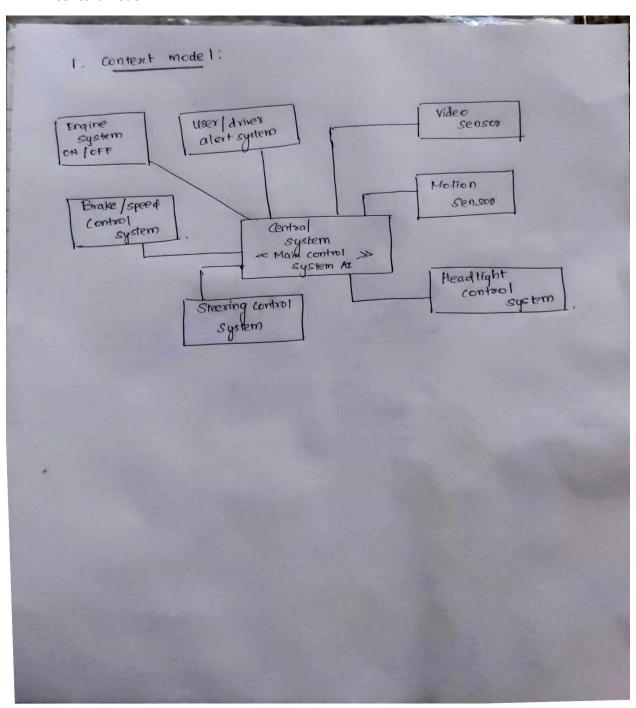
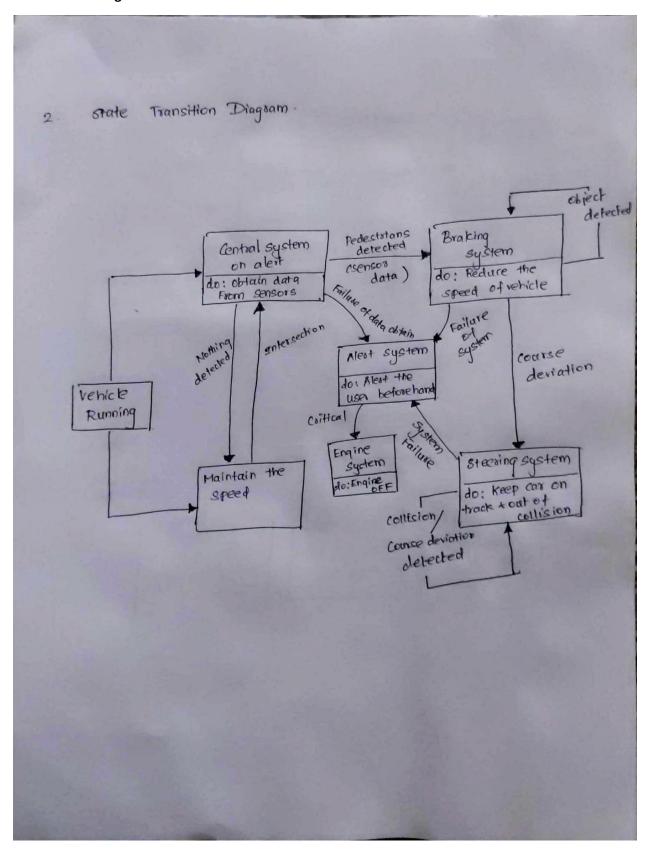
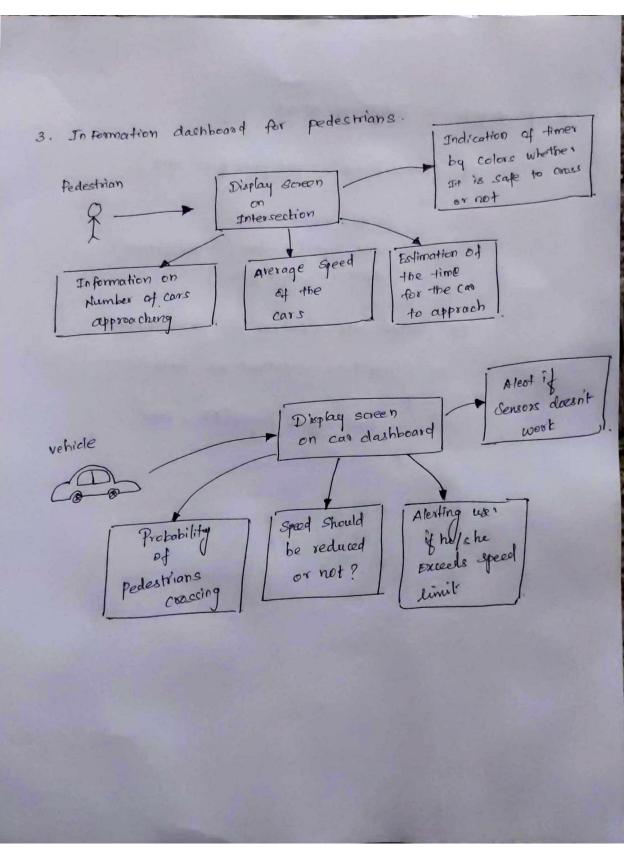
### 1. Context model



## 2. State diagram



### 3. Information dashboard



### 4. Pseudo code

```
4. Pseudocode for failure of sensor:
If ( Sensor Datab == undefined ) or Null )
           Failed_sensor = True;
           Send_Signal_Failure (Failed_Sensor)
           Alext_user_high (True)
 IF ( Sensor Data - Coitical & Desisor Data ==
   If (Sensor Data == "critical" del Failed Sensor == True)
            Send_ signal_ Engine OFF = True ;
```

### 5. Test plan how the system is efficient and safe

System is efficient:

### **Test case for Efficiency:**

Input (Initial): Data from sensors

### Execution:

- 1. Analyze the data from sensors
- 2. Categorize them based on criticality.
- 3. Give the user the analyzed data and inform necessary steps to be taken to avoid collision.

Output: User is clear about the condition of the car

Input: Data from road side cameras and speed monitors

#### **Execution:**

- 1. Obtain the data from the cameras and monitors
- 2. Calculate the necessary details (average speed, time for the car to reach intersection).
- 3. Display the detail in the information dashboard for the pedestrians

Output: Pedestrians understand the situation and decide whether to proceed/retreat from crossing.

### **Test case for Safety:**

Input: Failed sensor or controller system

### **Execution:**

- 1. Find out which sensor failed to work or which controller (brake or steering).
- 2. Check whether the vehicle is in critical condition
- 3. Main system instructs to slow down and turn off the engine if necessary

**Output:** Vehicle should be kept safe despite the critical collision probability and reduce the damage by maximum amount.