

# **EE 240B – Fall 2019**

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## **Advanced Analog Integrated Circuits**

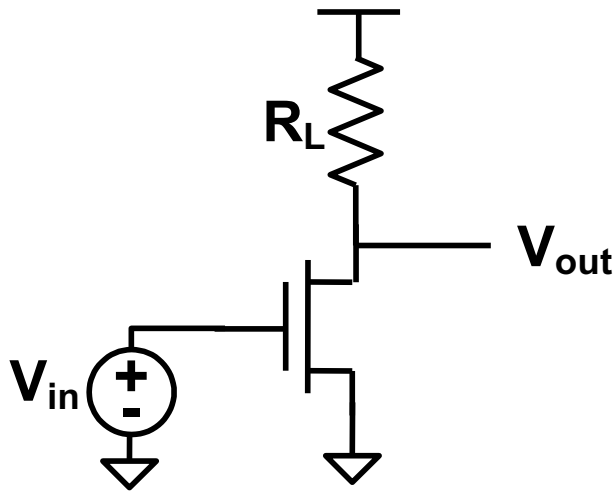
### **Lecture 7: Noise- and SNR-Limited Amplifier Design Methodology**



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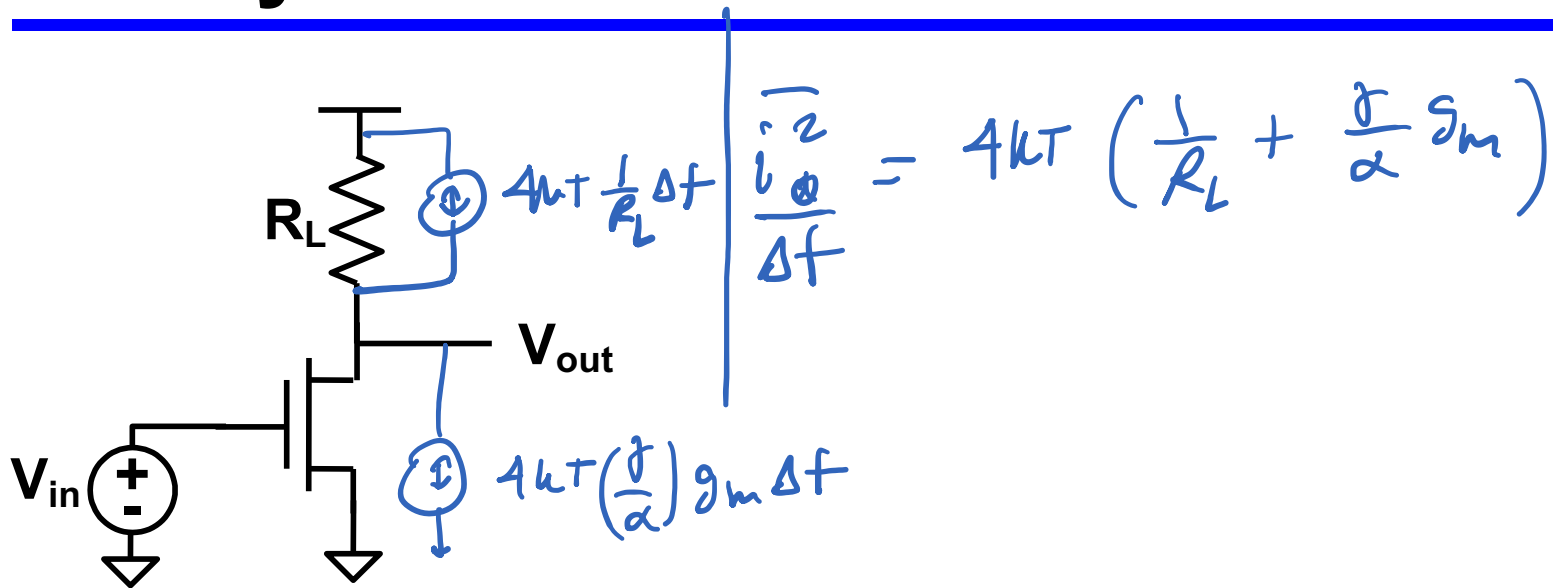
# Noise Density Limited Amplifier Design Methodology

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- **Input specifications:**
  - Minimum small signal gain  $A_v$
  - Supply voltage  $V_{dd}$
  - Fixed  $V^*$
  - Maximum input-referred noise spectral density  $v_{i,n}^2/\Delta f$
- **Goal: minimize power**

# Small Signal Model and Noise Analysis



$$\frac{\overline{V_i^2}}{\Delta f} = \frac{\overline{i_o^2} / \Delta f}{g_m^2} = 4kT \frac{1}{g_m} \left( \frac{1}{g_m R_L} + \frac{\gamma}{\alpha} \right)$$

$$\frac{\overline{V_{i,max}^2}}{\Delta f} < \overline{V_i^2} = 4kT \frac{1}{g_m} \left( \frac{1}{A_{vo}} + \left( \frac{\gamma}{\alpha} \right) \right)$$

↑  
excess noise

# Resulting Design

$$g_m \geq \frac{4kT \left( \frac{1}{A_{v0}} + \frac{\gamma}{2} \right)}{\left( \overline{v_{i,max}^2} / \Delta f \right)}$$

$$I_D = \frac{g_m V_{i0}^*}{2} = \frac{4kT}{2} \left( \frac{1}{A_{v0}} + \frac{\gamma}{2} \right) \cdot \frac{V_{i0}^*}{\left( \overline{v_{i,max}^2} / \Delta f \right)}$$

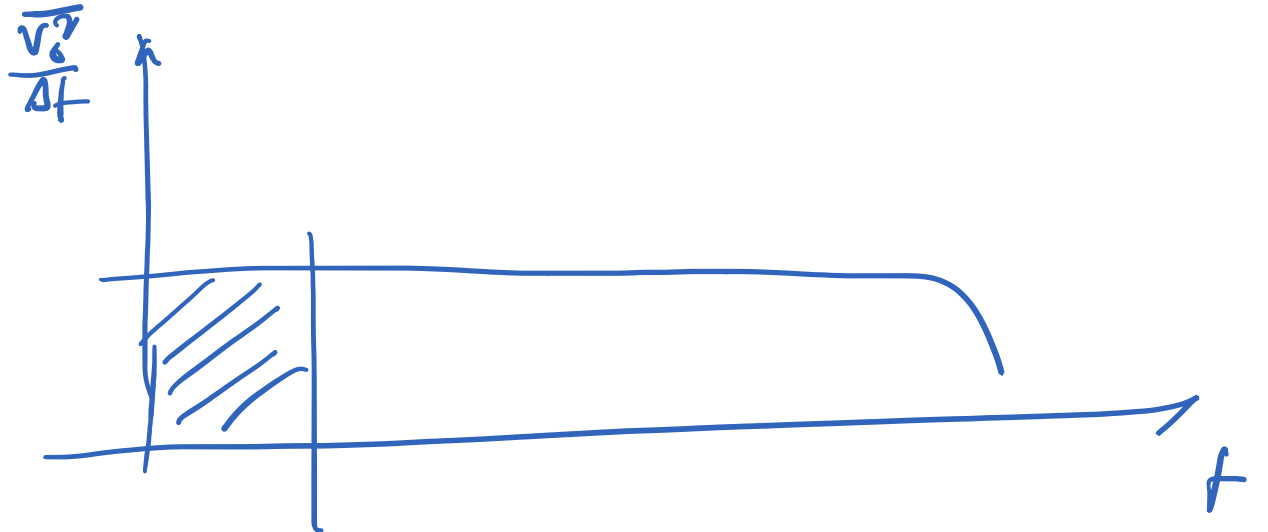
$$A_v = g_m (R_L \parallel r_o) = \frac{g_m}{\frac{1}{R_L} + \frac{1}{r_o}} = \frac{g_m R_L}{1 + \frac{g_m R_L}{a_{v0}}} = \frac{A_{v0}}{1 + \frac{A_{v0}}{a_{v0}}}$$

$$A_{v0} = A_v \left( 1 + \frac{A_{v0}}{a_{v0}} \right) \quad A_{v0} \left( 1 - \frac{A_v}{a_{v0}} \right) = A_v$$

$$\boxed{A_{v0} = \frac{A_v}{1 - \frac{A_v}{a_{v0}}}} = g_m R_L$$

# Discussion (1)

- Why did we not even specify the capacitive load?



Explicitly set BW for  
noise (digital or analog)  
domain

# Discussion (2)

- If you could exactly set  $a_{v0}$ , what value would you pick?

$$A_{v0} = \frac{A_v}{1 - \frac{A_v}{a_{v0}}}$$

$$g_m = \frac{4kT \left(1 + \frac{g}{\alpha} A_{v0}\right)}{A_{v0} (\overline{v_{in}^2}/\Delta f)}$$

$$= \frac{4kT \left(\frac{g}{\alpha}\right)}{(\overline{v_{in}^2}/\Delta f)}$$

$$R_L = \infty \Omega$$

$$(a_{v0} = A_v)$$

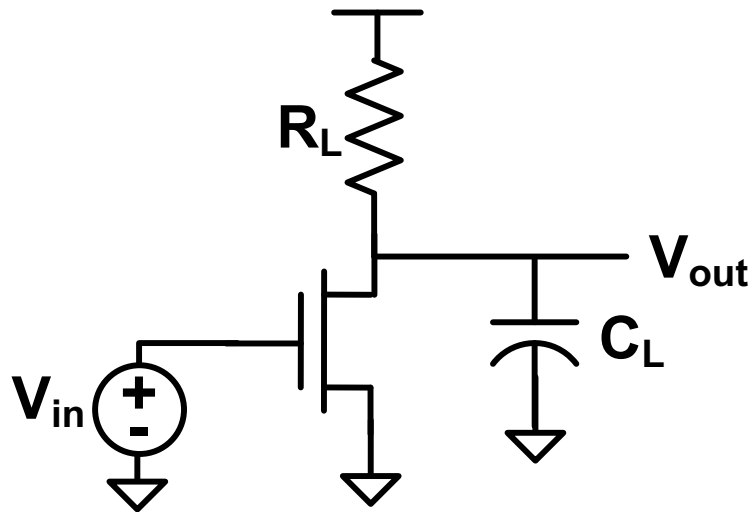
Supply Limited

$A_v$  - gain

$a_{v0}$  - intrinsic gain

$A_{v0}$  - gain if  $r_o = \infty \Omega$

# Integrated Noise-Limited Amplifier



- **Input specifications:**
  - Minimum small signal gain  $A_v$
  - Minimum 3dB bandwidth  $\omega_{bw}$
  - Supply voltage  $V_{dd}$
  - Fixed  $V^*$
  - Maximum noise variance  $v_{o,n}^2$
- **Goal: minimize power**

$C_L$  is a design parameter

# Required $C_L$ , $g_m$ , and $I_D$

$$\overline{V_{o,T}^2} = \frac{kT}{C_L} \left( 1 + \frac{\beta}{\alpha} A_{v0} \right)$$

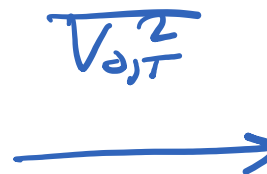
$$A_{v0} \triangleq g_m R_L$$

$$C_L \geq \frac{kT \left( 1 + \frac{\beta}{\alpha} A_{v0} \right)}{\overline{V_{o,T}^2}}$$

$$GBW = \frac{g_m}{C_L} = A_v \omega_{BW}$$

$$g_m = \frac{A_v \omega_{BW} \cdot kT \left( 1 + \frac{\beta}{\alpha} A_{v0} \right)}{\overline{V_{o,T}^2}}$$

$$I_D = \frac{g_m V^*}{2}$$



$R_L$  SET AGAIN  
BY GAIN



# Discussion (1)

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- For both noise-density and integrated noise-limited amplifiers, what  $V^*$  should you pick?

$$V^* \leftarrow J \text{ (current density)}$$

— Input noise density  $\rightarrow V^*$  large enough to meet GBW req

— For integrated noise, adding  $C_L$  to meet GBW.  $C_{tot} > C_L$ ,  $\uparrow V^*$

# Discussion (2)

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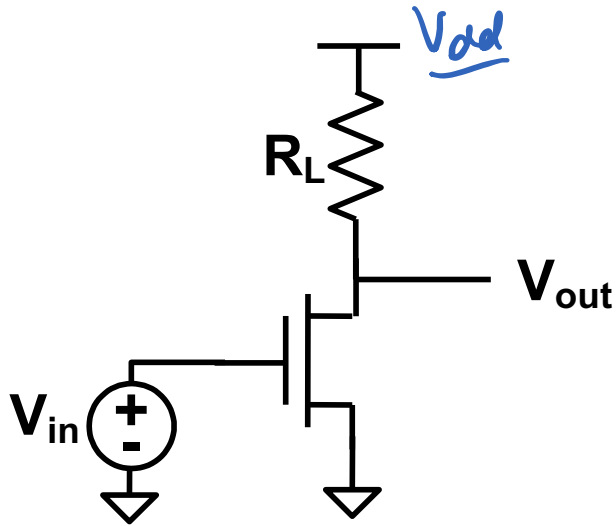
- How would one know the  $v_{i,n}^2/\Delta f$  or  $v_{o,n}^2$  spec?

• Usually we care about SNR, not just noise

• What is limiting out signals

(e.g.  $V_{DD}$ )

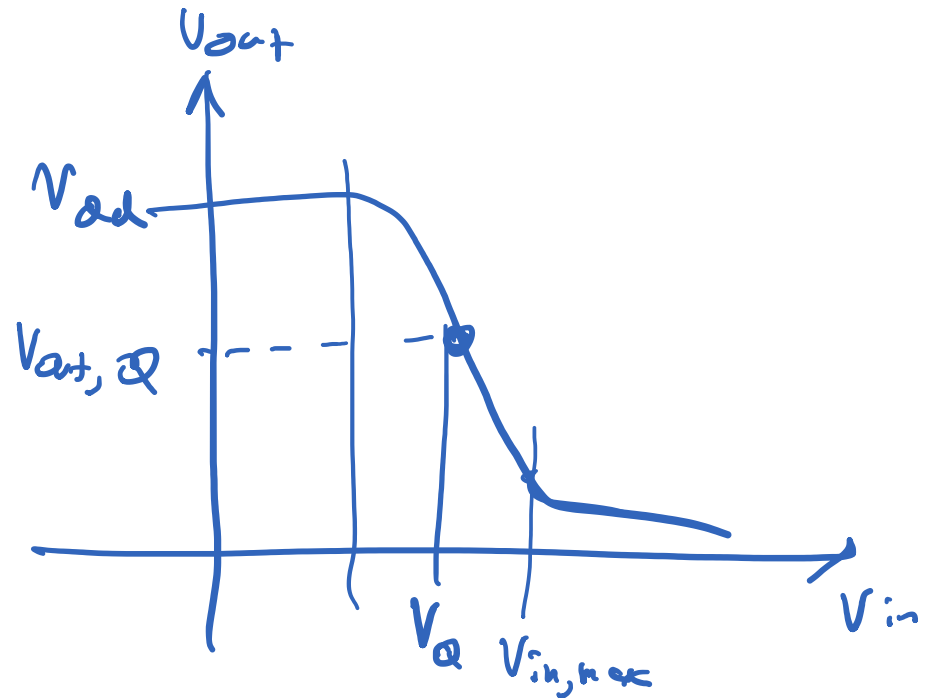
# Signal Swing Limitations



LINEARITY  
DETERMINES  
SWING

$$V_{out,Q} \approx \frac{V_{dd}}{2} + \delta V$$

$$V_{out,min} \approx V_{th}$$



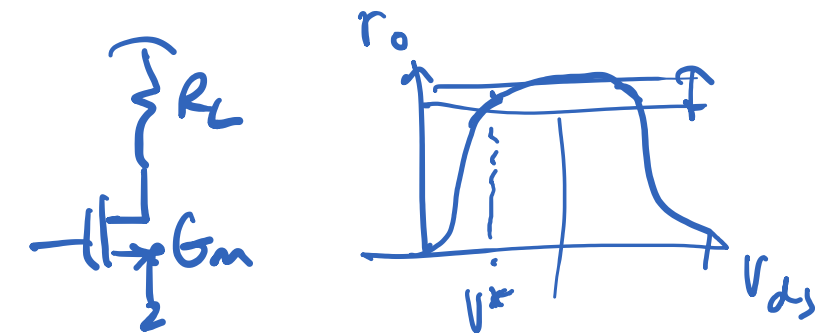
# Why Linearity Matters

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- **Option 1: Retaining the original shape of the input inherently matters**
  - E.g., oscilloscope, spectrum analyzer
  - (Actually also often matters in communication systems)
- **Option 2: Need to be able to discern a (small) signal out of the combination of many others**
  - E.g., RF, neural front-ends
  - “Other” signals could
- **Precise linearity metric depends on usage scenario**
  - More next time – will use simplified metric for now

# Sources of Non-Linearity

- Output limited:  
Non-linear  $Z_{out} (r_o)$



— Want  $r_o > k \cdot R_L$

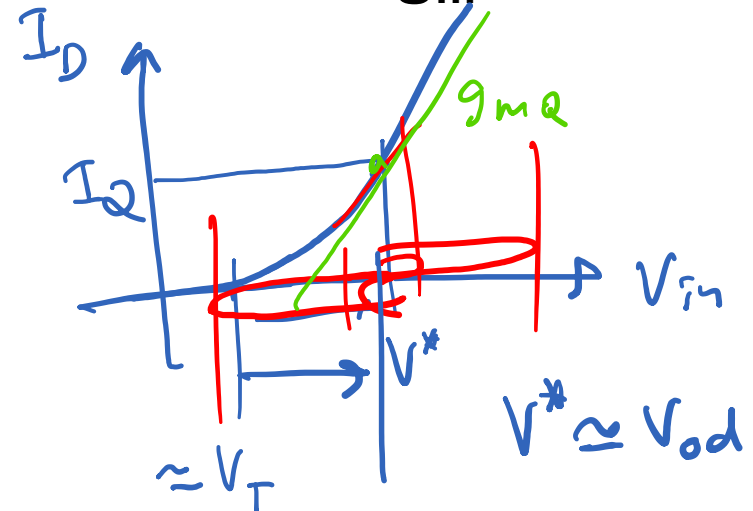
$$a_{vo} = g_m r_o \geq k \underbrace{R_L \cdot g_m}_{A_{vo}}$$

$$a_{vo} \geq k \frac{A_v}{1 - A_v/a_{vo}}$$

$$a_{vo} - A_v \geq k A_v$$

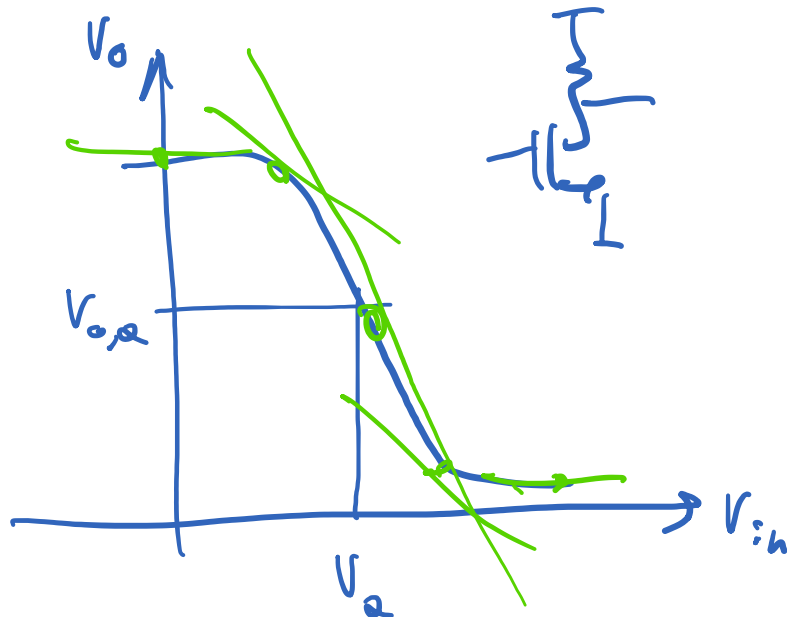
$$a_{vo} \geq (k+1) A_v$$

- Input limited:  
Non-linear  $g_m$



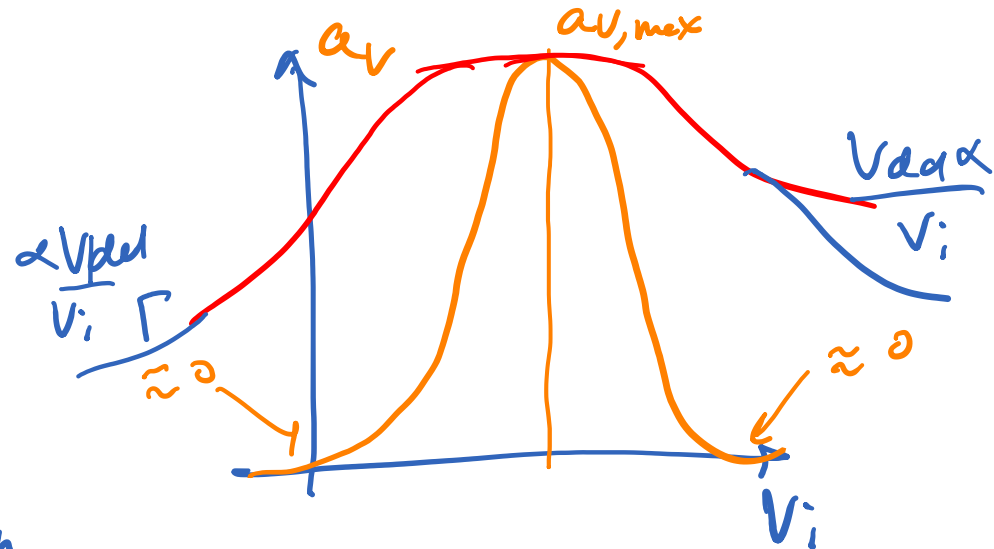
input swing  $< v^*$   
 $\Rightarrow I_d$  "clips"

# Linearity: Small vs. Large-Signal Gain



- **Small Signal:**

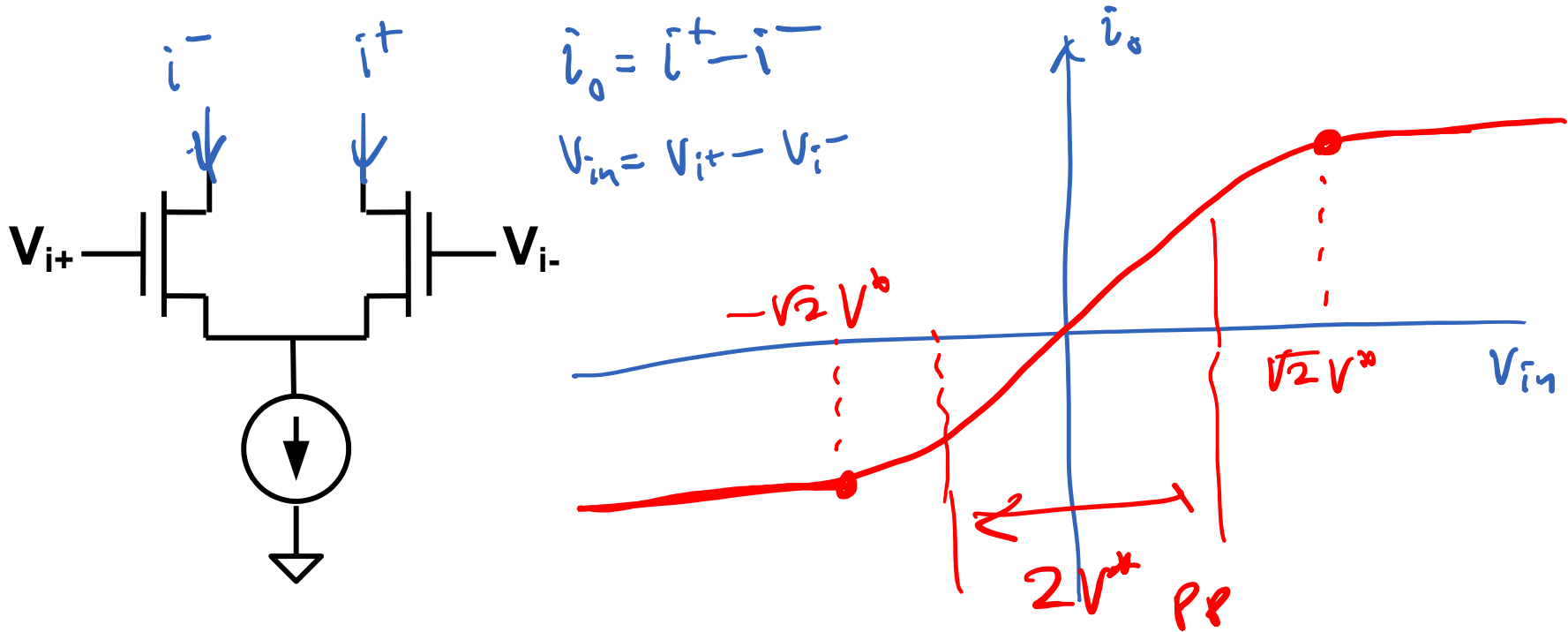
$$a_{vo} = \frac{dV_{out}}{dV_{in}}$$



- **Large Signal:**

$$A_{vo} = \frac{V_{out} - V_{out\_o}}{V_{in} - V_{in\_o}}$$

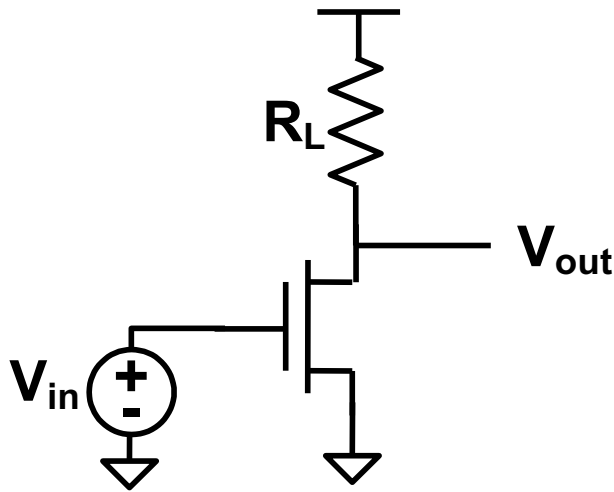
# Input Non-Linearity with a Diff. Pair



$\approx 2 \times$  Better than single FET  
CS amp

# Full Circle: SNR-Limited Design (noise density)

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- **Input specifications:**
  - Minimum small signal gain  $A_v$
  - Supply voltage  $V_{dd}$
  - Input-referred maximum linear amplitude  $V_{i,max}$  ( $\approx V^*$ )
  - Signal shape (usually sinusoid) and amplitude  $V_{sig}$
  - Externally determined bandwidth  $f_{bw}$
  - Minimum signal-to-noise ratio  $SNR_{min}$
- **Goal: minimize power**



# Required $v_{i,n}/\Delta f$

• Assume sinusoidal signal drive

• Signal power =  $\frac{1}{2} V_{sig}^2$

• Input refer noise power =

$$4KT \left( \frac{g}{\alpha} + \frac{1}{A_{v0}} \right) f_{bw} \cdot \frac{1}{g_m}$$

$$SNR_{min} = \frac{\frac{1}{2} V_{sig}^2 \cdot g_m}{4KT \cdot \left( \frac{g}{\alpha} + \frac{1}{A_{v0}} \right) f_{bw}} \Rightarrow \text{Solve for } g_m$$


# Required $V^*$

$$g_m > \frac{8 kT \left( \frac{1}{\alpha} + \frac{1}{A_{v0}} \right) f_{bw} \cdot SNR_{min}}{V_{sig}^2}$$

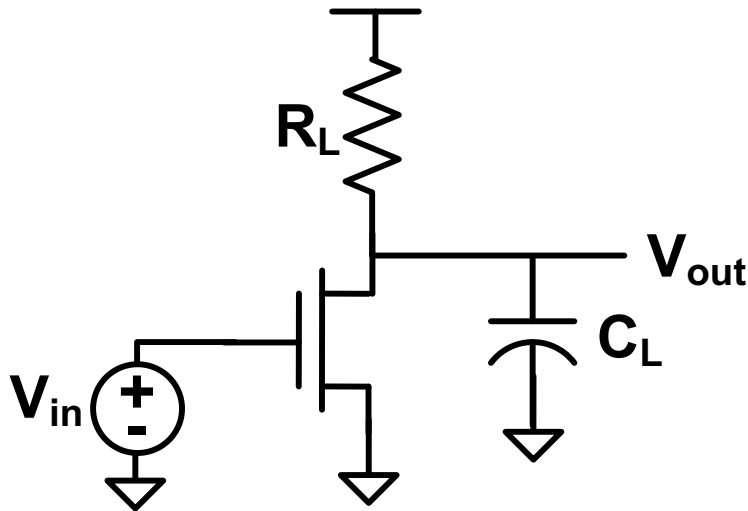
$$V_{i,max} < \frac{V^*}{2}$$

$$V^* = 2 V_{i,max}$$

$$\frac{2 I_D}{2 V_{i,max}} = \frac{8 kT \left( \frac{1}{\alpha} + \frac{1}{A_{v0}} \right) f_{bw} \cdot SNR_{min}}{V_{sig}^2}$$

$$I_D = \frac{8 kT \left( \frac{1}{\alpha} + \frac{1}{A_{v0}} \right) f_{bw} \cdot SNR(V_{i,max})}{V_{sig}^2}$$


# SNR-Limited Design (total noise)



- **Input specifications:**
  - Minimum small signal gain  $A_v$
  - Minimum 3dB bandwidth  $\omega_{bw}$
  - Supply voltage  $V_{dd}$
  - Input-referred maximum linear amplitude  $V_{i,max}$
  - Signal shape (usually sinusoid) and amplitude  $V_{sig}$
  - Minimum signal-to-noise ratio  $SNR_{min}$
- **Goal: minimize power**

# Methodology


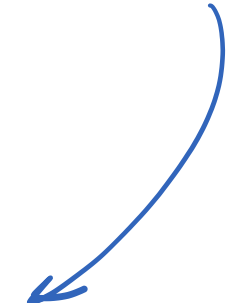
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$$\textcircled{1} \bullet \frac{V^*}{2} = V_{i, \max}$$

$$\textcircled{3} \bullet g_m = A_v \cdot \omega_{bw} \cdot C_L$$

$$\textcircled{4} \bullet I_d = \frac{g_m V^*}{2}$$

$$\textcircled{2} \bullet SNR_{\min} = \frac{\frac{1}{2} A_v^2 V_{sig}^2}{\frac{kT}{C_L} \left(1 + \frac{r}{\alpha} A_{v0}\right)}$$


$$C_L = \frac{2 kT SNR_{\min} \left(1 + \frac{r}{\alpha} A_{v0}\right)}{A_v^2 V_{sig}^2}$$


# Discussion

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