Vihang Patil

Ph.D Student in Reinforcement and Deep Learning

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EDUCATION

Johannes Kepler Universität Linz

Linz, Austria

Ph.D. student in Reinforcement Learning advised by Prof. Sepp Hochreiter

Sep. 2019 - Ongoing

Universita Della Svizzera Italiana

Lugano, Switzerland

Master of Science in Artificial Intelligence (9.00/10)

Zurich, Switzerland

ETH Zurich
Exchange Semester and Master Thesis

2018 - 2019

2017 - 2019

University of Mumbai

Mumbai, India

Bachelor of Engineering in Electronics (First Class)

2011 - 2015

Research Experience

Amazon

Seattle, USA

Applied Science Intern - AGI

September 2023 - December 2023

Amazon

Seattle, USA

Applied Science Intern - Alexa AI

January 2022 - May 2022

• Reinforcement Learning For Information Retrieval: Worked at the intersection of Data Structures, Information Retrieval, graph neural networks, and Reinforcement Learning.

Institute for Machine Learning, Johannes Kepler Universität Linz

Austria

Research Assistant - Advised by Prof. Sepp Hochreiter

Sep 2019 - Ongoing

Data Analytics Group, ETH Zurich

Zurich, Switzerland

Master Thesis Student - Advised by Dr. Aurelien Lucchi

Oct 2018 - Sep 2019

• Reinforcement Learning under Constraints: Studied various derivative-free methods for reinforcement learning under constraints. Developed a convergent evolutionary algorithm.

Institute for Machine Learning, Johannes Kepler Universität Linz

Austria

Visiting Student Researcher - Advised by Prof. Sepp Hochreiter

Jun 2018 - Nov 2018

• Credit Assignment in StarCraft-II: Implemented Reward redistribution for various mini-games in StarCraft-II with delay in reward and long episode length. Designed and trained deep neural network policies using PPO.

University of Mumbai

Mumbai, India

Student Researcher - Advised by Prof. Sandeep Mishra

May 2014 - May 2015

• Path Planning for Robots: Implemented various path-planning algorithms in a multi-robot system. The project was selected for ARM design contest and presented at ADCOM, Bangalore, 2014.

RESEARCH PAPERS

Contrastive Abstraction for Reinforcement Learning

V. Patil, E. Rumetshofer, M. Hofmarcher, S. Hochreiter (Gen Plan Workshop 2023)

InfODist: Online distillation with Informative rewards improves generalization

Siripurapu, Patil, Schweighofer, Dinu, Schmied, Holzleitner, Eghbal-Zadeh, Kopp, Hochreiter (Deep RL Workshop 2022)

Align-RUDDER: Learning From Few Demonstrations

V. Patil, M. Hofmarcher, M. Dinu, M. Dorfer, P. Blies, J. Brandstetter, J. Arjona, S. Hochreiter (ICML 2022)

History Compression via Language Models in Reinforcement Learning

F. Paischer, T. Adler, V. Patil, A. Bitto, S. Lehner, H. Eghbal-Zadeh, S. Hochreiter (ICML 2022)

A Globally Convergent Evolutionary Strategy for Stochastic Constrained Optimization

<u>V. Patil*</u>, Youssef Diouane*, Aurelien Lucchi* (AISTATS 2022)

A Dataset Perspective on Offline Reinforcement Learning

K. Schweighofer, A. Radler, M. Dinu, M. Hofmarcher, V. Patil, A. Bitto, H. Zadeh, S. Hochreiter (COLLAS 2022)

XAI and Strategy Extraction via Reward Redistribution

M. Hofmarcher, M. Dinu, V. Patil, M. Dorfer, P. Blies, J. Brandstetter, J. Arjona, S. Hochreiter (XXAI - Book Chapter)

Reactive Exploration to Cope with Non-Stationarity in Lifelong Reinforcement Learning

C. Steinparz, T. Schmied, F. Paischer, M. Dinu, <u>V. Patil</u>, A. Bitto, H. Zadeh, S. Hochreiter (COLLAS 2022)

Understanding the effect of Dataset Composition on Offline Reinforcement Learning

K. Schweighofer, M. Dinu, M. Hofmarcher, A. Bitto, P. Renz, <u>V. Patil</u>, S. Hochreiter (Deep RL workshop Neurips 2021)

Modern Hopfield Networks for Return Decomposition for Delayed Rewards

M. Widirich, M. Hofmarcher, A. Bitto, <u>V. Patil</u>, S. Hochreiter (Deep RL workshop Neurips 2021)

Guided Search for Maximum Entropy Reinforcement Learning

V. Patil

Competitions

MyoChallenge at Neurips 2022

Co-Winners of the MyoChallenge 2022 at Neurips 2022

Aug 2022 - Nov 2022

Robocon

Programmer/Team Leader - Advised by Prof. Prashant Upadhyay

Dec 2013 - Mar 2015

Mumbai, India

• ABU-ROBOCON competition: Co-founded the team in 2013 and was programming lead(2013-2014) and Team leader(2015). Designed, built, and programmed robots for tasks ranging from pick and place to playing double Badminton. Led a team of 20 students (2015) and oversaw mechanical, electronics, and software aspects of robot design. Improved rank to 10th from 40+ in the previous years in about 100 contesting teams at Robocon 2015.

Industry Experience

Fractal Analytics

Mumbai, India

Associate (Data Science)

Jan 2016 - Jul 2017

- Sales Incentive Optimizer: Assisted a consumer products good major in incentivizing salesman using regression and clustering. Deployed the product to users on R-Shiny dashboard.
- Customer and Loyalty Analytic's: Objective was to forecast sales qualified lead for 6 months. Developed an ARIMA time series model for forecasting sales leads and interfaced the model with Hive for forecasting on real time data.

OTHER

Reviewing Conferences

NeurIPS (2023, 2022, 2021, 2020), ICML (2024, 2023, 2022, 2021, 2020), ICLR (2022, 2021, 2020)

Deep Reinforcement Learning

Austria

Teaching Assistant - Johannes Kepler Universität Linz

2024, 2023, 2021, 2020 Summer Semester

TECHNICAL SKILLS

• Languages: Python, MATLAB, R, HTML, CSS

• Frameworks: Pytorch, Tensorflow, ROS

SCHOLARSHIPS

LIT AI Lab PhD Scholarship

2019 - 2024

Tution Fee Waiver Scholarship, Govt. of India

Awarded to top 5% of the class.

2011 - 2015

LINKS

• Github, Website, Google Scholar, Twitter