# Vinayak Paroonon Kooloth

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#### Professional Summary

Innovative AI & Robotics master's student experienced in LLMs, agentic workflows, and explainable AI. Skilled in building production-grade MVPs using Python, RAG pipelines, SHAP, and vector databases. Passionate about autonomous systems and applied machine learning in real-world and research settings.

#### **EDUCATION**

## Hof University of Applied Sciences

Germany

M.Sc. in Artificial Intelligence & Robotics

Mar 2024 - Oct 2026 (Expected)

Email: vinayakparoononkooloth@gmail.com

# CMS College of Engineering and Technology

India

B.Eng. in Computer Science and Engineering

Aug 2019 - Jul 2023

Mobile: +49 15560026916

Location: Braunschweig, Germany

## EXPERIENCE

### Fricke und Mallah Microwave Technology

Peine, Germany

Working Student - AI Agent Development

Jun 2025 - Present

- **LLM-Based Agent Automation**: Designed and deployed AI agents using OpenAI GPT-4 and LangChain for automating multilingual content creation, lead generation, and marketing strategy planning. Integrated with company CRM tools and email pipelines.
- Vector Database Integration: Implemented FAISS-based memory for context-aware email generation and follow-ups. Reduced manual email drafting by over 60%.
- Website NLP Optimization: Analyzed and enhanced multilingual website content (microwaveheating.net, hhft.de) using NLP techniques for SEO and user personalization, increasing site traffic by 25%.
- Analytics Dashboarding: Created performance dashboards using Power BI and Python scripts to monitor agent performance, email engagement, and lead conversion metrics.

#### Technische Universität Chemnitz

Chemnitz, Germany

Student Assistant - Surgical Lamp Simulation (autoPre)

March 2025 - Present

- ROS2-Based Simulation Development: Built a robotic simulation environment using ROS2 and Gazebo for autonomous control of surgical lamp movement based on operator gestures and target zones.
- Human-Robot Interaction (HRI): Implemented motor actuation logic and behavior trees for simulating realistic lamp response in surgical settings. Focused on safety, precision, and latency.
- Collaborative Research: Supported EU-funded autoPre project with Prof. Maik Berger, contributing to modular robotic assembly systems and HRI interface design.
- Testing & Documentation: Developed test scripts and technical documentation for simulation modules, ensuring reproducibility and transferability to real-world robotic arms.

## Hof University of Applied Sciences

Germany

Student Researcher - Applied Machine Learning

Oct 2024 - Mar 2025

- Phishing Email Classifier: Trained a DistilBERT transformer model for email classification, achieving over 92% accuracy on custom English-language phishing datasets.
- Explainability via SHAP: Integrated SHAP explainability into the model pipeline to visualize token-level phishing indicators. Deployed interpretability through FastAPI frontend.
- Experiment Tracking: Utilized MLflow and Git versioning for reproducible experiments and tracked model performance across 15+ variations.
- Research Contribution: Produced a technical report and visualization dashboard, contributing to the department's AI interpretability research initiative.

### PROJECTS

- LLM-Powered Email Classification with Explainability: Focus: Secure NLP pipeline for phishing detection | Tech: DistilBERT, SHAP, FastAPI, Docker | Contributions: Built end-to-end XAI pipeline with real-time inference; used SHAP for token-level interpretation | Impact: 92% F1 on in-house dataset
- Generative QA with RAG and GPT-4: Goal: Fact-grounded question answering using generative models | Stack: GPT-4, FAISS, LangChain, Python | Design: RAG with document retrievers and citation mechanism | Outcome: Deployed prototype used in compliance/legal AI demos
- Autonomous Research Agent for Scientific Literature Discovery: Objective: Automate academic research via generative agents | Tech: LangChain, GPT-4, Pinecone, Streamlit | System: Recursive search + summarization + citation validation | Use Case: Thesis literature automation
- UWB-Based Localization Simulator for Robots: Use Case: Indoor autonomous navigation | Built With: Python, simulated UWB RSSI model, heatmap visualization | Results: Achieved ;1m positional accuracy in constrained environments | Relevance: Tied to robotics AI projects at TU Chemnitz
- Multimodal Emotion Recognition for Human-Robot Interaction: Goal: Real-time emotion detection for social robots | Architecture: CNN + wav2vec2 + BiLSTM | Dataset: RAVDESS, AffectNet | Performance: 87.2% F1-score | AI Use: Improved human-awareness in robotics simulations
- ML Monitoring Dashboards with Auto-Retraining Trigger: Function: Live tracking of ML KPIs and drift detection | Tools: Power BI, AWS Lambda, Scikit-learn | Feature: Custom triggers to retrain stale models based on performance decay

#### TECHNICAL SKILLS

• Programming Languages: Python, C++, SQL, Bash, Java (basic)

Machine Learning & AI: Transformers (Hugging Face), SHAP, LangChain, OpenAI APIs, RAG Pipelines, Scikit-learn, CNNs, BiLSTM, wav2vec2

Generative AI: GPT-4, LLaMA (prompt design), FAISS, Pinecone, LangChain, Retrieval-Augmented Generation (RAG)

**Software Development**: FastAPI, Flask (basic), Docker, Git, REST APIs, Unit Testing, Clean Code Principles

MLOps / DevOps: MLflow, GitHub Actions (basic), AWS Lambda, Power BI, Model Monitoring, CI/CD pipelines

Robotics & Simulation: ROS2, SLAM (intro), UWB Localization, Gazebo (simulated), Behavior Trees (basic)

Databases & Vectors: PostgreSQL, SQLite, FAISS, Pinecone

Tools & IDEs: Jupyter, GitHub, LaTeX, Postman, VS Code, Streamlit

#### Languages

• English: C1 – Professional proficiency

• German: B1 – Conversational (improving)

#### Interests

• Tech Blogging, Reading Science Fiction, Hiking and Outdoor Adventures, Puzzles and Problem Solving