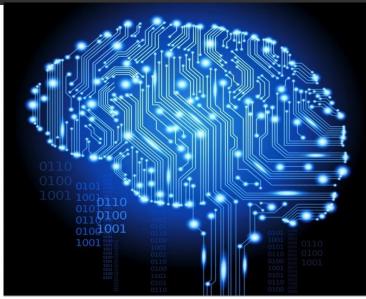


#### **Information Technology**

## Heaps II

Prepared by Maria Garcia de la Banda Updated by Brendon Taylor





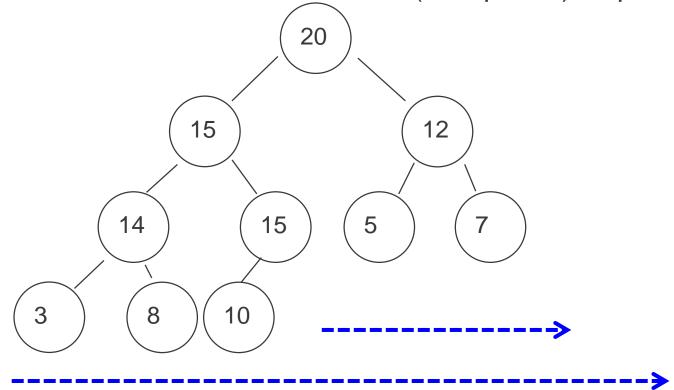
#### Objectives for these two lectures

- To understand a simple implementation of Heaps
  - To be able to reason about the complexity of its operations
  - To be able to implement them and modify them
- To consider a particular application:
  - Sorting a priority queue
- To understand a "cleverer" construction method for Heaps
  - Bottom-up heap construction
- To understand heap-sort
  - A fast, recursive alternative to mergesort and quicksort



#### **Recall: Basics of heaps**

- A heap is a binary tree that is :
  - Complete: All levels but the last are full; the last is filled from the left
  - Heap-ordered: each child is smaller than (or equal to) its parent



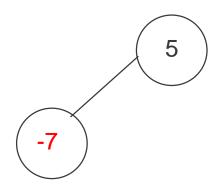


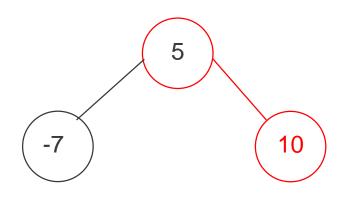


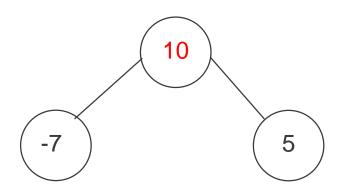
## Heap vs BST

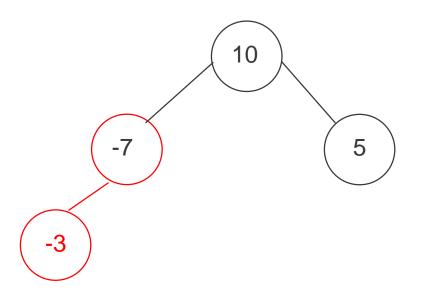


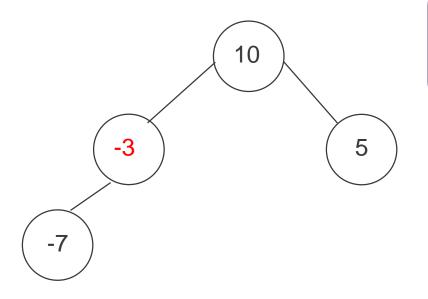


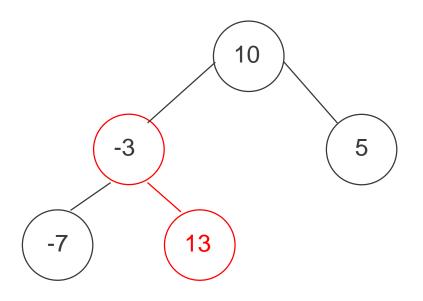


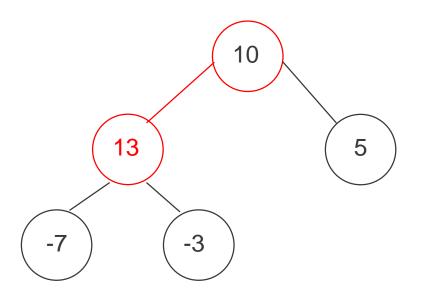


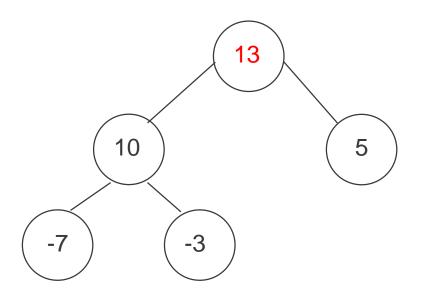


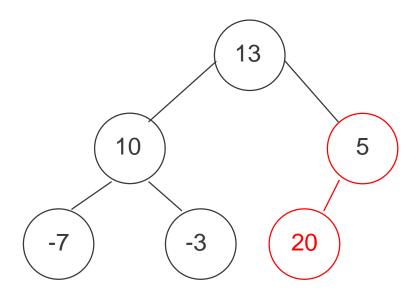


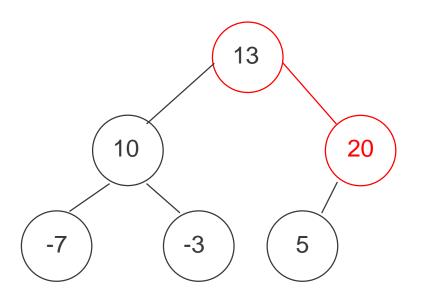


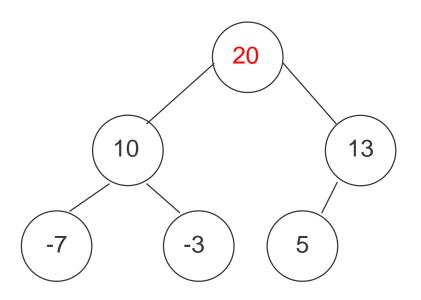


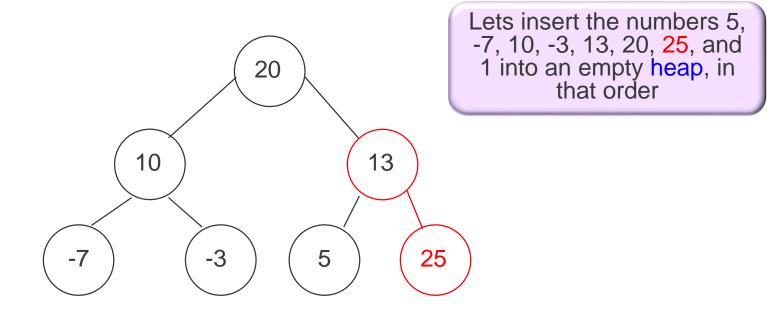


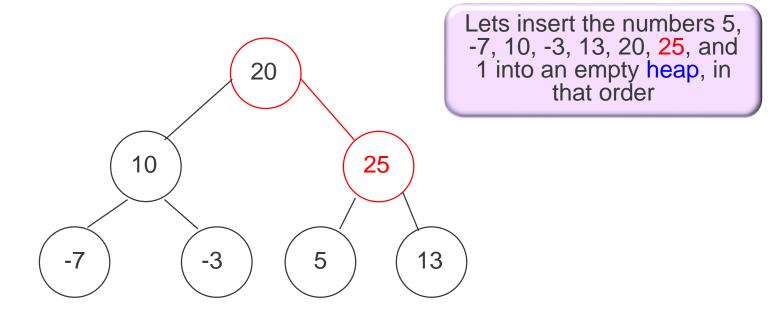




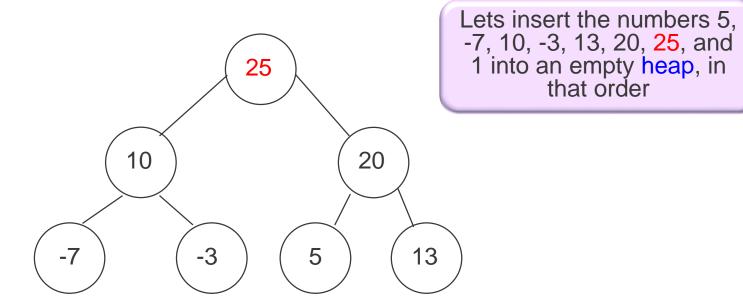




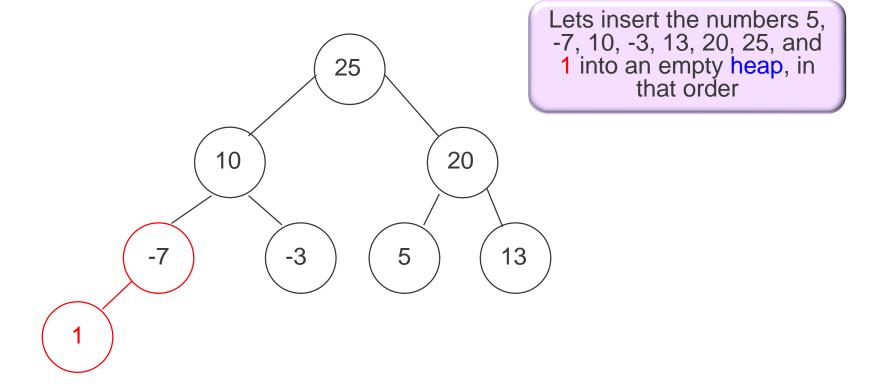




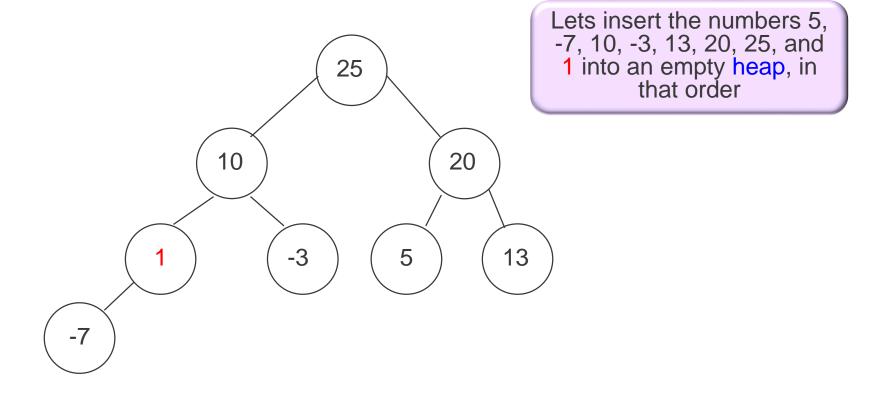






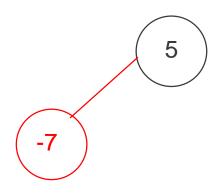


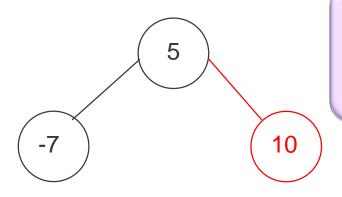


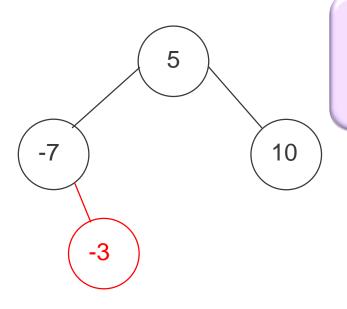


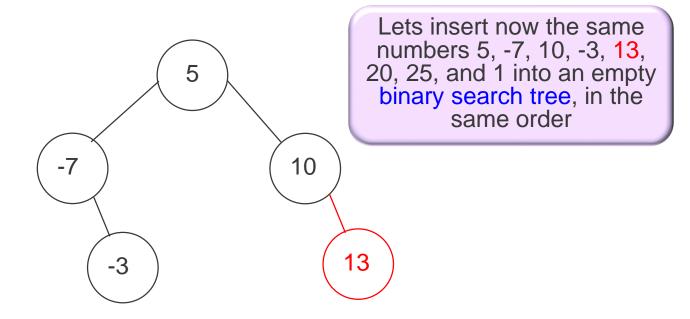




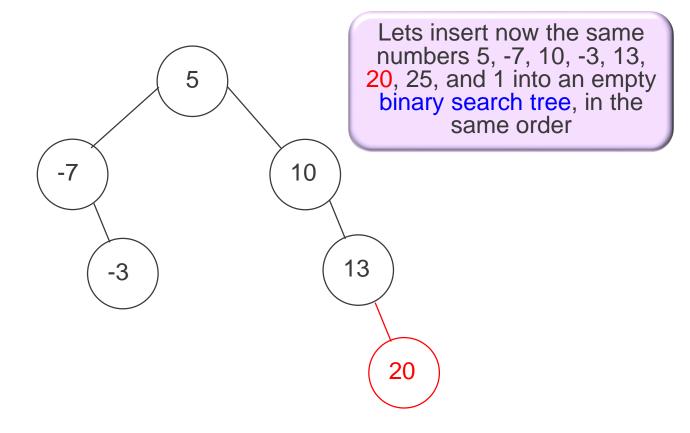




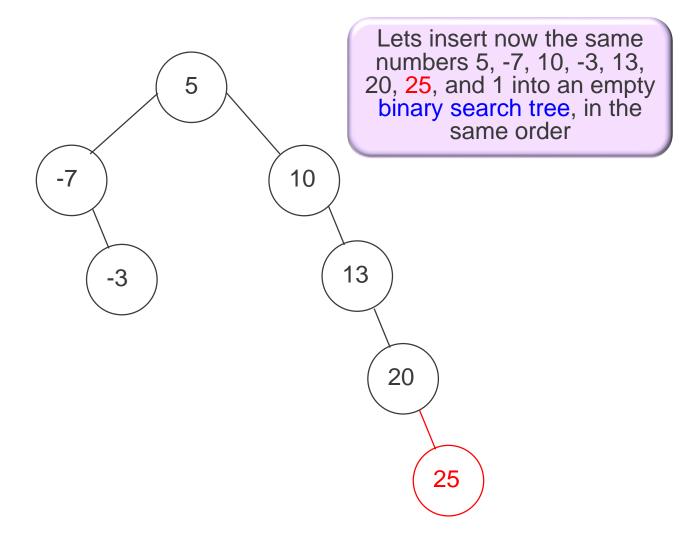




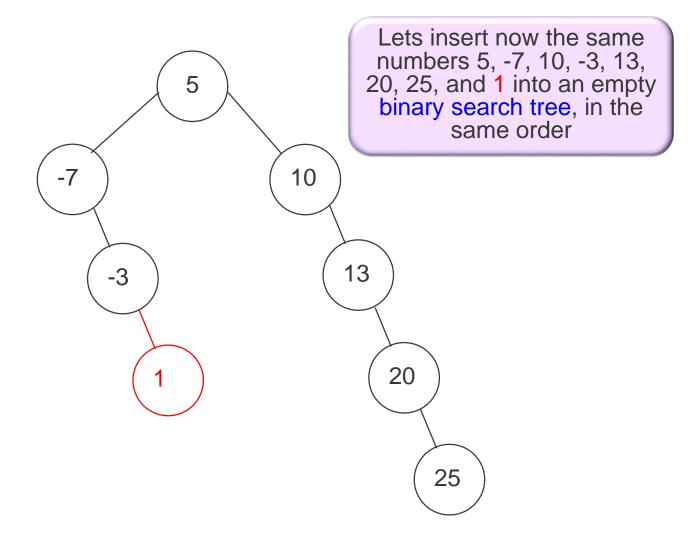




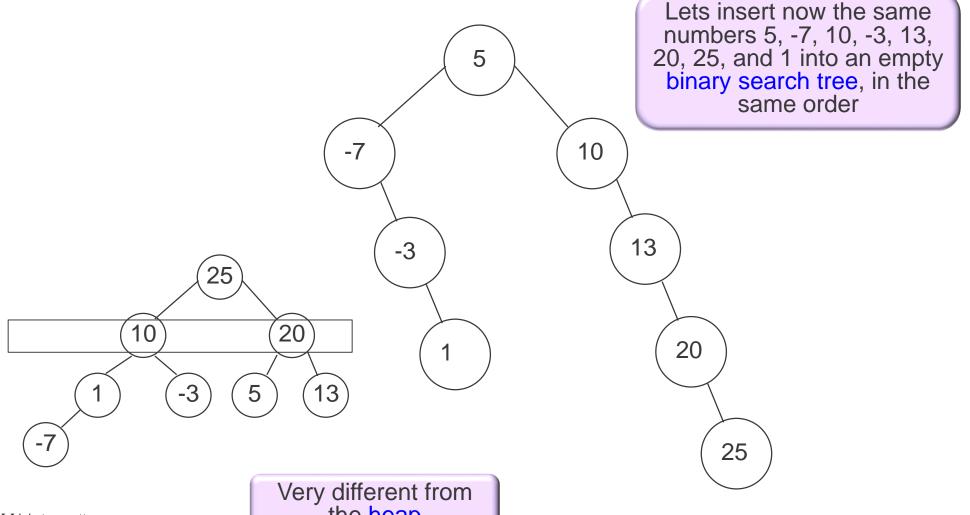














the heap



# Priority Queue Implementation

#### **Implementation**

- How can we implement this data type?
- With a binary tree made of linked nodes
  - Downside: complex -- requires extra pointers to move up the tree (rise a node)
  - Which also means it requires a lot of extra memory
- With an array
  - Possible thanks to completeness
  - Very compact

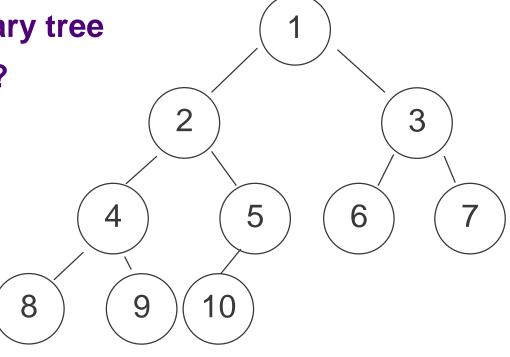


#### Implementing it with an array

Consider the following complete binary tree

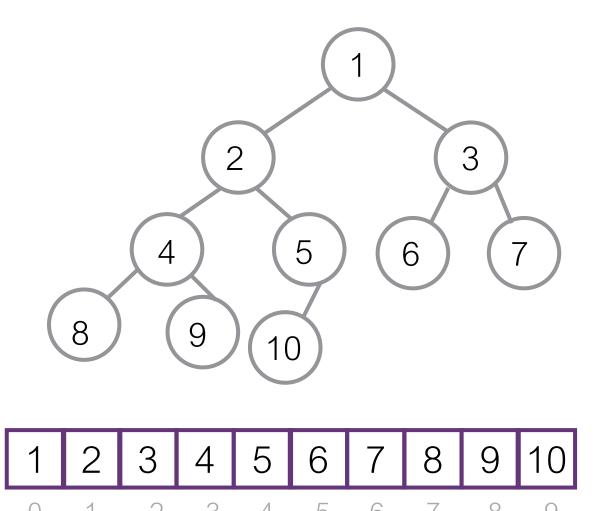
Where are the children of each node?

- And the parent of each node?
- We will see in the next slides!



The figure shows both the binary tree and the array equivalent. We will highlight in grey each parent (so, inner nodes) with their children.

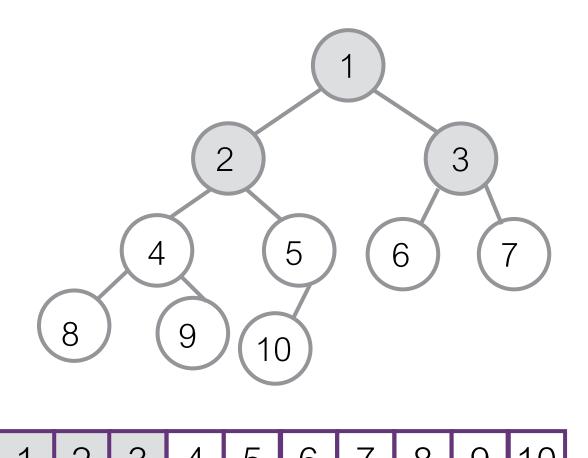
The table will show the array index of the grey nodes



Parent Position	Child Left	Child Right

The figure shows both the binary tree and the array equivalent. We will highlight in grey each parent (so, inner nodes) with their children.

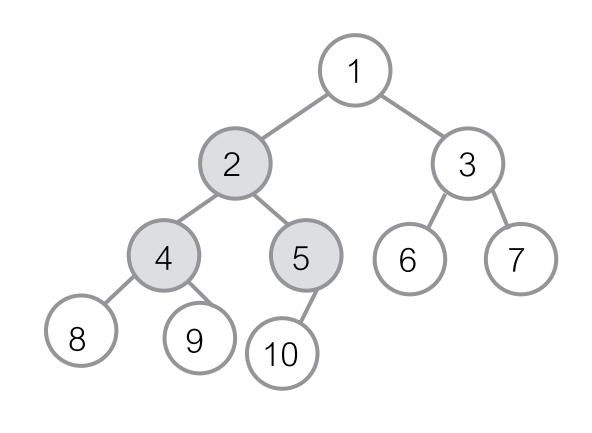
The table will show the array index of the grey nodes



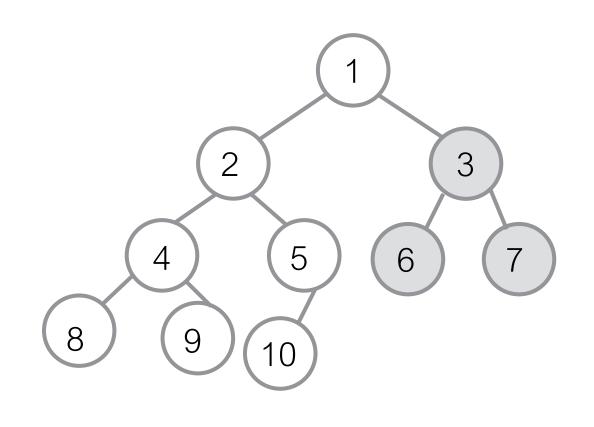
Child Left	Child Right
1	2
	Left

The figure shows both the binary tree and the array equivalent. We will highlight in grey each parent (so, inner nodes) with their children.

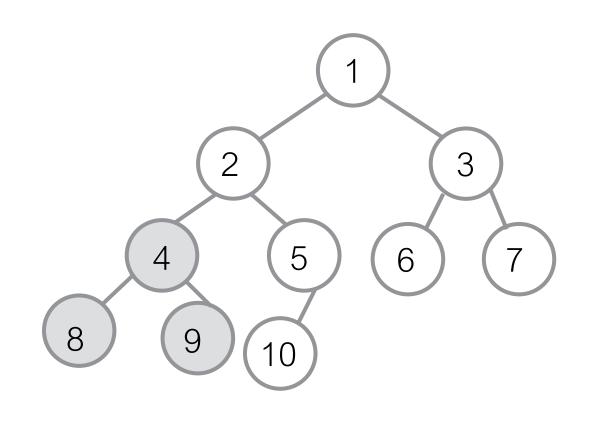
The table will show the array index of the grey nodes



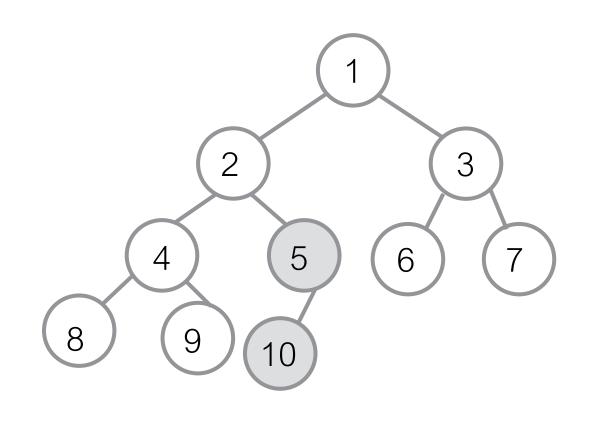
Parent Position	Child Left	Child Right
0	1	2
1	3	4



Parent Position	Child Left	Child Right
0	1	2
1	3	4
2	5	6

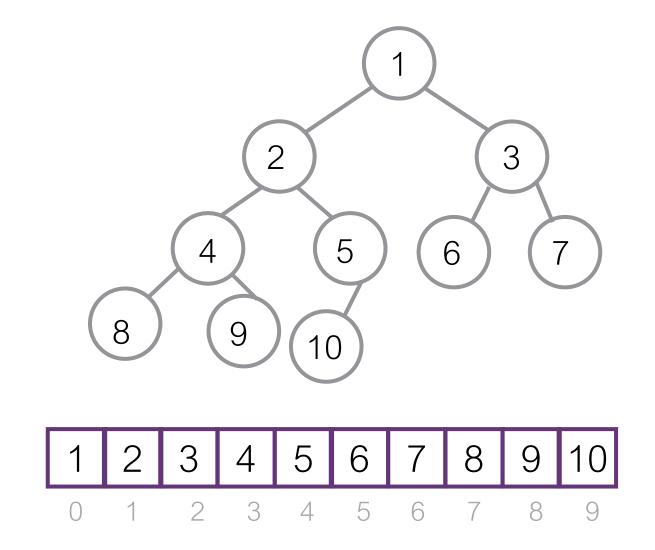


Parent Position	Child Left	Child Right
0	1	2
1	3	4
2	5	6
3	7	8



Parent Position	Child Left	Child Right
0	1	2
1	3	4
2	5	6
3	7	8
4	9	

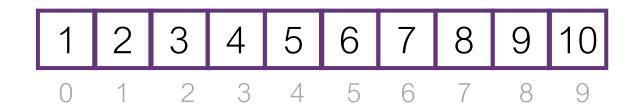
The table will show the array index of the grey nodes

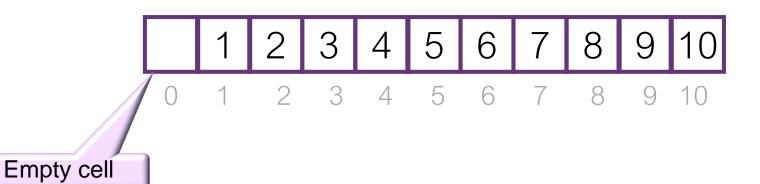


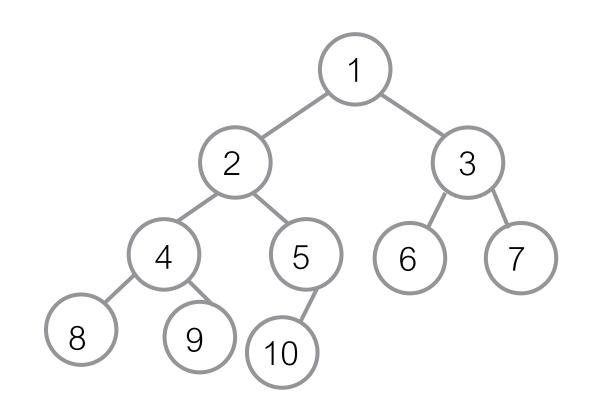
Parent Position	Child Left	Child Right
0	1	2
1	3	4
2	5	6
3	7	8
4	9	
k	?	?

Not as clear as we would like

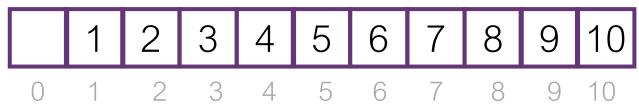
# If we shift by 1, it will clarify positions

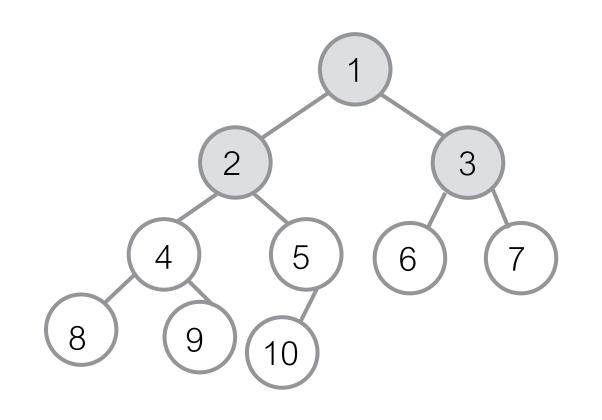






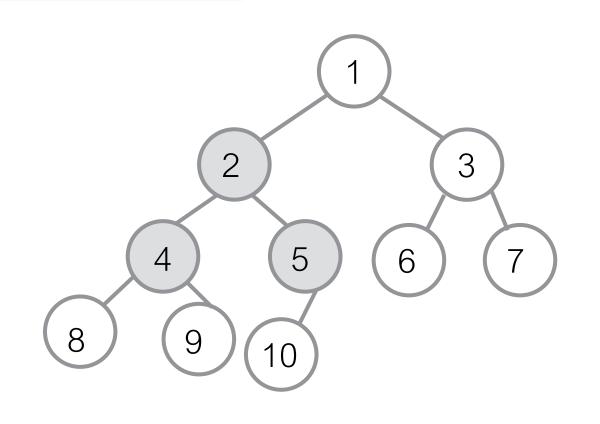
Parent Position	Child Left	Child Right



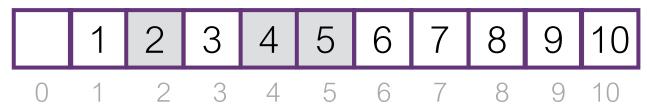


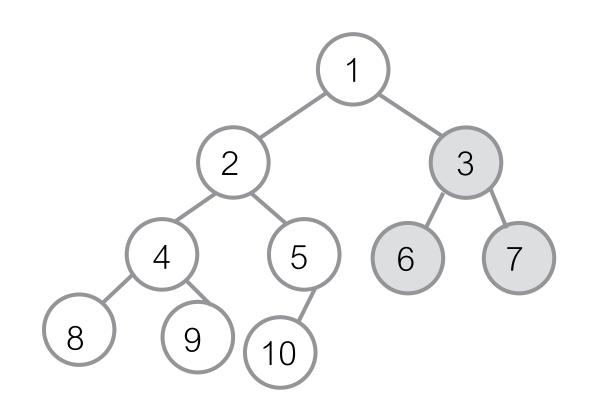
Parent Position	Child Left	Child Right
1	2	3

	1	2	3	4	5	6	7	8	9	10
0	1	2	3	4	5	6	7	8	9	10

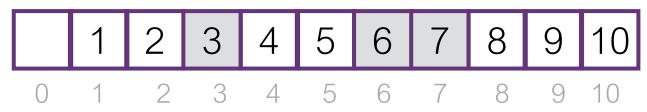


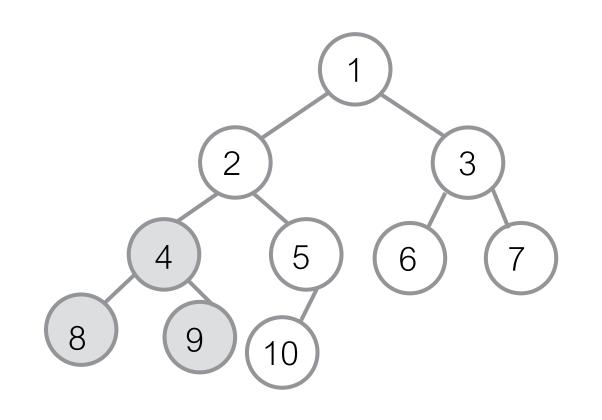
Parent Position	Child Left	Child Right
1	2	3
2	4	5





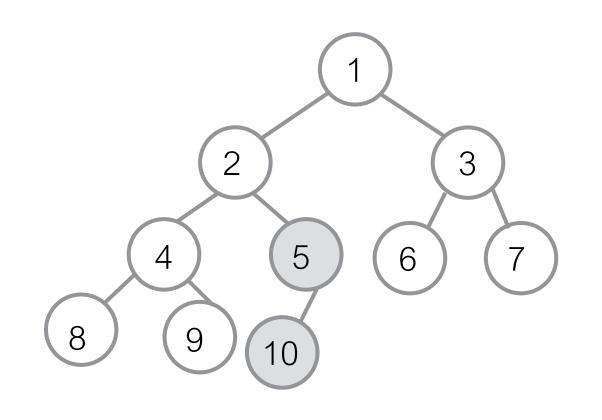
Parent Position	Child Left	Child Right
1	2	3
2	4	5
3	6	7





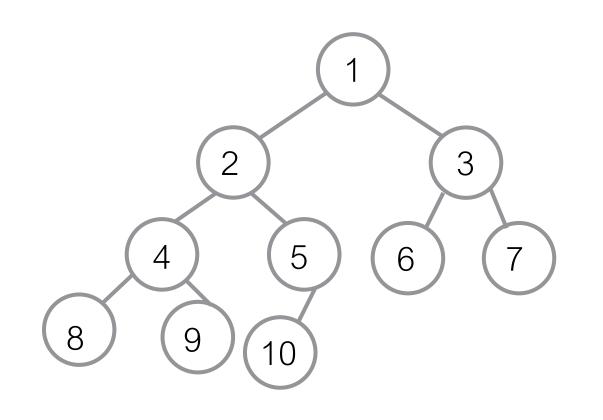
Parent Position	Child Left	Child Right
1	2	3
2	4	5
3	6	7
4	8	9



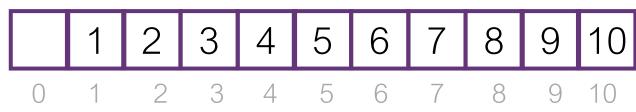


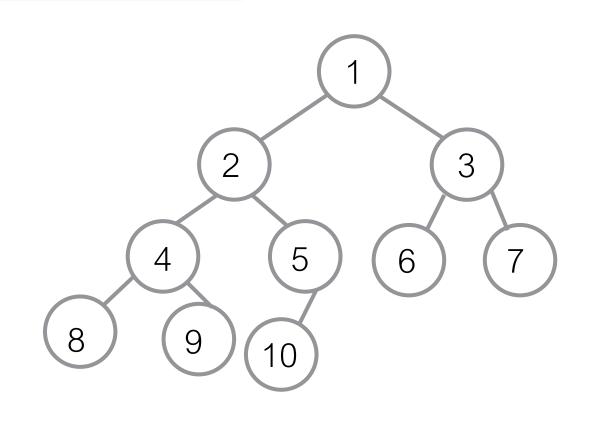
Parent Position	Child Left	Child Right
1	2	3
2	4	5
3	6	7
4	8	9
5	10	



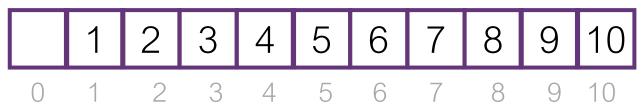


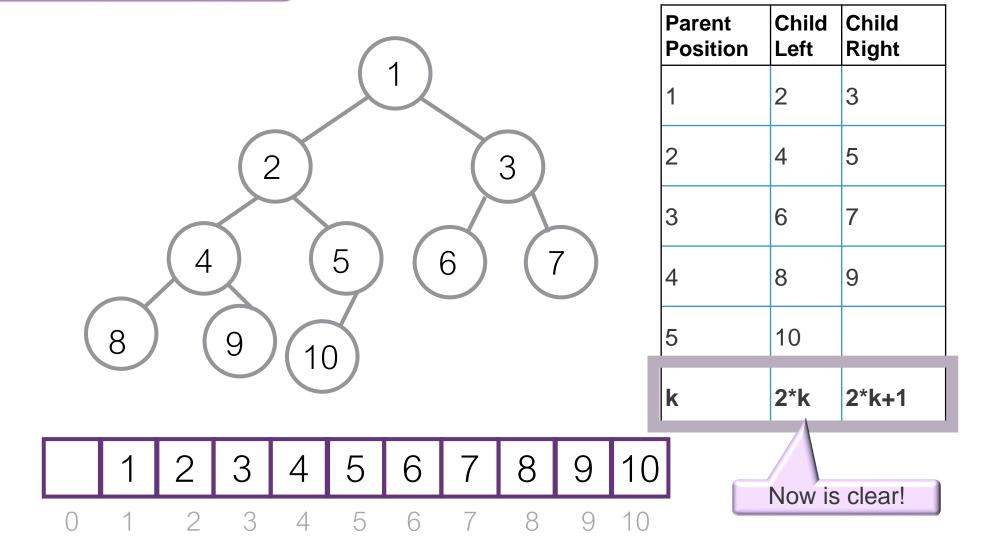
Parent Position	Child Left	Child Right
1	2	3
2	4	5
3	6	7
4	8	9
5	10	
k		





Parent Position	Child Left	Child Right
1	2	3
2	4	5
3	6	7
4	8	9
5	10	
k	2*k	



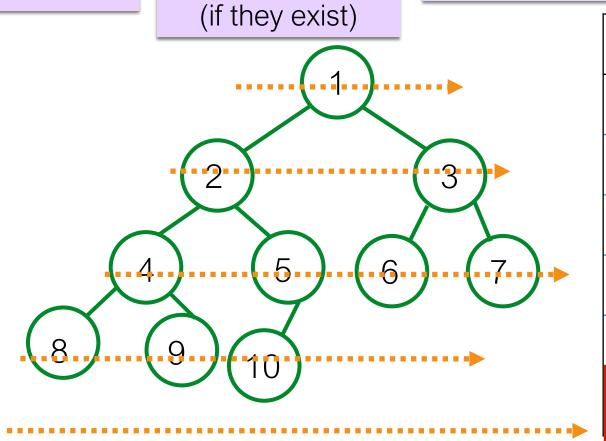


Root at position 1

## Children of k: 2\*k 2\*k+1

Parent of k: position k//2 (except for root)

9



Parent Position	Child Left	Child Right
1	2	3
2	4	5
3	6	7
4	8	9
5	10	
k	2*k	2*k+1

#### A concrete implementation

```
class Heap(Generic[T]):
    MIN_CAPACITY = 1

    def __init__(self, max_size: int) -> None:
        self.length = 0
        self.the_array = ArrayR(max(self.MIN_CAPACITY, max_capacity) + 1)

def __len__(self) -> int:
        return self.length

def is_full(self) -> bool:
        return self.length+1 == len(self.the_array)
How many items are
    stored. Points to the last
    item added (if any) - rather
    than to the first empty cell
        length that the start at 1

Indices start at 1
```

#### Note that we need an extra cell in the array

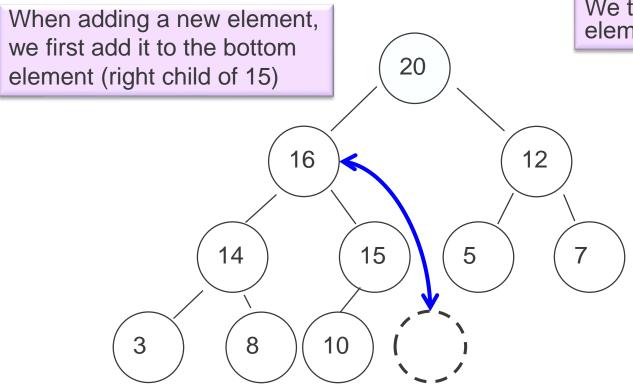
- If our heap has 10 elements, we use indices 1..10 to store them
  - Thus, we need an array of 11 cells





# Heap Implementation Add

### Recall: adding a new element (say 18)



We then need to make this element "rise" to the right place

To rise we need to compare with the parent, if any

#### Algorithm for the add operation

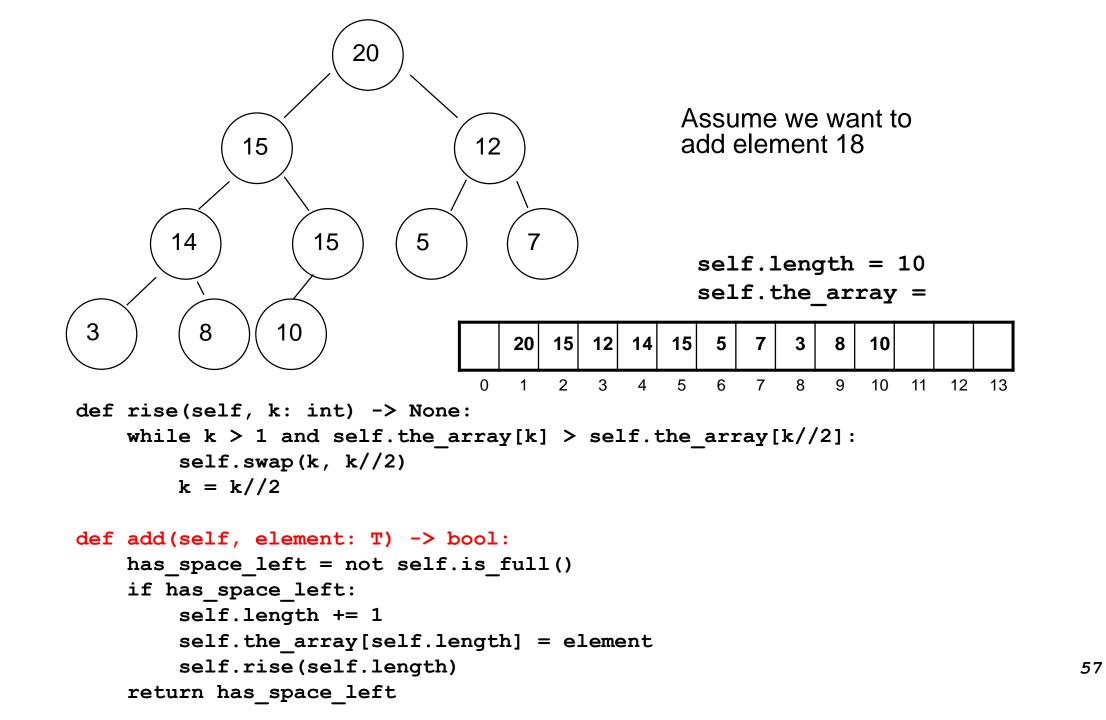
- 1. If there is no space, return False
- 2. If there is space
  - II. Put new element at the bottom of heap
  - III. While the heap-order is broken (element is smaller than its parent)
    - rise: swap new element with parent
  - IV. Return True

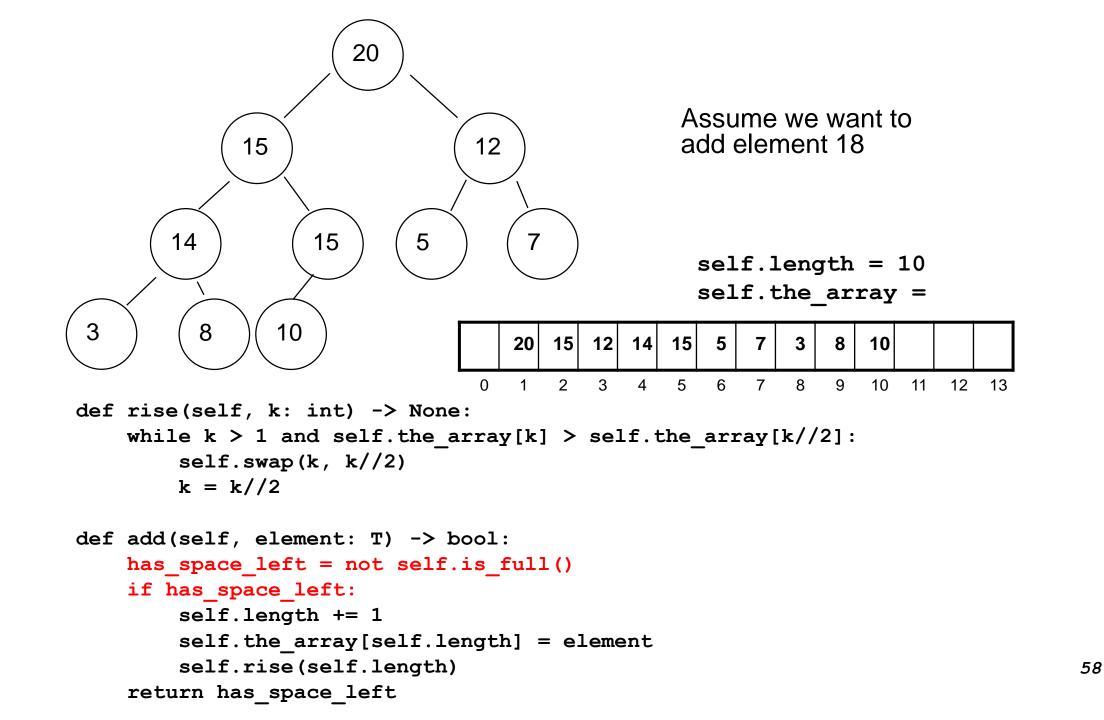
We could also have decided to resize when full and returned nothing...

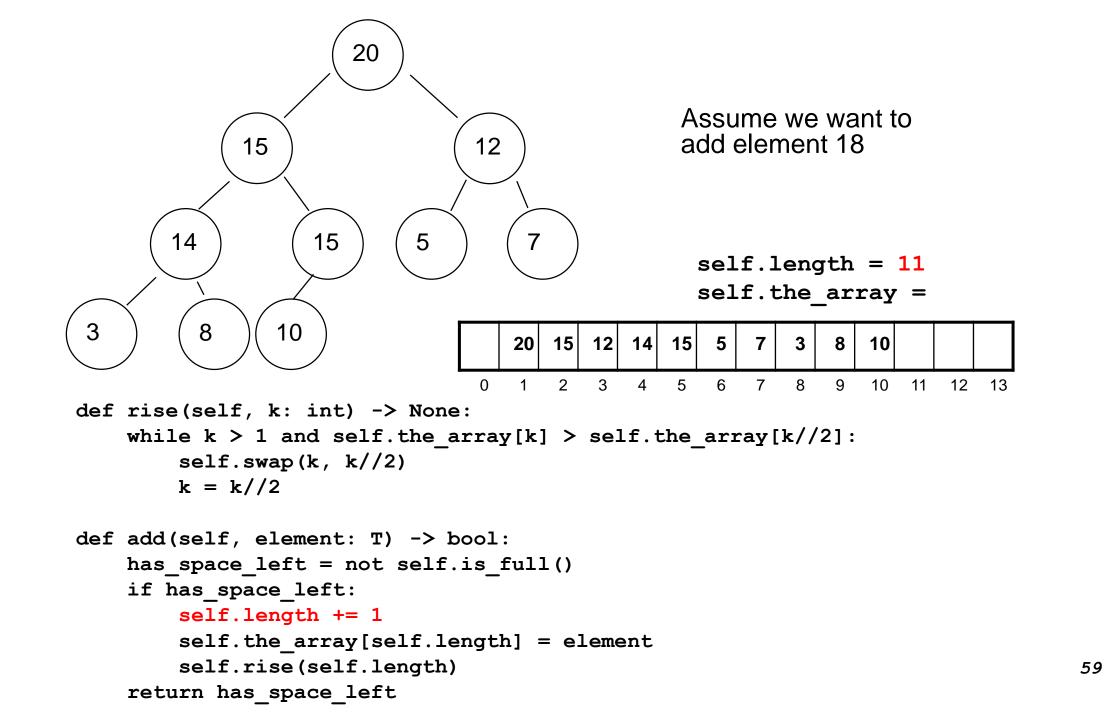
#### A concrete implementation for add

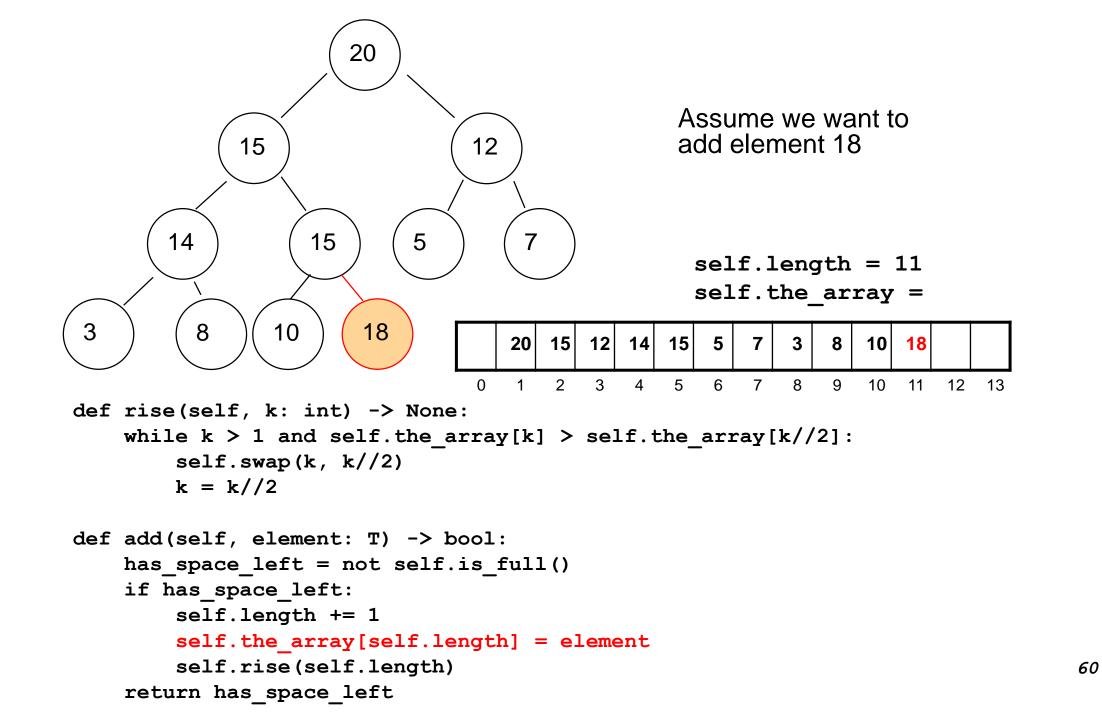
```
"""Rise element at index k to its correct position
:pre: 1<= k <= self.length"" Not enforced
                                                    k has a parent
def rise(self, k: int) -> None:
    while k > 1 and self.the array[k] > self.the array[k//2]:
        self.swap(k, k//2)
                                                           parent is smaller
        k = k//2
                                                        Remember, if k has a
def add(self, element: T) -> bool:
                                                        parent, it is found at k//2
    has space left = not self.is full()
    if has space left:
        self.length += 1
        self.the array[self.length] = element
        self.rise(self.length)
    return has space left
                                   20
                                      15
                                         12
                                           14
                                              15
                                                  5
                                                             10
```

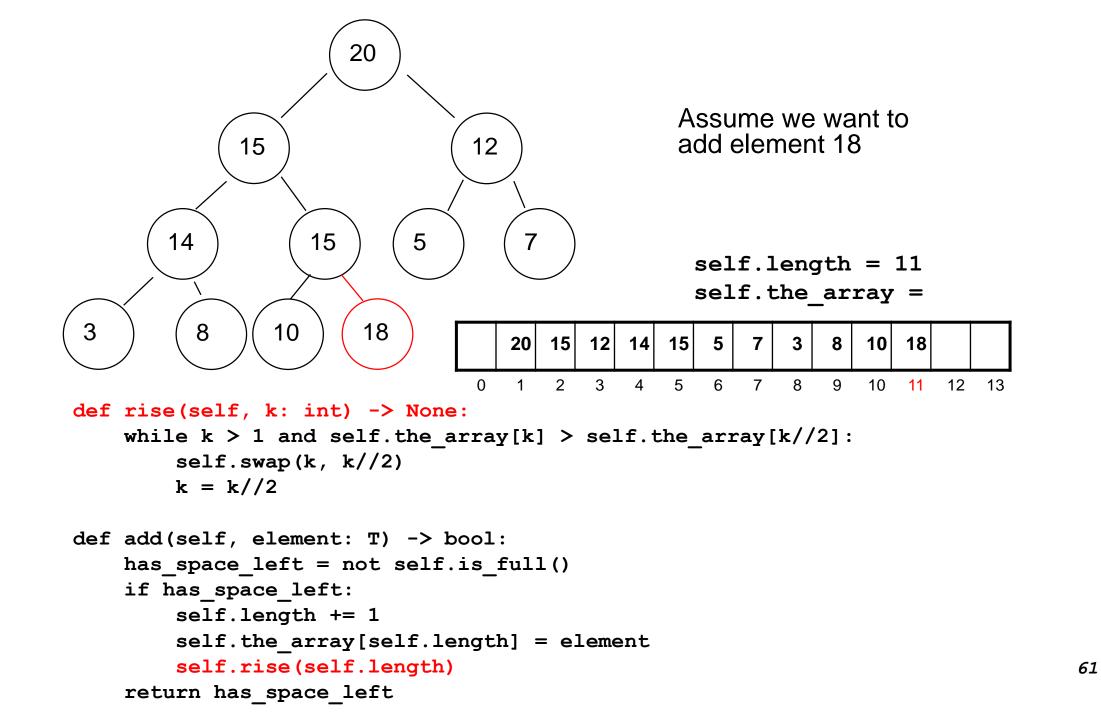


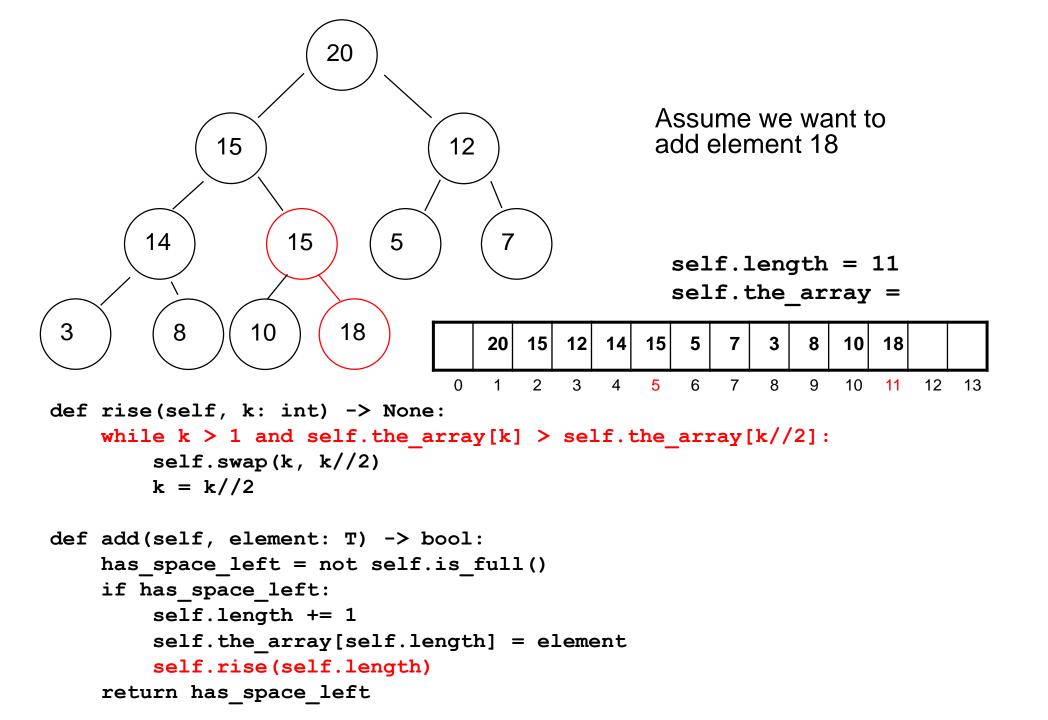


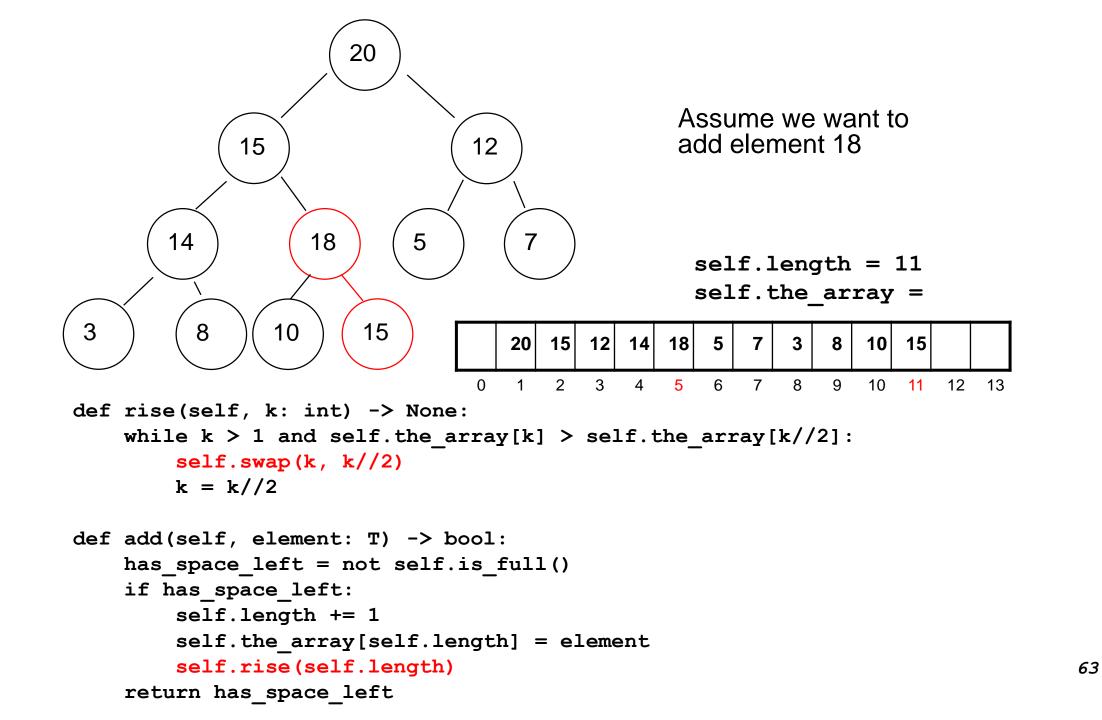


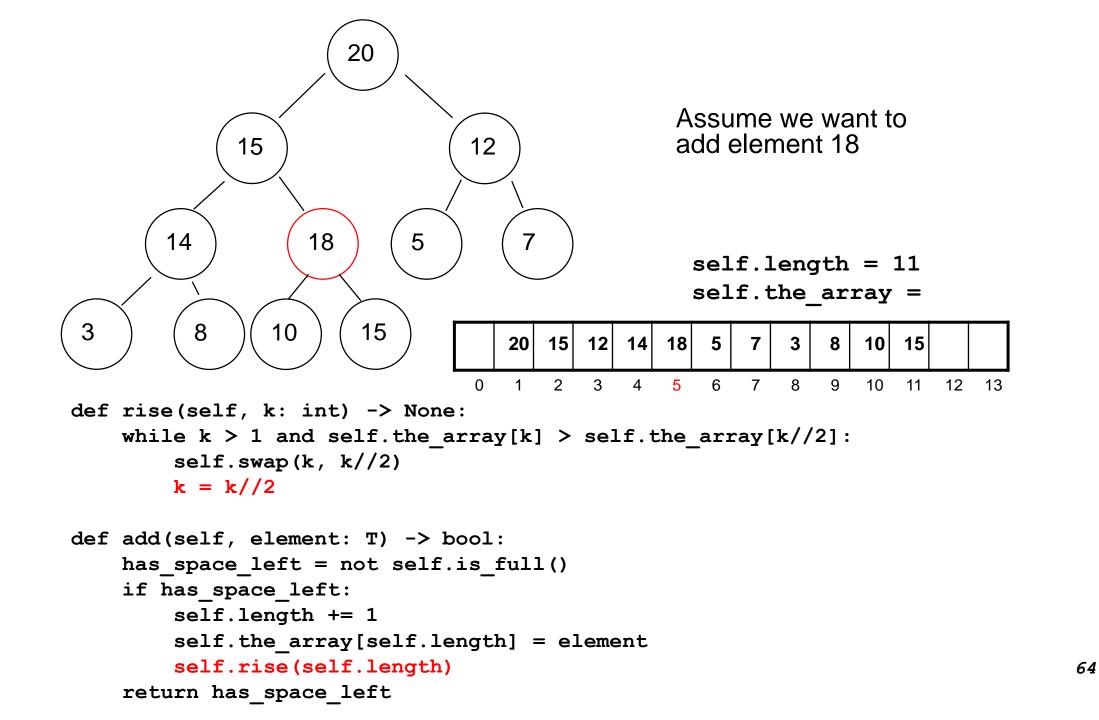


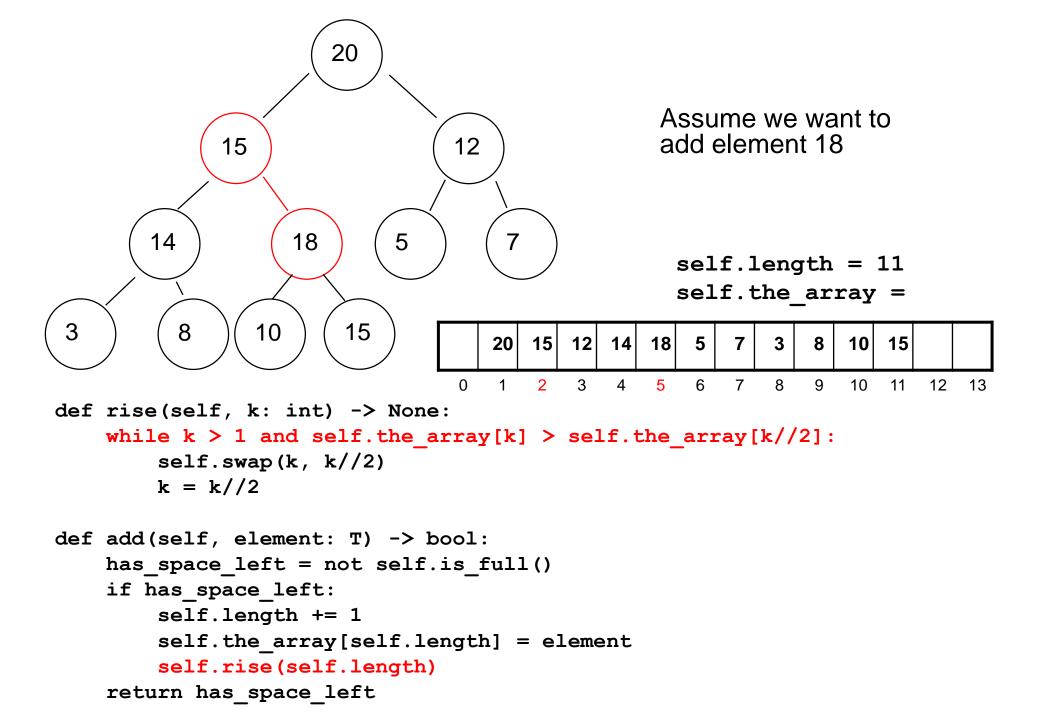


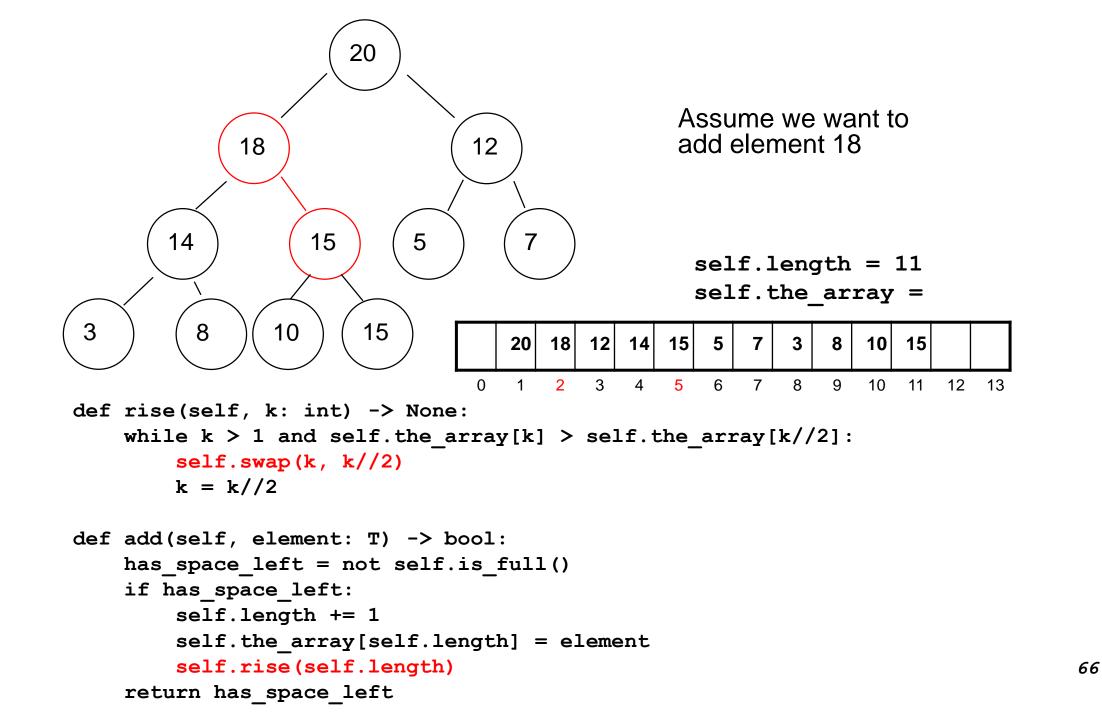


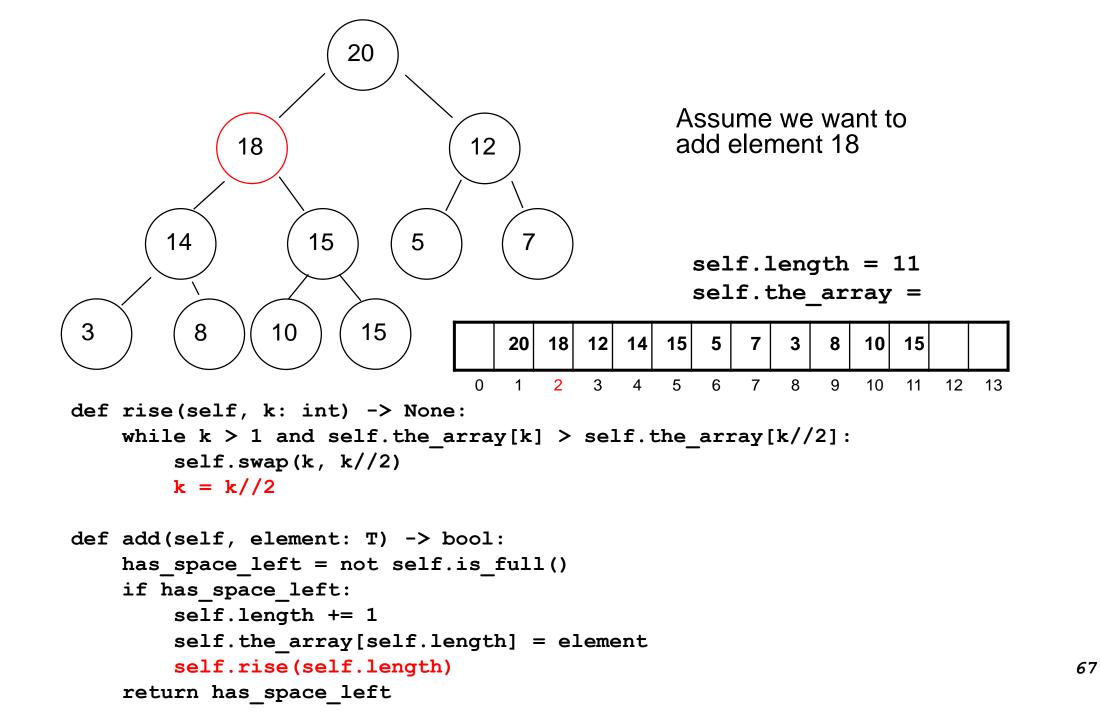


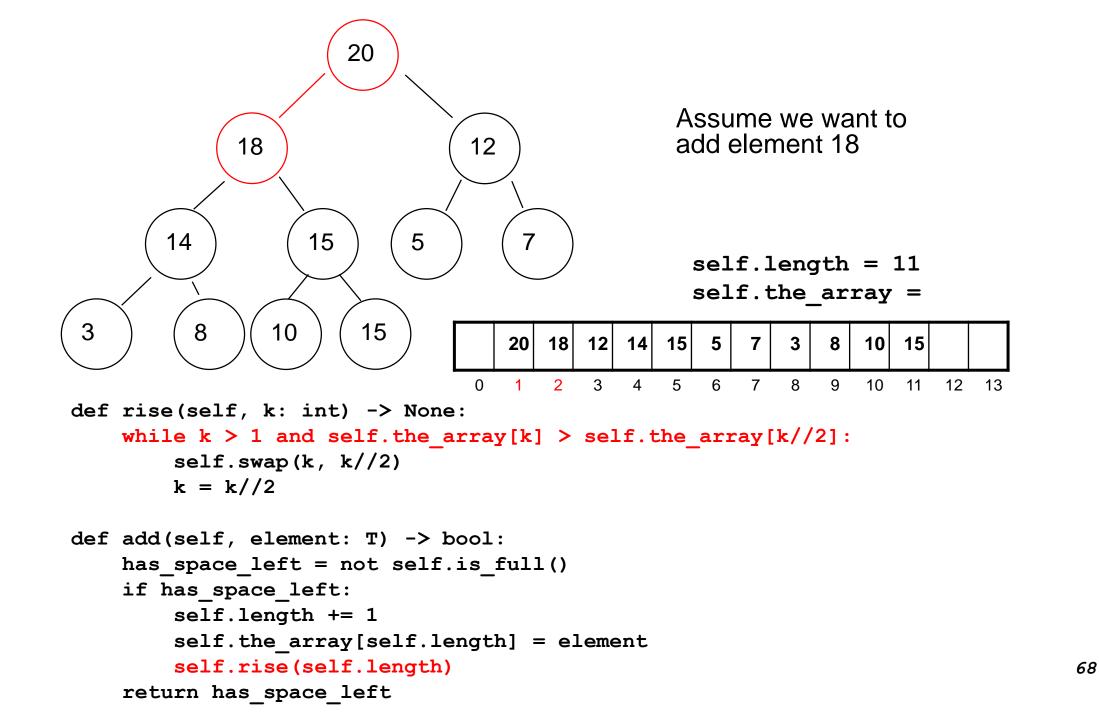


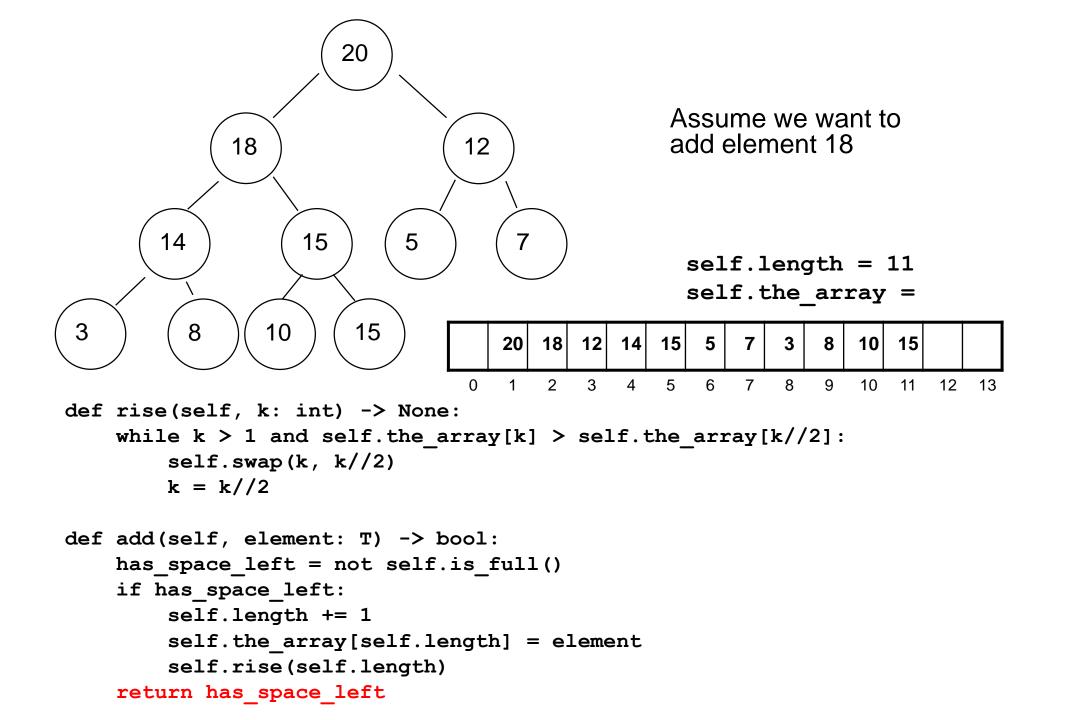












#### An alternative implementation for add

```
""" Rise element at index k to its correct position
:pre: 1<= k <= self.length """
def rise(self, k: int, element: T) -> int:
    while k > 1 and element > self.the array[k//2]:
                                                        Shuffles parents
        self.the_array[k] = self.the array[k//2]
                                                        down
        k = k//2
    return k
                                      Returns the position
                                      of the "hole"
def add(self, element: T) -> bool:
                                                                       This is faster,
    has space left = not self.is full()
                                                                        but less clear
    if has space left:
        self.length += 1
        self.the array[self.rise(self.length, element)] = element
    return has space left
```



No swaps, just shuffles parents down to make a hole for the new element, and then put it in the hole

#### Another alternative for add

```
def add(self, element: T) -> bool:
    has space left = not self.is full()
    if has space left:
        self.length += 1
        k = self.length
        while k > 1 and element > self.the array[k//2]:
           self.the array[k] = self.the array[k//2]
           k = k//2
        self.the array[k] = element
    return has space left
```

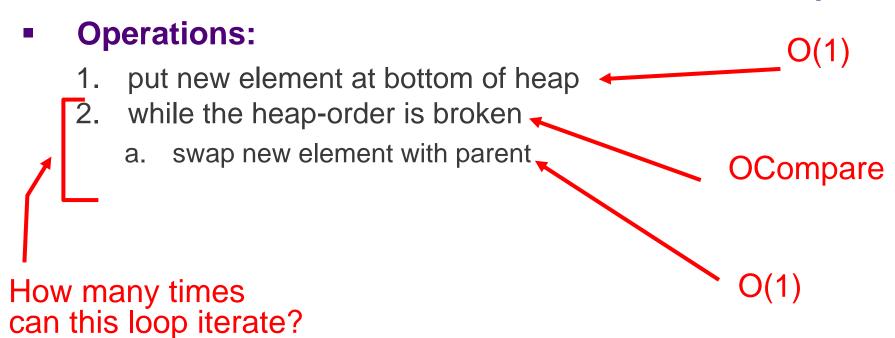
If we eliminate the modularisation (i.e., call to rise)

This version is the fastest, but least maintainable

Eliminating rise is not a good idea: what if the priority of a node has a sudden increase?

#### Complexity of add

Start with the first version and assume there is space



### Complexity of add

Is the depth of a heap always ≈ log N?

#### ■ Loop 2 can iterate at most Depth times ≈ log N

Yes! As it is complete

- after Depth iterations, the new element is at the root
- Best case:
  - O(1) + OCompare when the element is smaller or equal than its parent, which means OCompare.

#### Worst case:

 O(1) + O(logN)\*O(1)\*OCompare when the element rises all the way to the top, which means O(logN)\*OCompare

#### Same for all versions?

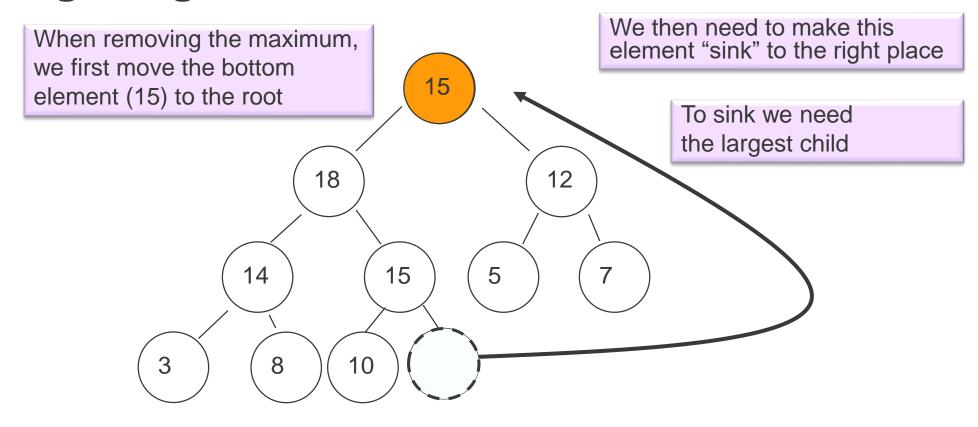
Yes: some do less copies (less swaps), but have the same O(1)





# Heap Implementation Get max

### Recall: getting the max element





## Algorithm for get\_max

- 1. swap root element with bottom-right element
- 2. remove that element
- 3. while the heap-order is broken
  - sink: swap the out-of-place element with its largest child

#### A concrete implementation

```
""" Returns the index of the largest child of k.
pre: 2*k <= self.length (at least one child)</pre>
                                                         Left greater than right
def largest child(self, k: int) -> int:
    if self.the array[2*k] > self.the array[2*k+1]:
        return 2*k
                                                      Somewhere in here
    else:
                                                      lies a subtle error
        return 2*k+1
""" Make the element at index k sink to the correct position.
def sink(self, k: int) -> None:
                                                k has at least one child
    while 2*k <= self.length:
        child = self.largest child(k)
        if self.the array[k] >= self.the array[child]:
            break
                                        Element >= than its largest child
        self.swap(child,k)
        k = child
```

#### **Correct version**

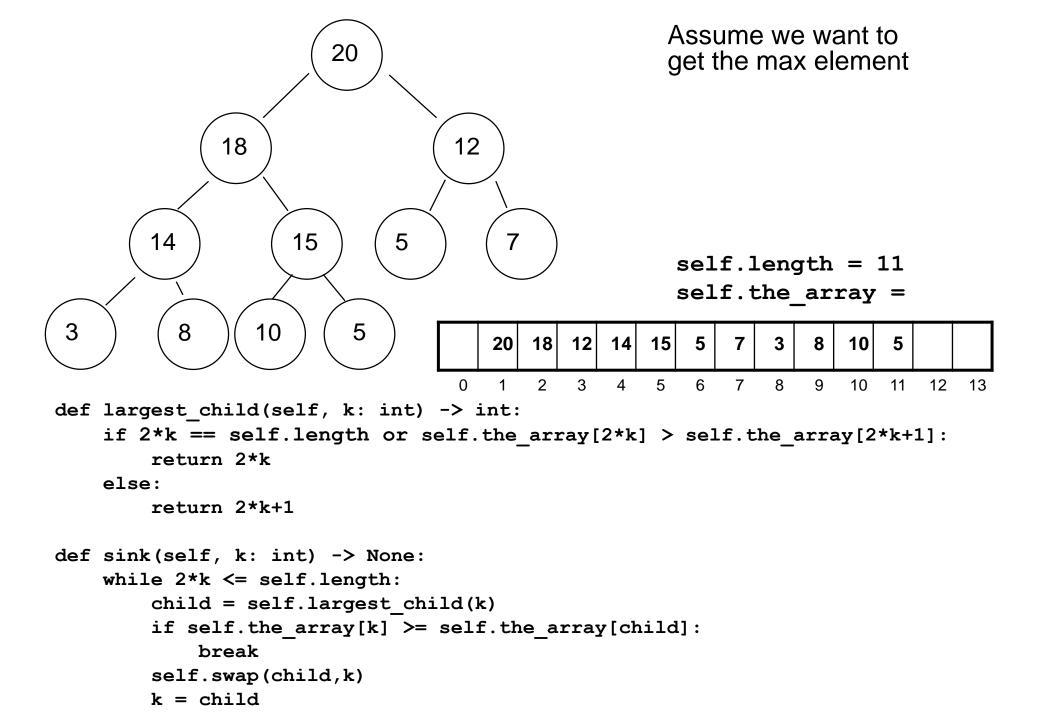
```
def largest_child(self, k: int) -> int:
    """ Check also for k having only one child. """
    if 2*k == self.length or
        self.the_array[2*k]> self.the_array[2*k+1]:
        return 2*k
    else:
        return 2*k+1
```

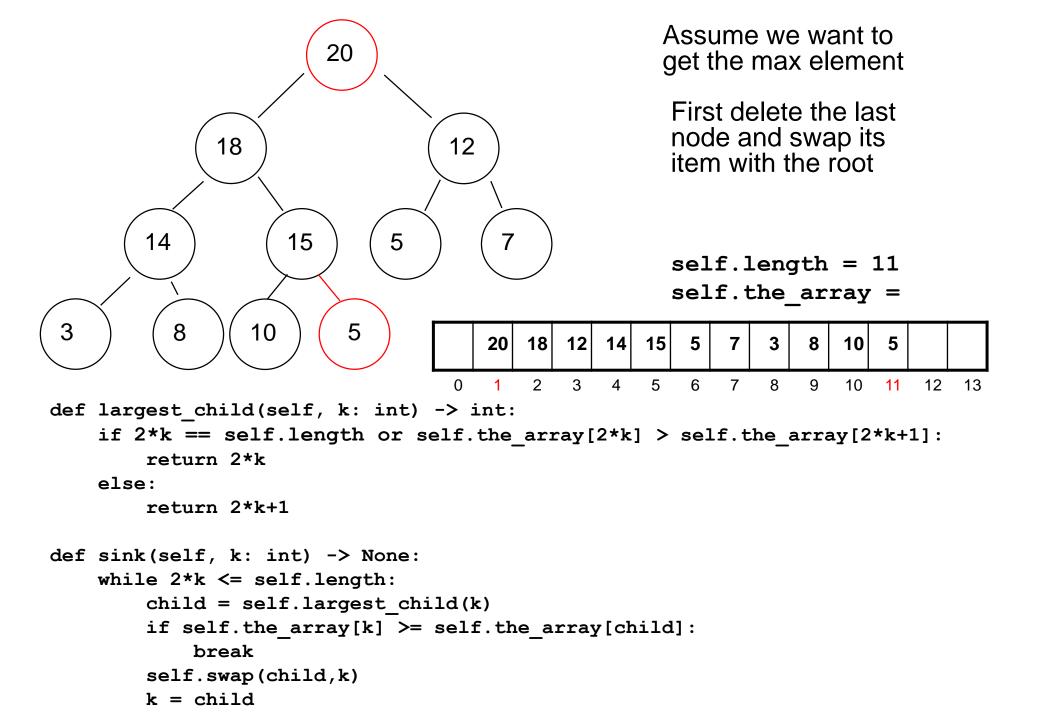


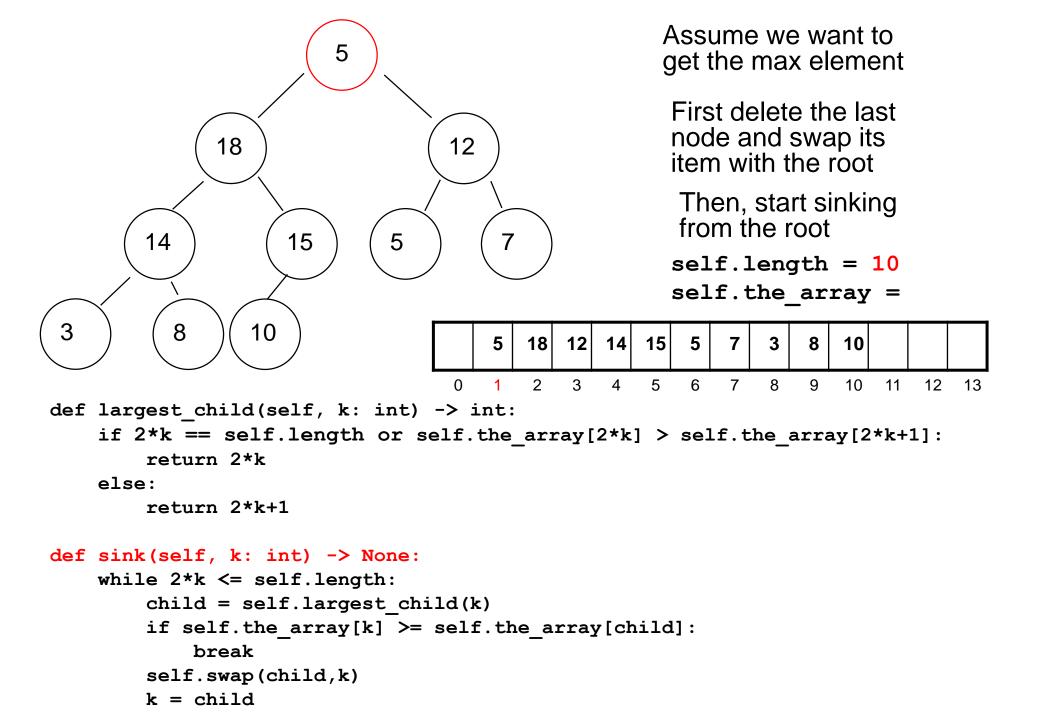
#### Aside: subtle errors

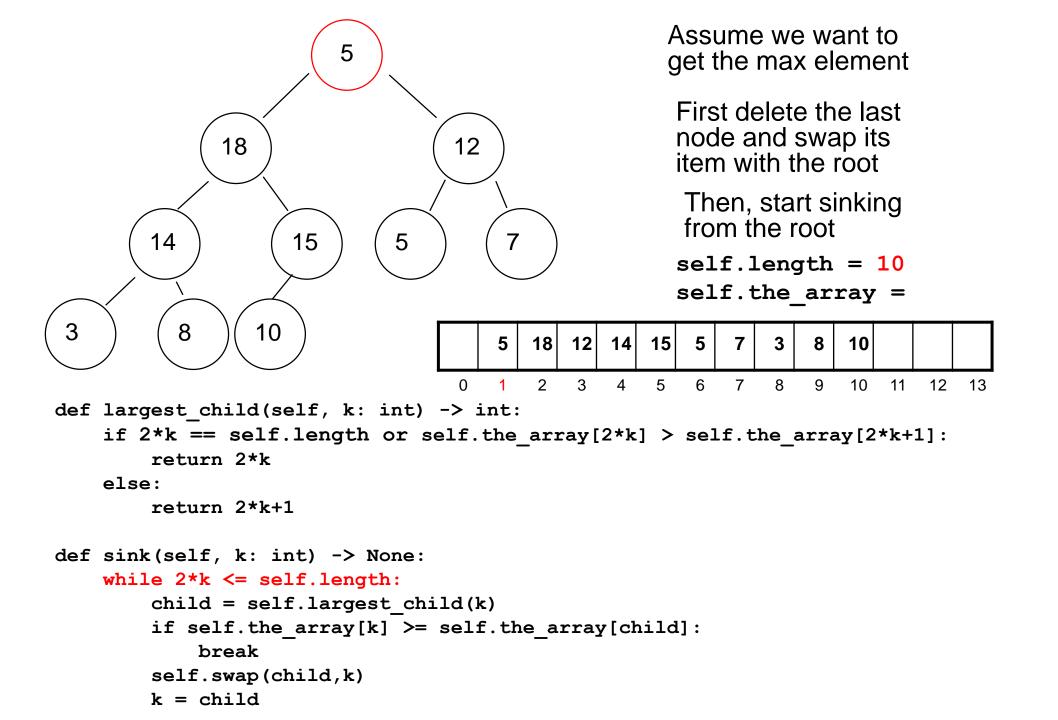
- Errors like that are very easy to make, and hard to spot.
- Your armoury against them includes:
  - Thorough testing
  - Code review
  - Proofs of correctness

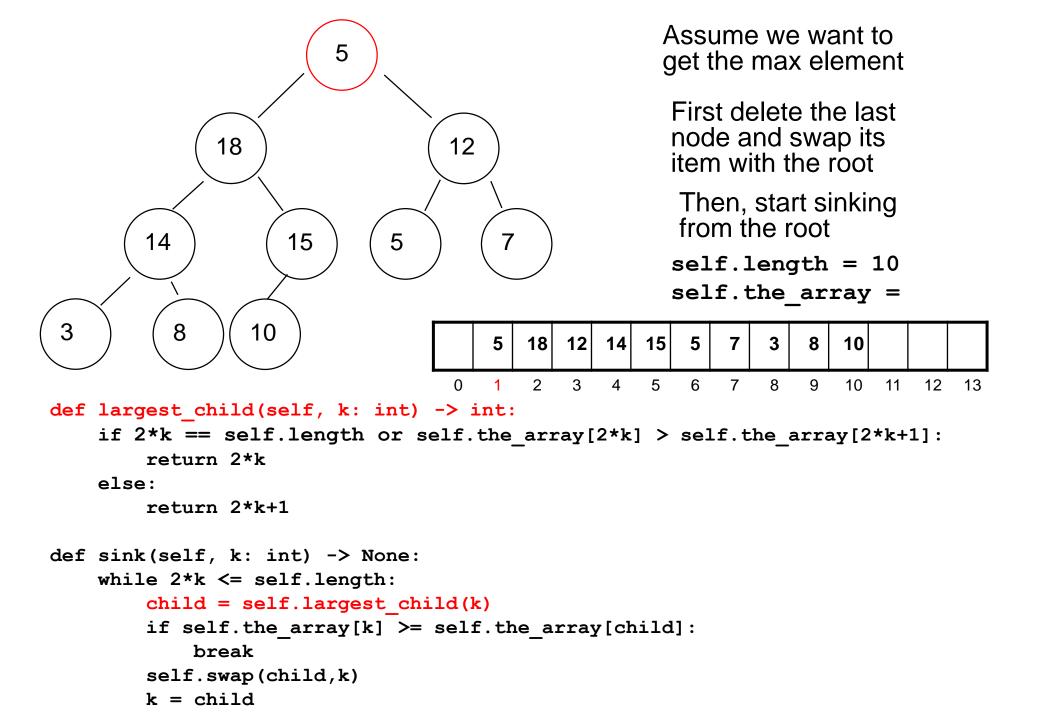


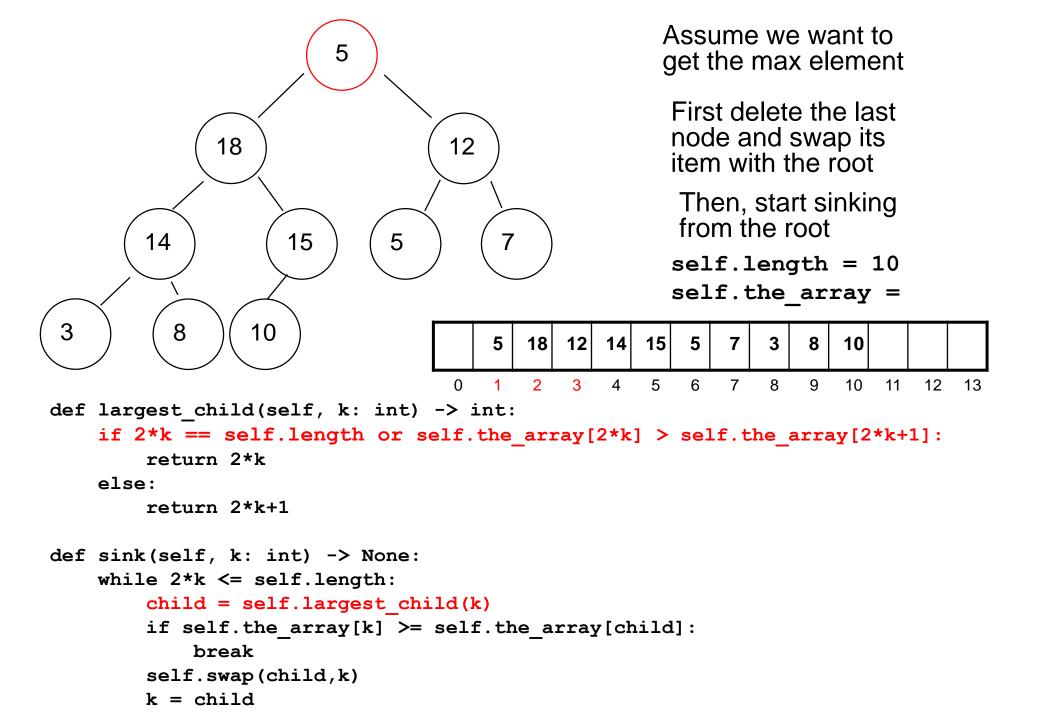


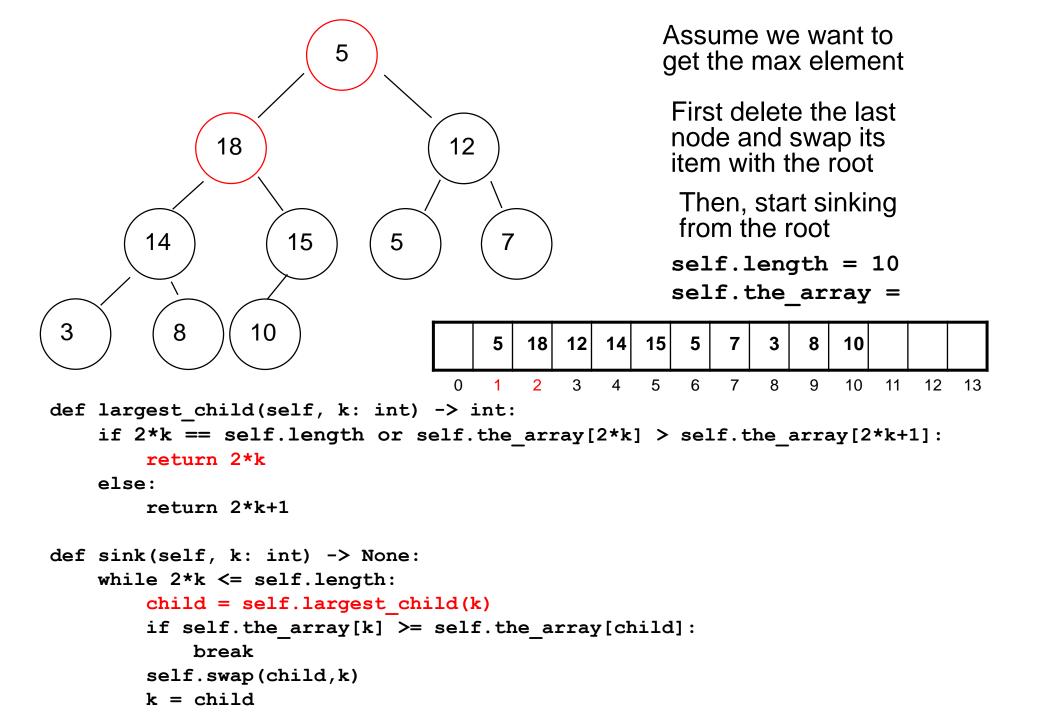


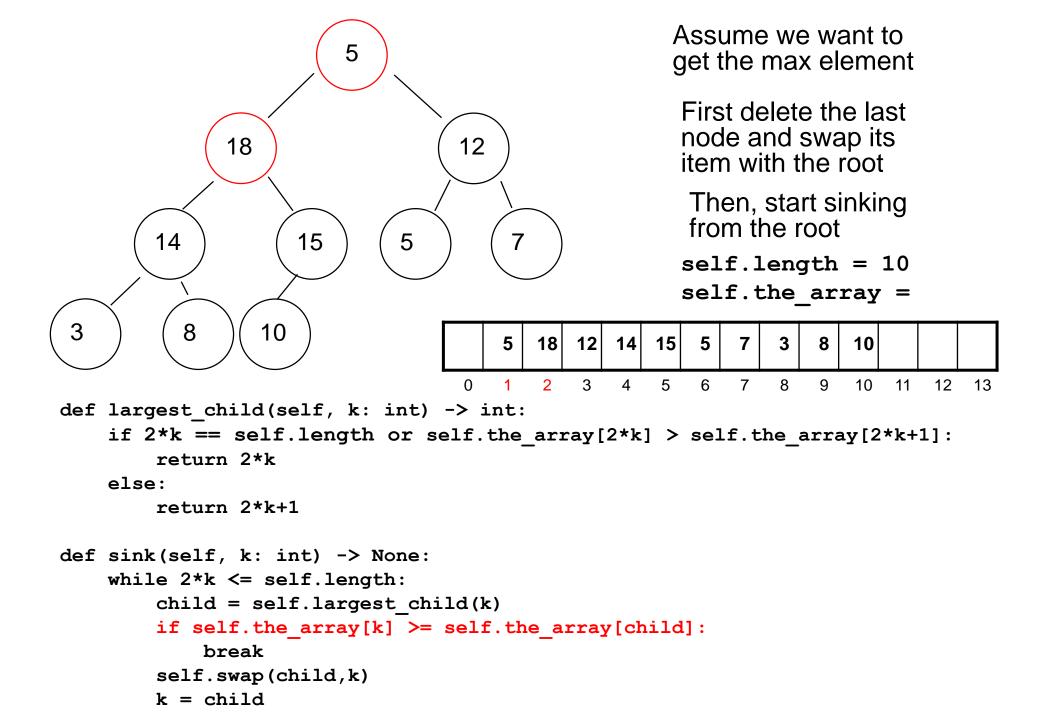


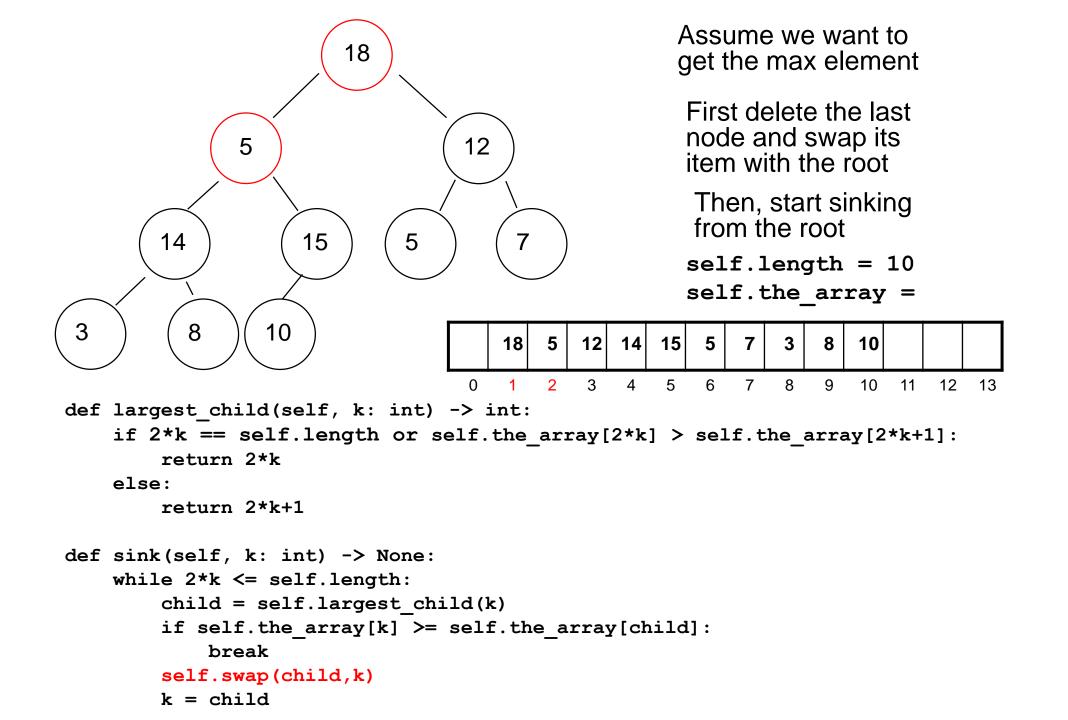


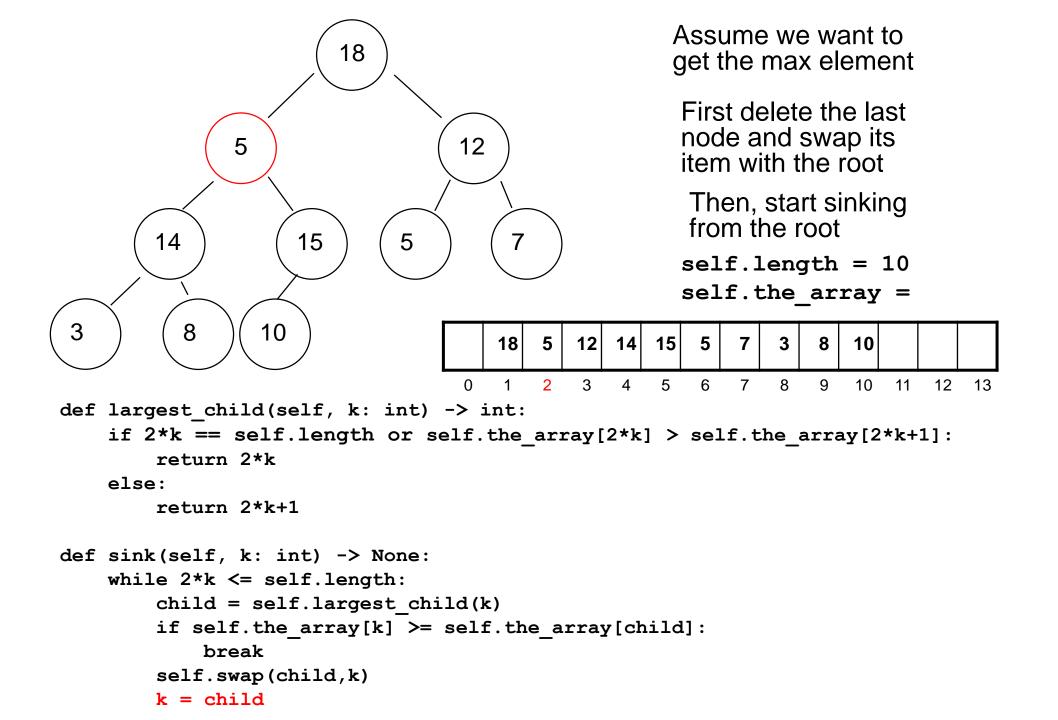


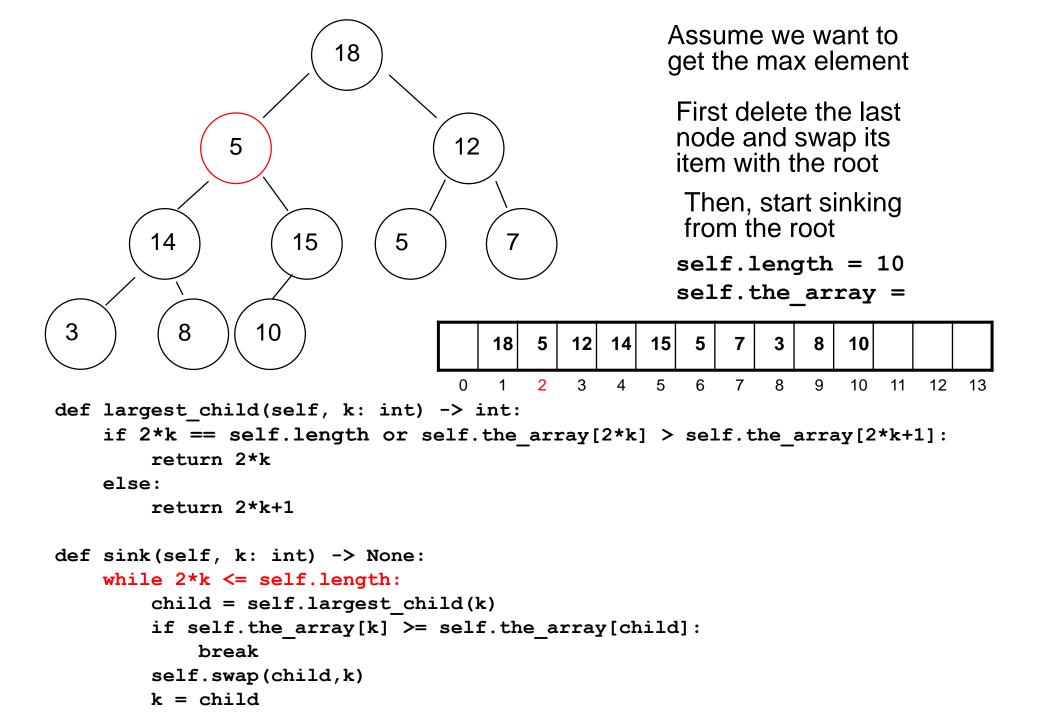


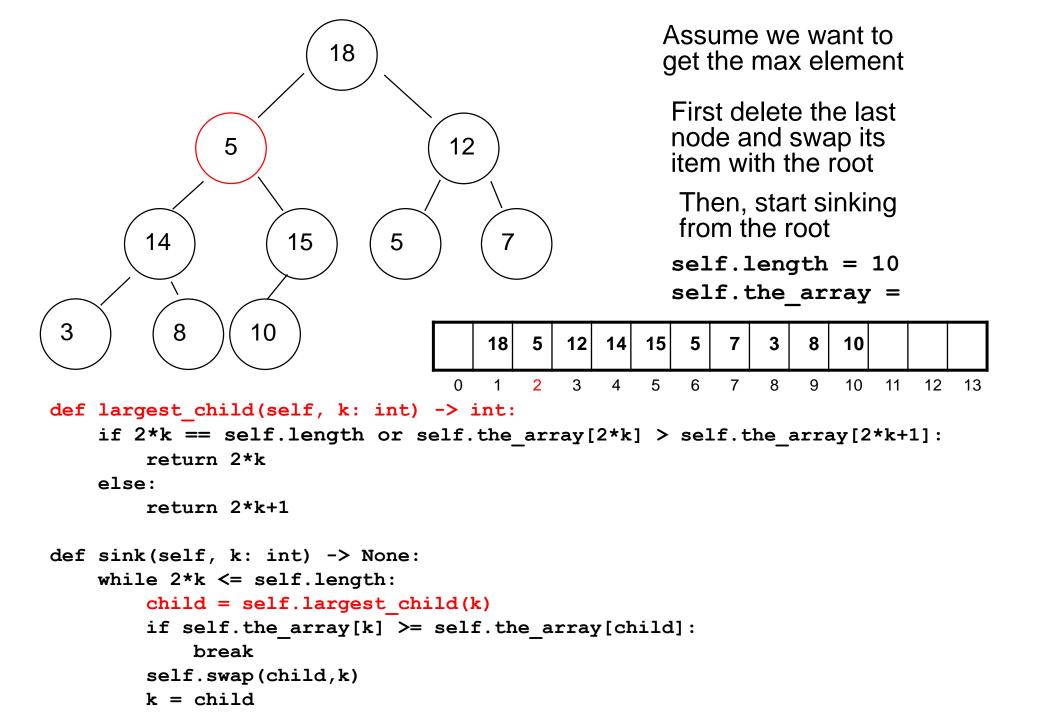


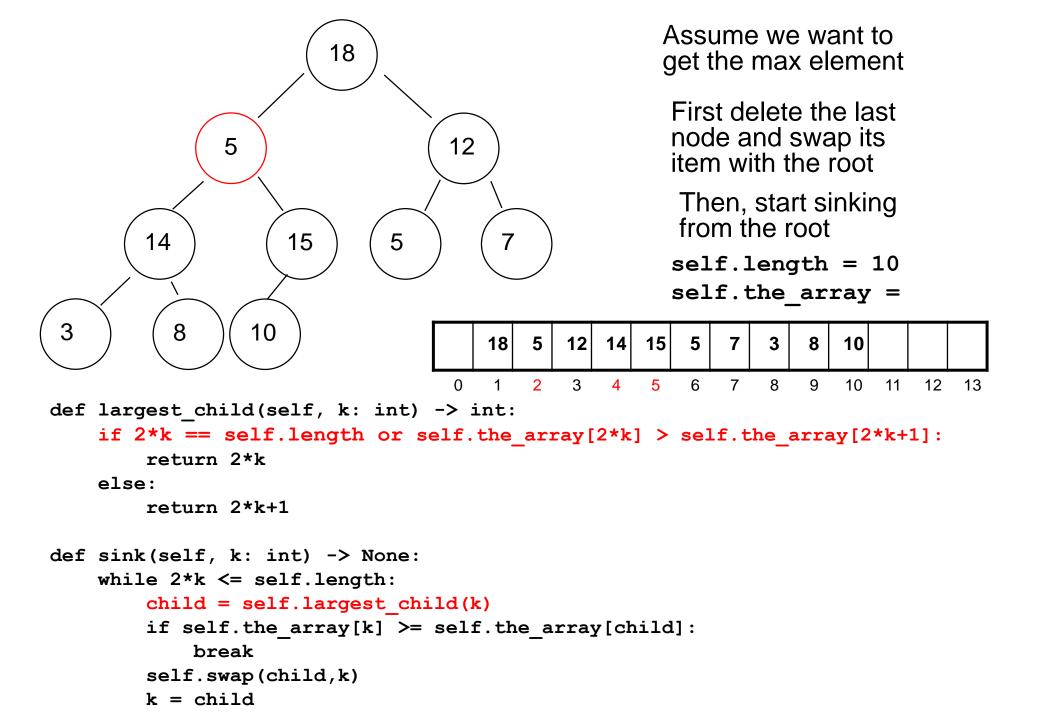


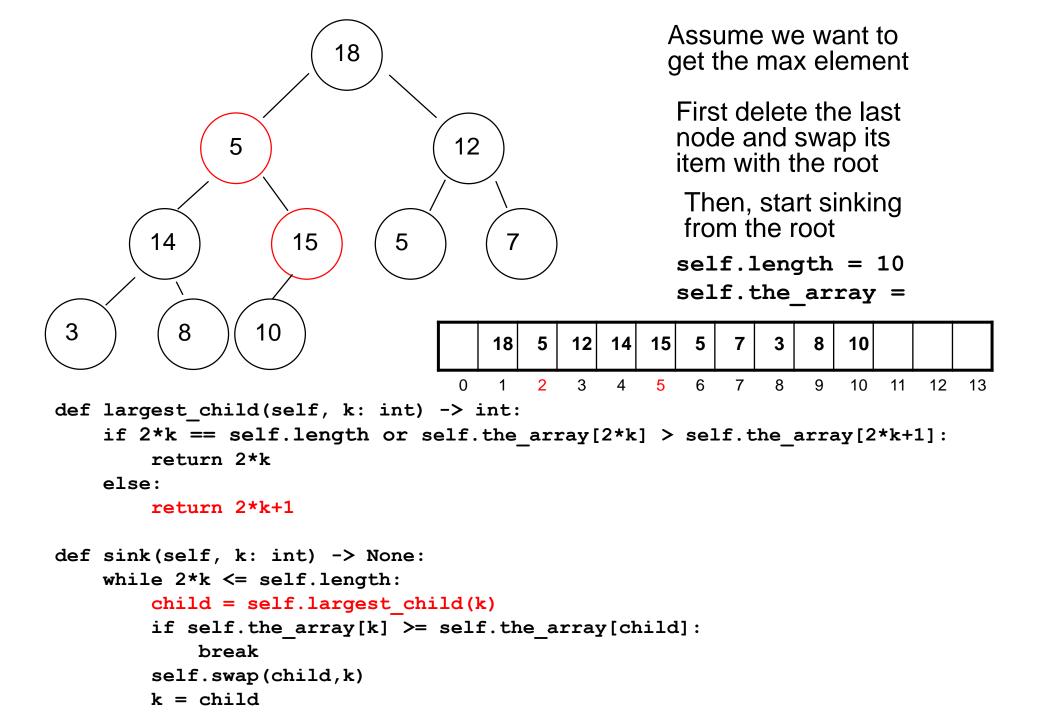


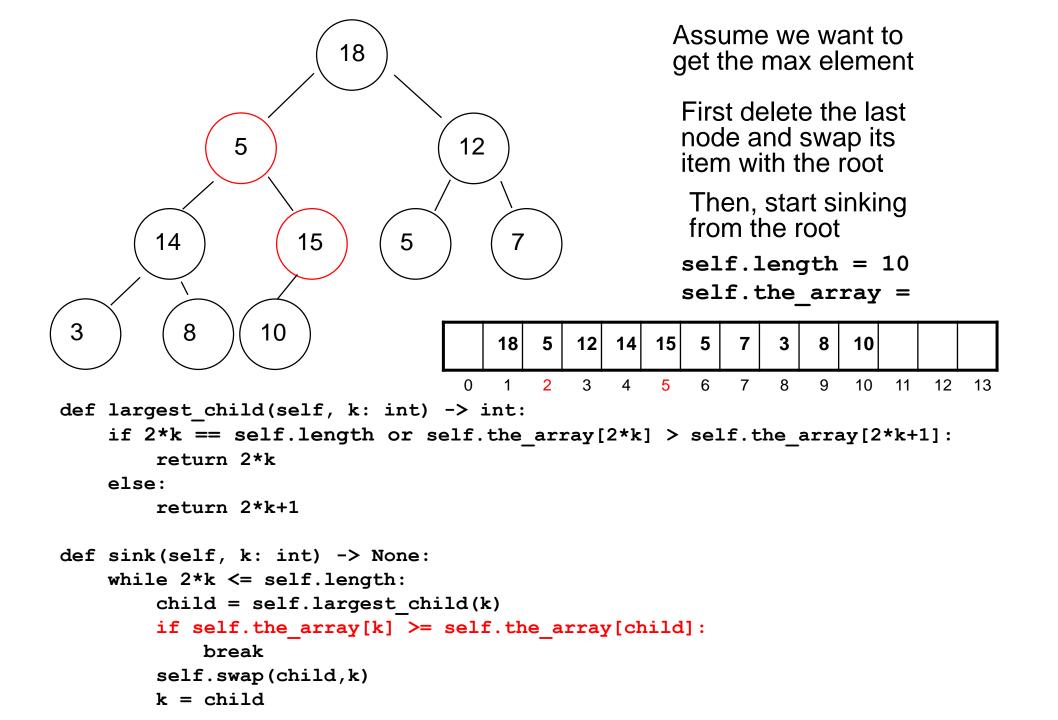


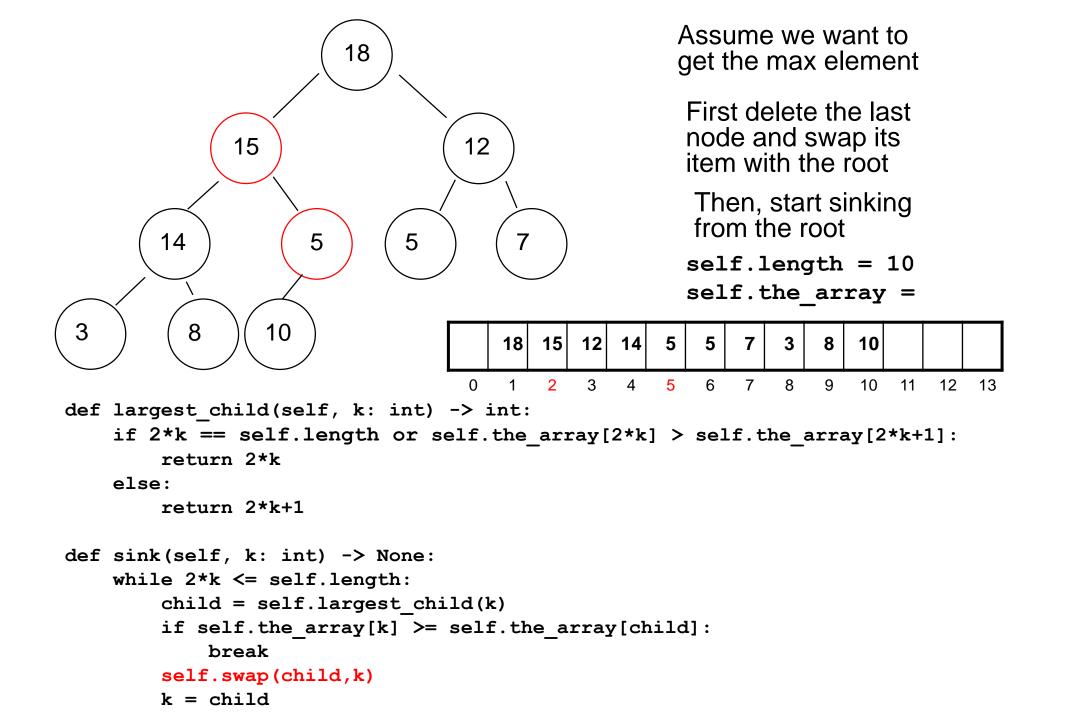


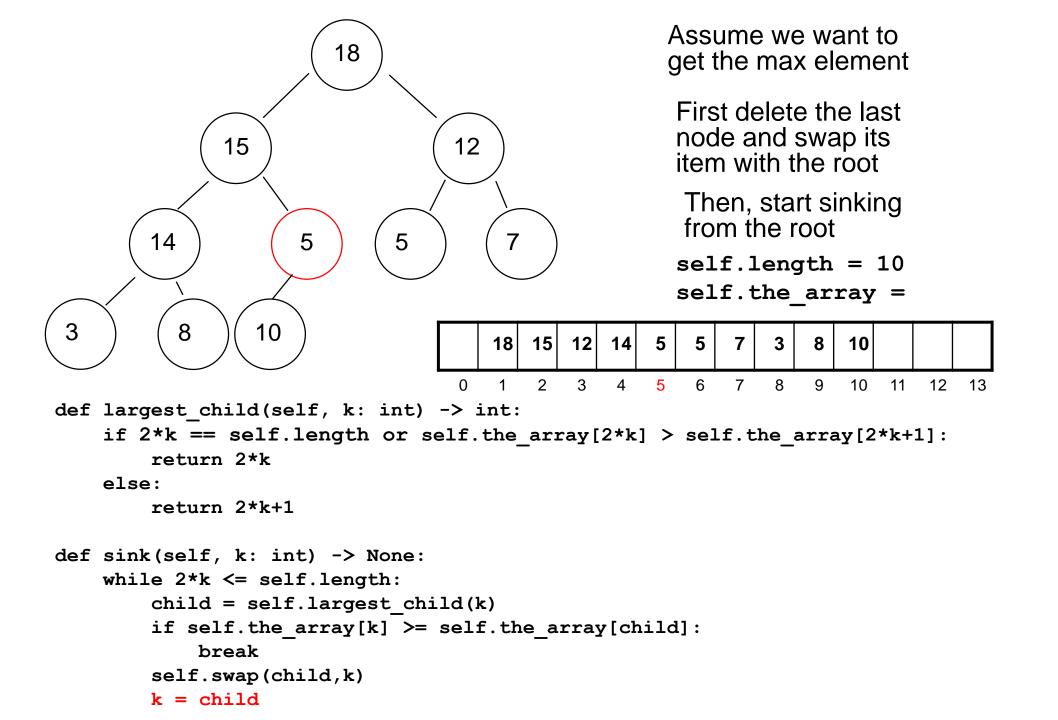


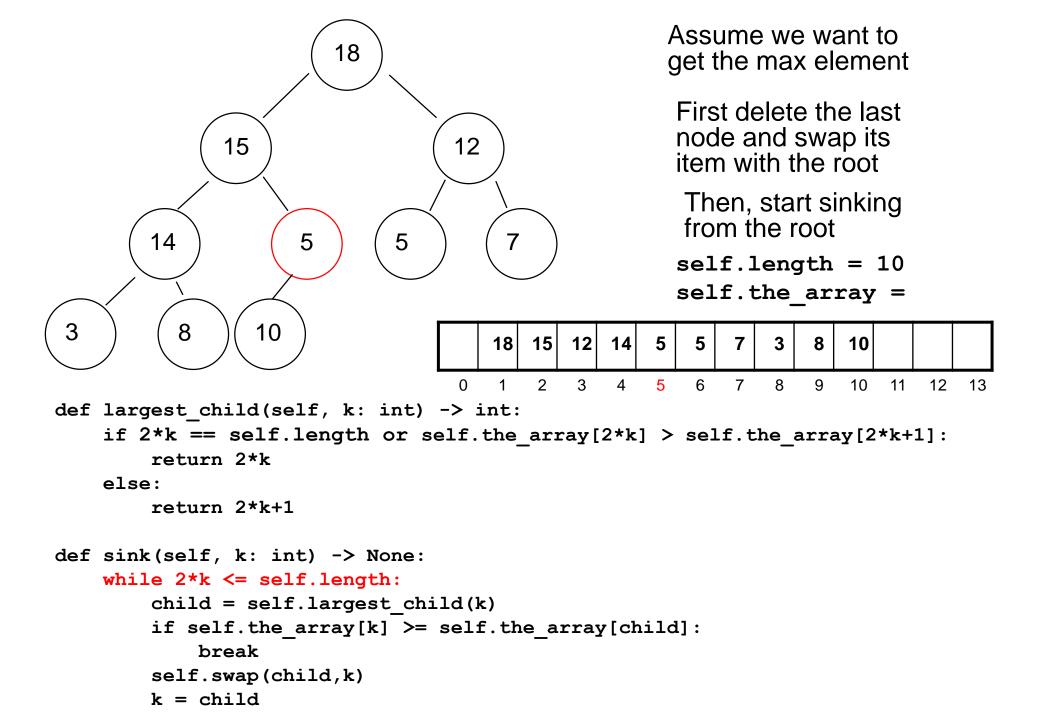


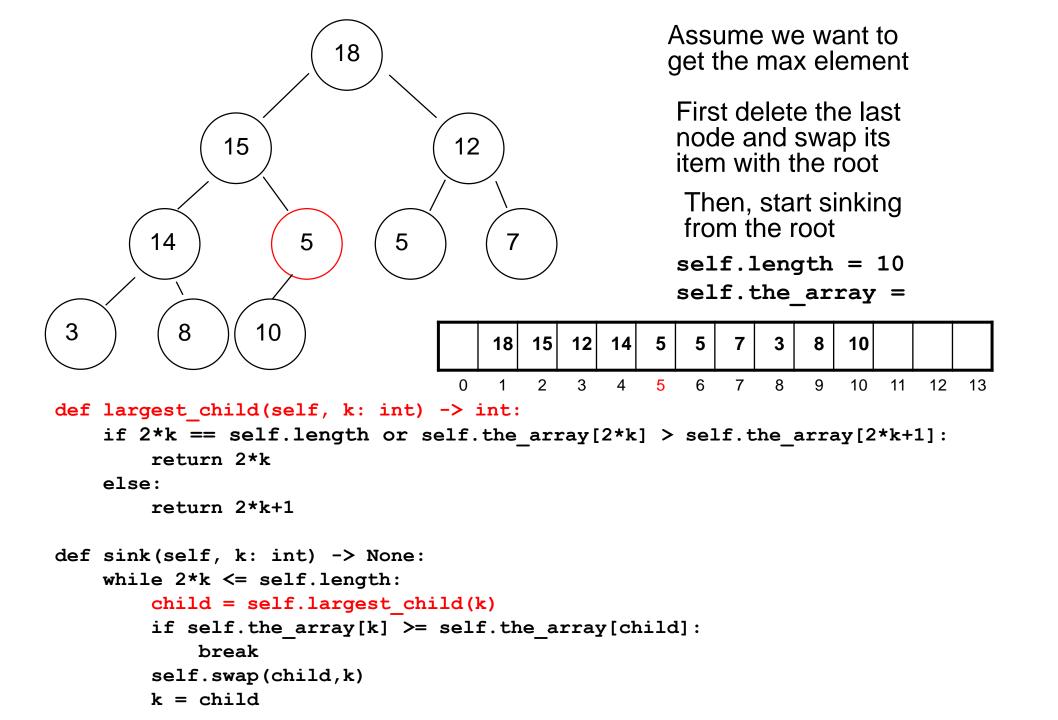


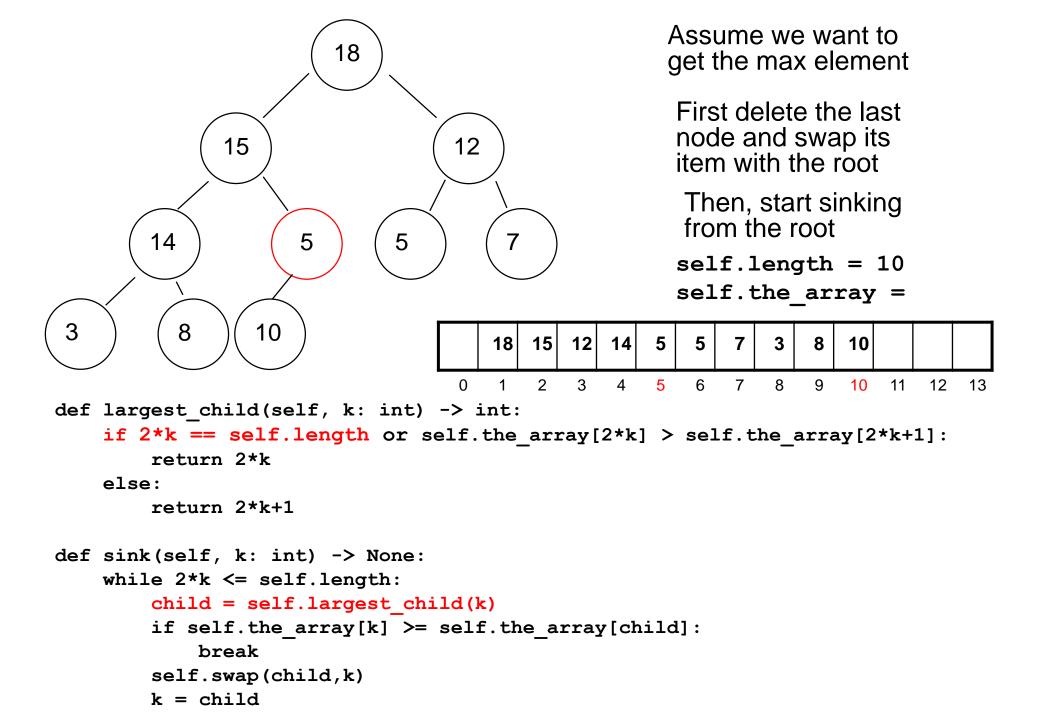


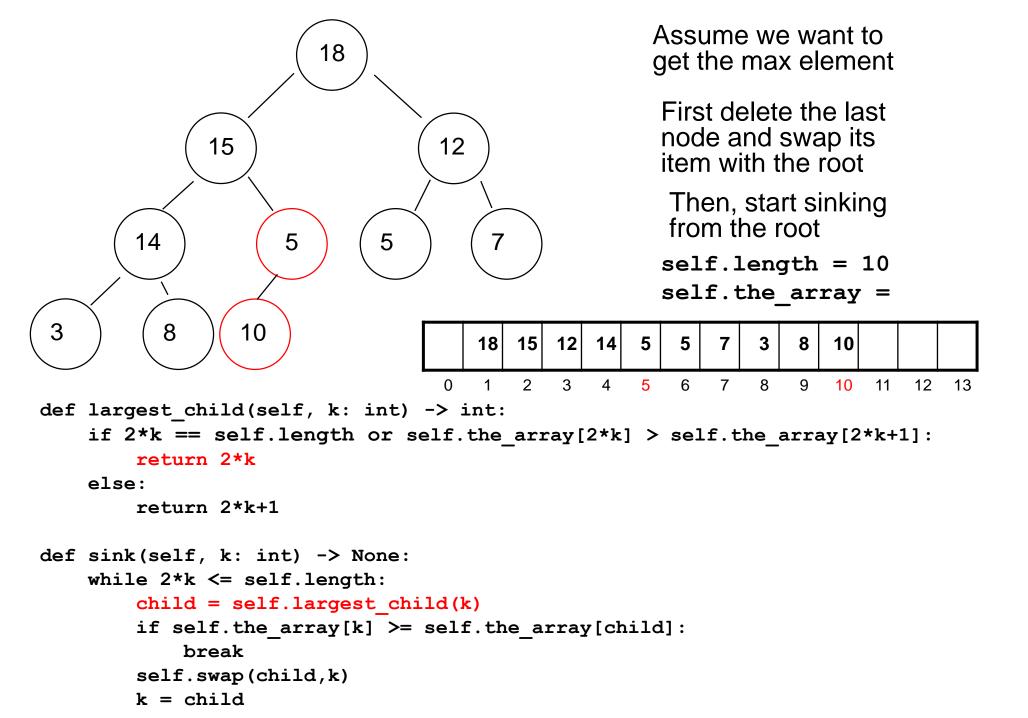


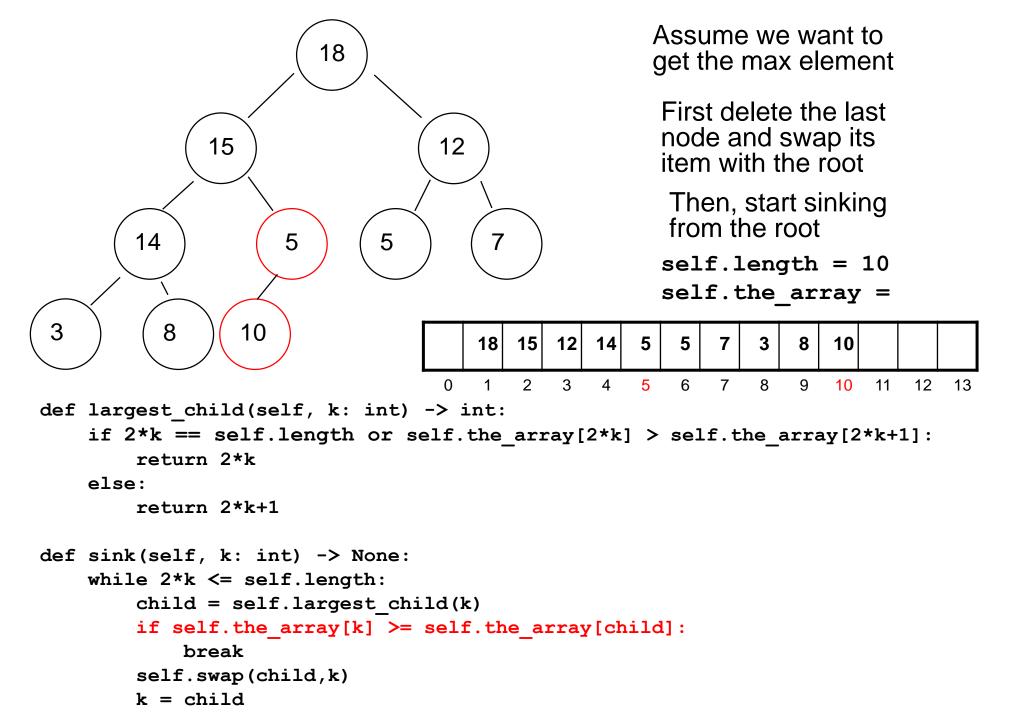


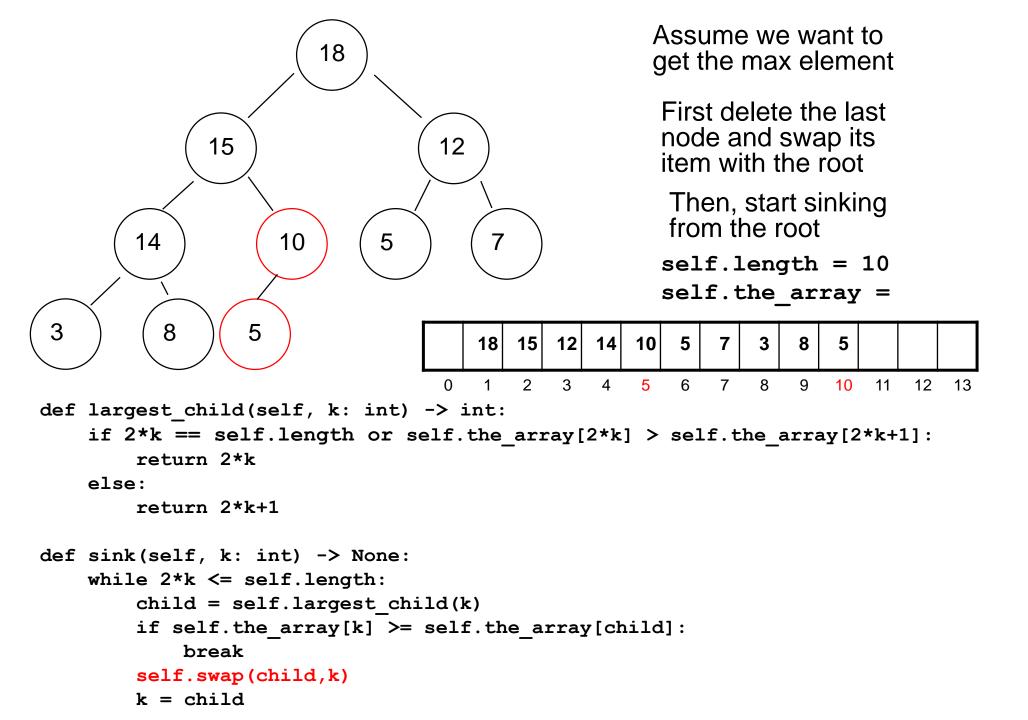


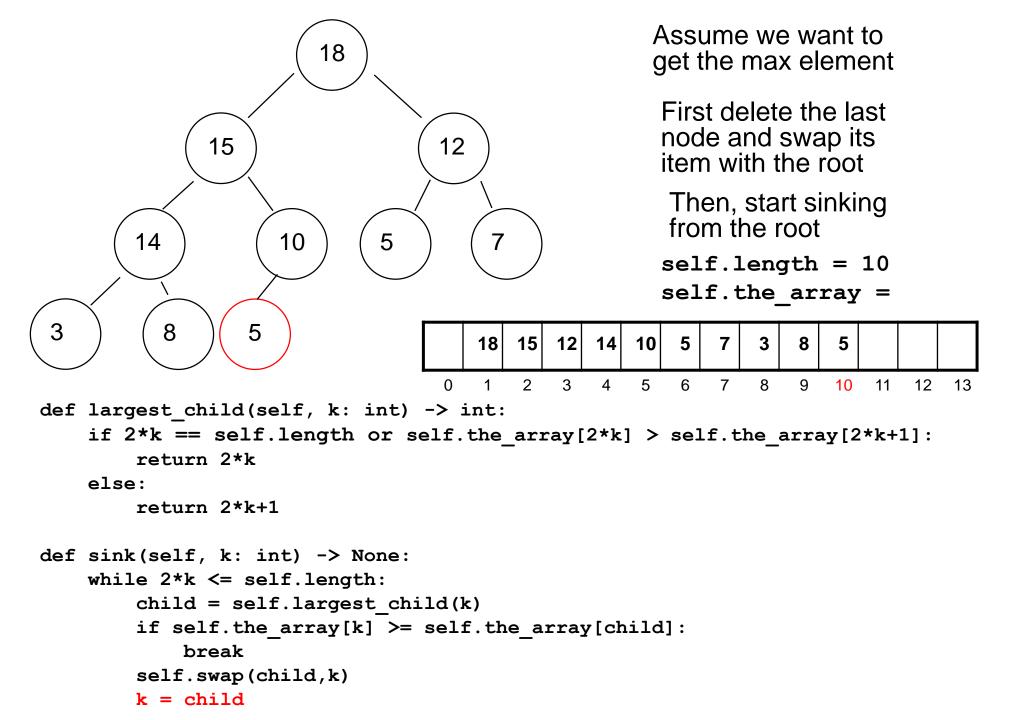


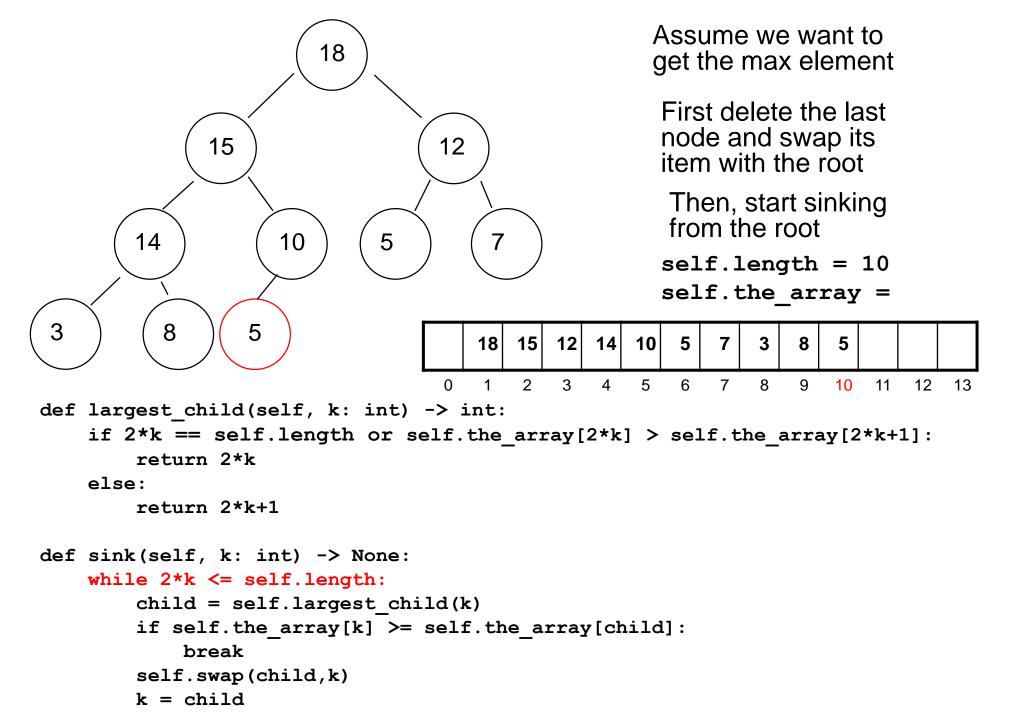












## Complexity of getMax

1. swap root element with bottom-right element
2. remove that element
3. while the heap-order is broken
a. swap the out-of-place element with its largest child

How many times can this loop iterate?

### Complexity of get\_max

- Loop 3 can iterate only Depth times ≈ log N
  - After Depth iterations, the new element is at the bottom of the tree
- Best case:
  - O(1) + O(1) + OCompare when the element is greater or equal to one of its children (cannot be smaller), which means OCompare
- Worst case:
  - O(1)+O(1) +O(logN)\*O(1)\*OCompare when the element sinks all the way to the bottom, which means O(logN)\*OCompare

Thus, both add and get\_max are O(log N)\*Ocompare. Better than O(N) – which was the case for lists…



# **Priority Queue Sort**

#### An application of Heaps: "PQueue-sort"

- Remember:
  - We are using Heaps to implement Priority Queues
- With a fast get\_max we can also sort any list quickly
  - 1. Put all elements into a p-queue
  - 2. Call get max *n* times
- Gives all the elements in descending order
- Possible for any Priority Queue implementation
  - BUT only worth it if it is fast



### "PQueue-sort" properties for a heap impl.

- Step 1: N add operations to the queue
  - For a heap: O(N\*logN) (\*comparisons)
- Step 2: N get max operations
  - For a heap: O(N\*logN) (\*comparisons)
- Total for a heap implementation:

$$O(N*logN + N*logN) = O(N*logN)$$

- If putting them back into the list is O(N)
  - We get the same complexity as quick\_sort and merge\_sort

#### **Properties of "PQueue-sort"**

#### Advantages

Works with any implementation of priority queues

#### Disadvantages

- Requires O(N) space for the new queue
- O(N\*logN) heap construction





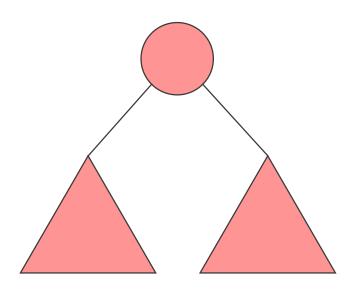
Heaps
Bottom up construction

### Cleverer: Bottom-up heap construction

- We've been constructing the heap one element at a time
- After each element is added, we "heapify" the entire heap
  - O(logN) per element added
- If we know many elements in advance, we can do it more quickly

### Cleverer: Bottom-up heap construction

 Recall that a binary search tree is recursive: a BST is an element plus two children that are also BSTs

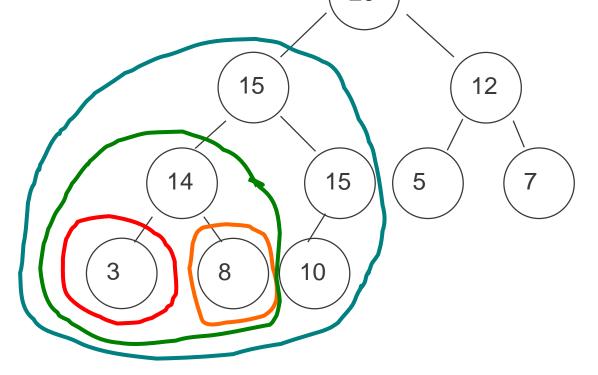


### **Cleverer: Bottom-up heap construction**

Remember, heaps are also recursive

A heap is an element with two children that are both heaps

Every circle is a heap



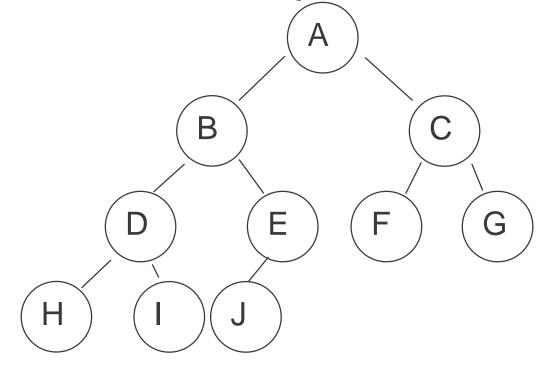
- So, to build a heap, we can start from the bottom and make little heaps
- By definition, every leaf node is a heap
  - So leaves are already done: less work!
- In a complete binary tree with N elements, how many leaves are there?

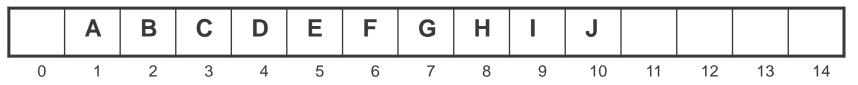


### How many leaves?

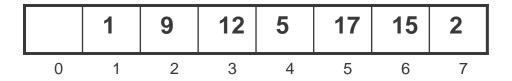
The first non-leave is the parent of the last element

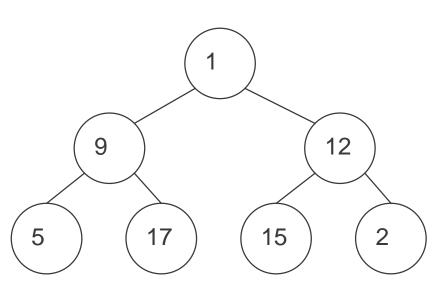
N//2



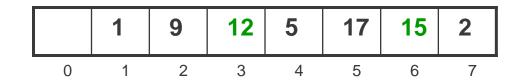


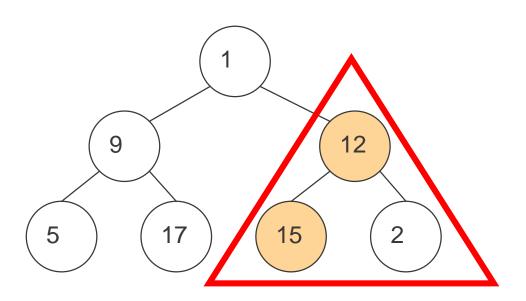
- Start with an array in arbitrary order
- Build sub-heaps, starting at the bottom right
- The leaves are already done, so we start at "12"
  - number elements//2



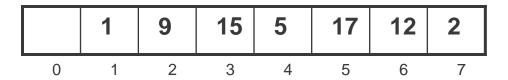


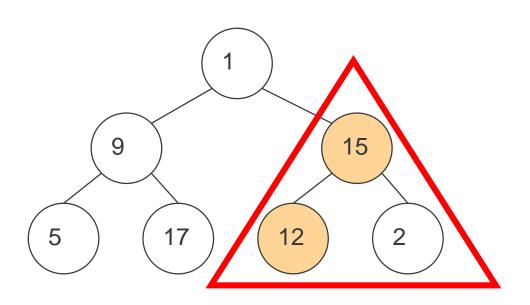
It's out of order, so swap with its largest child



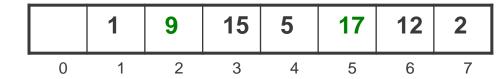


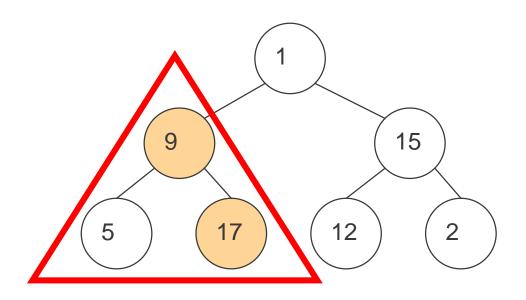
- It's out of order, so push the root down until it's correct
- Now it's a heap



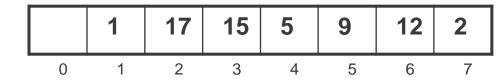


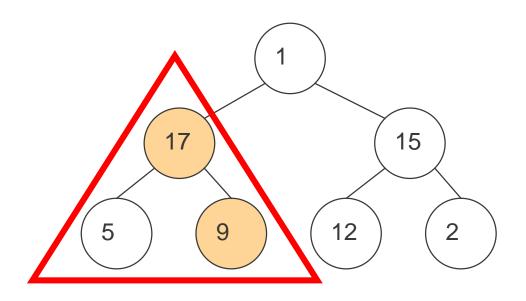


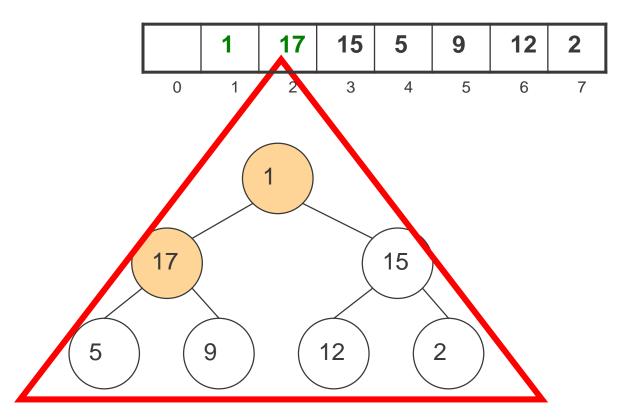




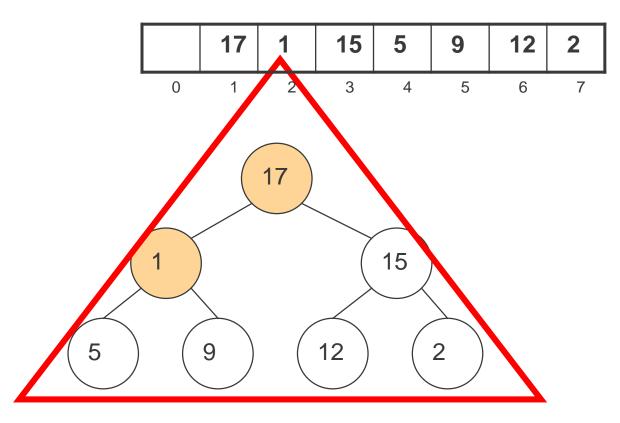


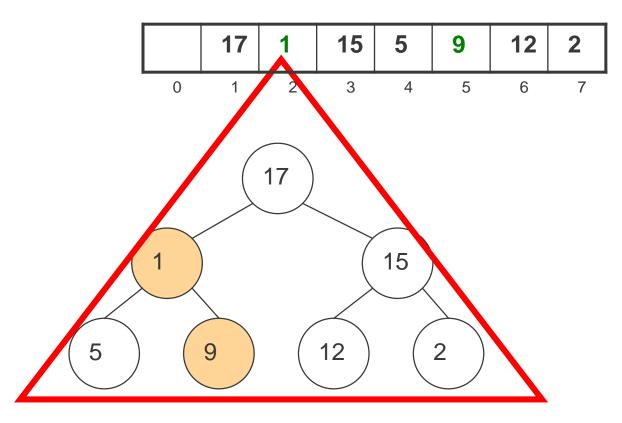




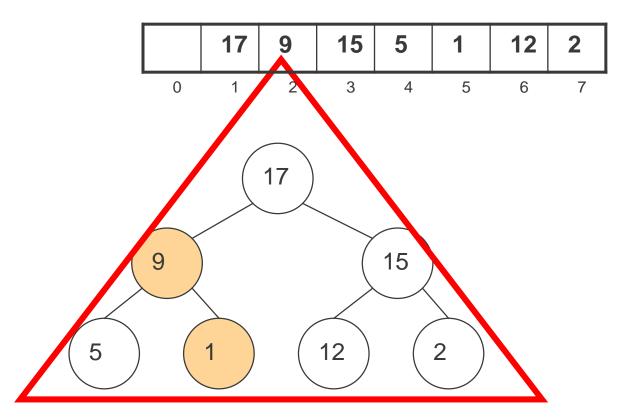








Done!





#### **Alternative** \_\_init\_\_ for known elements

MONASH University

```
""" If elements are known in advance, they are in an array
Assume that max size=len(an array) if given """
def init (self, max size: int, an array = None: ArrayR[T]) -> None:
    self.the array = ArrayR(max(self.MIN CAPACITY, max capacity) + 1)
    self.length = max size
    if an array is not None:
        # copy an array to self.the array (shift by 1)
        for i in range(self.length):
            self.the array[i+1] = an array[i]
        # heapify every parent
        for i in range(max size//2,0,-1):
            self.sink(i)
```

### Complexity of creating a heap of N elems

• At worst, how far does each node need to be pushed down?

Its height!

#### Complexity of creating a heap of N elems

No. nodes Height

Sum of all heights in heap:

$$-S = 1(2^{h-2}) + 2(2^{h-3}) + ... + (h-3)2^{2} + (h-2)2^{1} + (h-1)2^{0}$$

Simplify

### Complexity of creating a heap of N elems

#### Multiply by two:

- 
$$S = 1(2^{h-2}) + 2(2^{h-3}) + ... + (h-3)2^2 + (h-2)2^1 + (h-1)2^0$$
  
-  $2S = 1(2^{h-1}) + 2(2^{h-2}) + ... + (h-3)2^3 + (h-2)2^2 + (h-1)2^1$ 

#### Realign:

$$-2S = 1(2^{h-1}) + 2(2^{h-2}) + ... + (h-3)2^{3} + (h-2)2^{2} + (h-1)2^{1}$$

$$-S = 1(2^{h-2}) + ... + (h-4)2^{3} + (h-3)2^{2} + (h-2)2^{1} + (h-1)2^{0}$$

#### • Subtract (2S-S):

$$- S = 1(2^{h-1}) + 1(2^{h-2}) + ... + (1)2^{3} + (1)2^{2} + (1)2^{1} - (h-1)2^{0}$$

$$= 2^{h-1} + 2^{h-2} + ... + 2^{3} + 2^{2} + 2^{1} - (h-1)2^{0}$$

$$= 2^{h-1} + 2^{h-2} + ... + 2^{3} + 2^{2} + 2^{1} + 2^{0} - h$$

$$= 2^{h} - 1 - h$$

Complexity is O(N) where N is the number of nodes (since N is 2<sup>h</sup>-1)





# In-place Heap Sort

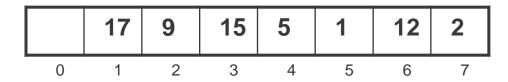
- Our earlier queue sort requires O(N) extra space for the queue
- We can sort an array in-place (O(1) extra space) using heap principles

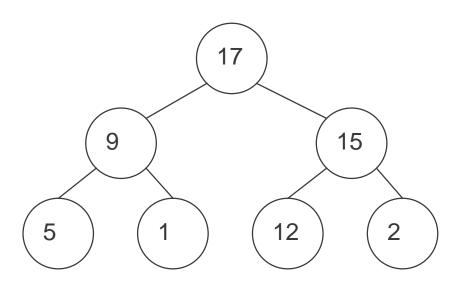


- 1. Construct heap: O(N)
- 2. Do N times:
  - Get max element: O(logN)
  - 2. Put it in the "hole" made by previous step: O(1)
- Summary: O(N\*logN) time, O(1) space

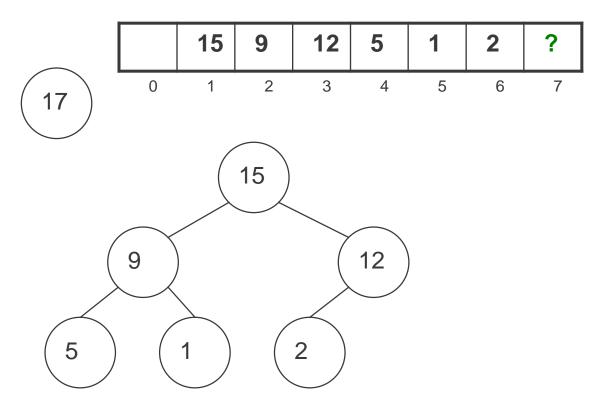


• After making the heap...

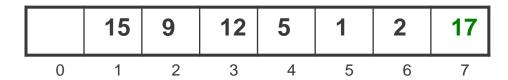


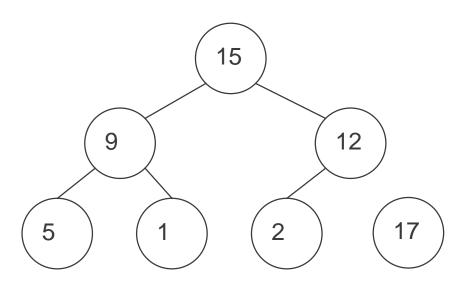


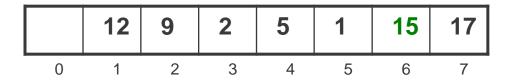
Remove the max element...

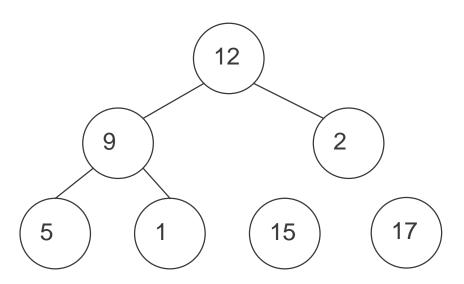


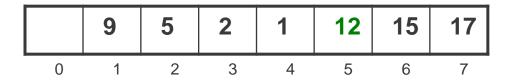
Put it in the hole.

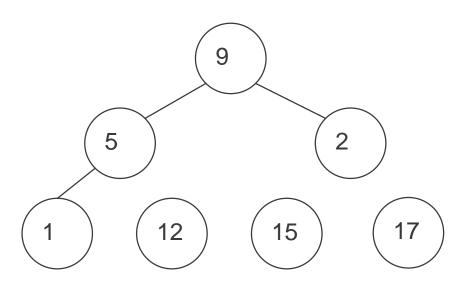


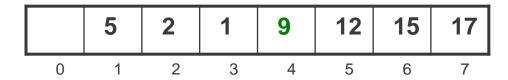


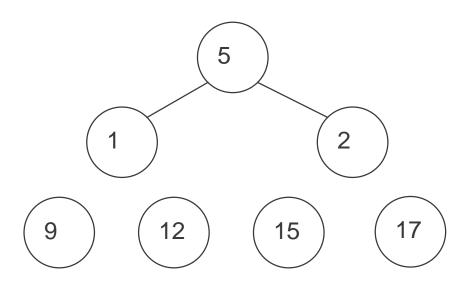


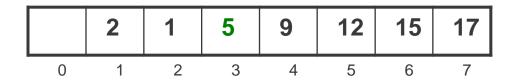


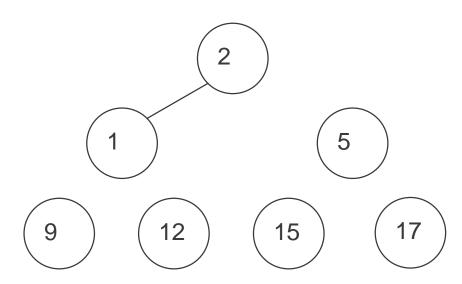




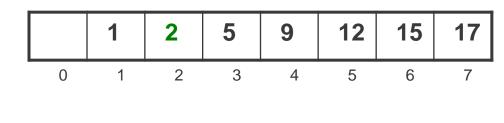


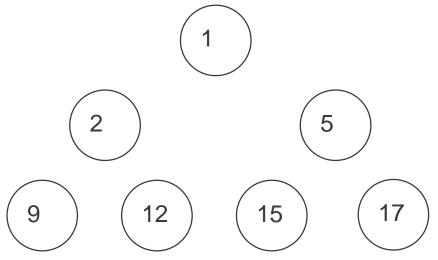






Done





### Summary

- A simple Heap implementation
  - rise
  - sink
  - largest\_child
- Queue-Sort
- Operations for a clever Heap implementation for Priority Queues
  - Complexity and correctness



