# DEEP LEARNING MODEL TO CLASSIFY ADINOMA AND ADINOCARCINOMA

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### **ABBREVIATIONS**

CNN - Convolution Neural Network

RNN - Recursive Neural Network

WSI - Whole Slide Images

LSTM - Long-Short term Memory

RAM - Random Access Memory

GPU - Graphics Processing Unit

AUC - Area Under the Curve

ROC curve - Receiver Operating Characteristic curve

ABSTRACT

Computerized microscopic image analysis plays an important role in computer related

diagnosis and prognosis. Machine learning techniques have powered many aspects of

medical investigation and clinical practices. Recently, deep learning is emerging as a

leading machine learning tool in computer vision and has attracted considerable attention

in biomedical image analysis. Stomach and colon cancers are amongst the most common

leading causes of cancer deaths in the world, with stomach cancer ranking fourth in men

and seventh in women, and colon cancer ranking third in men and second in women. This

problem can be solved by training a machine learning model to classify cancers. In this

project two models will be created using different algorithms and deep learning networks.

Utilizing aggregation techniques such as max-pooling (MP-aggr) and RNN (RNN-aggr),

the models can be trained with recurrent neural networks (RNN) and convolution neural

networks (CNN) on histopathological whole-slide images (WSI). WSIs are image samples

that are obtained through specialized scanning devices that are comparable to microscopic

images in primary diagnosis. The models were developed to categorize WSIs into different

tumour categories. The outcomes show how our algorithms may be used in the medical

sector on a regular basis to classify the various tumours in a histopathological WSI.

**KEYWORDS:** Recurrent Neural Network (RNN), Convolution Neural Network (CNN),

Whole-Slide Images (WSI), Max Pooling, RNN Aggregation, colon ca

## SUMMARY OF THE BASE PAPER

#### 1.1 PAPER DETAILS

Authors : Amu Iizuka, Fahdi Kanavati, Kei Kato, Michael Rambeau,

Koji Arihiro & Masayuki Tsuneki

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#### 1.2 INTRODUCTION

Colon and stomach cancers are among the most common tumours worldwide, according to a new analysis on global cancer statistics. In 2018, stomach cancer caused 8.2% of all cancer deaths worldwide, whereas colon cancer caused 9.2% of all cancer deaths. Among the other cancer types, stomach cancer is the third most common cause of death, followed by colon cancer. For the histopathological examination of specimens in a typical pathological diagnosis, light microscopy is used.

Whole slide images (WSIs) are image samples acquired using specialised scanning equipment that can serve as a substitute for microscopic pictures for the purposes of first diagnosis. The introduction of WSIs paved the way for image analysis methods in the medical sector. Pathologists can analyse WSIs and diagnose cancer with the aid of machine learning and deep learning techniques. Deep CNNs in particular have demonstrated excellent performance in a wide range of computer vision and medical image analysis applications.

Segmentation and cancer categorization are examples of promising computational pathology applications. Installing deep learning-based tools and workflow systems can enable pathologists to work more quickly, read images accurately, and with fewer errors by installing these programmes.

#### 1.3 SYSTEM MODEL FOR BASE PAPER:

The WSIs are initially pre-processed and augmented into a number of 512x512 pixel pictures. The model is trained using a variety of augmentation approaches that were imported from the Python libraries. For classification into adenoma and adenocarcinoma, the pictures are loaded into the proposed architecture model.

Some of the augmentation techniques that are used are scaling, hue saturation offsets, rotating, shear, contrast and brightness variations. The images were also rescaled between the values of [-1.0, 1.0].

In order to classify the WSI images various parameters were taken into consideration namely depth multiplier of 0.35 with 625k iterations and a batch size of 128. The model also had a least learning rate of 0.001 and most learning rate of 0.05. The model also used the Adam optimisation technique, with values for momentum, epsilon, and decay rate of 0.9, 1.0, and 1.0 respectively. In addition to these methods, the weighted cross entropy loss function was used to obtain the lowest loss value attainable.

The pathologists collected millions of tiles from WSI pictures and classified them into a tile consisting of two labels, adenoma and adenocarcinoma, after applying the aforementioned procedures. This model was created utilising the Inception V3 architecture. Then, these classified images from the CNN model are aggregated utilising two distinct techniques. There are two types of aggregation: 1) Max-Pooling and 2) LSTM RNN. Each WSI picture is given the label with the highest probability from all of its samples in the max pooling aggregation technique, whereas in the LSTM Recursive Neural Network (RNN) aggregation, the model was trained to incorporate the given information from all of the samples. Deep Convolution Neural Network (CNN) characteristics were used as input in this.

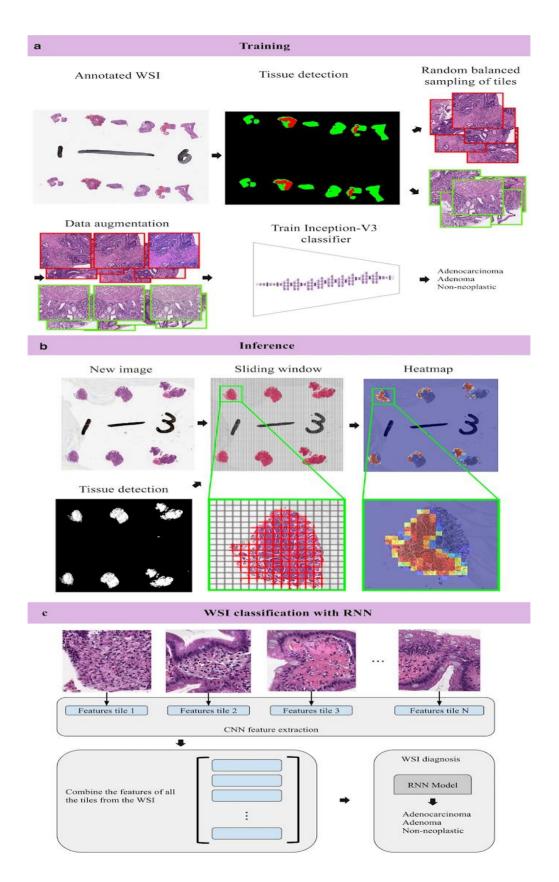


Fig 1.1: Summary of pipeline. (a) From WSI images of the training set, augmentation is done and inception v3 is trained. (b) A picture example of inference based on a new Whole Slide Image (WSI). (c) WSI using RNN.

#### **MERITS AND DEMERITS**

#### **2.1 MERITS**

- 1. Time complexity for creating the model is lesser compared to the diagnosis done by the pathologists via observing through the microscope.
- 2. The accuracy of classifying the images by the pathologists only increases based on the experience gained by each pathologist.
- 3. The time taken for the model to be trained is directly proportional to the accuracy it yields.
- 4, The model could act as a second person to evaluate the results or warn the pathologist in case of different output on primary diagnosis and hence avoiding human errors.

#### 2.2 DEMERITS

- 1. Huge size of WSI takes a lot of computational resources to process such as RAM and GPU space.
- 2. Every epoch takes a huge amount of time to train the model
- 3. Varying architecture and augmentation techniques show a big variation in the accuracy of the model.

#### **DATASET**

#### 3.1 About dataset used

Dataset given has data labelled whether it is adenocarcinoma and adenoma. The dataset [13] which contains colon cancer WSI (adenoma and adenocarcinoma) was used to train the models. The images consist of 96x96 pixel images. A total of ~2.2 lakhs images were present from it. This Dataset is derived from 400 Whole Slide Images(WSI).

#### 3.2 Stage 1: Image Pre-processing

The dataset that has been given consists of WSIs. So in order to get accurate images for the pathologist to diagnose the images given in the dataset are converted into 1s and 0s or true or false.

#### 3.3 Stage 2: Image Classification

These pre-processed images are then classified into adenocarcinoma as 1 and adenoma as 0 and are stored in an excel sheet. Once the images have been classified the max-pooling aggregation and RNN aggregation is performed in each of the models.

#### PROPOSED METHODOLOGY

#### 4.1 Platform used

The model was trained with the help of Kaggle notebook kernel which had a maximum RAM size of 16 GB when GPU was not utilized and 13 GB when GPU was utilized. The GPU had a size of 16 GB. Python language was used to train the models.

#### 4.1.1 Model 1 - Inception V3 architecture

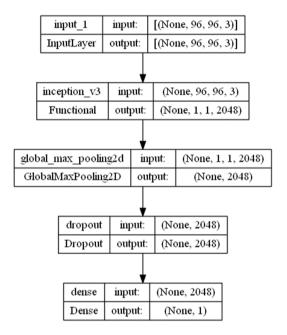


Fig 4.1: Model 1-layer structure

The classified images from the excel sheet are retained into a variable that are later used for image augmentation to improve the model accuracy. The augmentations that we used in the following given model are random horizontal and vertical flips, maximum rotation range of 90 degrees, zoom, width and height shift and shearing of images.

Compared to that of the standard CNN model, Inception v3 architecture is best efficient in time complexity. Secondly, inception v3 architecture can utilize the imagenet package in a well efficient manner. Here the images are trained with a maximum of 16 epochs. GPU is utilized in kaggle and took around 15 mins to train the model for each epoch.

#### 4.1.2 Model 2 - InceptionV3 with Simple RNN

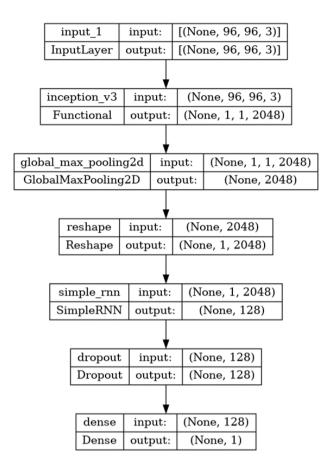


Fig 4.2: Model 2-layer structure

Similar to that of model 1, the data augmentation process remains the same. Only the hyperparameters and the architecture used changes, we have added Reshape and Simple RNN layers to it. Reshape function is useful when we need to change the dimensions of an array, for example, when we want to convert a one-dimensional array into a two-dimensional array or vice versa. It can also be used to create arrays with a specific shape, such as matrices and tensors. In the case of using a simple RNN for image classification, the approach would be to treat each pixel in an image as a sequence of values, where the values represent the pixel intensity or color. This would result in a sequence of values for each pixel location in the image. The RNN would then be trained on these sequences to learn patterns in the data that can be used for classification.

#### 4.1.3 Model 3 - InceptionV3 with LSTM

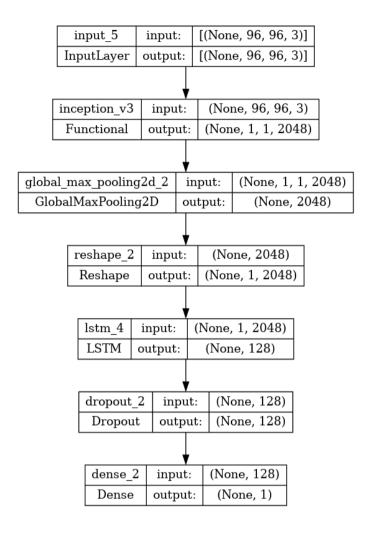


Fig 4.3: Model 3-layer structure

This model is similar to model 2. We have replaced the SimpleRNN with the LSTM( Long Short Term Memory). A proper RNN structure had been generated by using the LSTM (Long Short-Term Memory) architecture. This is used to make sure that it doesn't forget longer sequences and stores them in memory with the help of gates, whereas in SimpleRNN it can't remember longer sequences. This helps the model retain important information. The LSTM model is then trained, similar to other models mentioned above, on the sequences to identify patterns to classify the images into Adenoma or Adenocarcinoma.

#### **SOURCE CODE**

### 5.1 Model 1 - Inception V3 architecture

%matplotlib inline

!pip install livelossplot

# Imports

import numpy as np

import pandas as pd

from glob import glob

import os

import shutil

import matplotlib.pyplot as plt

from sklearn.metrics import roc\_curve, auc, roc\_auc\_score, confusion\_matrix,

classification\_report, ConfusionMatrixDisplay

from sklearn.model\_selection import train\_test\_split

import seaborn as sn

from keras.preprocessing.image import ImageDataGenerator

from keras.layers import Dropout, Flatten, Dense, GlobalMaxPooling2D, Input,

Concatenate

from keras.models import Model, Sequential

from keras.callbacks import CSVLogger, ModelCheckpoint

from keras.optimizers import Adam

from keras.applications.inception\_v3 import InceptionV3

from livelossplot import PlotLossesKeras

#### # Hyperparams

 $SAMPLE\_COUNT = 85000$ 

TRAINING RATIO = 0.9

 $IMAGE\_SIZE = 96$ 

EPOCHS = 16

BATCH SIZE = 216

VERBOSITY = 1

TESTING BATCH SIZE = 5000

#### # Output files

TRAINING\_LOGS\_FILE = "training\_logs.csv"

MODEL\_FILE = "histopathologic\_cancer\_detector.h5"

TRAINING\_PLOT\_FILE = "training.png"

VALIDATION\_PLOT\_FILE = "validation.png"

ROC PLOT FILE = "roc.png"

MODEL\_LAYERS\_SIMPLIFIED = "model\_plot\_simplified.png"

MODEL\_LAYERS = "model\_plot.png"

INPUT\_DIR = '../input/histopathologic-cancer-detection/'

training\_path = '../training'

```
validation_path = '../validation'
# Read the train labels and import as DataFrame
training dir = INPUT DIR + 'train/'
data frame = pd.DataFrame({'path': glob(os.path.join(training_dir,'*.tif'))})
data frame['id'] = data frame.path.map(lambda x: x.split('/')[4].split('.')[0])
labels = pd.read csv(INPUT DIR + 'train labels.csv')
data frame = data frame.merge(labels, on = 'id')
negatives = data_frame[data_frame.label == 0].sample(SAMPLE_COUNT)
positives = data_frame[data_frame.label == 1].sample(SAMPLE COUNT)
data_frame = pd.concat([negatives, positives]).reset_index()
data frame = data frame[['path', 'id', 'label']]
# Create folder for training and validation and sub folders for splitting the data
# as binary classification
for folder in [training_path, validation_path]:
  for subfolder in ['0', '1']:
    path = os.path.join(folder, subfolder)
    os.makedirs(path, exist_ok=True)
# Split the data according to TRAINING RATIO and copy the files to destination
folders
training, validation = train test split(data frame, train size=TRAINING RATIO,
stratify=data_frame['label'])
data frame.set index('id', inplace=True)
for images_and_path in [(training, training_path), (validation, validation_path)]:
  images = images and path[0]
  path = images and path[1]
  for image in images['id'].values:
    file name = image + '.tif'
    label = str(data frame.loc[image,'label'])
    destination = os.path.join(path, label, file name)
    if not os.path.exists(destination):
       source = os.path.join(INPUT_DIR + 'train', file_name)
       shutil.copyfile(source, destination)
# Data Augmentation and Reading the reading the images
# Data generation
training_generator = ImageDataGenerator(rescale=1./255,
                           horizontal flip=True,
                           vertical_flip=True,
                           rotation range=90,
                           zoom range=0.2,
                           width_shift_range=0.1,
                           height_shift_range=0.1,
                           shear range=0.05,
                           channel_shift_range=0.1).flow_from_directory(training_path,
                         target_size=(IMAGE_SIZE,IMAGE_SIZE),
```

```
batch_size=BATCH_SIZE,
                       class mode='binary')
validation=ImageDataGenerator(rescale=1./255).flow from directory(validation path,
                                         target size=(IMAGE SIZE,IMAGE SIZE),
                                            batch size=BATCH SIZE,
                                            class mode='binary')
# Defining the layers of CNN
input_shape = (IMAGE_SIZE, IMAGE_SIZE, 3)
model = Sequential()
model.add(Input(input shape))
model.add(InceptionV3(include_top=False, input_shape=input_shape))
model.add(GlobalMaxPooling2D())
model.add(Dropout(0.5))
model.add(Dense(1, activation='sigmoid'))
# compile the model
model.compile(optimizer=Adam(learning rate=0.001,
decay=0.0001,beta 1=0.9,epsilon=1.0),
        loss='binary_crossentropy',
        metrics=['accuracy'])
model.summary()
# Plot the model layer and save it as a file
from IPython.display import SVG
from keras.utils.vis_utils import model_to_dot
SVG(model to dot(model).create(prog='dot', format='svg'))
from keras.utils.vis utils import plot model
plot model(model, to file=MODEL LAYERS SIMPLIFIED, show shapes=True,
show_layer_names=True, expand_nested=False)
plot model(model, to file=MODEL LAYERS, show shapes=True,
show layer names=True, expand nested=True)
# Model Training
history = model.fit(training_generator,
                 steps per epoch=len(training generator),
                 validation_data=validation_generator,
                 validation_steps=len(validation_generator),
                 epochs=EPOCHS,
                 verbose=VERBOSITY,
                 callbacks=[PlotLossesKeras(),
                       ModelCheckpoint(MODEL_FILE,
                                monitor='val accuracy',
                                verbose=VERBOSITY,
                                save_best_only=True,
                                mode='max'),
                       CSVLogger(TRAINING_LOGS_FILE,
                             append=False,
                    separator=',')])
```

```
# Three callbacks
# 1) Plot accuracy and loss graph live
# 2) Save the best model every epoch
# 3) Log the accuracy and loss for each epoch
model.save(MODEL FILE)
# Load the weights from training
model.load_weights(MODEL_FILE)
# Plot training, validation accuracy and loss vs epoch
epochs = [i for i in range(1, len(history.history['loss'])+1)]
plt.style.use('dark background')
plt.plot(epochs, history.history['loss'], color='blue', label="training loss")
plt.plot(epochs, history.history['val_loss'], color='red', label="validation loss")
plt.legend(loc='best')
plt.title('training')
plt.xlabel('epoch')
plt.savefig(TRAINING PLOT FILE, bbox inches='tight')
plt.show()
plt.plot(epochs, history.history['accuracy'], color='blue', label="training accuracy")
plt.plot(epochs, history.history['val_accuracy'], color='red',label="validation_accuracy")
plt.legend(loc='best')
plt.title('validation')
plt.xlabel('epoch')
plt.savefig(VALIDATION PLOT FILE, bbox inches='tight')
plt.show()
# Plot ROC validation curse from validation data
roc validation generator =
ImageDataGenerator(rescale=1./255).flow_from_directory(validation_path,
target_size=(IMAGE_SIZE,IMAGE_SIZE), batch_size=BATCH_SIZE,
                                                   class mode='binary',
                                                   shuffle=False)
predictions = model.predict_generator(roc_validation_generator,
steps=len(roc_validation_generator), verbose=VERBOSITY)
false_positive_rate, true_positive_rate, threshold =
roc_curve(roc_validation_generator.classes, predictions)
area_under_curve = auc(false_positive_rate, true_positive_rate)
plt.plot([0, 1], [0, 1], 'k--')
plt.plot(false_positive_rate, true_positive_rate, label='AUC =
{:.3f}'.format(area_under_curve))
plt.xlabel('False positive rate')
plt.vlabel('True positive rate')
plt.title('ROC curve')
plt.legend(loc='best')
```

```
plt.savefig(ROC_PLOT_FILE, bbox_inches='tight')
plt.show()

y_act = roc_validation_generator.classes
y_pred = [1 if i > 0.5 else 0 for i in predictions]
class_labels = list(roc_validation_generator.class_indices.keys())
cm=confusion_matrix(y_true=y_act, y_pred=y_pred)
disp = ConfusionMatrixDisplay(cm)
disp.plot()
print(classification_report(y_act, y_pred,target_names=class_labels))
```

## 5.2 Model 2 - InceptionV3 with Simple RNN

```
% matplotlib inline
```

```
!pip install livelossplot
```

#### # Imports

import numpy as np

import pandas as pd

from glob import glob

import os

import shutil

import matplotlib.pyplot as plt

from sklearn.metrics import roc\_curve, auc, roc\_auc\_score, confusion\_matrix,

classification\_report, ConfusionMatrixDisplay

from sklearn.model\_selection import train\_test\_split

import seaborn as sn

from keras.preprocessing.image import ImageDataGenerator

from keras.layers import Dropout, Flatten, Dense, GlobalMaxPooling2D, Input,

Concatenate

from keras.models import Model, Sequential

from keras.callbacks import CSVLogger, ModelCheckpoint

from keras.optimizers import Adam

from keras.applications.inception\_v3 import InceptionV3

from livelossplot import PlotLossesKeras

#### # Output files

TRAINING LOGS FILE = "training logs.csv"

MODEL\_FILE = "histopathologic\_cancer\_detector.h5"

TRAINING\_PLOT\_FILE = "training.png"

VALIDATION\_PLOT\_FILE = "validation.png"

ROC\_PLOT\_FILE = "roc.png"

MODEL\_LAYERS\_SIMPLIFIED = "model\_plot\_simplified.png"

MODEL\_LAYERS = "model\_plot.png"

INPUT\_DIR = '../input/histopathologic-cancer-detection/'

training\_path = '../training'

validation\_path = '../validation'

#### # Hyperparams

SAMPLE\_COUNT = 85000

TRAINING RATIO = 0.9

 $IMAGE\_SIZE = 96$ 

EPOCHS = 16

BATCH SIZE = 216

VERBOSITY = 1

TESTING BATCH SIZE = 5000

#### # Data setup

training\_dir = INPUT\_DIR + 'train/'

```
data_frame = pd.DataFrame({'path': glob(os.path.join(training_dir,'*.tif'))})
data frame['id'] = data frame.path.map(lambda x: x.split('/')[4].split('.')[0])
labels = pd.read csv(INPUT DIR + 'train labels.csv')
data_frame = data_frame.merge(labels, on = 'id')
negatives = data frame[data frame.label == 0].sample(SAMPLE COUNT)
positives = data frame[data frame.label == 1].sample(SAMPLE COUNT)
data frame = pd.concat([negatives, positives]).reset index()
data_frame = data_frame[['path', 'id', 'label']]
# Create folder for training and validation and sub folders for splitting the data
# as binary classification
for folder in [training_path, validation_path]:
  for subfolder in ['0', '1']:
    path = os.path.join(folder, subfolder)
    os.makedirs(path, exist ok=True)
training, validation = train_test_split(data_frame, train_size=TRAINING_RATIO,
stratify=data_frame['label'])
data frame.set index('id', inplace=True)
for images and path in [(training, training path), (validation, validation path)]:
  images = images_and_path[0]
  path = images_and_path[1]
  for image in images['id'].values:
    file_name = image + '.tif'
    label = str(data_frame.loc[image,'label'])
    destination = os.path.join(path, label, file_name)
    if not os.path.exists(destination):
       source = os.path.join(INPUT DIR + 'train', file name)
       shutil.copyfile(source, destination)
# Data generation
training generator = ImageDataGenerator(rescale=1./255,
                           horizontal_flip=True,
                           vertical_flip=True,
                           rotation range=90,
                           zoom_range=0.2,
                           width_shift_range=0.1,
                           height_shift_range=0.1,
                           shear_range=0.05,
                           channel shift range=0.1).flow from directory(training path,
                                            target_size=(IMAGE_SIZE,IMAGE_SIZE),
                                                       batch size=BATCH SIZE,
                                                       class mode='binary')
validation=ImageDataGenerator(rescale=1./255).flow_from_directory(validation_path,
                                            target_size=(IMAGE_SIZE,IMAGE_SIZE),
                                               batch size=BATCH SIZE,
                                               class mode='binary')
```

```
input_shape = (IMAGE_SIZE, IMAGE_SIZE, 3)
model = Sequential()
model.add(Input(input shape))
model.add(InceptionV3(include top=False, input shape=input shape))
model.add(GlobalMaxPooling2D())
model.add(Reshape((1, -1)))
model.add(SimpleRNN(128))
model.add(Dropout(0.5))
model.add(Dense(1, activation='sigmoid'))
# compile the model
model.compile(optimizer=Adam(learning rate=0.001,
decay=0.0001,beta_1=0.9,epsilon=1.0),
        loss='binary_crossentropy',
        metrics=['accuracy'])
model.summary()
# Plot the model layer and save it as a file
from IPython.display import SVG
from keras.utils.vis utils import model to dot
SVG(model_to_dot(model).create(prog='dot', format='svg'))
from keras.utils.vis_utils import plot_model
plot_model(model, to_file=MODEL_LAYERS_SIMPLIFIED, show_shapes=True,
show layer names=True, expand nested=False)
plot_model(model, to_file=MODEL_LAYERS, show_shapes=True,
show layer names=True, expand nested=True)
# fit the model on data generator
history = model.fit(training generator,
     steps_per_epoch=len(training_generator),
     validation data=validation generator,
     validation steps=len(validation generator),
     epochs=EPOCHS,
     verbose=VERBOSITY,
     callbacks=[PlotLossesKeras(),
            ModelCheckpoint(MODEL FILE,
                     monitor='val_accuracy',
                     verbose=VERBOSITY,
                     save_best_only=True,
                     mode='max'),
            CSVLogger(TRAINING_LOGS_FILE,
                 append=False,
                 separator=',')])
model.load_weights(MODEL_FILE)
# Training plots
epochs = [i for i in range(1, len(history.history['loss'])+1)]
plt.style.use('dark_background')
```

```
plt.plot(epochs, history.history['loss'], color='blue', label="training_loss")
plt.plot(epochs, history.history['val loss'], color='red', label="validation loss")
plt.legend(loc='best')
plt.title('training')
plt.xlabel('epoch')
plt.savefig(TRAINING PLOT FILE, bbox inches='tight')
plt.show()
plt.plot(epochs, history.history['accuracy'], color='blue', label="training accuracy")
plt.plot(epochs, history.history['val_accuracy'], color='red',label="validation_accuracy")
plt.legend(loc='best')
plt.title('validation')
plt.xlabel('epoch')
plt.savefig(VALIDATION_PLOT_FILE, bbox_inches='tight')
plt.show()
roc validation generator =
ImageDataGenerator(rescale=1./255).flow_from_directory(validation_path,
target size=(IMAGE SIZE,IMAGE SIZE),
                                                    batch size=BATCH SIZE,
                                                    class mode='binary',
                                                    shuffle=False)
predictions = model.predict(roc validation generator,
steps=len(roc_validation_generator), verbose=VERBOSITY)
false_positive_rate, true_positive_rate, threshold =
roc curve(roc validation generator.classes, predictions)
area_under_curve = auc(false_positive_rate, true_positive_rate)
plt.plot([0, 1], [0, 1], 'k--')
plt.plot(false positive rate, true positive rate, label='AUC =
{:.3f}'.format(area under curve))
plt.xlabel('False positive rate')
plt.ylabel('True positive rate')
plt.title('ROC curve')
plt.legend(loc='best')
plt.savefig(ROC_PLOT_FILE, bbox_inches='tight')
plt.show()
y_act = roc_validation_generator.classes
y_pred = [1 \text{ if } i > 0.5 \text{ else } 0 \text{ for } i \text{ in predictions}]
class_labels = list(roc_validation_generator.class_indices.keys())
cm=confusion_matrix(y_true=y_act, y_pred=y_pred)
disp = ConfusionMatrixDisplay(cm)
disp.plot()
print(classification report(y act, y pred,target names=class labels))
```

## 5.3 Model 3 - Inception V3 with LSTM

% matplotlib inline

```
!pip install livelossplot
```

# Imports

import numpy as np

import pandas as pd

from glob import glob

import os

import shutil

import matplotlib.pyplot as plt

from sklearn.metrics import roc\_curve, auc, roc\_auc\_score, confusion\_matrix,

classification report, ConfusionMatrixDisplay

from sklearn.model selection import train test split

import seaborn as sn

from keras.preprocessing.image import ImageDataGenerator

from keras.layers import Dropout, Flatten, Dense, GlobalMaxPooling2D, Input,

Concatenate, LSTM, SimpleRNN, Conv2D, MaxPooling2D, Reshape

from keras.models import Model, Sequential

from keras.callbacks import CSVLogger, ReduceLROnPlateau, ModelCheckpoint,

EarlyStopping

from keras.optimizers import Adam

from keras.applications.inception\_v3 import InceptionV3

from livelossplot import PlotLossesKeras

#### # Output files

TRAINING\_LOGS\_FILE = "training\_logs.csv"

MODEL FILE = "histopathologic cancer detector.h5"

TRAINING PLOT FILE = "training.png"

VALIDATION\_PLOT\_FILE = "validation.png"

ROC\_PLOT\_FILE = "roc.png"

MODEL\_LAYERS\_SIMPLIFIED = "model\_plot\_simplified.png"

MODEL\_LAYERS = "model\_plot.png"

INPUT\_DIR = '../input/histopathologic-cancer-detection/'

training\_path = '../training'

validation\_path = '.../validation'

#### # Hyperparams

 $SAMPLE\_COUNT = 85000$ 

TRAINING RATIO = 0.9

 $IMAGE\_SIZE = 96$ 

EPOCHS = 16

 $BATCH_SIZE = 216$ 

VERBOSITY = 1

TESTING\_BATCH\_SIZE = 5000

#### # Data setup

training\_dir = INPUT\_DIR + 'train/'

```
data_frame = pd.DataFrame({'path': glob(os.path.join(training_dir,'*.tif'))})
data frame['id'] = data frame.path.map(lambda x: x.split('/')[4].split('.')[0])
labels = pd.read csv(INPUT DIR + 'train labels.csv')
data_frame = data_frame.merge(labels, on = 'id')
negatives = data frame[data frame.label == 0].sample(SAMPLE COUNT)
positives = data frame[data frame.label == 1].sample(SAMPLE COUNT)
data frame = pd.concat([negatives, positives]).reset index()
data_frame = data_frame[['path', 'id', 'label']]
# Create folder for training and validation and sub folders for splitting the data
# as binary classification
for folder in [training_path, validation_path]:
  for subfolder in ['0', '1']:
    path = os.path.join(folder, subfolder)
    os.makedirs(path, exist ok=True)
training, validation = train_test_split(data_frame, train_size=TRAINING_RATIO,
stratify=data frame['label'])
data frame.set index('id', inplace=True)
for images_and_path in [(training, training_path), (validation, validation_path)]:
  images = images_and_path[0]
  path = images and path[1]
  for image in images['id'].values:
    file name = image + '.tif'
    label = str(data frame.loc[image,'label'])
    destination = os.path.join(path, label, file_name)
    if not os.path.exists(destination):
       source = os.path.join(INPUT_DIR + 'train', file_name)
       shutil.copyfile(source, destination)
# Data generation
training_generator = ImageDataGenerator(rescale=1./255,
                           horizontal flip=True,
                           vertical flip=True,
                           rotation_range=90,
                           zoom_range=0.2,
                           width shift range=0.1,
                           height_shift_range=0.1,
                           shear range=0.05,
                           channel_shift_range=0.1).flow_from_directory(training_path,
target_size=(IMAGE_SIZE,IMAGE_SIZE),
                                                       batch_size=BATCH_SIZE,
                                                       class mode='binary')
validation generator =
ImageDataGenerator(rescale=1./255).flow_from_directory(validation_path,
target_size=(IMAGE_SIZE,IMAGE_SIZE),
                                               batch size=BATCH SIZE,
                                               class_mode='binary')
```

```
input shape = (IMAGE SIZE, IMAGE SIZE, 3)
model = Sequential()
model.add(Input(input_shape))
model.add(InceptionV3(include_top=False, input_shape=input_shape))
model.add(GlobalMaxPooling2D())
model.add(Reshape((1, -1)))
model.add(LSTM(128))
model.add(Dropout(0.5))
model.add(Dense(1, activation='sigmoid'))
# compile the model
model.compile(optimizer=Adam(learning_rate=0.001,
decay=0.0001,beta_1=0.9,epsilon=1.0),
        loss='binary crossentropy',
        metrics=['accuracy'])
model.summary()
# Plot the model layer and save it as a file
from IPython.display import SVG
from keras.utils.vis_utils import model_to_dot
SVG(model to dot(model).create(prog='dot', format='svg'))
from keras.utils.vis_utils import plot_model
plot model(model, to file=MODEL LAYERS SIMPLIFIED, show shapes=True,
show_layer_names=True, expand_nested=False)
plot model(model, to file=MODEL LAYERS, show shapes=True,
show_layer_names=True, expand_nested=True)
# fit the model on data generator
history = model.fit(training_generator,
     steps per epoch=len(training generator),
     validation data=validation generator,
     validation steps=len(validation generator),
     epochs=EPOCHS,
     verbose=VERBOSITY,
     callbacks=[PlotLossesKeras(),
            ModelCheckpoint(MODEL_FILE,
                     monitor='val_accuracy',
                     verbose=VERBOSITY,
                     save_best_only=True,
                     mode='max'),
            CSVLogger(TRAINING_LOGS_FILE,
                  append=False,
                  separator=',')])
# Training plots
epochs = [i for i in range(1, len(history.history['loss'])+1)]
plt.style.use('dark_background')
```

```
plt.plot(epochs, history.history['loss'], color='blue', label="training_loss")
plt.plot(epochs, history.history['val loss'], color='red', label="validation loss")
plt.legend(loc='best')
plt.title('training')
plt.xlabel('epoch')
plt.savefig(TRAINING PLOT FILE, bbox inches='tight')
plt.show()
plt.plot(epochs, history.history['accuracy'], color='blue', label="training_accuracy")
plt.plot(epochs, history.history['val accuracy'], color='red',label="validation accuracy")
plt.legend(loc='best')
plt.title('validation')
plt.xlabel('epoch')
plt.savefig(VALIDATION_PLOT_FILE, bbox_inches='tight')
plt.show()
model.load_weights(MODEL_FILE)
roc_validation_generator =
ImageDataGenerator(rescale=1./255).flow from directory(validation path,
target size=(IMAGE SIZE,IMAGE SIZE),
                                                  batch_size=BATCH_SIZE,
                                                  class mode='binary',
                                                  shuffle=False)
predictions = model.predict(roc_validation_generator,
steps=len(roc_validation_generator), verbose=VERBOSITY)
roc validation generator =
ImageDataGenerator(rescale=1./255).flow from directory(validation path,
target_size=(IMAGE_SIZE,IMAGE_SIZE),
                                                  batch size=BATCH SIZE,
                                                  class mode='binary',
                                                  shuffle=False)
# roc_valid_gen = custom_generator(roc_validation_generator)
predictions = model.predict generator(roc validation generator,
steps=len(roc_validation_generator), verbose=VERBOSITY)
false_positive_rate, true_positive_rate, threshold =
roc_curve(roc_validation_generator.classes, predictions)
area_under_curve = auc(false_positive_rate, true_positive_rate)
plt.plot([0, 1], [0, 1], 'k--')
plt.plot(false positive rate, true positive rate, label='AUC =
{:.3f}'.format(area under curve))
plt.xlabel('False positive rate')
plt.ylabel('True positive rate')
plt.title('ROC curve')
plt.legend(loc='best')
plt.savefig(ROC_PLOT_FILE, bbox_inches='tight')
```

```
plt.show()

y_act = roc_validation_generator.classes
y_pred = [1 if i > 0.5 else 0 for i in predictions]
class_labels = list(roc_validation_generator.class_indices.keys())
cm=confusion_matrix(y_true=y_act, y_pred=y_pred)
disp = ConfusionMatrixDisplay(cm)
disp.plot()
print(classification_report(y_act, y_pred,target_names=class_labels))
```

## CHAPTER 6 OUTPUT SNAPSHOTS

## 6.1 Model 1 - Inception V3 architecture

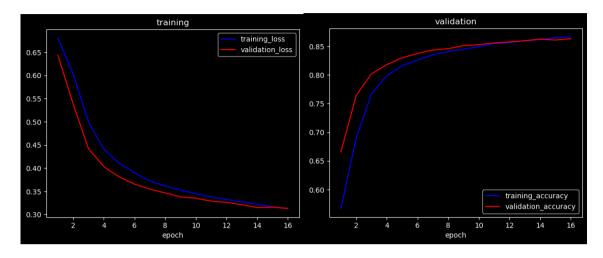


Fig 6.1 The diagrams show training and validation loss(left) and accuracy(right) of model 1 which runs with a maximum epoch of 16.

```
accuracy
                                        0.567, max:
       training
                                (min:
                                                       0.866, cur:
                                                                      0.866)
       validation
                                (min:
                                        0.666, max:
                                                       0.863, cur:
                                                                      0.863)
Loss
       training
                                (min:
                                        0.313, max:
                                                       0.681, cur:
                                                                      0.313)
       validation
                                (min:
                                        0.313, max:
                                                       0.643, cur:
                                                                      0.313)
709/709 [============ ] - 530s 748ms/step - loss: 0.3127 - accuracy: 0.8661 - val_1
oss: 0.3131 - val_accuracy: 0.8632
```

Fig 6.2 The Figure gives the minimum and maximum accuracy and loss for the training and validation set for the model 1.

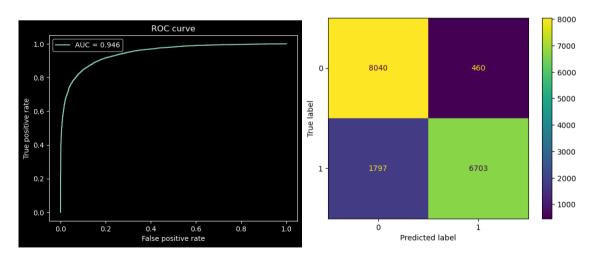


Fig 6.3 The diagram shows the ROC curve of model 1 which has the Area Under the Curve (AUC) value (left) and Confusion matrix for the model(right).

	precision	recall	f1-score	support
0	0.82	0.95	0.88	8500
1	0.94	0.79	0.86	8500
accuracy			0.87	17000
macro avg	0.88	0.87	0.87	17000
weighted avg	0.88	0.87	0.87	17000

Fig 6.4 The figure shows the classification report for Model 1

## 6.2 Model 2 - InceptionV3 with Simple RNN

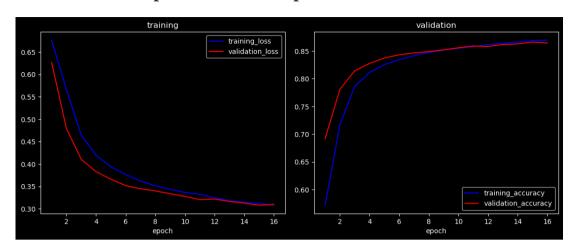


Fig 6.5 The diagrams show training and validation loss(left) and accuracy(right) of model 2 which runs with a maximum epoch of 16.

```
accuracy
      training
                                           0.870, cur:
                         (min:
                               0.572, max:
                                                      0.870)
     validation
                               0.692, max:
                                           0.866, cur:
                         (min:
                                                      0.864)
Loss
      training
                         (min:
                                0.308, max:
                                           0.676, cur:
                                                      0.308)
     validation
                                           0.627, cur:
                         (min:
                               0.308, max:
                                                      0.310)
Epoch 16: val_accuracy did not improve from 0.86594
ss: 0.3099 - val_accuracy: 0.8643
```

Fig 6.6 The Figure gives the minimum and maximum accuracy and loss for the training and validation set for the model 2.

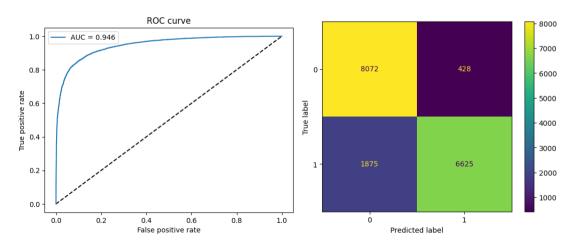


Fig 6.7 The diagram shows the ROC curve of model 1 which has the Area Under the Curve (AUC) value (left) and Confusion matrix for the model(right).

	precision	recall	f1-score	support
0	0.81	0.95	0.88	8500
1	0.94	0.78	0.85	8500
accuracy			0.86	17000
macro avg	0.88	0.86	0.86	17000
weighted avg	0.88	0.86	0.86	17000

Fig 6.8 This figure shows the classification report for Model 2

## 6.3 Model 3 - InceptionV3 with LSTM

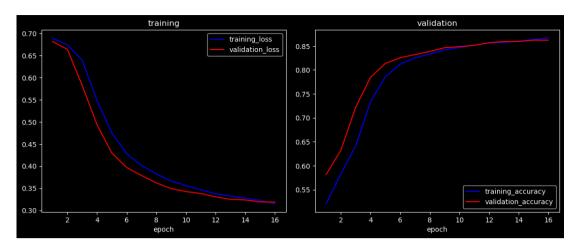


Fig 6.9 The diagrams show training and validation loss(left) and accuracy(right) of model 3 which runs with a maximum epoch of 16.

```
accuracy
                                                       0.866)
      training
                         (min:
                                0.521, max:
                                           0.866, cur:
      validation
                         (min:
                                0.582, max:
                                           0.862, cur:
                                                       0.862)
Loss
      training
                         (min:
                                0.315, max:
                                           0.689, cur:
                                                       0.315)
                                0.319, max:
                                           0.682, cur:
      validation
                                                       0.319)
                         (min:
Epoch 16: val_accuracy did not improve from 0.86212
ss: 0.3186 - val_accuracy: 0.8621
```

Fig 6.10 The Figure gives the minimum and maximum accuracy and loss for the training and validation set for the model 3.

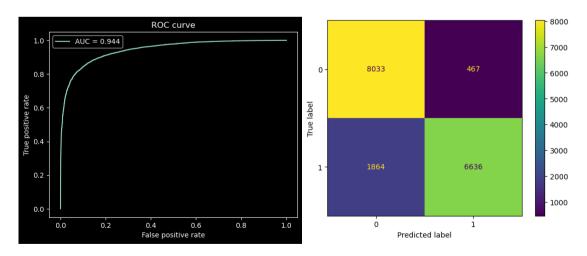


Fig 6.11 The diagram shows the ROC curve of model 1 which has the Area Under the Curve (AUC) value (left) and Confusion matrix for the model(right).

	precision	recall	f1-score	support
0	0.81	0.95	0.87	8500
1	0.93	0.78	0.85	8500
accuracy			0.86	17000
macro avg	0.87	0.86	0.86	17000
weighted avg	0.87	0.86	0.86	17000

Fig 6.12 The figure shows the classification report for Model 3

## 7.1 CONCLUSION

It is to be noted that each model takes a huge time to train the data. Especially model 3 which took more than ~3.5 hours to train. Model 1 and 2 took approx. ~15 mins for each epoch and hence ~3 hours for both models (16 epochs) to train the data. Model 2 has the highest accuracy and the lowest loss in both training and validation set compared to the other models thus model 2 can be used to classify adenocarcinoma and adenoma. Table 5.1 shows the overall accuracy and loss of each model that is used.

	MODEL 1 (InceptionV3)	MODEL 2 (InceptionV3 with Simple RNN)	MODEL 3 (InceptionV3 with LSTM)
Training accuracy	0.866	0.870	0.866
Validation accuracy	0.863	0.864	0.862
Training loss	0.313	0.308	0.315
Validation loss	0.313	0.310	0.319

Table 7.1 Accuracy and loss of all three models obtained