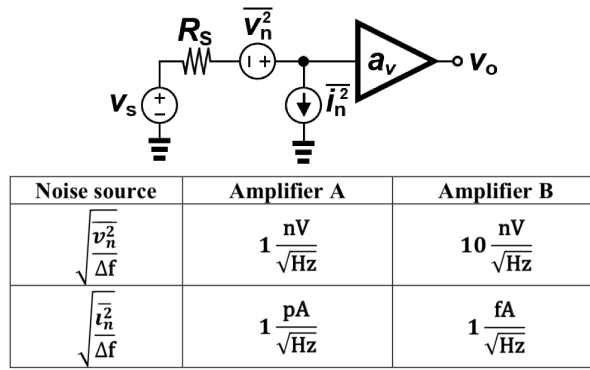


# EE240B HW 2

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## 1 Electronic Noise



- (a) Calculate the input referred noise in  $V/\sqrt{\text{Hz}}$  achieved with the two amplifiers for  $R_s = 50\Omega, 5\text{M}\Omega$ . Only consider the amplifier noise. Assume the amplifier voltage and current sources are uncorrelated.

$R_s$	Amplifier A	Amplifier B
$50 \Omega$	$1.05 \frac{\text{nV}}{\sqrt{\text{Hz}}}$	$10 \frac{\text{nV}}{\sqrt{\text{Hz}}}$
$5 \text{ M}\Omega$	$5000 \frac{\text{nV}}{\sqrt{\text{Hz}}}$	$15 \frac{\text{nV}}{\sqrt{\text{Hz}}}$

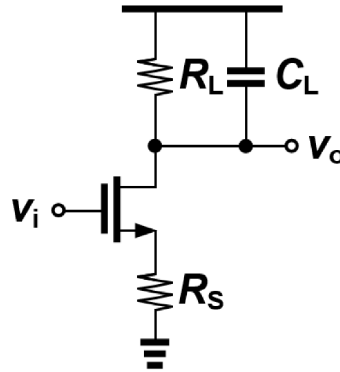
- (b) Significance of the result?

If the input voltage source's resistance is low, an amplifier with low voltage noise should be chosen (since the amplifier's current noise won't see a large resistance). Use a BJT op-amp.

If the input voltage source's resistance is high, an amplifier with low current noise should be chosen. This is usually a FET op-amp.

## 2 Amplifier Noise

Derive analytical expressions as a function of  $g_m, \gamma, f_T, R_L, R_S$ , and  $C_L$ . Consider only thermal noise from  $R_S, R_L$ , and transistor shot noise. Ignore flicker noise,  $r_o$ , and body effect.  $C_L$  is fixed and  $C_{gs}$  is expressed in terms of  $f_T$ .



- (a) The voltage gain  $a_v(s) = v_o/v_i$

This is a standard source-degenerated common-source amplifier with a complex load. We need to consider  $C_{gs}$  which will give a 2nd-order transfer function and makes the algebra complicated. I'm using the sympy CAS to do the algebra. I'll provide the source and the derived solution. Check this IPython notebook for all the source code.

```
from sympy import *
def ll(a, b): # Put impedances a and b in parallel symbolically
    return (a*b) / (a + b)
s, RL, CL, ZL, Cgs, Rs, gm = symbols("s R_L C_L Z_L C_{gs} R_s g_m")
igate, isource, idrain = symbols("i_g i_s i_d")
vs, vd, vi = symbols("v_s v_d v_i")
sol = nonlinsolve([
    igate - ((vi - vs) / (1 / (s*Cgs))),
    isource - (vs / Rs),
    idrain - gm*(vi - vs),
    -vd - idrain*ZL,
    isource - igate - idrain
], [igate, isource, idrain, vd, vs])
vd_sol = sol.args[0][3]
gain = vd_sol / vi
ZL_sol = ll(CL, RL)
ZL_sol = ZL_sol.subs(CL, (1 / (s*CL))).simplify()
display(gain.subs(ZL, ZL_sol).simplify())
```

$$a_v(s) = -\frac{R_L g_m}{(C_L R_L s + 1)(C_{gs} R_s s + R_s g_m + 1)}$$

- (b) The PSD of the noise in  $\frac{V}{\sqrt{\text{Hz}}}$  at node  $v_o$

I derived the noise due to  $R_S$ ,  $R_L$ , and the transistor using the hybrid-pi model and a CAS.

$$V_{n,out,R_s}(s) = \frac{R_L g_m v_{nS}}{(C_L R_L s + 1)(C_{gs} R_s s + R_s g_m + 1)}$$

$$V_{n,out,R_L}(s) = \frac{R_L i_{nL}}{C_L R_L s + 1}$$

$$V_{n,out,transistor}(s) = -\frac{R_L i_{nT}(C_{gs} R_s s + 1)}{(C_L R_L s + 1)(C_{gs} R_s s + R_s g_m + 1)}$$

We can easily substitute for  $v_{nS}$ ,  $i_{nL}$ ,  $i_{nT}$  with the actual noise voltage and current of  $R_S$ ,  $R_L$  and the transistor respectively. To find output noise power, these quantities need to be squared and added together.

- (c) The total noise integrated over all frequencies at node  $v_o$

Take the total output noise power and integrate from  $s = 0 \rightarrow \infty j$ . See the lecture slides for the standard integrals.

- (d) The dynamic range of the circuit as a function of the peak-to-peak voltage range  $V_{o,pp}$  at node  $v_o$

$$\text{Output Dynamic Range} = dB_{power} \left( \frac{V_{o,pp}^2 + \overline{V_{n,out,total}^2}}{\overline{V_{n,out,total}^2}} \right)$$

- (e) The minimum detectable signal in  $\frac{nV}{\sqrt{Hz}}$  at low frequency and  $\mu V_{rms}$  based on the total noise at the output of the amplifier

Find the transfer function of the noise sources, but this time treat  $C_{gs}$  and  $C_L$  as opens at low frequency (set them to 0).

$$\overline{V_{n,out,lowfreq}} = \frac{2R_L \left( I_d R_L q + 2K R_L R_s T g_m^2 + 2KT (R_s g_m + 1)^2 \right)}{(R_s g_m + 1)^2}$$

- (f) Comment on the effect of  $R_S$  on the dynamic range and minimum detectable signal of the circuit

$R_S$  suppresses the shot noise of the transistor which improves the minimum detectable signal, but it reduces the maximum output swing by a larger margin which degrades the dynamic range. There is probably a specification-specific optimal choice of  $R_S$  if output swing isn't critical.