Commands to execute launch files:

Go to root folder of the package.

<u>gazebo.launch:</u>

- ros2 launch car_robot gazebo.launch.py.

<u>display.launch:</u>

- ros2 launch car_robot display.launch.py

<u>competition.launch:</u>

- ros2 launch car_robot competition.launch.py

<u>debug.launch:</u>

- ros2 launch car_robot debug.launch.py

Commands to execute the teleop and proportional node :

Go to root/src

- Python3 tele_op.py
- Python3 imu_odom.py