

## Education

<b>Purdue University - School of Aeronautics and Astronautics</b>	<b>West Lafayette, USA</b>
<b>Master of Science - Aeronautics and Astronautics (Aerospace Engineering)</b> ( * = Ongoing )	2021-Present
Coursework: Artificial Intelligence, Statistical Methods*, Autonomous Systems*, System of Systems Modeling and Analysis*	
<b>SRM University</b>	<b>Chennai, IN</b>
<b>Bachelor of Technology - Mechanical Engineering</b>	2016-2020

## Skills

**Programming:** C++, Python, MATLAB, R, Bash, HTML, CSS,  $\LaTeX$   
**Frameworks/Libraries:** openCV, ROS, numpy, PyTorch, Keras, Tensorflow, scikit-learn, matplotlib, pandas, seaborn  
**Tools:** Git, Linux, CMake, GDB, LLDB, PDB, Jupyter, Gazebo, Confluence, Jira  
**Ongoing Additional Coursework:** Machine Learning, Computer Vision, Deep Learning, Robotics, Model Based Systems Engineering

## Projects

<b>Avionics Engineer - Purdue Vertical Flight Systems</b>	<b>West Lafayette, USA</b>
<i>Purdue University   Skills Used: ROS, Python, C++, Gazebo</i>	Jan 2022 - Present
<ul style="list-style-type: none"> <li>Facilitated a transition to a GitHub organization for better code management and collaboration</li> <li>Currently working on gaining a thorough understanding of the software stack consisting of the PX4 Pixhawk Autopilot Software, QGroundControl and simulation using ROS &amp; Gazebo</li> </ul>	
<b>Building an Autonomous Robot to navigate through a model town (Ongoing)</b>	<b>West Lafayette, USA</b>
<i>Purdue University   ROS, Python, CMake, XML, Robot Kinematics, Linux, Computer Vision, SLAM</i>	Jan 2022 - Present
<ul style="list-style-type: none"> <li>Working on an intensive course project involving building an autonomous robot consisting of Ultrasonic sensing, Computer Vision, and Line Tracking capabilities by handling all the sensor data and processing it on a Raspberry Pi using Python and ROS</li> <li>Upcoming work involves implementing Control System Algorithms, Path Planning, Trajectory Optimization, SLAM and Perception capabilities into the autonomous robot</li> </ul>	
<b>Aerodynamics Team Member - Purdue Electric Racing</b>	<b>West Lafayette, USA</b>
<i>Purdue University   Skills Used: ANSYS, SolidWorks, Fusion 360, Confluence, Jira</i>	Aug 2021 - Present
<ul style="list-style-type: none"> <li>Designed CFD simulations to correlate Wind Tunnel testing data with simulated data, and achieved ~ 7% margin of error.</li> <li>Designed a parametric CFD study for cooling the motor controller of the vehicle with an underbody ducting system, and presented results to the team leads and other members through extensive written documentation on Confluence</li> </ul>	
<b>Responsive Website Design - Portfolio</b>	<b>West Lafayette, USA</b>
<i>Purdue University   Skills Used: HTML, SCSS, Javascript, JSON, Version Control (Git), UI and User Experience</i>	Dec 2021
<ul style="list-style-type: none"> <li>Created a responsive portfolio website detailing all projects and relevant information using the Hugo Static Site Generator, HTML, Javascript, and CSS for visualization.</li> <li>Maintained a repository using Git version control on GitHub to efficiently deploy changes to the website</li> </ul>	
<b>Using a GAN with a Perceptual Loss Function for Image Super Resolution</b>	<b>West Lafayette, USA</b>
<i>Purdue University   Skills Used: Python, TensorFlow/Keras, matplotlib, HDF5, Data Analysis, Deep Learning</i>	Aug 2021 - Dec 2021
<ul style="list-style-type: none"> <li>Implemented a Deep Generative Adversarial Network, having 16 Residual Blocks and a Generator-Discriminator pair, performing Unsupervised Learning with a Supervised Loss Function for image super-resolution using TensorFlow 2 and Keras</li> <li>Trained the neural network for 50,000 steps using test/train splits to handle ~ 10GB datasets efficiently and visualized the results using matplotlib</li> </ul>	
<b>Vice Captain and Design Lead - Hawkz Racing Formula Student Team</b>	<b>Chennai, IN</b>
<i>SRM University   Skills Used: ANSYS, CATIA, Leadership, Problem Solving, Automotive, Research and Development</i>	2017 - 2018
<ul style="list-style-type: none"> <li>Successfully managed a team of 30 people, working across multiple departments (powertrain, chassis, vehicle dynamics, business), to secure National Awards in Sales and Business Presentation, along with a National Rank of 4 at the Design Presentation</li> <li>Oversaw the development and integration of core vehicle components from design through to manufacturing and assembly.</li> </ul>	

## Experience

<b>Research Intern - Aerodynamics</b>	<b>Kanpur, IN</b>
<i>IIT Kanpur - Non Equilibrium Flow Simulation Lab   Skills Used: ANSYS (FLUENT, ICEM, MECHANICAL), PuTTY, HPC</i>	Jun 2019
<ul style="list-style-type: none"> <li>Utilized grid adaptation techniques and performed mesh independence studies to simulate fluid flow through a CD Nozzle with supersonic jet control to study mixing characteristics of the plume with the atmosphere.</li> </ul>	