# **VIGNESH SUNDARARAJAN**

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# **Education**

Purdue University | Master of Science - Aeronautics and Astronautics Engineering

Extra Curricular Work: Aerodynamics Team Member - Purdue Electric Racing | % Blog Link

West Lafavette, USA 2021 - Present

**SRM University** | Bachelor of Technology - Mechanical Engineering

Extra Curricular Work: Design Lead and Team Vice Captain for collegiate FSAE Team

Chennai, IN 2016-2020

#### **Skills**

Programming: C++, Python, MATLAB, SQL, R, Lua, HTML, CSS, Javascript, LATEX

Frameworks/Libraries: Tensorflow/Keras, PyTorch, Scikit-Learn, Numpy, Eigen, openCV, Matplotlib, Pandas, Dask, Plotly, Folium, Flask Developer Tools: AWS, GCP, Git, Vim, Linux, openMPI, CMake, Meson, ROS, Gazebo, Docker, Kubernetes, Confluence, Jira

# **Experience**

# Graduate Data Science Researcher | John Deere + The Purdue Data Mine

West Lafavette, USA

Tools Used: AWS, Python, SQL, Spark, ARCGIS, Machine Learning, Computer Vision, Geospatial Data Analysis

Aug 2022 - Present

• Developing an automated, large scale system to identify wildlife conservation opportunities for the Pheasant and Quail Foundation(PQF) by ingesting satellite data and producing profitability maps in ARCGIS for agricultural planning.

# Data Scientist | Wabash National + Dauch Center for the Management of Manufacturing Enterprises

West Lafayette, USA

Tools Used: Python, Scikit-learn, Pandas, Dask, Parquet, Plotly, Folium, Geopy, Telematics

Jun 2022 - Aug 2022

- · Performed a univariate exploratory data analysis to study sensor ping frequency for Wabash's nationwide fleet of trucks.
- Achieved a 60× speed improvement and an 85% storage use reduction by implementing a parallelized data ingestion and cleaning pipeline to handle multi-year raw Telematics data of the order of 100GB, using Python and Dask. Wrote documentation on the dataset.
- Built Python software to visualize high-traffic trucking hubs across North America using yearly fleet GPS data as input and employing the Mini-Batch K-Means clustering algorithm. Presented findings to the business end of both organizations.

# **Projects**

#### Object tracking and following Robot in Gazebo | G Github Link

West Lafayette, USA

Tools Used: Python, ROS, OpenCV, Linux, Computer Vision

Apr 2022

- · Computed distance to the object by performing image masking on a real time RGB video feed and calculating it's centroid.
- Developed a proportional velocity controller to check for the object in robot's FOV before following it.

#### Monocular Vision based Navigation of a 4-wheeled robot | Github Link

West Lafayette, USA

Tools Used: Python, C++, CMake, Computer Vision, OpenCV, ROS, Raspberry Pi, L293D driver board

Mar 2022 - Apr 2022

- Calibrated a monocular camera interfaced with a Raspberry Pi acting as the vision system for a 4 wheeled DC Motor driven robot. Performed 3D localization of the robot in the environment using the Fiducials ROS package.
- Built a PID controller based motion algorithm to navigate the robot towards an Aruco marker placed in the environment.
- · Developed a line following mechanism by interfacing IR sensors to the robot as a fallback in case the vision system fails.

#### Image Super-Resolution using a GAN with a Perceptual Loss Function | Q Github Link

West Lafavette, USA

Tools Used: Python, Tensorflow/Keras, Matplotlib, Numpy, Pillow

Aug 2021 - Dec 2021

- Implemented SRGAN, based on the ResNet architecture(16 Residual Blocks with skip connections), with a perceptual loss function that uses high level feature maps of the VGG network
- Trained the neural network for 50,000 steps on the DIV2K data set and visualized the 4× upsampled images using matplotlib

### CNN Autoencoder for Image Denoising | Github Link

Tools Used: Python, Pytorch, Deep Learning, MNIST

loss of 17.33 after 10 epochs

West Lafayette, USA

• Performed data augmentation on the MNIST dataset by adding a Gaussian Noise with  $\mu = 0$  and  $\sigma = 0.5$ 

· Built a Convolutional Neural Network based autoencoder model to remove noise from augmented dataset and achieved an average

Oct 2021

# KNN Classifier to detect potential Credit Card fraud | S Blog Link

Tools Used: Python, Scikit-learn, Predictive Modelling

West Lafayette, USA

Sep 2021

• Built a predictive model to determine whether a credit card transaction is fraudulent or not and achieved 95.468% training accuracy and 90.625% test accuracy. Employed K-Nearest Neighbors Classification with cross validation to optimize the hyperparameters.

# **Miscellaneous Projects**

- Neovim Code Editor configuring Lua Integrated LSP and fuzzy finding capabilities with 4ms startup time | ? Github Link
- Portfolio website development using Hugo Javascript, HTML, CSS, Markdown | 🗘 Github Link