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Finding minimum optimum point in the Rosenbrock function using Particle Swarm Optimization technique.

Rosenbrock Function is represented by:

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f(x,y) = (1-x)^2 + 100 * (y-x*x)^2
```

We use PSO to find the minimum value of variable x and y which makes the Rosenbrock function minimum. The particle has the following characteristics:

- 1)position The current position of the particle.
- 2) fitness Fitness of the particle.
- 3)velocity- Velocity of the particle.
- 4)bestPosition Best position from group of particle.
- 5)bestFitness Best Fitness in a group of particle.

Initially for our program we take 10 particles and assign them a random velocity and random position. The velocity and position are assigned in such a way that it does not exceed the limits of Rosenbrock function, which is from -10 to 10. The particles which are at random position in a parabolic shaped flat valley tries to adjust their position and velocity based on the global best position and global best fitness. The new velocity is calculated based on a formula:

```
NewVelocity = (w * currParticle velocity) +
(c1 * r1* (currParticle bestposition – currParticle position)) +
(c2 * r2 * (bestGlobalPosition – currParticle position))
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NewPosition = currParticle position + NewVelocity

Where,

w – Inertia Weight.

c1 – Cognitive weight.

c2 – Social weight

r1, r2 – Random Numbers.

We set the value for w, the inertia weight, to 0.729. This value was recommended by a research paper that investigated the effects of various PSO parameter values on a set of benchmark minimization problems. Instead of a single, constant value for w, an alternative approach is to vary the value of w. For example, if the PSO algorithm is set to iterate 10,000 times, you could initially set w to 0.90 and gradually decrease w to 0.40 by reducing w by 0.10 after every 2,000 iterations. The idea of a dynamic w is that early in the algorithm you want to explore larger changes in position, but later on you want smaller particle movements. Then we set the values for both c1 and c2, the cognitive and social weights, to 1.49445. Again, this value was recommended by a research study. The c1 weight can be set as larger than c2, in that case we place more weight on a particle's best known position than on the swarm's global best known position, and vice versa. The random variables c1 and c2 add a random component to the PSO algorithm and help prevent the algorithm from getting stuck at a non-optimal local minimum or maximum solution. We allow this to run for 1200 iterations and eventually at the end we arrive at a global optimum solution at c1 and c2 and c3 and c4 and c4 which is c4 and c4 and

Below is an output showing the global optimum achieved for Rosenbrock function: