

RESEARCH INTEREST

- Model Predictive Control
- Learning for Dynamics and Control
- Distributed Optimization
- Multi-Agent Systems
- Connected and Automated Vehicles
- Robotics

EDUCATION

University of Delaware

Ph.D. in Mechanical Engineering

Newark, DE USA

Aug. 2021–Aug. 2025

Advisor: Dr. Andreas Malikopoulos, (currently Professor at School of Civil and Environmental Engineering, Cornell University)

Northern Arizona University

M.Sc. in Informatics (with Distinction)

Flagstaff, AZ USA

Aug. 2019–May 2021

Advisor: Dr. Truong X. Nghiem, (currently Associate Professor at Department of Electrical and Computer Engineering, University of Central Florida)

Hanoi University of Science and Technology

B.Sc. in Control Engineering and Automation

Hanoi, Vietnam

Aug. 2014–Jun. 2019

PROFESSIONAL EXPERIENCE

Cornell University

Visiting Graduate Scholar

Ithaca, NY USA

Aug. 2023–Present

- Learning and Control for Connected and Automated Vehicles in Mixed Traffic
- Development of IDS's Scaled Smart City Robotic Testbed (Version 2.0 at Cornell University)

Honda Research Institute USA

Graduate Student Intern

Ann Arbor, MI USA

Jun. 2023–Aug. 2023

- Social Navigation for Multiple Robots in Crowded Environments

University of Delaware

Graduate Research Assistant at Information and Decision Science Laboratory

Newark, DE USA

Aug. 2021–May 2023

- Learning and Control for Connected and Automated Vehicles in Mixed Traffic

University of Delaware

Graduate Teaching Assistant at Department of Mechanical Engineering

Newark, DE USA

Aug. 2021–May 2022

- Vibration and Control (Lab) - MEEG 312 - Fall 2021
- Dynamics - MEEG 211 - Spring 2022

Northern Arizona University

Graduate Research Assistant at Intelligent Control System Laboratory

Flagstaff, AZ USA

Aug. 2019–May. 2021

- Learning-Based Model Predictive Control with Gaussian Processes
- Adaptive Sampling for Mobile Robotic Sensor Networks

Vietnam Maritime University

Undergraduate Research Intern at School of Mechanical Engineering

Haiphong, Vietnam

Sep. 2017–Mar. 2019

- Applications of Modern Control Theory in Designing Digital Controllers for Crane Systems
- Research, Design, and Manufacture of a Floating Crane Testbed in the Laboratory

PUBLICATIONS

JOURNAL ARTICLES

- [1] **V.-A. Le** and A. A. Malikopoulos, “Controller Adaptation via Learning Solutions of Contextual Bayesian Optimization”, *IEEE Robotics and Automation Letters* (accepted), *arXiv preprint arXiv:2403.04881*, 2025.
- [2] **V.-A. Le** and A. A. Malikopoulos, “Distributed Optimization for Traffic Light Control and Connected Automated Vehicle Coordination in Mixed-Traffic Intersections”, *IEEE Control Systems Letters*, vol. 8, pp. 2721–2726, 2024.
- [3] **V.-A. Le**, B. Chalaki, F. N. Tzortoglou, and A. A. Malikopoulos, “Stochastic Time-Optimal Trajectory Planning for Connected and Automated Vehicles in Mixed-Traffic Merging Scenarios”, *IEEE Transactions on Control Systems Technology*, 2024.
- [4] A. Mokhtarian, P. Scheffe, M. Kloock, S. Schäfer, H. Bang, **V.-A. Le**, S. Sankaramangalam Ulhas, J. Betz, S. Wilson, S. Berman, A. Prorok, and B. Alrifaae, “A Survey on Small-Scale Testbeds for Connected and Automated Vehicles and Robot Swarms”, *IEEE Robotics and Automation Magazine*, 2024.
- [5] A. I. Mahbub, **V.-A. Le**, and A. A. Malikopoulos, “A safety-prioritized receding horizon control framework for platoon formation in a mixed traffic environment”, *Automatica*, vol. 155, p. 111 115, 2023.
- [6] **V.-A. Le**, L. Nguyen, and T. X. Nghiem, “Multistep Predictions for Adaptive Sampling in Mobile Robotic Sensor Networks Using Proximal ADMM”, *IEEE Access*, vol. 10, pp. 64 850–64 861, 2022.
- [7] **V.-A. Le**, L. Nguyen, and T. X. Nghiem, “ADMM-Based Adaptive Sampling Strategy for Nonholonomic Mobile Robotic Sensor Networks”, *IEEE Sensors Journal*, vol. 21, no. 13, pp. 15 369–15 378, 2021.
- [8] **V.-A. Le**, X. H. Le, L. Nguyen, and X. M. Phan, “An efficient adaptive hierarchical sliding mode control strategy using neural networks for 3D overhead cranes”, *International Journal of Automation and Computing*, vol. 16, no. 5, pp. 614–627, 2019.
- [9] H. X. Le, T. V. Nguyen, **V.-A. Le**, T. A. Phan, N. H. Nguyen, and M. X. Phan, “Adaptive hierarchical sliding mode control using neural network for uncertain 2D overhead crane”, *International Journal of Dynamics and Control*, vol. 7, pp. 996–1004, 2019.
- [10] A. T. Le, M. C. Hoang, V. T. Pham, C. N. Luong, D. T. Vu, and **V.-A. Le**, “Adaptive neural network sliding mode control of shipboard container cranes considering actuator backlash”, *Mechanical Systems and Signal Processing*, vol. 112, pp. 233–250, 2018.

CONFERENCE PAPERS

- [1] **V.-A. Le**, B. Chalaki, V. Tadiparthi, H. N. Mahjoub, J. D’Sa, and E. Moradi-Pari, “Social Navigation in Crowded Environments with Model Predictive Control and Deep Learning-Based Human Trajectory Prediction”, in *2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2024, pp. 4793–4799.
- [2] **V.-A. Le**, V. Tadiparthi, B. Chalaki, H. N. Mahjoub, J. D’sa, E. Moradi-Pari, and A. A. Malikopoulos, “Multi-robot cooperative navigation in crowds: A game-theoretic learning-based model predictive control approach”, in *2024 IEEE International Conference on Robotics and Automation (ICRA)*, IEEE, 2024, pp. 4834–4840.
- [3] **V.-A. Le**, H. M. Wang, G. Orosz, and A. A. Malikopoulos, “Coordination for Connected Automated Vehicles at Merging Roadways in Mixed Traffic Environment”, in *2023 62th IEEE Conference on Decision and Control (CDC)*, 2023, pp. 4150–4155.
- [4] N. Venkatesh, **V.-A. Le**, A. Dave, and A. A. Malikopoulos, “Connected and Automated Vehicles in Mixed-Traffic: Learning Human Driver Behavior for Effective On-Ramp Merging”, in *2023 62th IEEE Conference on Decision and Control (CDC)*, 2023, pp. 92–97.
- [5] **V.-A. Le** and A. A. Malikopoulos, “Optimal Weight Adaptation of Model Predictive Control for Connected and Automated Vehicles in Mixed Traffic with Bayesian Optimization”, in *2023 American Control Conference (ACC)*, 2023, pp. 1183–1188.
- [6] **V.-A. Le** and A. A. Malikopoulos, “A Cooperative Optimal Control Framework for Connected and Automated Vehicles in Mixed Traffic Using Social Value Orientation”, in *2022 61th IEEE Conference on Decision and Control (CDC)*, 2022, pp. 6272–6277.
- [7] A. M. I. Mahbub, **V.-A. Le**, and A. A. Malikopoulos, “Safety-Aware and Data-Driven Predictive Control for Connected Automated Vehicles at a Mixed Traffic Signalized Intersection”, in *10th IFAC International Symposium on Advances in Automotive Control*, IFAC, 2022, pp. 51–56.

- [8] **V.-A. Le** and T. X. Nghiem, “Distributed Experiment Design and Control for Multi-agent Systems with Gaussian Processes”, in *2021 60th IEEE Conference on Decision and Control (CDC)*, 2021, pp. 2226–2231.
- [9] **V.-A. Le** and T. X. Nghiem, “A Receding Horizon Approach for Simultaneous Active Learning and Control using Gaussian Processes”, in *2021 IEEE Conference on Control Technology and Applications (CCTA)*, IEEE, 2021, pp. 453–458.
- [10] **V.-A. Le**, L. Nguyen, and T. X. Nghiem, “An Efficient Adaptive Sampling Approach for Mobile Robotic Sensor Networks using Proximal ADMM”, in *2021 American Control Conference (ACC)*, IEEE, 2021, pp. 1101–1106.
- [11] **V.-A. Le** and T. X. Nghiem, “Gaussian Process Based Distributed Model Predictive Control for Multi-agent Systems using Sequential Convex Programming and ADMM”, in *2020 IEEE Conference on Control Technology and Applications (CCTA)*, IEEE, 2020, pp. 31–36.
- [12] T. X. Nghiem, T.-D. Nguyen, and **V.-A. Le**, “Fast Gaussian Process based Model Predictive Control with Uncertainty Propagation”, in *2019 57th Annual Allerton Conference on Communication, Control, and Computing (Allerton)*, IEEE, 2019, pp. 1052–1059.
- [13] **V.-A. Le**, X. H. Le, D. T. Vu, V. T. Pham, A. T. Le, and M. C. Hoang, “Designing an adaptive controller for 3D overhead cranes using hierarchical sliding mode and neural network”, in *2018 International Conference on System Science and Engineering (ICSSE)*, IEEE, 2018, pp. 1–6.

PREPRINTS

- [1] **V.-A. Le**, P. Kounatidis, and A. A. Malikopoulos, “Combining Graph Attention Networks and Distributed Optimization for Multi-Robot Mixed-Integer Convex Programming”, (submitted to 2025 64th IEEE Conference on Decision and Control, arXiv preprint arXiv:2503.21548).

FELLOWSHIPS AND AWARDS

- Aug. 2023: Student Travel Award by IEEE Control Systems Society for the 2023 IEEE Conference on Decision and Control
- Oct. 2022: IEEEExtreme Programming Competition - Global Rank: 949/6373, US Rank: 12/99
- Apr. 2022: Student Travel Awards by the University of Delaware’s Graduate College and IEEE Control Systems Society for the 2022 American Control Conference
- Sep. 2021: Student Travel Award by IEEE Control Systems Society for the 2021 IEEE Conference on Decision and Control
- Jun. 2021: Student Travel Award by IEEE Control Systems Society for the 2021 IEEE Conference on Control Technology and Applications
- Aug. 2020: Student Travel Award by IEEE Control Systems Society for the 2020 IEEE Conference on Control Technology and Applications
- Aug. 2019: Northern Arizona University’s Presidential Fellowship
- Aug. 2018: Odon Vallet’s Scholarship (established by Prof. Odon Vallet from Sorbonne University) for undergraduate students
- Jun. 2018: Conference Travel Award by Vietnam’s National Foundation for Science and Technology Development (NAFOSTED) for the 2018 IEEE International Conference on System Science and Engineering
- Apr. 2015: Gold Medal in the 2015 Vietnam’s National Mathematical Olympiad for undergraduate students

SKILLS

- Theoretical knowledge: Model Predictive Control, Optimal Control, Optimization Algorithms, Gaussian Process, Bayesian Optimization, Graph Neural Networks, Distributed Computing
- Programming languages: Python, Julia, C/C++, MATLAB
- Software/Tools:
 - General: Git, LaTeX, Docker

- Robotics/Control: Robot Operating Systems (ROS), Labview
- Optimization/Optimal Control: CVXOPT, JuMP.jl, Yalmip, CasADi, Gurobi
- Machine Learning: PyTorch, Flux.jl
- Traffic Simulators: VISSIM, SUMO

ACADEMIC ACTIVITIES

- Membership

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| – Student Member, Institute of Electrical and Electronics Engineers (IEEE) | 2020–Present |
| – Student Member, IEEE Control System Society | 2020–Present |
| – Student Member, IEEE Intelligent Transportation Systems Society | 2022–Present |
| – Student Member, IEEE Robotics and Automation Society | 2022–Present |
| – Member, IEEE-CSS Technical Committee on Smart Cities | 2022–Present |
| – Member, IEEE-CSS Technical Committee on Automotive Controls | 2024–Present |

- Reviewer

- Journals: Automatica, IEEE Transactions on Automatic Control; IEEE Transactions on Intelligent Transportation Systems; Transportation Research Part C: Emerging Technologies; IEEE/ASME Transactions on Mechatronics; IEEE Transactions on Robotics; IEEE Control Systems Letters; Journal of the Franklin Institute; IEEE Transactions on Control Systems Technology; IEEE Transactions on Vehicular Technology; IEEE Transactions on Intelligent Vehicles, IEEE Open Journal of Control Systems
- Conferences: IEEE Conference on Control Theory and Applications; IEEE Conference on Decision and Control; American Control Conference; European Control Conference; IEEE International Conference on Intelligent Transportation Systems; IEEE/RSJ International Conference on Intelligent Robots and Systems; IEEE Intelligent Vehicles Symposium; Modeling, Estimation and Control Conference