





Kshatriya Electric

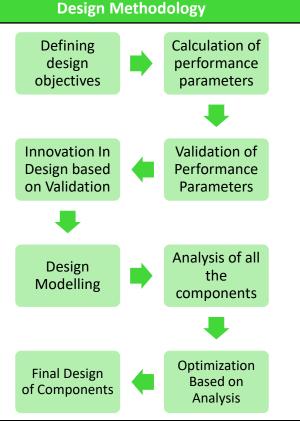
Vellore Institute of Technology – Vellore

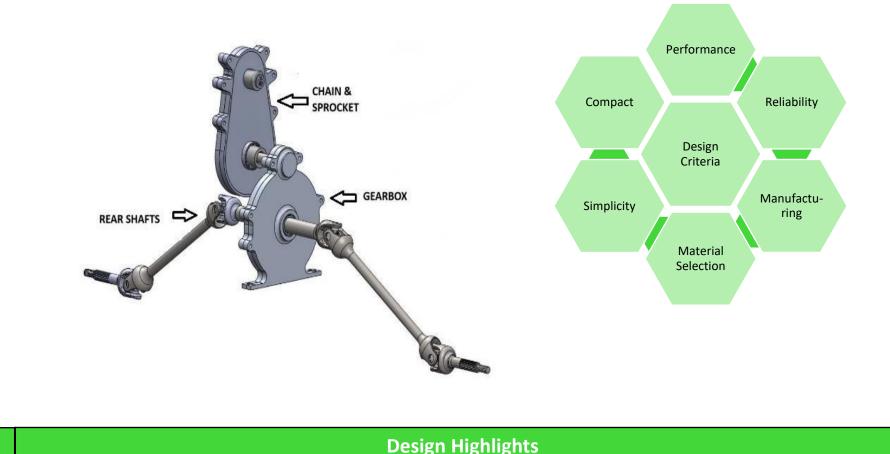
Team ID: 252084

DRIVETRAIN



OBJECTIVES AND PERFORMANCE





Max Speed 55 km/h Max Tractive Force 1872 N Acceleration 7.2 m/s² Gradeability (%) 53% Gearbox Ratio 4.3

- 1. A single stage chain and sprocket and a single stage gearbox has been used in the vehicle to provide superior speed along with extraordinary gradeability.
- 2. The drivetrain components have been designed in a way which helps in giving a better off roading performance and reduce tire wear.
- 3. Unibody Shaft has been employed to reduce the occurrence of failure in the shafts.
- 4. A swappable 90Ah battery is employed to power the car and reduce the curb weight of the car compared to the 120Ah battery.

POWERTRAIN

MOTOR CONT	ROLLER SPECS.	VEHICLE PA	ARAMETERS		TOTAL REDU	TYRE SPECIFICATION							
		Top Speed	55 km/h		CHAIN & SPROCKET	}	Front	23"x7"- 10"					
KLS7	275HC 	Gradeability	53 %										
Input Voltage	24V - 72V	Peak Acc.	7.2 m/s ²		GEARBOX	4.30	0	Rear 23"x7"-1					
		POWERTRAIN	LAYOUT	GE	ARBOX & CHAIN AND SPRO	OCKET	ι	UNOBODY HALF SHAFT					
Rating	90 Amps DC		CHAIN &										
МОТО	R SPECS.		CHAIN & SPROCKET										
Output Power	7200 W	REAR SHAFTS 👄											
Voltage	48 V		50										
Speed	4100 rpm												
BATTEDV CDE	CIFICACTION	GEARS AN	ALYSIS		BUCKLING ANALYSIS	OIL SLOSHING							
DATTERT SPE	CITICACTION	Contour Plot Element Stresses (2D & 3D)(vonMises) Analysis system		Contour Plot Buckling Mo Analysis syst	ode(Mag)		oil.Volume						
Lithium-ion Battery Pack		1.789E+02	TOWN PROJ. sent Stresses (2D & 30)XvonMises) yick system 1,2106-02 7,472-02 2	1.000E+0 8.889E-0 7.778E-0 6.667E-0	01		7.500e	10000					
Rating	48 V	1.074E+02	1.2744-102 3.3974-02 3.396-02 3.396-02 3.396-03 3.396-03 3.386-03 3.276-03	5.556E-0 4.444E-0 3.333E-0 2.222E-0	01 -01 01 01		- 5.000e	-01					
Capacity	120 Ah	Max = 3.221E+02 3D 601130 Min = 1.322E-02 3D 685190	160128 - 100	1.111E-0 0.000E+0 Mo Result Max = 1.000 Grids 142583	+00 OE+00 83		2.500e 1.000e		wan in the second				
Cell Type	21700 - NMC		FOS=1.8	Min = 0.000E Grids 220571		31	1.0000		······································				

TRACTIVE SYSTEM SPECIFICATIONS

38V

Phase current

Battery

Lower Cut-off Voltage

NMC

Chemistry

MCU

Discharge

3-speed regulation function

Nominal Capacity 90Ah		Lower Cut-on voitag	364	Peak		36A			Sport mode						
Temr	perature				- Continuou	IS	25A	Maximum	150A	Normal Mode					
		Upper Cut-off Voltag	ge	54.6V	ļ					Eco Mode					
Operation Range	0-50	degree				Throttle Input Type	t Hall sensor		PMSM Motor and Motor controller wiring diagran						
Battery Cooling		ural Air oled	Nominal Voltage		48.1V	Cooling Type natura		atural							
We	eight		Dimer	nsions	;	IP R	ating		SIX-PHASE PMSM MO	IOR III					
3	5 kg		Length		14in	IP	67								
33 kg			Width	Width 12in				t			Hall sensor wire				
IP Rating			Height	Height 9in					r		1,2,3 Speed selector switch				
IP67			MO		Motor c	ontro	ller			Electric key lock					
Swaj	ppable										switch (battery +) Phase signal instrument panel				
Y	/ES		Ville				0 0		Circuit-breaker		Electronic brake switc				
Accur	mulator	-	3			0	S. S. S.			Modular controllre	Hall signal instrument panel Throttle				
Series	1	13s					om Blue Gr ttery	RÉEN TELLOT		modulal controlle					
Parallel	2	24p							+ 1						
Discharge								+ +							
Max Cont.	Max Cont. 180A														
Instantaneou		300A					<u> </u>		1-++						
Regen Curren	it	8A							Battery						

GLV system & Component analysis

Frequency

TSAL

2 Hz

Sensors and other components

Ultrasonic

Battery

Lower Cut-off

38V

Kill switch

ISO 13485

Cockpit Switch

DC-DC converter

42-60V DC-DC

Voltage Range

_		External				HC SR04	Proximity	Voltage			
Input	48V DC	Switch	ISO 13485		Switch ISO 13485					Upper Cut-off	
Fuse		Microco	ntroller	Supply	120	Hall sensor	Display	Voltage	54.6V		
		Daanh	own / Di	Calaum	A wa b a w			Nominal Voltage	48.1V		
Туре	SKU: 639209	Raspb	erry Pi	Colour	Amber	DHT11	LM35	Fuse			
Wiring Harness	Yes	Node	MCU		Circu						
Brakeli		DC DC cc	onverter		_	KEY SW	ITCH				
			C		SE LIGHT SE ALARM	BATTERY 48 V	DC-DC CONVERTOR	F-N-R selector	switch		
TSA		Kill St	witch	BRAK	E LIGHT ETDS OUTPUT CO	FUSE SKILL SWITCH			2		

DESIGN VALIDATION PLAN

Acceptance

Level: Vehicle,

SI. No.	Level: Vehicle, Aggregate or part	Performance Target	Acceptance Criteria / Target	Validation Test & Method	Test Resource	No. of Tests	Start Dt.	Finish Dt.	Remarks	Report No.
1	Transmission	4. seconds for 150 feet	Data comparison	Acceleration Test: Straight 150 ft track	Ultrasonic Sensor	10 28-09- 2024		Ongoing	NA	NA
2	- Transmission	9 seconds for 150 feet	with MATLAB model	Hill Climb Test: 30° Gradient track	Ultrasonic Sensor	5	28-09- 2022	Ongoing	NA	NA
4	IPG CarMaker	7 seconds for 150 feet	Data comparison with MATLAB model	Acceleration Test: Straight 150 ft track with 'aggressive driver' mode	IPG Carmaker	5	26-10- 2024	30-10- 2024	The CG height was within acceptan ce criteria.	5.3 seconds for 150 feet

	TRANSMISSION DFMEA														
				Potential						Responsibility	Action Results				
ITEM / Function	Potential Failure Mode	Potential Effect(s) of Failures		Cause(s)/Mecha nism(s) of Failures	Ο	Current Design Control	D	R P N	Recommended Action(s)	& Target Completion Date	Action Taken	S	O	D	R P N
	unstable			Improper thermal management system, poor BMS quality, lithium Ion material ignition due to over- heating	4	Active and passive cooling system, improvised BMS	4 -	160	Verified BMS implementation and ventilation and connected BMS to display using Bluetooth	Riya	Stable connection between BMS and the display, controlled overheating	10	3	4	12 0

design to control

BMS power

supply at 12v or

24v

Switching to

2WD/ unlock

and reversing

back the vehicle

Anisha

5 90 center differential

Check whether the

bus matching

resistance is correct

and establish a stable

connection between

BMS and ECU

4 72

BMS used for balancing cells

in a battery

pack and

monitoring

Overcharging,

causing the

detection wire battery to swell

Poor connection,

6 crimping process 3

or poor contact

Failure of

voltage

TRANSMISSION DFMEA

Action Results

				Potential							Action Results					
ITEM / Function	Potential Failure Mode	Potential Effect(s) of Failures	S	Cause(s)/Mech anism(s) of Failures		Current Design Control	D	R P N	Recommended Action(s)	Responsibility & Target Completion Date		S	0	D	R P N	
Halfshaft: Transmission of Power from gearbox to the wheels	Ductile Fracture	Seizes The Power Delivering To Wheels Grounding Of The Vehicle	10	The Yield Strength Of The Shaft Being Too Low	6	Preventive control - Design per torque requirement	1	60	Revision in design and hardening technique	Athul	Reduce HRC value from 40 HRC to 30-35 HRC change design to unibody half shaft	10	4	1	40	
PMSM Motor: Provides power to the wheels for the movement of the vehicle	Winding rupture, short circuit, breaking failure	Decrease in RPM, abnormal starting, and decreased efficiency	8	Improper installation, Debris Reaccumulatio n	5	Connected carefully, removal of debris, check for misalignment	2	80	Check connections and ventilation	Riya	Increased efficiency, stable RPM range and controlled over heating	8	3	2	48	







Thank You



