

A Review of The Google File System

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Distributed Systems
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Overview

- What is a file system?
- What is a distributed file system?
- The Google File System (GFS)
 - Design Goals
 - Architecture & Implementation
- Operations
 - Write
 - Record Append
 - Snapshot
- Fault Tolerance and Diagnosis
- Current State of GFS



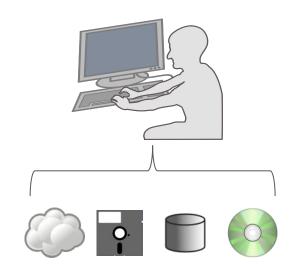
What is a (computer) File System?

A means of organizing and accessing files on storage

Logical Layer

Virtual Layer

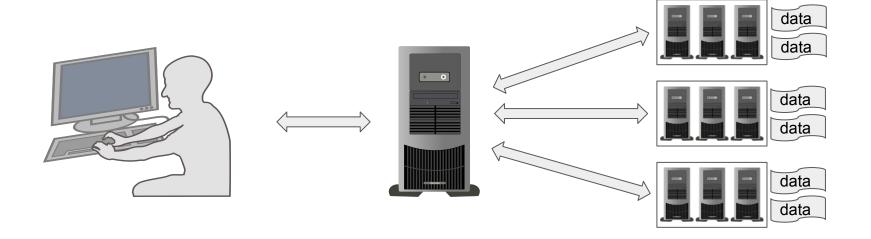
Physical Layer





What is a *Distributed* File System?

A File System that is simultaneously mounted on multiple servers that share data access via network protocols



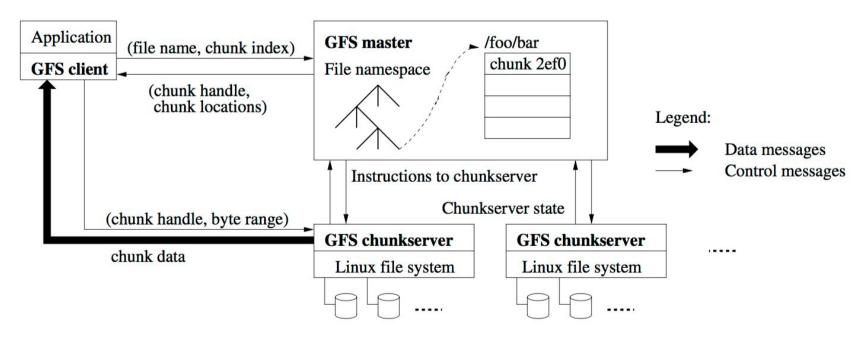


The Google File System (GFS) - Design Goals

- Specifically designed to handle Google's application workload
- Shared goals availability, scalability, performance, reliability
- Designers made several key assumptions
 - Hardware failures are the norm, not the exception
 - The files are huge
 - Writes are mostly appends
 - Must support multiple clients appending to same file
 - Reads are mostly sequential
 - Bandwidth is more important than latency



The Google File System (GFS) - Architecture



The Google File System. Sanjay Ghemawat, Howard Gobioff, Shun-Tak Leung, Proceedings of the 19th ACM Symposium on Operating Systems Principles, 2003, Figure 1



The Google File System (GFS) - Architecture

- Chunk size is 64MB
 - Reduces load on master
 - Reduces network traffic
 - Reduces storage requirements for metadata
 - Disadvantage small files could become hotspots

- Master Metadata
 - File and chunk namespace
 - File to chunk mapping ——— Written to operation log
 - Location of replicas -- Not persisted locally



GFS Operations

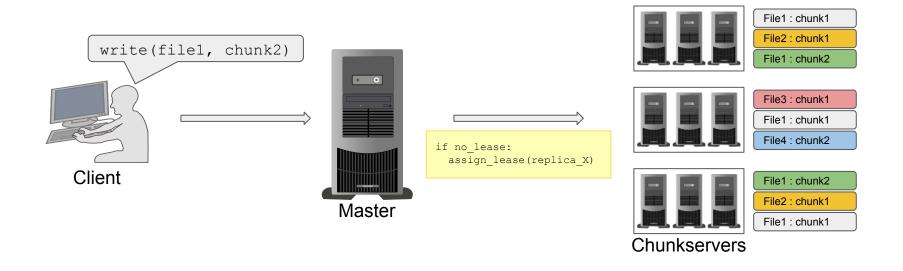
- GFS "provides a familiar file system interface"
 - Does not implement a standard like POSIX, though
- Typical file access operations are supported
 - o e.g. open, close, read, write

- Snapshot
 - Low-cost copy operation
- Record Append
 - Concurrent atomic file appending



Step 1: Client asks master for current lease-holder and replica locations

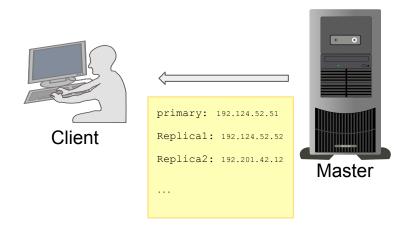
If no current lease, master assigns lease to one of the replicas

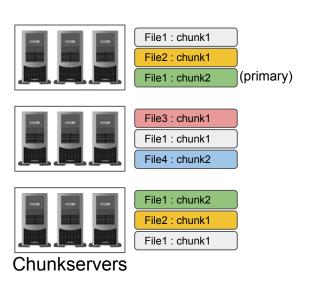




Step 2: Master responds with identity of primary chunk and location of secondaries

Client caches this data, no further communication with master (unless problems arise)

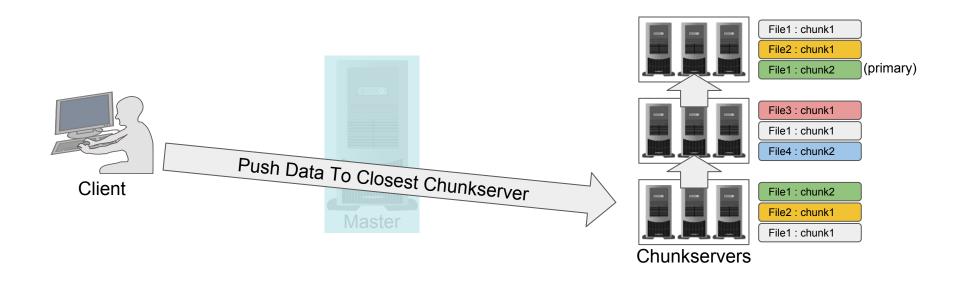






Step 3: Client pushes directly data to closest replica

Data is pushed along a linear chain of chunkservers, optimized by proximity

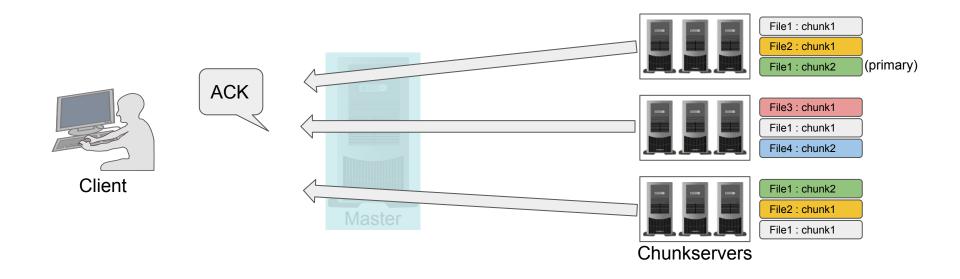




Step 4: Chunkservers ACK receipt of data

Client sends write request to primary

Primary assigns serial #s to mutations and applies to its own state

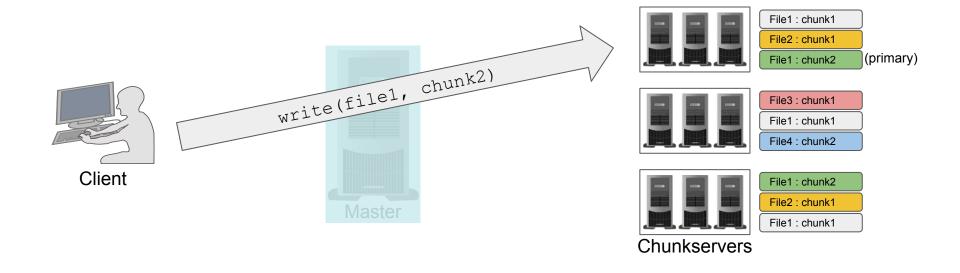




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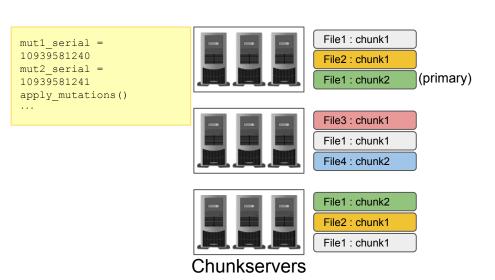
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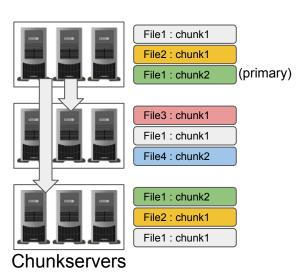


Step 5: Primary forwards write requests to secondary replicas

Secondary replicas apply mutations ordered by serial #







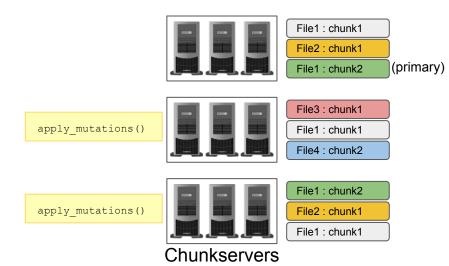


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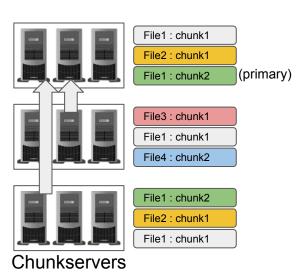




Step 6: Secondaries reply to primary indicating complete



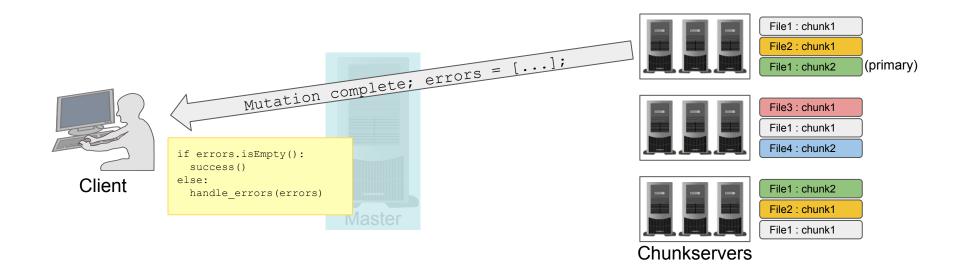






Step 7: Primary replies to client, reporting any errors

Client handles errors by (essentially) retrying failed mutation





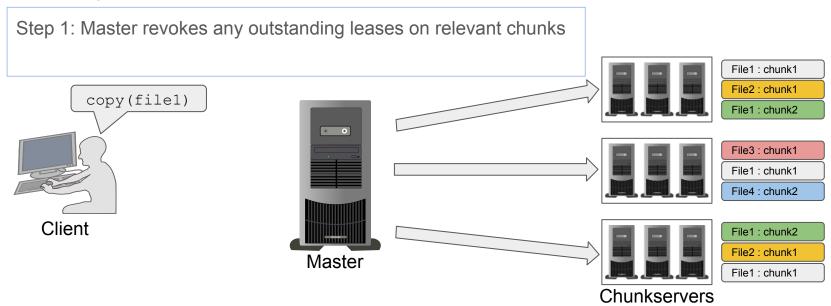
- Make a very fast (almost instantaneous) copy of a file or directory
- Copy-on-write

Step 0: Client makes copy request File1: chunk1 File2: chunk1 copy(file1) File1: chunk2 File3: chunk1 File1: chunk1 File4: chunk2 Client File1: chunk2 File2: chunk1 Master File1: chunk1

Chunkservers

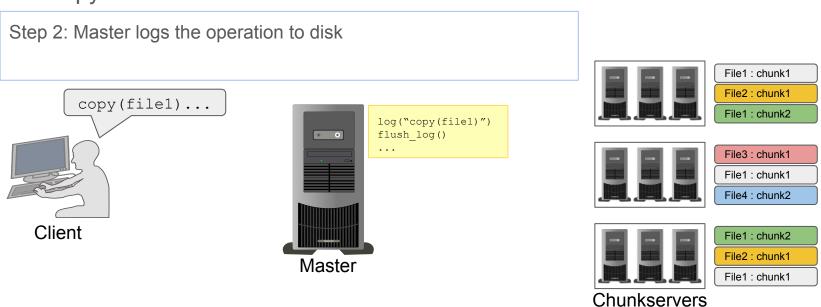


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- Copy-on-write



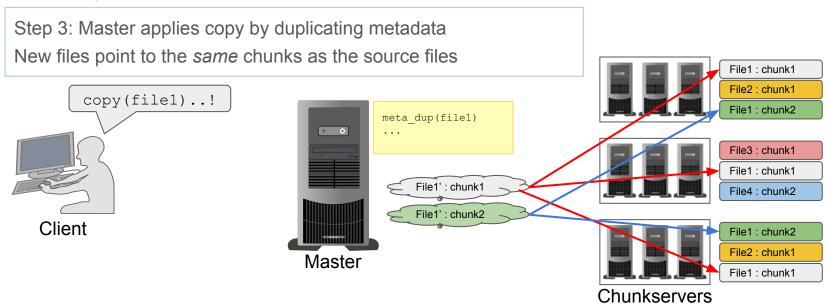


- Make a very fast (almost instantaneous) copy of a file or directory
- Copy-on-write



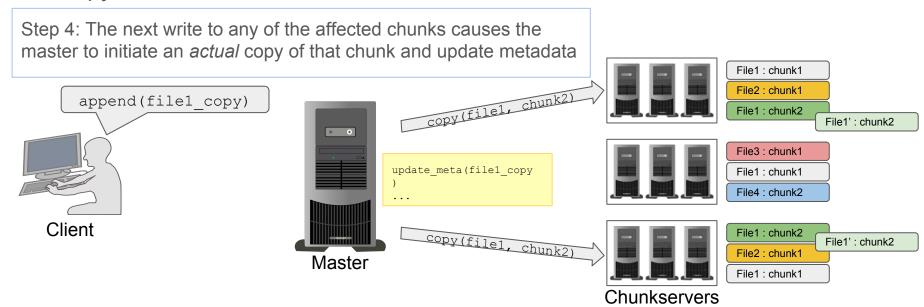


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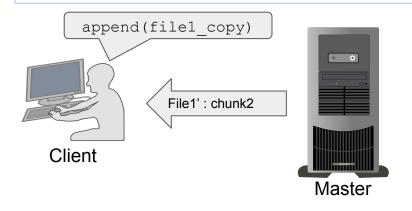
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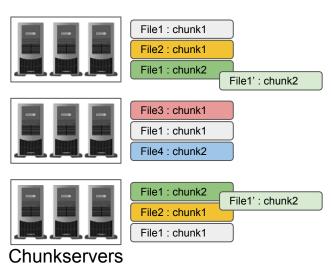




- Make a very fast (almost instantaneous) copy of a file or directory
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Step 5: Return the location of the *new* primary chunk and proceed as normal







The Record Append Operation

- Atomic append operation
- Important for target use-case: distributed read/append
- Client specifies data, GFS determines byte offset
- GFS Guarantees record will be appended in its entirety at least once
 - If a replica fails during append, client retries the operation
 - May result in different data between replicas, or duplicate records
 - Successful append regions are defined
 - Failed regions are inconsistent
 - Clients are expected to be able to handle inconsistent regions
- Record_append



Fault Tolerance and Diagnosis

- High availability
 - Fast recovery failure is the new normal
 - Chunkserver Replication controlled by the master
 - Master Replication "shadows", not mirrors
- Data integrity
 - Checksum used to detect corruption
 - Verified on reads stops propagation of errors
 - Recomputed on writes optimized for appends
- Diagnostic Tools
 - Logs, logs, more logs
 - Written continuously and asynchronously
 - Can be freely deleted without affecting the system



Current State of the GFS ---> Colossus!

- GFS was introduced (to the public) in 2003
- GFS was designed primarily for batch operations (web crawling, search indexing, etc)
- GFS was not designed for low-latency, highly interactive web apps!
- Enter GFSv2 -- Colossus!
- Not much is publicly known about colossus! (only a few articles)
 - o Removes the single-master paradigm
 - Built for real-time applications
 - Coupled with improved search-engine-engine "Caffeine"
 - Underlies ALL OF GOOGLE'S ONLINE EMPIRE! (search, gmail, drive, GCP, etc)



Resources

https://research.google.com/archive/gfs.html

http://www.cs.unc.edu/~jasleen/Courses/Fall09/slides/dfs-Google.pdf

https://pdos.csail.mit.edu/6.824/papers/gfs-faq.txt

https://www.wired.com/2012/07/google-colossus/

https://www.theregister.co.uk/2009/08/12/google_file_system_part_deux/

All images from https://openclipart.org/