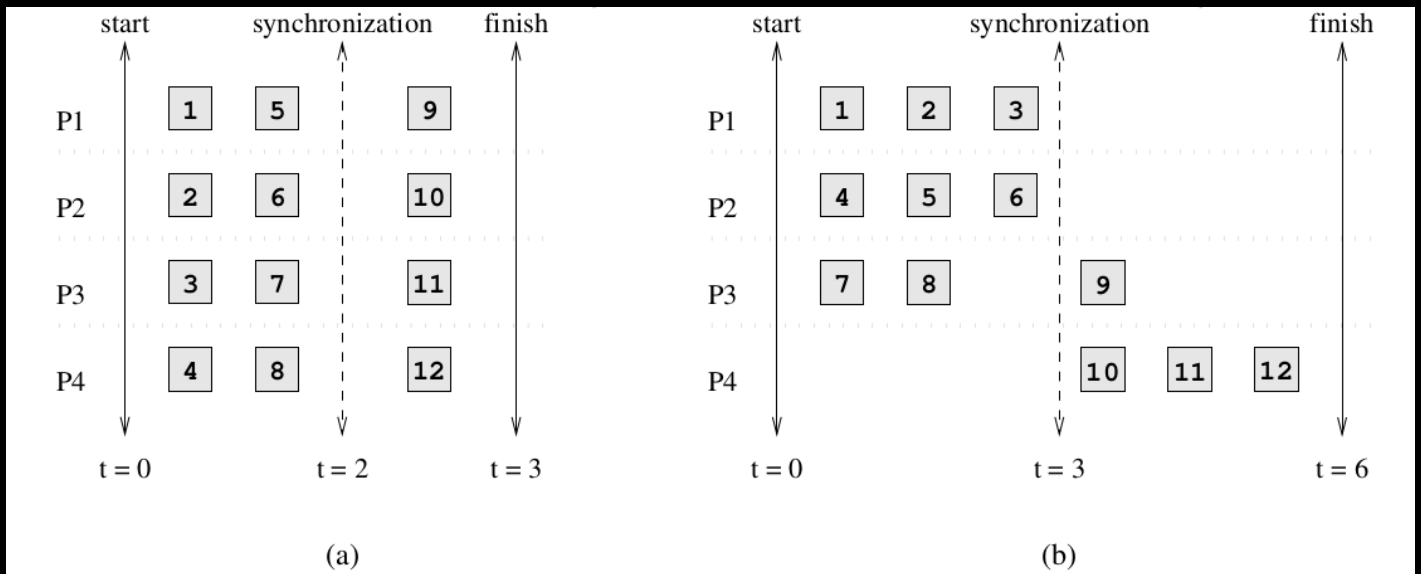
Low Idle time
Process Interaction
Same as Task
Interaction?



Reduced Process
Interaction.
Idle time?

⇒ Optimal Mapping balances Computations and Interactions.
(Non-Trivial Problem)

Task Dependency also plays a Critical Role



(9-12 depend on completion of 1-8)

Static

Dynamic

→ Maps Tasks to processes prior to execution of the algorithm

→ Map Tasks to processes during the execution of the algorithm

→ can be applied only when Tasks are statically generated

→ Can be applied for both statically or dynamically generated Tasks

→ Good Mapping depends on knowledge of Task Sizes, Data Sizes, inter-task interaction etc.

→ If Task Sizes are unknown, dynamic mapping is more effective

→ Optimal Mapping for non-Uniform Tasks is not easy (NP-Complete)

→ May involve data movement at runtime for better data distribution

- But inexpensive heuristics provide acceptable approximate solutions.
- Generally, easier to design and program

→ Usually, more complicated, particularly in the Message-Passing paradigm

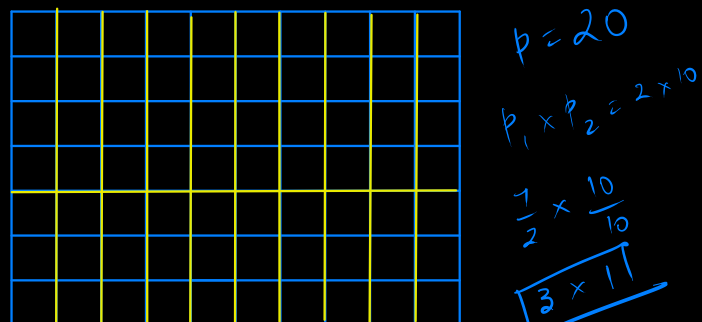
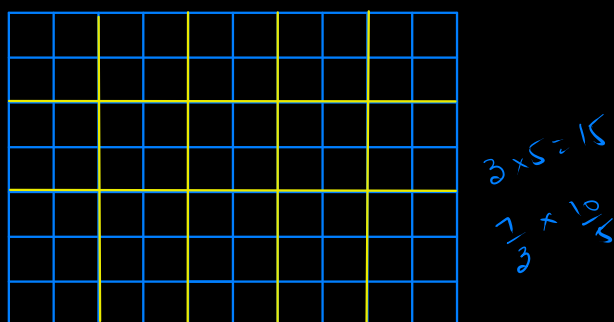
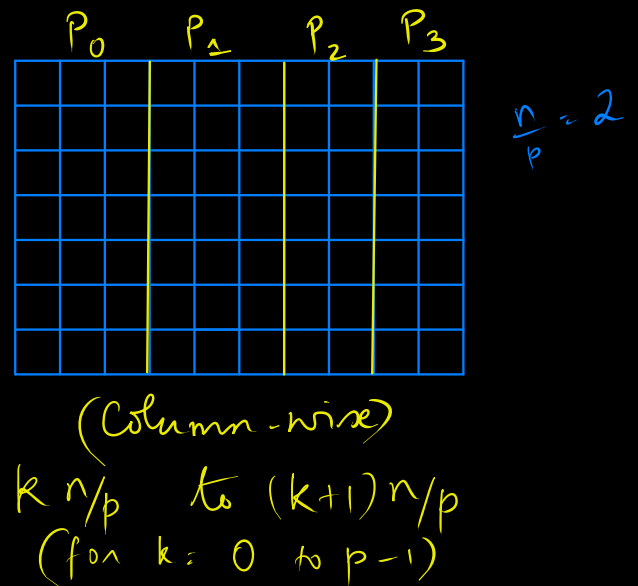
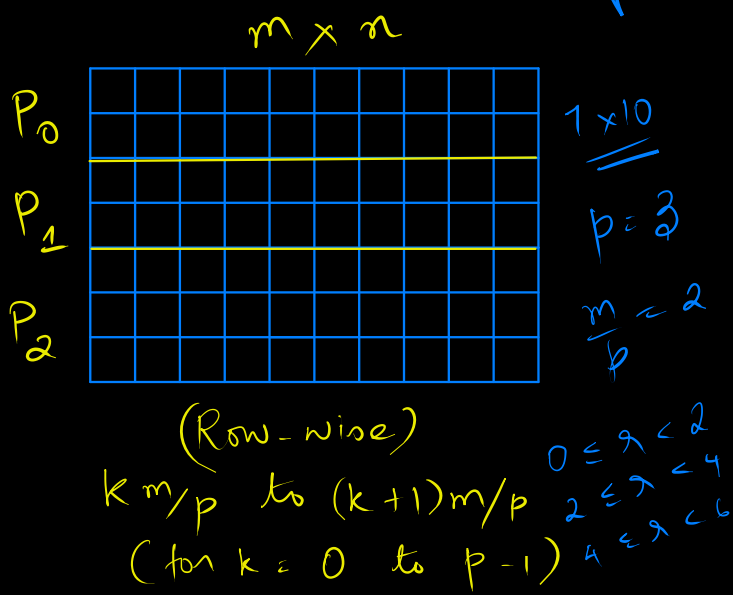
Static Mapping

Mapping based on Data partitioning

Mapping based on Task partitioning

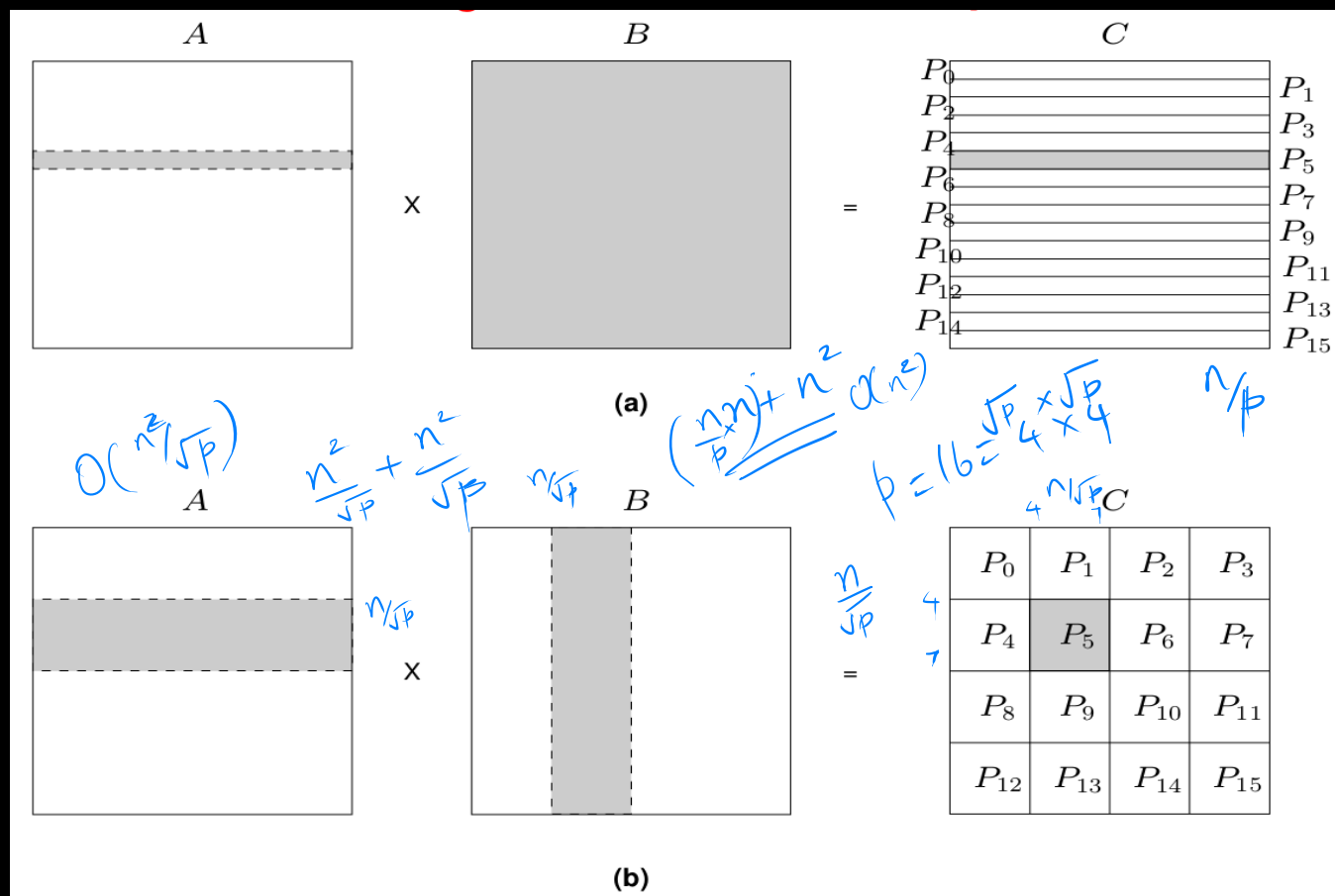
[Data Partitioning leads to Task Decomposition + Mapping]

I. Block Distributions: Assign uniform contiguous portions (Tasks) of an array to different Processes.



$$m/p_1 \times n/p_2, p_1 \times p_2 = p$$

Let A, B & C be $n \times n$ matrices $\Rightarrow AB = C$



Two ways to decompose :

One-dimensional

Set of rows of C to
(block)
One Process

Each process gets
 n/p rows

Maximum n Processes

Lower degree of Concurrency

Higher Interaction between
processes

(Data accessed : $\frac{n^2}{p} + n^2 : O(n^2)$)

Two-dimensional

One block of C to one
(2d)
Process

Each process gets $\frac{n}{\sqrt{p}} \times \frac{n}{\sqrt{p}}$
Size block

Maximum n^2 processes

Higher degree of Concurrency

Lower Interaction between
Processes

(Data accessed : $\frac{n^2}{\sqrt{p}} + \frac{n^2}{\sqrt{p}} : O(\frac{n^2}{\sqrt{p}})$)

$k = 2 \Rightarrow$ Nothing to be done

$$2^{\text{nd}} \text{ col of } L: \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad 2^{\text{nd}} \text{ row of } U: \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}$$

$$A = LU \rightarrow \text{indices from } 1 \rightarrow$$

$$\begin{bmatrix} L_{11} & 0 & 0 \\ L_{21} & L_{22} & 0 \\ L_{31} & L_{32} & L_{33} \end{bmatrix} \begin{bmatrix} U_{11} & U_{12} & U_{13} \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix}$$

$$A_{11} = L_{11} U_{11} \Rightarrow \text{Fix } L_{11} = 1 \Rightarrow U_{11} = L_{11}^{-1} A_{11}$$

$$A_{21} = L_{21} U_{11} \Rightarrow L_{21} = A_{21} U_{11}^{-1}$$

$$A_{31} = L_{31} U_{11} \Rightarrow L_{31} = A_{31} U_{11}^{-1}$$

$$A_{12} = L_{11} U_{12} \Rightarrow U_{12} = L_{11}^{-1} A_{12} \quad (\text{compute needed if } L_{11} \neq 1)$$

$$A_{13} = L_{11} U_{13} \Rightarrow U_{13} = L_{11}^{-1} A_{13} \quad (\text{compute needed if } L_{11} \neq 1)$$

$$A_{22} = L_{21} U_{12} + L_{22} U_{22} \Rightarrow A_{22} = A_{22} - L_{21} U_{12} \\ \text{and } U_{22} = L_{22}^{-1} A_{22}$$

$$A_{32} = L_{31} U_{12} + L_{32} U_{22} \Rightarrow A_{32} = A_{32} - L_{31} U_{12} \\ \text{and } L_{32} = U_{22}^{-1} A_{32}$$

$$A_{23} = L_{21} U_{13} + L_{22} U_{23} \Rightarrow A_{23} = A_{23} - L_{21} U_{13} \\ \text{and } U_{23} = L_{22}^{-1} A_{23}$$

$$A_{33} = L_{31} U_{13} + L_{32} U_{23} + L_{33} U_{33}$$

$$\Rightarrow A_{33} = A_{33} - L_{31} U_{13}$$

$$A_{33} = A_{33} - L_{32} U_{23}$$

$$U_{33} = L_{33}^{-1} A_{33}$$

$$\begin{pmatrix} A_{1,1} & A_{1,2} & A_{1,3} \\ A_{2,1} & A_{2,2} & A_{2,3} \\ A_{3,1} & A_{3,2} & A_{3,3} \end{pmatrix} \rightarrow \begin{pmatrix} L_{1,1} & 0 & 0 \\ L_{2,1} & L_{2,2} & 0 \\ L_{3,1} & L_{3,2} & L_{3,3} \end{pmatrix} \cdot \begin{pmatrix} U_{1,1} & U_{1,2} & U_{1,3} \\ 0 & U_{2,2} & U_{2,3} \\ 0 & 0 & U_{3,3} \end{pmatrix}$$

$$\begin{array}{l|l|l} 1: A_{1,1} \rightarrow L_{1,1}U_{1,1} & 6: A_{2,2} = A_{2,2} - L_{2,1}U_{1,2} & 11: L_{3,2} = A_{3,2}U_{2,2}^{-1} \\ 2: L_{2,1} = A_{2,1}U_{1,1}^{-1} & 7: A_{3,2} = A_{3,2} - L_{3,1}U_{1,2} & 12: U_{2,3} = L_{2,2}^{-1}A_{2,3} \\ 3: L_{3,1} = A_{3,1}U_{1,1}^{-1} & 8: A_{2,3} = A_{2,3} - L_{2,1}U_{1,3} & 13: A_{3,3} = A_{3,3} - L_{3,2}U_{2,3} \\ 4: U_{1,2} = L_{1,1}^{-1}A_{1,2} & 9: A_{3,3} = A_{3,3} - L_{3,1}U_{1,3} & 14: A_{3,3} \rightarrow L_{3,3}U_{3,3} \\ 5: U_{1,3} = L_{1,1}^{-1}A_{1,3} & 10: A_{2,2} \rightarrow L_{2,2}U_{2,2} & \end{array}$$

If we consider a 3×3 , 2d block distribution, to compute respective elements, then we map all Tasks associated with 1×1 in A to a process (total 9).

\Rightarrow Leads to Load Imbalance

P₀ T ₁	P₃ T ₄	P₆ T ₅
P₁ T ₂	P₄ T ₆ T ₁₀	P₇ T ₈ T ₁₂
P₂ T ₃	P₅ T ₇ T ₁₁	P₈ T ₉ T ₁₃ T ₁₄

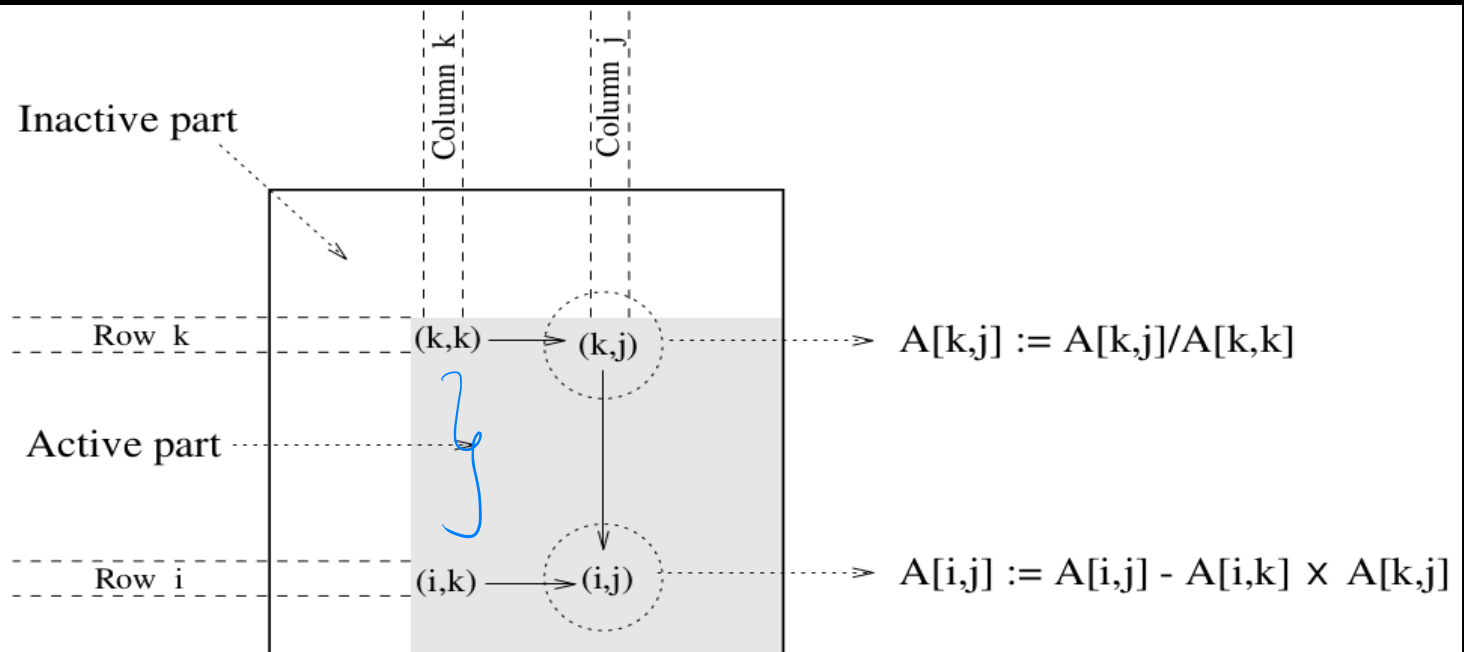
Computing final value of A_{11} needs only 1 Task.
(Task 1)

But A_{33} needs 3 Tasks (Task 9, Task 13 & Task 14)

Also processes can be idle due to Task Dependency.

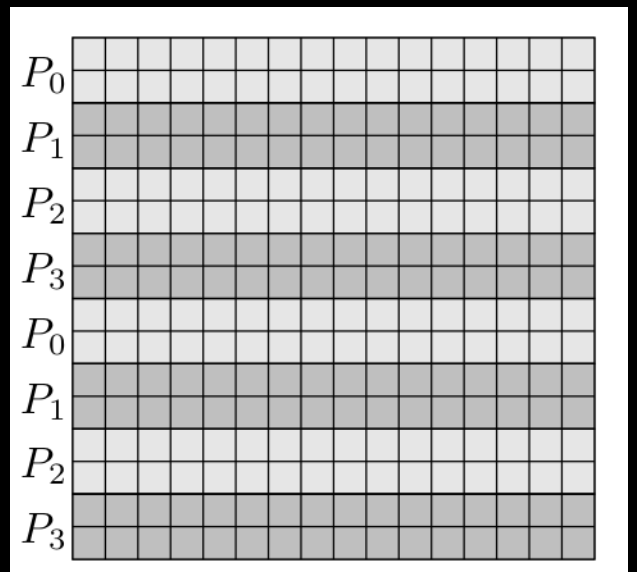
$$T_7 \rightarrow T_{11} \quad \text{and} \quad T_4 \rightarrow T_7$$

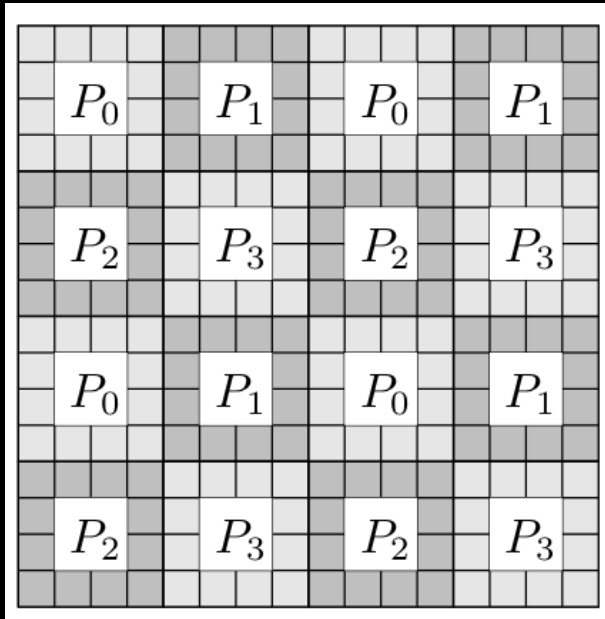
⇒ Processes assigned to left columns & top rows perform much less work compared to processes that are assigned later rows and columns.



16×16
$$2 + 4 = 8 \text{ blocks}$$

28





2-d Block cyclic distribution

$n \times n$, p processes

\downarrow
 $\alpha\sqrt{p} \times \alpha\sqrt{p}$
 $= \sqrt{p} \times \sqrt{p}$

4 x 4

\Rightarrow Reduces idling as processes get Tasks from all parts of the matrix

- \rightarrow Overall work gets balanced out
- \rightarrow Good chance that some Tasks are ready for execution at any given time

$\alpha = n/p \Rightarrow 1d$: Each row is a block

$2d$: Each element is a block ($\alpha = n/\sqrt{p}$)

\rightarrow Cyclic distribution

Good load balance due to fine grained decomposition

But Performance penalties due to lack of locality

Can lead to high degree of Interaction relative to the amount of computation

