

## RESEARCH INTEREST

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- Model Predictive Control
- Learning for Optimization and Control
- Distributed Optimization
- Multi-Agent Systems
- Connected and Automated Vehicles
- Robotics

## EDUCATION

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<b>University of Delaware</b> Ph.D. in Mechanical Engineering	Newark, DE USA Aug. 2021–Aug. 2025
<b>Northern Arizona University</b> M.Sc. in Informatics (with Distinction)	Flagstaff, AZ USA Aug. 2019–May 2021
<b>Hanoi University of Science and Technology</b> B.Sc. in Control Engineering and Automation	Hanoi, Vietnam Aug. 2014–Jun. 2019

## PROFESSIONAL EXPERIENCE

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<b>University of Pennsylvania</b> Postdoctoral Researcher - Department of Electrical and Systems Engineering	Philadelphia, PA USA Aug. 2025–Present
<b>Cornell University</b> Visiting Graduate Scholar - Systems Engineering Field <ul style="list-style-type: none"><li>– Learning and Control for Connected and Automated Vehicles in Mixed Traffic</li><li>– Development of IDS's Scaled Smart City Robotic Testbed (Version 2.0 at Cornell University)</li></ul>	Ithaca, NY USA Aug. 2023–Aug. 2023
<b>Honda Research Institute USA</b> Graduate Student Intern <ul style="list-style-type: none"><li>– Social Navigation for Multiple Robots in Crowded Environments</li></ul>	Ann Arbor, MI USA Jun. 2023–Aug. 2023
<b>University of Delaware</b> Graduate Research Assistant - Department of Mechanical Engineering <ul style="list-style-type: none"><li>– Learning and Control for Connected and Automated Vehicles in Mixed Traffic</li></ul>	Newark, DE USA Aug. 2021–May 2023
<b>University of Delaware</b> Graduate Teaching Assistant - Department of Mechanical Engineering <ul style="list-style-type: none"><li>– Vibration and Control (Lab) - MEEG 312 - Fall 2021</li><li>– Dynamics - MEEG 211 - Spring 2022</li></ul>	Newark, DE USA Aug. 2021–May 2022
<b>Northern Arizona University</b> Graduate Research Assistant - School of Informatics, Computing, and Cyber Systems <ul style="list-style-type: none"><li>– Learning-Based Model Predictive Control with Gaussian Processes</li><li>– Adaptive Sampling for Mobile Robotic Sensor Networks</li></ul>	Flagstaff, AZ USA Aug. 2019–May. 2021
<b>Vietnam Maritime University</b> Undergraduate Research Intern - School of Mechanical Engineering <ul style="list-style-type: none"><li>– Applications of Modern Control Theory in Designing Digital Controllers for Crane Systems</li><li>– Research, Design, and Manufacture of a Floating Crane Testbed in the Laboratory</li></ul>	Haiphong, Vietnam Sep. 2017–Mar. 2019

## PUBLICATIONS

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### JOURNAL ARTICLES

- [1] **V.-A. Le** and A. A. Malikopoulos, “Controller Adaptation via Learning Solutions of Contextual Bayesian Optimization”, *IEEE Robotics and Automation Letters*, vol. 10, no. 8, pp. 8308–8315, 2025.
- [2] **V.-A. Le** and A. A. Malikopoulos, “Distributed Optimization for Traffic Light Control and Connected Automated Vehicle Coordination in Mixed-Traffic Intersections”, *IEEE Control Systems Letters*, vol. 8, pp. 2721–2726, 2024.
- [3] **V.-A. Le**, B. Chalaki, F. N. Tzortoglou, and A. A. Malikopoulos, “Stochastic Time-Optimal Trajectory Planning for Connected and Automated Vehicles in Mixed-Traffic Merging Scenarios”, *IEEE Transactions on Control Systems Technology*, vol. 33, no. 4, pp. 1403–1417, 2025.
- [4] A. Mokhtarian, P. Scheffe, M. Kloock, S. Schäfer, H. Bang, **V.-A. Le**, S. Sankaramangalam Ulhas, J. Betz, S. Wilson, S. Berman, A. Prorok, and B. Alrifae, “A Survey on Small-Scale Testbeds for Connected and Automated Vehicles and Robot Swarms”, *IEEE Robotics and Automation Magazine*, 2024.
- [5] A. I. Mahbub, **V.-A. Le**, and A. A. Malikopoulos, “A safety-prioritized receding horizon control framework for platoon formation in a mixed traffic environment”, *Automatica*, vol. 155, p. 111 115, 2023.
- [6] **V.-A. Le**, L. Nguyen, and T. X. Nghiem, “Multistep Predictions for Adaptive Sampling in Mobile Robotic Sensor Networks Using Proximal ADMM”, *IEEE Access*, vol. 10, pp. 64 850–64 861, 2022.
- [7] **V.-A. Le**, L. Nguyen, and T. X. Nghiem, “ADMM-Based Adaptive Sampling Strategy for Nonholonomic Mobile Robotic Sensor Networks”, *IEEE Sensors Journal*, vol. 21, no. 13, pp. 15 369–15 378, 2021.
- [8] **V.-A. Le**, X. H. Le, L. Nguyen, and X. M. Phan, “An efficient adaptive hierarchical sliding mode control strategy using neural networks for 3D overhead cranes”, *International Journal of Automation and Computing*, vol. 16, no. 5, pp. 614–627, 2019.
- [9] H. X. Le, T. V. Nguyen, **V.-A. Le**, T. A. Phan, N. H. Nguyen, and M. X. Phan, “Adaptive hierarchical sliding mode control using neural network for uncertain 2D overhead crane”, *International Journal of Dynamics and Control*, vol. 7, pp. 996–1004, 2019.
- [10] H. X. Le, **V.-A. Le**, and L. Nguyen, “Adaptive fuzzy observer based hierarchical sliding mode control for uncertain 2D overhead cranes”, *Cyber-Physical Systems*, vol. 5, no. 3, pp. 191–208, 2019.
- [11] A. T. Le, M. C. Hoang, V. T. Pham, C. N. Luong, D. T. Vu, and **V.-A. Le**, “Adaptive neural network sliding mode control of shipboard container cranes considering actuator backlash”, *Mechanical Systems and Signal Processing*, vol. 112, pp. 233–250, 2018.

### CONFERENCE PAPERS

- [1] **V.-A. Le**, P. Kounatidis, and A. A. Malikopoulos, “Combining Graph Attention Networks and Distributed Optimization for Multi-Robot Mixed-Integer Convex Programming”, in *2025 64th IEEE Conference on Decision and Control*, (accepted, arXiv preprint arXiv:2503.21548).
- [2] **V.-A. Le**, B. Chalaki, V. Tadiparthi, H. N. Mahjoub, J. D’Sa, and E. Moradi-Pari, “Social Navigation in Crowded Environments with Model Predictive Control and Deep Learning-Based Human Trajectory Prediction”, in *2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2024, pp. 4793–4799.
- [3] **V.-A. Le**, V. Tadiparthi, B. Chalaki, H. N. Mahjoub, J. D’sa, E. Moradi-Pari, and A. A. Malikopoulos, “Multi-robot cooperative navigation in crowds: A game-theoretic learning-based model predictive control approach”, in *2024 IEEE International Conference on Robotics and Automation (ICRA)*, IEEE, 2024, pp. 4834–4840.
- [4] I. V. Chremos, H. Bang, A. Dave, **V.-A. Le**, and A. A. Malikopoulos, “A study of an atomic mobility game with uncertainty under prospect theory”, in *2024 European Control Conference (ECC)*, IEEE, 2024, pp. 1006–1011.
- [5] **V.-A. Le**, H. M. Wang, G. Orosz, and A. A. Malikopoulos, “Coordination for Connected Automated Vehicles at Merging Roadways in Mixed Traffic Environment”, in *2023 62th IEEE Conference on Decision and Control (CDC)*, 2023, pp. 4150–4155.
- [6] N. Venkatesh, **V.-A. Le**, A. Dave, and A. A. Malikopoulos, “Connected and Automated Vehicles in Mixed-Traffic: Learning Human Driver Behavior for Effective On-Ramp Merging”, in *2023 62th IEEE Conference on Decision and Control (CDC)*, 2023, pp. 92–97.

- [7] **V.-A. Le** and A. A. Malikopoulos, “Optimal Weight Adaptation of Model Predictive Control for Connected and Automated Vehicles in Mixed Traffic with Bayesian Optimization”, in *2023 American Control Conference (ACC)*, 2023, pp. 1183–1188.
- [8] **V.-A. Le** and A. A. Malikopoulos, “A Cooperative Optimal Control Framework for Connected and Automated Vehicles in Mixed Traffic Using Social Value Orientation”, in *2022 61th IEEE Conference on Decision and Control (CDC)*, 2022, pp. 6272–6277.
- [9] A. M. I. Mahbub, **V.-A. Le**, and A. A. Malikopoulos, “Safety-Aware and Data-Driven Predictive Control for Connected Automated Vehicles at a Mixed Traffic Signalized Intersection”, in *10th IFAC International Symposium on Advances in Automotive Control*, IFAC, 2022, pp. 51–56.
- [10] **V.-A. Le** and T. X. Nghiem, “Distributed Experiment Design and Control for Multi-agent Systems with Gaussian Processes”, in *2021 60th IEEE Conference on Decision and Control (CDC)*, 2021, pp. 2226–2231.
- [11] **V.-A. Le** and T. X. Nghiem, “A Receding Horizon Approach for Simultaneous Active Learning and Control using Gaussian Processes”, in *2021 IEEE Conference on Control Technology and Applications (CCTA)*, IEEE, 2021, pp. 453–458.
- [12] **V.-A. Le**, L. Nguyen, and T. X. Nghiem, “An Efficient Adaptive Sampling Approach for Mobile Robotic Sensor Networks using Proximal ADMM”, in *2021 American Control Conference (ACC)*, IEEE, 2021, pp. 1101–1106.
- [13] **V.-A. Le** and T. X. Nghiem, “Gaussian Process Based Distributed Model Predictive Control for Multi-agent Systems using Sequential Convex Programming and ADMM”, in *2020 IEEE Conference on Control Technology and Applications (CCTA)*, IEEE, 2020, pp. 31–36.
- [14] T. X. Nghiem, T.-D. Nguyen, and **V.-A. Le**, “Fast Gaussian Process based Model Predictive Control with Uncertainty Propagation”, in *2019 57th Annual Allerton Conference on Communication, Control, and Computing (Allerton)*, IEEE, 2019, pp. 1052–1059.
- [15] **V.-A. Le**, X. H. Le, D. T. Vu, V. T. Pham, A. T. Le, and M. C. Hoang, “Designing an adaptive controller for 3D overhead cranes using hierarchical sliding mode and neural network”, in *2018 International Conference on System Science and Engineering (ICSSE)*, IEEE, 2018, pp. 1–6.

## FELLOWSHIPS AND AWARDS

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- Jul. 2025: Best Paper Finalist by the ASME Automotive and Transportation Systems Technical Committee (ATS-TC) for the 2025 American Control Conference
- Aug. 2023: Student Travel Award by IEEE Control Systems Society for the 2023 IEEE Conference on Decision and Control
- Oct. 2022: IEEEExtreme Programming Competition - Global Rank: 949/6373, US Rank: 12/99
- Apr. 2022: Student Travel Awards by the University of Delaware’s Graduate College and IEEE Control Systems Society for the 2022 American Control Conference
- Sep. 2021: Student Travel Award by IEEE Control Systems Society for the 2021 IEEE Conference on Decision and Control
- Jun. 2021: Student Travel Award by IEEE Control Systems Society for the 2021 IEEE Conference on Control Technology and Applications
- Aug. 2020: Student Travel Award by IEEE Control Systems Society for the 2020 IEEE Conference on Control Technology and Applications
- Aug. 2019: Northern Arizona University’s Presidential Fellowship
- Aug. 2018: Odon Vallet’s Scholarship (established by Prof. Odon Vallet from Sorbonne University) for undergraduate students
- Jun. 2018: Conference Travel Award by Vietnam’s National Foundation for Science and Technology Development (NAFOSTED) for the 2018 IEEE International Conference on System Science and Engineering
- Apr. 2015: Gold Medal in the 2015 Vietnam’s National Mathematical Olympiad for undergraduate students

## SKILLS

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- Theoretical knowledge: Model Predictive Control, Optimal Control, Optimization Algorithms, Gaussian Process, Bayesian Optimization, Graph Neural Networks, Distributed Computing
- Programming languages: Python, Julia, C/C++, MATLAB
- Software/Tools:
  - General: Git, LaTeX, Docker
  - Robotics/Control: Robot Operating Systems (ROS), Labview
  - Optimization/Optimal Control: CVXOPT, JuMP.jl, Yalmip, CasADi, Gurobi
  - Machine Learning: PyTorch, Flux.jl
  - Traffic Simulators: VISSIM, SUMO

## ACADEMIC SERVICES

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- Membership

– Member, Institute of Electrical and Electronics Engineers (IEEE)	2020–Present
– Member, IEEE Control System Society	2020–Present
– Member, IEEE Intelligent Transportation Systems Society	2022–Present
– Member, IEEE Robotics and Automation Society	2022–Present
– Member, IEEE-CSS Technical Committee on Smart Cities	2022–Present
– Member, IEEE-CSS Technical Committee on Automotive Controls	2024–Present
- Reviewer
  - Journals: Automatica, IEEE Transactions on Automatic Control; IEEE Transactions on Intelligent Transportation Systems; Transportation Research Part C: Emerging Technologies; IEEE/ASME Transactions on Mechatronics; IEEE Transactions on Robotics; IEEE Control Systems Letters; Journal of the Franklin Institute; IEEE Transactions on Control Systems Technology; IEEE Transactions on Vehicular Technology; IEEE Transactions on Intelligent Vehicles, IEEE Open Journal of Control Systems, IEEE Robotics and Automation Letters
  - Conferences: IEEE Conference on Control Theory and Applications; IEEE Conference on Decision and Control; American Control Conference; European Control Conference; IEEE International Conference on Intelligent Transportation Systems; IEEE International Conference on Robotics and Automation; IEEE/RSJ International Conference on Intelligent Robots and Systems; IEEE Intelligent Vehicles Symposium; Modeling, Estimation and Control Conference
- Editorial Board
  - Associate Editor, IEEE Intelligent Vehicles Symposium (IV) 2026