

EDUCATION

Hanoi University of Science and Technology

Hanoi, Vietnam

B.S in Automation and Control Engineering (Talented Program), GPA: 3.44/4.00

2014–2019

- Thesis: “Control methods for uncertain two-wheeled self-balancing mobile robots using Adaptive Dynamic Programming”

PROFESSIONAL EXPERIENCE

Northern Arizona University

Flagstaff, AZ, USA

Graduate Research Assistant at School of Informatics, Computing and Cyber Systems

2019 –Present

- Gaussian Process based Distributed Model Predictive Control for Multi-agent Systems
- Flagstaff’s F1/10 Robo-Racing Project

Vietnam Maritime University

Hai Phong, Vietnam

Research Intern at School of Mechanical Engineering

2017 –2019

- Robust adaptive control of shipboard container cranes using MRAC and neural networks
- Research, design and manufacture of the model of floating cranes for loading and unloading containers at Vietnam’s seaports

RESEARCH INTEREST

- Distributed Model Predictive Control for Multi-agent Systems
- Machine Learning based Control
- Robotics and Autonomous Systems

SCHOLARSHIPS AND AWARDS

- Student Travel Award by the IEEE Control Systems Society (CSS) to attend the 2020 IEEE Conference on Control Technology and Applications (CCTA)
- Northern Arizona University’s Presidential Fellowship award for incoming graduate students in 2019
- Odon Vallet’s Scholarship (established by Prof. Odon Vallet from France’s Sorbonne University) for Excellent Undergraduate Students in 2018
- Conference Travel Award by the Vietnam’s National Foundation for Science and Technology Development (NAFOSTED) to attend the 2018 IEEE Conference on System Science and Engineering (ICSSE)
- Gold Medal in the Vietnam’s National Mathematical Olympiad for Undergraduate Students in 2015

SKILLS

- **Programming languages:** Python, Julia, C/C++, MATLAB, R.
- **Tools:** Git, LaTeX, Robot Operating System (ROS).

PUBLICATIONS

- [1] **V.-A. Le** and T. X. Nghiem, “Gaussian process based distributed model predictive control for multi-agent systems using sequential convex programming and admm”, in *2020 IEEE Conference on Control Technology and Applications (CCTA)*, IEEE, 2020, pp. 31–36.
- [2] H. X. Le, **V.-A. Le**, and L. Nguyen, “Adaptive fuzzy observer based hierarchical sliding mode control for uncertain 2d overhead cranes”, *Cyber-Physical Systems*, vol. 5, no. 3, pp. 191–208, 2019.
- [3] **V.-A. Le**, H.-X. Le, L. Nguyen, and M.-X. Phan, “An efficient adaptive hierarchical sliding mode control strategy using neural networks for 3d overhead cranes”, *International Journal of Automation and Computing*, vol. 16, no. 5, pp. 614–627, 2019.
- [4] T. X. Nghiem, T.-D. Nguyen, and **V.-A. Le**, “Fast gaussian process based model predictive control with uncertainty propagation”, in *2019 57th Annual Allerton Conference on Communication, Control, and Computing (Allerton)*, IEEE, 2019, pp. 1052–1059.
- [5] V. T. Nguyen, T. K. D. Ha, **V.-A. Le**, T. D. Pham, H. T. Vo, and Q. T. Pham, “Modeling and integral hierarchical sliding-mode control for 2d ship-mounted crane”, in *2019 First International Symposium on Instrumentation, Control, Artificial Intelligence, and Robotics (ICA-SYMP)*, IEEE, 2019, pp. 82–85.
- [6] A. T. Le, M. C. Hoang, V. T. Pham, C. N. Luong, D. T. Vu, and **V.-A. Le**, “Adaptive neural network sliding mode control of shipboard container cranes considering actuator backlash”, *Mechanical Systems and Signal Processing*, vol. 112, pp. 233–250, 2018.
- [7] **V.-A. Le**, X. H. Le, D. T. Vu, V. T. Pham, A. T. Le, and M. C. Hoang, “Designing an adaptive controller for 3d overhead cranes using hierarchical sliding mode and neural network”, in *2018 International Conference on System Science and Engineering (ICSSE)*, IEEE, 2018, pp. 1–6.

REFERENCES

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