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## Project Report

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# Comprehensive analysis of electronic noise and their noise spectra of voltage regulator circuit with zener diode at low frequency

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## Abstract

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We present a noise analysis of regulated power supplies. Basic zener diode regulated power supply is employed. We studied noise characteristics at very low frequency (sub hertz), low frequency (up to 10k) and relatively high frequency (up to 100k). All this analysis is made from the LOCK IN amplifier which gives us direct frequency domain information about the device. For our purpose we used SR830 which is relatively low noise compared to our noise signal and can measure up to 10nV/Hz. We looked for traces of frequency dependent noise like flicker noise and white noise like shot noise, avalanche noise and thermal noise. We used a specific *zener diode* specifically BZX55C5V1 in the voltage regulator, which means exact results can be varied to different zener diodes but it should follow a similar trend. Our work in interfacing with the LOCK IN amplifier led to a new python package called *pyinstro*, which was intended as stream lined for laboratory instrument controlling and handling. We tried to make it as flexible and extensible as possible. This library is made as open source and supports every SCPI supported interface like GPIB, RS232, USB and LAN. This project is done as our semester project.

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# 1. Introduction

Regulated power sources are extremely important in day to day lab work. Zener diodes and passive elements share an integral part of the overall circuit of regulated power supply. When we are dealing with precision measurement and study we need the most precise power sources to work with but because of 'Noise' of components of zener diodes and passive elements it inherits noise internally. Since, this noise will be infested in precision work we are doing in the lab. It is better to study the known structure of noise in these devices to address methodic treatment to our data and circuits. With all this in mind we are doing noise measurement and studying the noise spectrum of the zener diode.

For this semester we had radical plans to try but it evolved into more mature or downgraded in a way. First tried as shot noise to generate a random number generator which could possibly be a true random generator with little transformations. Then we eyed the more on general idea of studying noise theoretically and doing analysis experimentally. Which is exactly what we are doing right now but change is that at start we are working with photodiode and now with zener diode. Thanks to Dr. U S Joshi sir who guided us to try different diodes against photodiode. In this report we are having the following parts in order. First we are studying theoretically components, then we will discuss methods and tools that we used included all instrumentation, data acquisition, data analysis etc., we will conclude with our results and discuss it. we took help from Electronic noise and interfering signals: principles and applications.[13] The foundational work in thermal noise was done by J B Johnson in his paper johnson1928thermal. Johanson also gave first experimental evidence of frequency dependent noise.[6]

# 2. Theoretical compilation

This section will deal with theoretical components from our project. Here, linear circuit analysis gives noise and output voltage relationship.

## 2.1. Linear circuit analysis

We have a voltage regulator circuit from a zener diode which regulates voltages at specific voltage known as zener voltage  $V_z$ . The fluctuation from these regulated voltages is what we call noise. Since ideal regulators only give pure DC voltages at output, this fluctuation is completely unwanted and only be resultant of intrinsic noise of this regulator circuit. We limit ourselves with only noise coming from zener diode which is not quite good practice. Since, noise can be added from extra resistors, wires and even the power supply itself. The resistor noise can be neglected because of their low values as we used 10k in series and 100k in parallel to output. We will see this later.

Let's take a basic voltage regulator circuit as shown in figure 1.

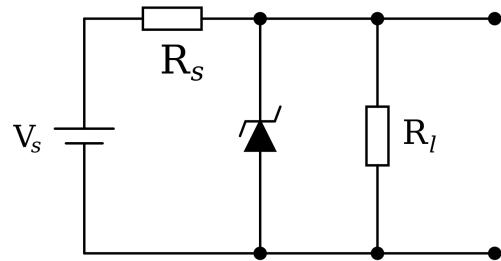


Figure 1: Simple voltage regulator circuit made from zener diode

As you can see we have a zener diode parallel to the power supply, which regulates at a certain degree. Since this is a linear circuit output voltage can be easily derived.

Applying kirchhoff current law in the figure 1,

$$\begin{aligned}
I_z &= I_{R_s} - I_L \\
&= \frac{V_s - V_o}{R_s} - \frac{V_o}{R_L} \\
&= -V_o \left( \frac{1}{R_s} + \frac{1}{R_L} \right) + \frac{V_s}{R_s} \\
&= -V_o A' + B'
\end{aligned}$$

Here,  $A' = (\frac{1}{R_s} + \frac{1}{R_L})$  and  $B' = \frac{V_s}{R_s}$ .

We can write  $I_z = \frac{V_z}{R_z}$ , where  $V_z$  and  $R_z$  are respectively zener voltages and impedance. This relation is quite linear in the breakdown region as you can see in the figure 2.<sup>1</sup>

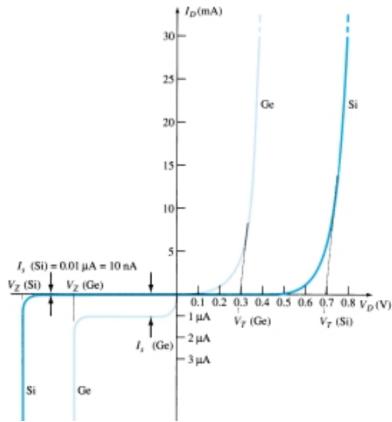


Figure 2: theoretical current and voltage relation for zener diode

Here we can assume equivalent circuit of 1 as figure 3

Further, simplifying the circuit,

This circuit is further simplified as we take  $V_z = V_{DC} + V_n$  where  $V_n$  is the noise voltage of the zener diode. If we neglect noise from other sources like resistors and power supply then from figure 4,

$$\begin{aligned}
\frac{V_z}{I_z} &= -V_o A' + B' \\
\frac{V_{DC} + V_n}{I_z} &= -V_o A' + B' \\
V_n &= -V_o A + B
\end{aligned}$$

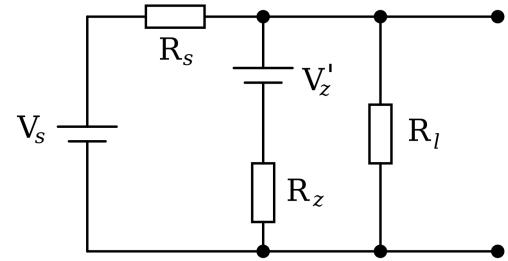


Figure 3: Equivalent circuit of figure 1

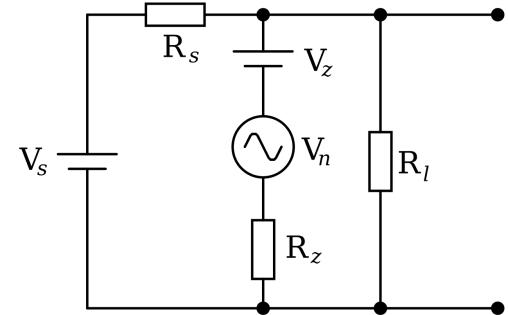


Figure 4: Equivalent circuit of figure 3

$$V_o = -\frac{V_n}{A} + \frac{B}{A} \quad (1)$$

So, we can conclude that here as  $V_o V_n$ . This will be the main focus of this project. Here we are neglecting  $V_{DC}$  and will be totally okay when we read data from the LOCK IN amplifier, since the DC component has zero frequency which can't be read from the LOCK IN amplifier.

## 2.2. Different noises in the circuit

The noise voltage  $V_n$  is made from different types of noise source which can act as a symbol

<sup>1</sup>Image is taken from Electronics Devices and Circuit Theory by Robert Boylestad

voltage source. So,  $V_n$  can be broken into sub noise sources such as  $V_n = V_{flicker} + V_{thermal} + V_{shot} + \dots$ . We will see this noise source and its origin then we will derive its respective distribution and equations.[8][14]

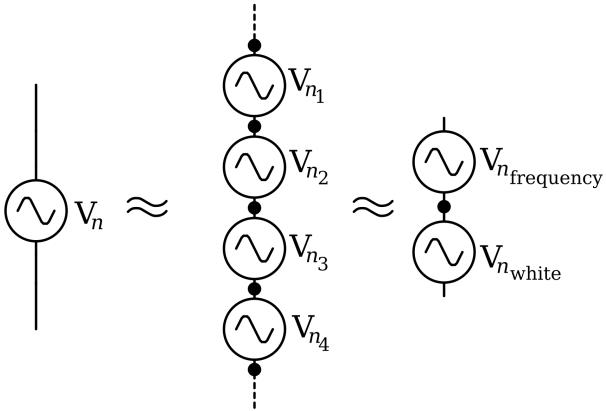


Figure 5: Equivalent noise sources

### 2.2.1. Flicker Noise

Flicker noise is also known as  $1/f$  noise in view of the fact that power density decreases with increasing frequency. This implies that at lower frequencies, the flicker noise dominates. This type of noise is found almost in any electronic device which is able to operate at lower frequencies. The main source of this type of noise is D.C supply. Its first evidence was given by J. B. Johnson [6]. Its first  $1/f$  form is derived by beck and spruit [1]. Now the form is given as

$$S(f) = \frac{\gamma}{f^\alpha} \quad (2)$$

Here,  $\gamma$  and  $\alpha$  determine the nature of flicker noise.  $\alpha$  determine relations with other noise elements.

1. ( $\alpha > 0$ ): This means that white noise is dominating the flicker noise as frequency increases.
2. ( $\alpha = 0$ ): This means that only white noise exists

3. ( $\alpha < 0$ ): This means noise is increasing as frequency. Also, shows that noise will be persistent with a higher range of frequencies. Typically white noise dominates traditional flicker noise.

We can see noise levels as from figure 2.2.3. mostly flicker noise is at considered as  $1/f$  noise. In which  $\alpha = 1$ .

### 2.2.2. $1/f^2$ noise

$1/f^2$  noise is a derivative of  $1/f$  noise and it's mostly seen in metal interconnections of integrated circuits.

It is modeled by following,

$$S_{1/f^2}(f) = C \frac{j^\beta}{f^\gamma \cdot T} \cdot e^{\frac{-E_a}{kT}}$$

Here,  $C$  is costant which can be found from experiment,  $E_a$  is activation energy for electromigration,  $k$  is boltzmann contant,  $T$  is temperature.  $j$  is current density,  $\beta$  and  $\gamma$  are contants canbe found from experiment. ( $\beta \geq 3$  and  $\gamma \geq 2$ ).

### 2.2.3. Shot noise

Shot noise is a form of noise that arises because of the discrete nature of the charges carried by charge carriers, electrons or holes or photons hitting the surface. Shot noise is analogous to the rainfall in which raindrop hitting the surface can be considered as discrete. The sound of rainfall is very similar to noise we hear from speakers when we are considering shot noise. Foundational studies in shot noise done my campbell.[2]

Since, shot noise is a phenomenon for discrete charge passing through a junction, it can be modelled by poisson distribution. Suppose that In the time interval the  $\tau$  Q charge passes through a junction in a semiconductor device (in present context zener diode). This gives rise to discrete probability distribution,

$$P(N) = \frac{e^{-\lambda\tau} (\lambda\tau)^N}{N!} \quad (3)$$

If  $N = 0$  charge passes in time interval  $\tau$  then  $P(N)$ will be,

$$P(0) = e^{-\lambda\tau} \quad (4)$$

Now suppose, probability of one and only one charge passing through junction in time  $\tau$ ,

$$P(\tau)d\tau = (P_\tau(0))(P_\tau(1))$$

From equation ??,

$$\begin{aligned} P(\tau)d\tau &= (e^{-I_0\tau})(e^{-I_0d\tau}I_0d\tau) \\ P(\tau) &= (e^{-I_0(\tau+d\tau)})I_0 \end{aligned}$$

We can write this equation in frequency domain and by,

$$P(f) = Sdf \quad (5)$$

Where  $S$  is the spectral density of noise.

Here we can write specific form for shot noise in equation ??.[2]

$$\langle V_{shot}^2 \rangle = 2eI_0df \quad (6)$$

Here,  $e$  is electron charge,

$I_0$  is average current,

$df$  is ENBW = Equivalent Noise Bandwidth

$$S(f) = 2eI_0 \quad (7)$$

This spectral density gives independence to frequency, which is called white noise.

#### 2.2.4. Avalanche or zener noise

Avalanche noise often considers the device's operating characteristics in the avalanche breakdown region. It is a major problem where the device is working in avalanche breakdown regions. It is multiplicative noise where chains of electrons crossing from junction rise to noise behaviour. It is very similar to shot noise and we can use that model and just use a multiplicative element in it.

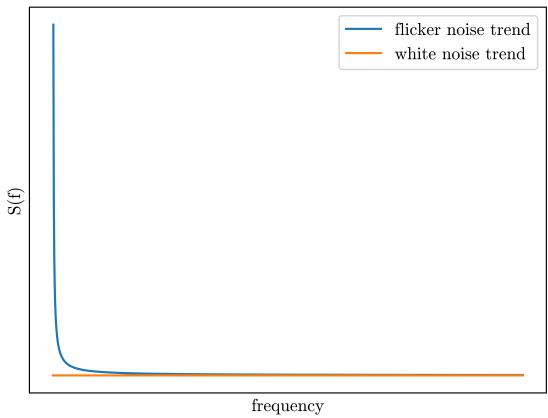


Figure 6: Equivalent noise sources

In our circuit this is significant since we are dealing with zener diode. With potential gradient inside the zener diode, if any hole and electron pair generates, it gets dragged by potential and hits the other lattice. This creates chain reaction and very high amplitude noise measured.

$$\langle V_{avalanche}^2 \rangle = M \langle V_{shot}^2 \rangle$$

$$\langle V_{avalanche}^2 \rangle = 2eMI_0df \quad (8)$$

So, the spectral density  $S(f)$  of this noise will be nearly white.

Here, we can combine this both avalanche and shot noise to make one noise source,

$$\begin{aligned} \langle V_s^2 \rangle &= \langle V_{shot}^2 \rangle + \langle V_{avalanche}^2 \rangle \\ &= 2eI_0df + 2eMI_0df \\ &= (M+1)2eI_0df \end{aligned}$$

And spectral density will be  $S(f) = (M+1)2eI_0$

Since this noise is white noise we can measure at every frequency. This is what we are going to do in the next chapter.

### 2.2.5. Thermal noise

Thermal noise, also called Johnson–Nyquist noise is the electronic noise generated by random motion of charge carriers. This charge carrier is generated by the thermal agitation inside an electrical conductor at equilibrium, which happens regardless of any applied voltage. Because of their random motion it can be said that they have a mean value at zero. This reason says that we can't model this noise by poisson distribution but have to model with normal or gaussian distribution. In 1936, J B Johnson first gave an idea about thermal noise in thermionic valves. [7]

The noise amplitude is very similar to that of shot noise and given as,

$$\langle V_{thermal}^2 \rangle = 4K_B R df \quad (9)$$

Here,  $K_B$  is boltzmann constant,  
 $R$  is resistance of device or component,  
 $df$  is ENBW.

$$S(f) = 4K_B R$$

By equation 11 we can see that thermal noise in an ideal resistor is approximately white, meaning that the power spectral density is nearly constant throughout the frequency spectrum. But practically it does decay to zero at extremely high frequencies (terahertz for room temperature). Also, we are neglecting quantum effects.

Total noise in the circuit will be frequency dependent noise and white noise,

$$V_n = V_n(f) + V_{white}$$

$$S(f) = \frac{\gamma}{f^\alpha} + (2e(M+1)I_0 + 4K_bR) + \mathcal{O}(other)$$

$$S(f) \approx \frac{\gamma}{f^\alpha} + (2e(M+1)I_0 + 4K_bR) \quad (10)$$

which is main derivation of our project.

## 3. Methodology

### 3.1. Our voltage regulation circuit

Our purpose was to regulate voltages and also study noise related to the circuit. If we choose a complicated circuit for voltage regulation then analysis of noise will be relatively complicated. So, we used a very basic voltage regulator circuit from a zener diode. Supply was given as DC power supply with voltage  $V_s$ . This voltage is decided by the zener voltage at hand.

The noise in the circuit will be relatively higher at the zener breakdown region. As we discussed from the theoretical part, noise power will be proportional to current flowing in the zener diode (here, we are assuming that noise from other parts is almost zero). To prepare a zener diode (BZX55C5V1) to break down the region we choose 5.4V. This is calculated from For our purpose we utilised a general purpose zener diode with breakdown region between 4.8V to 5.4V with current of  $\mu A$  order. We first did the Current and voltage characteristics of zener diodes. The useful information we got from there is source voltages, zener voltages and current that we particularly needed in our project. Our aim was to never exceed the LOCK IN amplifier's input limits. Current and voltage characteristics are down in figure 8. The zener diode we used had its datasheets, which you can see from Appendix. Its power rating is ... .[9]



Figure 7: Our zener diode

The zener diode was given proper voltages to work in reverse bias, specifically in the breakdown region. The overall circuit was identical to that of voltage regulator by zener diode. We gave particularly 5.0 V, 5.5V in two different runs from the powersource. The Zener diode regulated around 4.9 V.

Now, what we need is that fluctuation over the regulated DC voltage. These fluctuations have to be some function in the frequency domain as we assumed. This function must be made of different harmonics of sinusoidal waves with different phases and frequencies as thought by Fourier and his analysis. So basically we needed a system to measure different amplitudes of these harmonics at different frequencies to model our fluctuations. We needed a complete frequency spectrum at the particular bandwidth we are looking for in this analysis. The LOCK IN amplifier gives exactly that.

### 3.1.1. Theoretical noise spectral densities for our setup

From equation 10, we can calculate total noise spectral density. we can get white noise spectral density via adding our thermal, shot, avalanche etc white noise source.

- Shot noise and avalanche noise: From theoretical section we have equation 7 and corrected with multiplicative factor  $M$  after avalanche noise. Here, We have current values from current and voltage values from figure 8. At 5.4V it is  $\approx -4.186mA$ . Also,  $e = -1.602 \times 10^{-19}C$  and  $M$  for silicon based zener diode is about 5 to 10,

$$S(f) = 2(M + 1)eI_0$$

$$2(6)e|I_0| \geq S(f) \geq 2(11)e|I_0|$$

$$8.0371 \times 10^{-21}V^2/Hz \geq S(f) \geq 1.4735 \times 10^{-20}V^2/Hz$$

$$0.8965 \times 10^{-10}V/\sqrt{Hz} \geq \sqrt{S(f)} \geq 1.2139 \times 10^{-10}V/\sqrt{Hz}$$

- Thermal noise: If we compute this values for our values,  $K_B = 1.38064910^{-23}m^2kgs^{-2}K^{-1}$  and Trend from current and voltage relation is  $0.00544V_z + 0.02519$  gives impedance  $R = 183.823\Omega$

$$S(f) = 4K_B R \quad (11)$$

$$S(f) \approx 1.0147 \times 10^{-20}V^2/Hz \quad (12)$$

$$\sqrt{S(f)} \approx 1.0073 \times 10^{-10}V/\sqrt{Hz} \quad (13)$$

## 3.2. Measuring instrument: LOCK IN amplifier

LOCK IN amplifiers came in the 1930s and became very important in signal extraction from given frequency and phase. It is very helpful in measuring signals in a very noisy environment. It takes two inputs, one which is being measured and one which is given as a reference mono frequency signal. Reference signal gets multiplied with input signal and gives output through a process called Phase sensitive detection in which it uses homodyne detection scheme and filters out signal as DC component. We will see in a bit.[12][10][5][11]

### 3.2.1. Phase sensitive detection

In nutshell it uses frequency multiplication and generates double side bands which then pass through a low pass filter to extract signal. In figure ?? you can see a signal first goes into a low noise differential amplifier which strengthens the signal. Signal Gets multiplied by another reference signal. This gives rise to two bands which pass through a low pass filter which cancels higher degree signal and only left is low frequency signal.

If we take signal  $V_s(t)$  with frequency  $w_s$ , amplitude  $A$  and phase  $\theta$ .

$$V_s(t) = A \cos(w_s t + \theta)$$

$$= \frac{A}{2}(e^{i(w_s t + \theta)} + e^{-i(w_s t + \theta)})$$

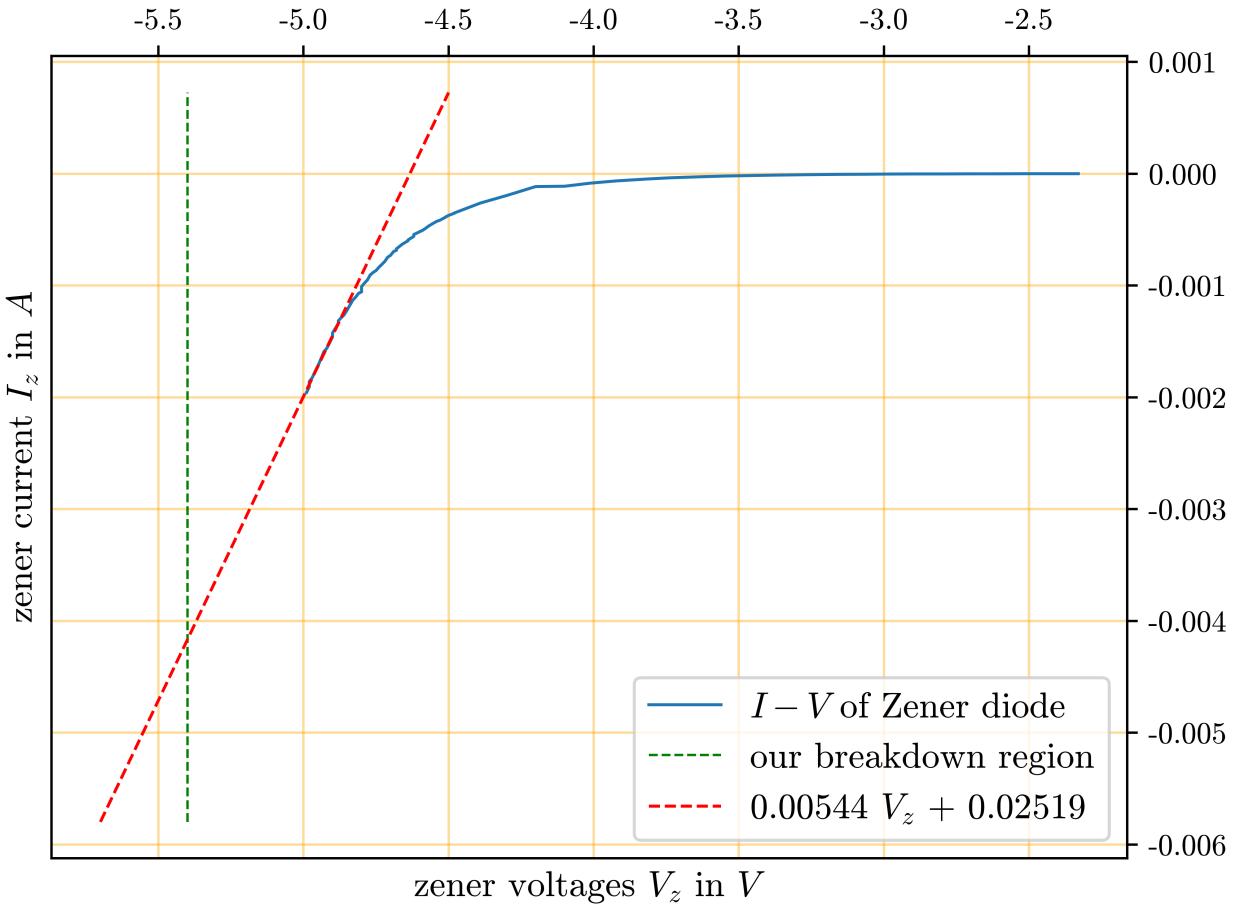


Figure 8: current and voltage characteristics of zener diode

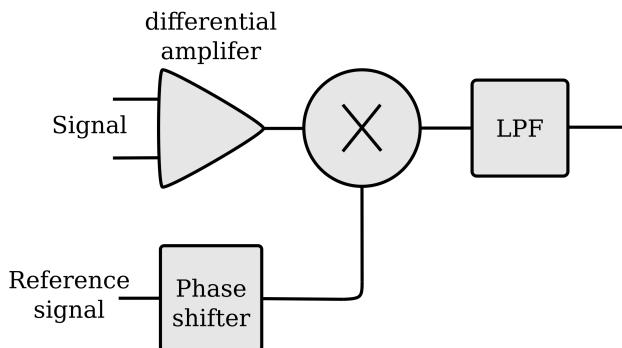


Figure 9: basic phase sensitive detector

Reference signal can be taken as following,

$$V_r(t) = B(e^{-i(w_r t + \phi)})$$

In common settings,  $\phi = 0$  and  $B = 1$ ,

$$V_r(t) = e^{i(-w_r t)}$$

Together after mixing the signals we have,

$$Z(t) = V_s(t)r(t)$$

$$= \frac{A}{2} (e^{i[(w_s - w_r)t + \theta]} + e^{-i[(w_s + w_r)t + \theta]})$$

$$= X(t) + Y(t)$$

Making  $w_s = w_r$  which makes subtraction vanishes and only one term with higher frequency lefts. Passing this signal through a low pass filter with very low cutoff gives only DC components and rejects noise even from neighbouring frequencies.

$$Z(t) = \frac{A}{2}(e^{i\theta})$$

Two component  $X(t)$  and  $Y(t)$  becomes,

$$X(t) = (Z(t))$$

$$= \frac{A}{2} \cos(\theta)$$

And,

$$Y(t) = (Z(t))$$

$$= \frac{A}{2} \sin(\theta)$$

So, Amplitude and Phase becomes,

$$\begin{aligned} R &= \sqrt{X(t)^2 + Y(t)^2} \\ &= \sqrt{\left(\frac{A}{2} \cos(\theta)\right)^2 + \left(\frac{A}{2} \sin(\theta)\right)^2} \\ &= \frac{A}{2} \\ \Theta &= \arctan\left(\frac{Y}{X}\right) \end{aligned}$$

So, the final product in PSD is the absolute amplitude of the signal and its phase.

### 3.2.2. Time Constant

Time constant ( $T$ ) is related to low pass filter in formal measurement system (PSD). most of the

LOCK IN amplifier uses  $n^{th}$  order butterworth's filter as low pass filter.

so time constant value will be solely determined by R, C components of it.

$$T = 2\pi RC$$

### 3.2.3. ENBW

ENBW calculations and correction is very important in noise measurements. Same noise measurement in different settings is completely different in different settings and also different instruments. Before understanding how it affects measurement, the full form of it will be important ENBW: Equivalent Noise Bandwidth. This is determined by the cut off frequency of the low pass filter and Roll off factor. The lock-in amplifier low pass filter is made of RC components ( $n^{th}$  order butterworth's filter). The roll off factor determined by order of low pass filter. For Gaussian noise, the equivalent noise band-width (ENBW) of a low pass filter is the bandwidth of the perfect rectangular filter which passes the same amount of noise as the real filter.

This also determines measurement time delay. For example with 100ms time constant and 12dB/oct roll off it almost takes 0.7s to get its 99

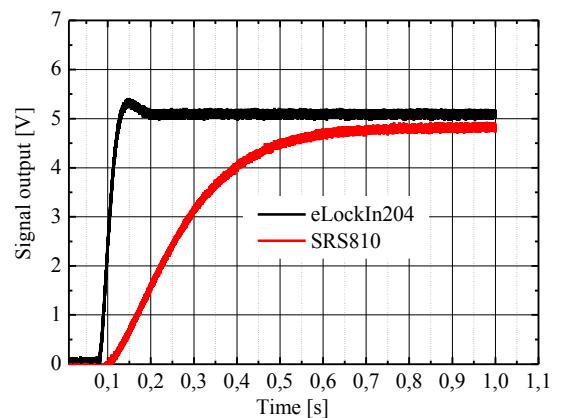


Figure 10: This is how ENBW and response time related, here two LOCK in amplifier are given give ref

For SR830, this time constant and ENBW relation is given by the following table.

Slope	ENBW	Wait Time
6 dB/oct	$1/4T$	$5T$
12 dB/oct	$1/8T$	$7T$
18 dB/oct	$3/32T$	$9T$
24 dB/oct	$5/64T$	$10T$

Here, T is time constant which is known. Output of LOCK IN amplifier is must be corrected by this values of ENBW for approximately true value of measurement.

### 3.2.4. How LOCK IN amplifier measure noise

LOCK IN amplifier can measure both amplitude and phase. As we have see from Phase Sensitive detection topic, It measures  $R$  as amplitude, but typical measurement also measure its  $X$  and  $Y$  components. So,  $R^2 = X^2 + Y^2$ , this give absolute amplitude. LOCK IN do time averaging to this measurement which is final  $R$ . The problem with only  $R$  is that it does not give any information about its mean (typically mean is zero for noise measurement but offset is probable). We assume in our measurement that there is zero offset from mean, which means zero mean. [15]

Suppose noise power is following,

$$P_w(t) = n_w^2(t)$$

$$P_w = \frac{1}{T} \int_T P_w(t) dt$$

$$P_w = R^2 = X^2 + Y^2$$

We have ensemble average values after doing multiple value mean. So, final power density

$$P_n = \mathbb{E}(P_w)$$

$$S_n = \frac{P_n}{2 \times ENBW}$$

$$S_n = \frac{\mathbb{E}(R^2)}{2 \times ENBW}$$

Here,  $S_n$  is Power spectral density measured in  $V^2/Hz$ . Spectral density is just  $\sqrt{S_n}$  and measured in  $V/\sqrt{Hz}$ .

### 3.2.5. LOCK IN amplifier over traditional measuring device/system

For noise analysis LOCK IN amplifiers are the optimal choice. Traditional approaches deal with the first measurement of a small signal in the time domain. This signal gets amplified with additional noise from the amplifier. Also, amplifiers attenuates signals with its limited bandwidth which is a measure of concern for certain use case scenarios. This attenuated signal gets into some detector. For signal analysis, this signal must go into other processes like analog to digital conversion then Fourier transformation. This whole process gives too much concerned noise which is not related to devices being analysed in our case the voltage regulator circuit. Alternative approach is to go with a LOCK IN amplifier. Which cancels out most burdens of traditional measurement steps. This whole combined help in reducing internal noise and increasing S/N ratio.

*Pros of LOCK IN amplifier:*

- LOCK In amplifiers reduces attenuation of signal with increasing frequency since it does not measure signal in the whole frequency spectrum.
- Increase S/N ratio over traditional amplifier circuit
- Gives direct data into frequency domain

*Cons of LOCK IN amplifier:*

- Relatively expensive
- Does not give information in time domain
- Relatively slow for whole analysis of frequency domain (low but accurate resolution of frequency domain)

### 3.3. SR830

We used a LOCK IN amplifier from Stanford Research Systems. It is used to detect low amplitude signals as low as  $10nV/Hz$  and frequency

as low as  $1\text{mHz}$ . and measure very small AC signals - upto few nanovolts. Accurate measurements may be made even when the small signal is obscured by noise sources many thousands of times larger.

Internal block diagram of SR830,

### 3.3.1. Inputs

The LOCK IN amplifier takes two inputs, one for the main signal and another for reference signal. SR830 has an internal oscillator for reference signal (1 mHz to 102 kHz), this means that only one input is needed to be given. SR830 also takes external reference signals up to (up to 300 kHz), which can be useful for slightly higher frequencies.

It can sense inputs from  $2\text{nV}$  to as high as  $1\text{V}$ . The current input on the SR830 uses the A input BNC. The current input has a  $1\text{ k}\Omega$  input impedance and a current gain of either  $10^6$  or  $10^8$  Volts/Amp. Currents from  $1\text{\mu A}$  down to  $2\text{ fA}$  full scale can be measured.

for more informations go to manual of SR830.[11]

### 3.3.2. Outputs

SR830 can give outputs from range  $\pm 10\text{V}$  full scale and  $10\text{mA}$  max current. the output can be showed to either both displays or can be output via BNC cables or can be logged out via interface.

### 3.3.3. Interfacing

The SR830 DSP Lock-in Amplifier may be remotely programmed via either the RS232 or GPIB (IEEE-488) interfaces. Any computer supporting one of these interfaces may be used to program the SR830. Both interfaces are receiving at all times, however, the SR830 will send responses to only one interface. Specify the output interface with the [Setup] key or use the OUTX command at the beginning of every program to direct the responses to the correct interface. The SR830 supports the IEEE-488.1 (1978) interface standard. It also supports the required common commands of the IEEE-488.2 (1987) standard. Before attempting to communicate with the SR830 over the GPIB interface, the SR830's device address must be set. The address is set with the [Setup]

key and may be set between 1 and 30. The SR830 supports the IEEE-488.1 (1978) interface standard. It also supports the required common commands of the IEEE-488.2 (1987) standard. Before attempting to communicate with the SR830 over the GPIB interface, the SR830's device address must be set. The address is set with the [Setup] key and may be set between 1 and 30. The SR830 is configured as a DCE ( transmit on pin 3, receive on pin 2) device and supports CTS/ DTR hardware handshaking. The CTS signal (pin 5) is an output indicating that the SR830 is ready, while the DTR signal (pin 20) is an input that is used to control the SR830's data transmission. If desired, the handshake pins may be ignored and a simple 3 wire interface (pins 2,3 and 7) may be used. The RS232 interface baud rate and parity must be set. These are set with the [Setup] key. The RS232 word length is always 8 bits. To assist in programming, the SR830 has 4 interface status indicators. The ACTIVE indicator flashes whenever a character is received or transmitted over either interface. The ERROR indicator flashes when an error, such as an illegal command, or parameter out of range, has been detected. The REMOTE indicator is on whenever the SR830 is in a remote state (front panel locked out). The SRQ indicator is on when the SR830 generates a service request. SRQ stays on until a serial poll is completed. Communications with the SR830 uses ASCII characters. Commands may be in either UPPER or lower case and may contain any number of embedded space characters. A command to the SR830 consists of a four character command mnemonic, arguments if necessary, and a command terminator. The terminator must be a linefeed <lf> or carriage return <cr> on RS232, or a linefeed <lf> or EOI on GPIB.

Example of commands,

FREQ 10E3 <lf>	Set the internal reference frequency to 10000 Hz (10 kHz)
*IDN? <lf>	Queries the device identification

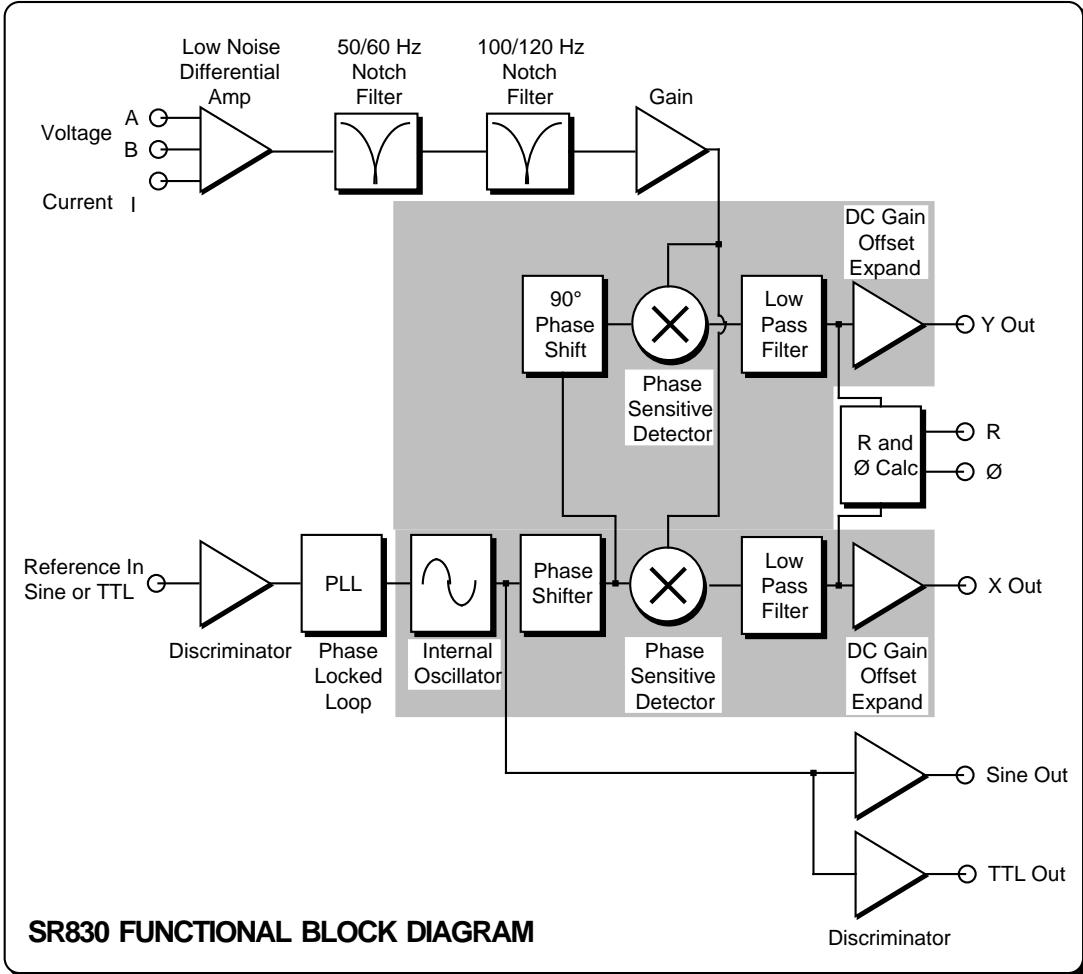


Figure 11: Internal Block diagram of SR830

## 4. Results and Analysis

We have surveyed voltage regulated circuits we made with zener diodes and found some satisfactory results. We take different results for different bandwidths. For context this is raw data from different bandwidth. Here, for each set of frequencies in bandwidth we took almost 50 to 100 readings.

### 4.1. Low frequency: up to 10k hertz

We are mainly focused low frequency results since we are only interested in regulated power supply applications. We had original assumption that in low frequency flicker noise is highly dominating.[3][4]

Here initial results were quite random, which means we have to filter our data a bit. For this reason we used a basic filtering method. In this method the data are sorted out as minimum deviation from their minimum then we took the upper 5 to 10 results and took the mean of it. The basic implementation is as following,

Let,  $X(f)$  as data point for specific  $f$  and  $Y(f)$  be sorted data with  $n$  number of results,

$$\langle X(f) \rangle = \sum_{i=0}^{N-1} X^{(i)}(f)$$

$$Y_n(f) = \min(t \text{ such that } \#\{s = |X(f) - \langle X(f) \rangle| \mid s \geq t\} = n)$$

$$\langle Y(f) \rangle = \sum_{i=0}^n Y^{(i)}(f)$$

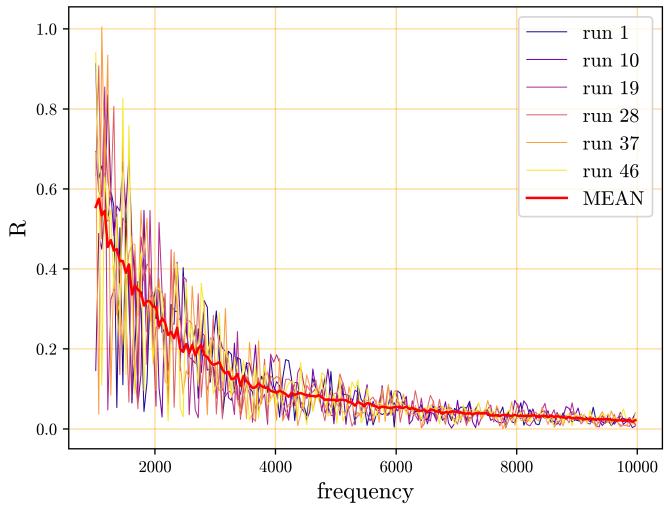


Figure 12: This is row data for 1k to 10k frequency band  
**TIME CONSTANT = 100 $\mu$ s and 12dB/oct**

This is how we implemented it with python. If you wanna checkout whole code then it is in the appendix.

```
1  for datapoint in data:
2      count+=1
3      if datapoint[0]==index:
4          temp_array.append(float(data_
5              ↵ point[1]))
6  else:
7      nlist = array(temp_array,dty_
8          ↵ pe=float)
9      m = mean(nlist)
10     sorted_deviation =
11         ↵ argsort(abs(nlist - m))
12     filtered_nlist = nlist[sorte_
13         ↵ d_deviation[:points]]
14     indexonelist =
15         ↵ array([index]*points)
16     final_list=
17         ↵ column_stack((indexoneli_
18             ↵ st,filtered_nlist))
```

Also, as discussed from the previous section we have to correct these terms with ENBW. Time constant ( $T$ ) = 100 and roll-off = 12 dB/oct

$$ENBW = \frac{1}{8T} = 1250\text{Hz}$$

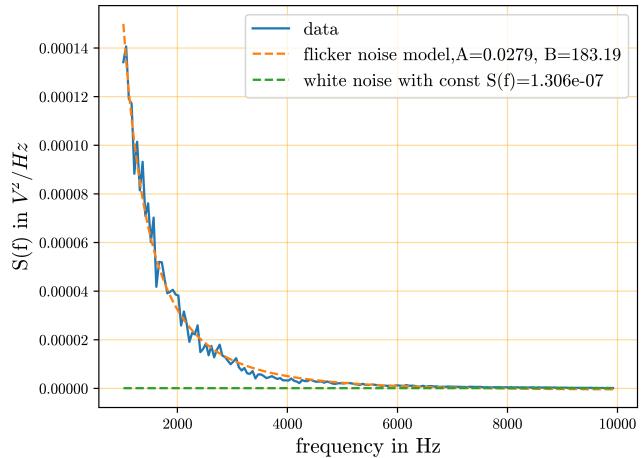


Figure 13: final analysed data for 1k to 10k hertz frequency with TIME CONSTANT =  $100\mu s$  and  $12dB/oct$

Here we can see some traces of flicker noise.  
Parameterized as follows,

$$S(f) = S_{flicker}(f) + S_{burst}(f) + S_{white}$$

$$S(f) = \frac{A}{f} + \frac{B}{f^2} + S_{white}$$

Here,  $A$  determines the magnitude of flicker noise and  $B$  determines the magnitude of burst noise.

$$S_{flicker}(f) = \frac{0.024474431610177427}{f} \quad (14)$$

$$S_{burst}(f) = \frac{179.6472361690183}{f^2} \quad (15)$$

$$S_{white}(f) = 1.305593689e - 07 \quad (16)$$

#### 4.2. Very low frequency: upto 1 hertz

Let's take a second data set where we have sub hertz frequency data. This data set have each frequency with corresponding 50 values. Raw data looks like figure 14.

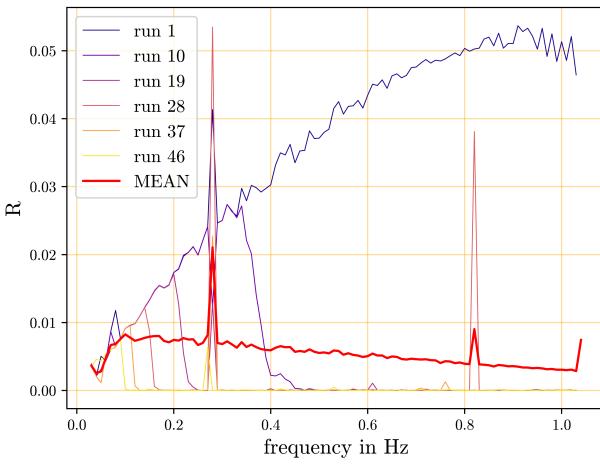


Figure 14: This is raw data for sub one hertz band with TIME CONSTANT = 100ms and roll off factor 12dB/oct

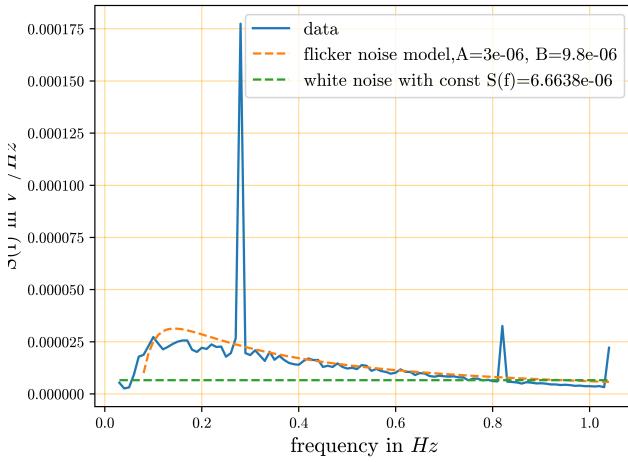


Figure 15: final analysed data for sub one hertz band with TIME CONSTANT = 100ms and roll off factor 12dB/oct

Final data will be look like this,

For analysing data ENBW is calculated for TIME CONSTANT = 100ms and roll off factor 12dB/oct,

$$ENBW = \frac{1}{8T} = 1.25\text{Hz}$$

Parameters are following,

$$S_{flicker}(f) = \frac{9.83301255e - 06}{f^1} \quad (17)$$

$$S_{burst}(f) = \frac{7.03135395e - 07}{f^2} \quad (18)$$

$$S_{white}(f) = 3.03149895e - 06 \quad (19)$$

### 4.3. High frequency data: up to 100k hertz

Same as we discussed previously raw data is given here, we have up to 50khz frequency domain data,

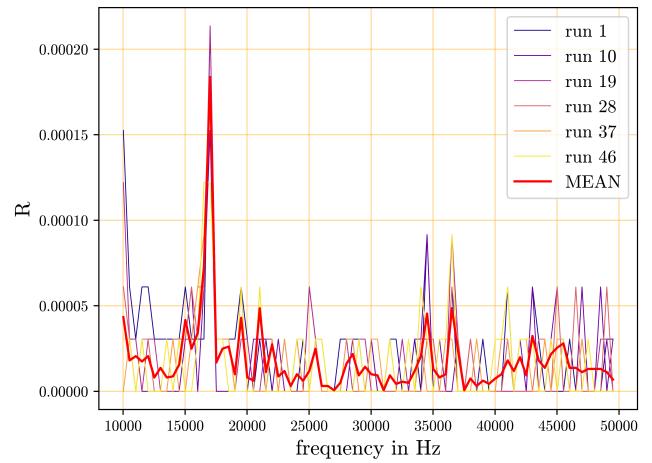


Figure 16: This is raw data for high frequency band with TIME CONSTANT = 100ms and roll off factor 12dB/oct

same as previous sections, we sorted data and take ENBW calculations at here.

the noise spectral density is as following.

$$S_{flicker}(f) = \frac{1.17694942e - 05}{f^1} \quad (20)$$

$$S_{burst}(f) = \frac{4.40498840e - 02}{f^2} \quad (21)$$

$$S_{white}(f) = 3.5367046e - 10 \quad (22)$$

## 5. Conclusions

Our analysis on noise spectrum analysis gave us insight of intrinsic noises in the circuit and zener

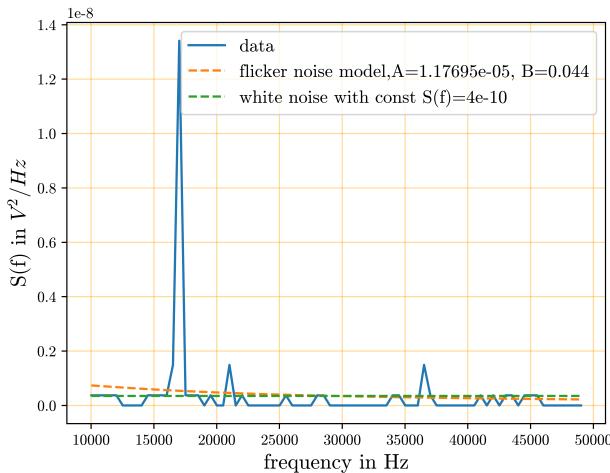


Figure 17: final analysed data for high frequency band with TIME CONSTANT =  $100ms$  and roll off factor  $12dB/oct$

diode. In results, we have got parameterised noise as our theoretical model was built.

In 1k to 10k data, we have specified magnitude flicker noise power AKA  $1/f$ , which is at  $0.024474431610177427$ . We have also observed  $1/f^2$  noise in the system and it is at  $179.6472361690183$ . white noise level in first data set ( $10kHz$ ), which is  $1.305593689e - 07V^2/Hz$ .

The most mysterious results came from second data sets, very low frequency data sets. Here, Raw data is quite opposite of any frequency dependent noise models. Our assumption here is that as frequency increases the white noise gets saturated to its related power. This means that white noise is not quite white as it seems. Assumption is also made that frequency dependence of flicker noise is not quite like that of distribution as theory discussed. Well, we have to dig deep into that. Analysed data gave magnitude for both  $1/f$  and  $1/f^2$  are  $9.83301255e - 06$  and  $7.03135395e - 07$  respectively. White noise bed is following at  $3.03149895e - 06V^2/Hz$ .

Last data gets following values  $1.17694942e - 05$  and  $4.40498840e - 02$  for  $1/f$  and  $1/f^2$  noise levels. It satisfies first data sets and closely correlate with the theoretical model. We have white noise level is similar to that of first data sets, but one

trend which we see in it is that as frequency get increased the white noise level decreases. This can be result from that of correlation from flicker noises and understandable as we can only get one noise source to strip down. (white noise level at  $3.5367046e - 10V^2/Hz$ ).

Further studies can be conducted to anomalous behaviour at very low frequency noise  $\approx 1Hz$ . This can be important in regulated power supply usage since 1Hz is very near to DC level.

We hope that our contribution to Open source community is well received and gets more contribution to our package **PyInstro**.

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# Appendix

## PyInstro

PyInstro is a package we made to communicate, control and data logging to any scientific instrument easily. The main work of it is giving utility for data logging and ease SCPI. Also, it does streamline instruments after extending it. It is just a cover for the PYVISA backend but it gives instrument specific tools. whole package in the following link, This is code for just the GPIB connection which we used. (it is also extensible to the RS232, LAN and USB ). You can find PyInstro in following repository, <https://github.com/vijaypanchalr3/pyinstro>.

*GPIB.py*

```
1 import pyvisa
2 import sys
3 from termcolor import cprint
4
5 class GPIB:
6     def __init__(self) -> None:
7         try:                                # GPIB connection check
8             cprint("-----checking GPIB connections-----",color="yellow")
9             resources = pyvisa.ResourceManager()
10            interface = None
11            resourceslist = resources.list_resources()
12            cprint(resourceslist,'blue',attrs=['bold'])
13            if resourceslist==():
14                cprint("ERROR: please check GPIB connection", "red")
15                sys.exit()
16            else:
17                while True:
18                    try:
19                        choise = int(input("please, choose your device from this
→   list: ")) - 1
20                        if choise > len(resourceslist):
21                            TypeError
22                        interface = resourceslist[choise]
23                        cprint("-----choose resource-----", color="green", attrs=["bold"])
24                        cprint("-----following device is
→   connected-----",color="green",attrs=["bold"])
25                        cprint(interface)
26                        break
27                    except:
28                        cprint("choose with interger and from
→   following...", "red")
29
30                    self.interface = resources.open_resource(interface)
31                except:
```

```

32         cprint("ERROR in detecting GPIB, there must be problem with setup of
33             ↵  pyvisa or there is no connection of gpib\n you should look
34             ↵  either in pyvisa documentation or try for RS232
35             ↵  interface","red",attrs=['bold'])
36         sys.exit()
37
38     def ping(self)-> None:
39         self.interface.write("*IDN?\n")
40
41     def read(self)-> None:
42         self.interface.read()
43
44     def reset(self)-> None:
45         self.interface.write("*RST\n")
46
47     def clear_status(self)-> None:
48         self.interface.write("*CLS\n")
49
50     def close(self)->None:
51         self.interface.close()
52

```

This is SR830 device commands,  
*SR830.py*

```

1  from pyinstro.utils import sysarg
2  from pyinstro.utils import datafile
3
4  new_instance = sysarg.CLI()
5
6  if new_instance.get_connection() == "GPIB":
7      from pyinstro.interfaces import gpib
8
9  class SR830(gpib.GPIB):
10      def __init__(self) -> None:
11          super().__init__()
12
13          file_init = datafile.Get_File(new_instance.get_file())
14
15          self.get_levels = new_instance.get_levels
16          self.get_partitions = new_instance.get_partitions
17          self.writerow = file_init.writerow
18          self.longwriterow = file_init.longwriterow
19          self.fmin = new_instance.get_fmin
20          self.fmax = new_instance.get_fmax

```

```

21         self.freq = new_instance.get_freq
22
23     def local_defaults(self) -> None:
24         pass
25
26     def local_arguments(self) -> None:
27         new_instance.ArgumentParser.add_argument('-fl', '--fmin', metavar='',
28             type=float, default=4545, help="give lower limit for reference
29             frequency")
30         new_instance.ArgumentParser.add_argument('-fr', '--freq', metavar='',
31             type=float, default=7888, help="give reference frequency")
32         new_instance.ArgumentParser.add_argument('-fh', '--fmax', metavar='',
33             type=float, default=1, help="give upper limit for reference
34             frequency")
35
35     def set_frequency(self, value, errdelay = 3) -> None:
36         """change reference frequency"""
37         self.interface.write("FREQ "+ "{:.4E}".format(value))
38         pass
39
39     def autogain(self) -> None:
40         self.interface.write("AGAN")
41
42     def set_phase(self,value) -> None:
43         self.interface.write("PHAS "+str(value))
44         pass
45
46     def time_constant(self,choise) -> None:
47         self.interface.write("OFLT "+str(choise))
48         pass
49
50
51     def sensitivity(self,choise) -> None:
52         self.interface.write("SENS "+str(choise))
53         pass
54
55     def set_sample_rate(self, choise) -> None:
56         self.interface.write("SRAT "+str(choise))
57
58     def start_data_acquisition(self) -> None:
59         self.interface.write("STRT")
60         pass
61
62     def pause_data_acquisition(self) -> None:
63         self.interface.write("PAUS")
64         pass
65
66     def reset_data_acquisition(self) -> None:

```

```

63         self.interface.write("REST")
64     pass
65
66     def get_data(self) -> None:
67         pass
68
69     def get_data_explicitly(self, data_variable=3, errdelay=3):
70         """
71             two params, give resource object and the second params is
72             → parameter to variable read,
73             default to data_variable = 3 which is equievalent to reading R.
74             as SR830manual,
75             data_variable = 1 => X,
76             data_variable = 2 => Y,
77             data_variable = 3 => R,
78             data_variable = 4 => phase
79         """
80
81         return self.interface.query("OUTP? "+str(data_variable))
82
83 else:
84
85     from pyinstro.interfaces import rs232
86
87     class SR830(rs232.RS232):

```

This is some utilities to ease control of scientific instruments,  
Filewrite simple data logger: *getfile.py*

```

1  from pyinstro.utils import getpath
2
3
4
5  import csv
6  import os
7
8
9
10 class Get_File:
11     """
12         INFO: just to write file, must be CSV
13     """
14     def __init__(self,file) -> None:
15         _project_dir_path_abs = getpath.getpath()
16
17         if os.path.exists(os.path.join(_project_dir_path_abs, "data")):
18             _data_dir_path_abs = os.path.join(_project_dir_path_abs, "data")
19         else:

```

```

20     os.mkdir(os.path.join(_project_dir_path_abs, "data"))
21     _data_dir_path_abs = os.path.join(_project_dir_path_abs, "data")
22
23     if file=='default':
24         file = "auto0.csv"
25         count = 0
26         while os.path.exists(os.path.join(_data_dir_path_abs,f"auto{count}.c
27             ↵ sv")):
28             count+=1
29             file = f"auto{count}.csv"
30
31
32     # i did not used re module down here
33     if not ((file[len(file)-1]=='v')and(file[len(file)-2]=='s')and(file[len(
34             ↵ file)-3]=='c')and(file[len(file)-4]=='.')):
35         file = file+".csv"
36     else:
37         pass
38
39     self.filepath = file
40     self.firsttime = True
41
42     def writerow(self, data)-> None:
43         """
44             open file one time ad write it
45         """
46         if self.firsttime:
47             self.file = open(self.filepath,'w',newline='')
48             self.writer = csv.writer(self.file)
49             self.writer.writerow(data)
50             self.firsttime = False
51             print(self.filepath)
52         else:
53             self.writer.writerow(data)
54
55     def longwriterow(self,data)->None:
56         """
57             for long data, i think it is suitable to write file each time open and
58             ↵ close
59         """
60         with open(self.filepath,'a',newline="") as datafile:
61             self.writer = csv.writer(datafile)
62             self.writer.writerow(data)

```

DEFAULT setting: *defaults.py*

```
1  from pyinstro.utils import getpath
2
3  import os
4  import configparser
5
6  class DefaultParams:
7      """
8          specify default parameters
9
10         for more info:
11             refer to SR830 manual for more info.
12             """
13
14         time_constant = 5
15         sensitivity = 5
16         # filter_slope =
17
18         baud_rate = 9600
19         sample_rate = 10
20         gpib_address = 1
21         time_delay = 1
22
23         connection = 1           # means GPIB, 1: GPIB, 2: RS232, 3: USB, 4: LAN
24         connections = {1:"GPIB", 2:"RS232", 3:"USB", 4:"LAN"}
25
26         fmin = 01E+3
27         fmax = 01E+5
28
29         partitions = 4
30         levels = 4
31
32         data= 3
33
34     def __init__(self) -> None:
35         self.defaults_params_list= [attr for attr in dir(self) if not
36             ↪ callable(getattr(self, attr)) and not attr.startswith("__")]
37         #defaults_params= dict(zip(defaults_params_list, list(
38             ↪ "*len(defaults_params_list))))"
39
40         self.target_path = getpath.getpath()
41         config_file = os.path.join(self.target_path,"config.ini")
42
43         print("checking config.ini file")
44
45         if os.path.exists(config_file):
46             config = configparser.ConfigParser()
```

```

44 config.read(config_file)
45 config_file_dict = config.defaults()
46 if len(config_file_dict)==len(self.defaults_params_list):
47     for keys in config_file_dict:
48         if (config_file_dict[keys].isspace() or not
49             config_file_dict[keys]):
50             pass
51         else:
52             setattr(self, keys, config_file_dict[keys])
53             print(keys+": "+config_file_dict[keys])
54     else:
55         for keys in self.defaults_params_list:
56             if not (keys in config_file_dict):
57                 with open(config_file, "w") as _conf_file:
58                     config.set("DEFAULT",keys, " ")
59                     config.write(_conf_file)
60             else:
61                 if (config_file_dict[keys].isspace() or
62                     config_file_dict[keys] == ""):
63                     pass
64                 else:
65                     setattr(self, keys, config_file_dict[keys])
66                     print(keys+": "+config_file_dict[keys])
67     else:
68         pass
69
70     def makeconfig(self):
71         config_file =os.path.join(self.target_path,"config.ini")
72         config = configparser.ConfigParser()
73         if os.path.exists(config_file):
74             config.read(config_file)
75             config_file_dict = config.defaults()
76             if len(config_file_dict)==len(self.defaults_params_list):
77                 pass
78             else:
79                 for keys in self.defaults_params_list:
80                     if not (keys in config_file_dict):
81                         with open(config_file, "w") as _conf_file:
82                             config.set("DEFAULT",keys, " ")
83                             config.write(_conf_file)
84
85                     else:
86                         pass
87             print("I had appened to full option to config file!")
88     else:
89         with open(config_file,'w') as config_file:

```

```

91         config_file.write("[DEFAULT]\n")
92         for params in self.defaults_params_list:
93             config_file.write(params+" = \n")
94         print("I had made config file in present directory !")
95

```

You can use this package following way. I made simple sampler for data acquision.

```

1  from pyinstro import SR830
2
3  import numpy
4  import sys
5  import time
6
7  class sampler:
8      """
9          function: very simpler data logger for SR830
10             write file, as what given from terminal or auto{number}.csv in
11                 ↳ present directory under data directory.
12     limitation: too much hard coded
13     """
14
15     def __init__(self) -> None:
16         self.device = SR830()
17         time.sleep(2)
18         self.device.ping()
19         time.sleep(0.5)
20         print(self.device.read())
21         time.sleep(2)
22         self.device.longwriterow(["Frequency", "RinV"])
23
24     def discrete_range(self, minimum, maximum, step):
25
26         self.device.set_frequency(minimum)
27         time.sleep(.8)
28         self.device.autogain()
29         input()
30         for freq in range(minimum, maximum, step):
31             self.device.set_frequency(freq)
32             print(freq)
33             time.sleep(.5)
34             self.device.autogain()
35             time.sleep(1)
36             for j in range(1):
37                 for i in range(50):
38                     data= float(self.device.get_data_explicitly(3))
39                     self.device.longwriterow([freq,data])
40                     # print(freq,data)

```

```

39             time.sleep(0.1)
40
41     def partition_loop(self, minimum, maximum, partitions, timedelay=0.2):
42         # time.sleep(2)
43         frange = numpy.linspace(minimum, maximum, partitions)
44         count = 1
45         for freq in frange:
46             self.device.set_frequency(freq)
47             time.sleep(timedelay)
48             for i in range(100):
49                 data = float(self.device.get_data_explicitly(3))
50                 self.device.longwriterow([freq, data])
51                 print(data)
52                 input()
53                 time.sleep(timedelay)
54                 if count==50:
55                     input("check setup and press enter")
56                     count = 1
57                 else:
58                     count+=1
59
60
61
62     if __name__=="__main__":
63         x = sampler()
64         x.discrete_range(1018,2018,50)
65         sys.exit()

```

## Code for data analysis

This is code for where I made my tools for data analysis. This tools presents with me file opening, file reading, taking mean over single frequency data, sorting my data with deviation method, plotting single data points form points etc. all the data and code is at following github link <https://github.com/vijaypanchalr3/shotnoise>.

*tools.py*

```

1  import csv
2  import re
3  from numpy import array,mean,abs,split,vstack,argsort,column_stack
4
5  __all__=[

6      "files"
7
8  ]
9
9  class files:
10
11     """
12
13     PARAMETER: filename as Relative path to __file__
14     RETURN: nil

```

```

13 FUNCTION: read files named filename, write other files with data
14 """
15 def __init__(self,filename:str,datatype=float) -> None:
16     self.datatype = datatype
17     self.filename = filename
18
19     with open(filename, 'r',) as newfile:
20
21         self.fobject = list(csv.reader(newfile))
22
23         # omit first member
24         try:
25             datatype(self.fobject[0][0])
26             self.header = None
27         except ValueError:
28             self.header = self.fobject.pop(0)
29
30         self.length = sum(1 for row in self.fobject)
31
32     def file_add(self,nameaddition:str="extra"):
33         _finalfile = re.split("\/",self.filename)
34         finalfile = re.split("\.", _finalfile[len(_finalfile)-1])
35         self.finalfile = "/".join(str(_finalfile[i]) for i in
36             range(len(_finalfile)-1))+"/"+finalfile[0]+nameaddition+finalfile[1]
37
38     def write_another(self,data:list)-> None:
39         with open(self.finalfile, 'wxs', newline="") as cleandata:
40             writer = csv.writer(cleandata)
41             writer.writerow(data)
42
43     def get_mean(self):
44         data = array(self.fobject)
45         try:
46             first_array,second_array = split(data,2,axis=1)
47         except IndexError:
48             print("from get_mean()::empty array from data")
49
50         extra_array,_first_array,_second_array = [],[],[]
51         count = 0
52         _first_array.append(first_array[count][0])
53         for i in range(0,len(data)):
54             if first_array[i][0]==_first_array[count]:
55                 extra_array.append(second_array[i][0])
56             else:
57                 _second_array.append(mean(array(extra_array,dtype=float)))
58                 count+=1
59                 _first_array.append(first_array[i][0])

```

```

59             extra_array=[]
60
61         if i==len(first_array)-1:
62             _second_array.append(mean(array(extra_array,dtype=float)))
63
64     return vstack((array(_first_array,dtype=float),array(_second_array,dtype_
65             =float))).T
66
67     def sort_on_deviation(self, points=5):
68         data = array(self.fobject, dtype=float)
69         filtered_data=[]
70         temp_error = []
71         index = float(data[0][0])
72         count = 0
73         for datapoint in data:
74             count+=1
75             if datapoint[0]==index:
76                 temp_error.append(float(datapoint[1]))
77             else:
78                 nlist = array(temp_error,dtype=float)
79                 m = mean(nlist)
80                 sorted_deviation = argsort(abs(nlist - m))
81                 filtered_nlist = nlist[sorted_deviation[:points]]
82                 indexonelist = array([index]*points)
83                 final_list= column_stack((indexonelist,filtered_nlist))
84                 for member in final_list:
85                     filtered_data.append(member)
86                 index = float(datapoint[0])
87                 temp_error = []
88
89             if count == len(data)-1:
90                 nlist = array(temp_error,dtype=float)
91                 m = mean(nlist)
92                 sorted_deviation = argsort(abs(nlist - m))
93                 filtered_nlist = nlist[sorted_deviation[:points]]
94                 indexonelist = array([index]*points)
95                 final_list= column_stack((indexonelist,filtered_nlist))
96                 for member in final_list:
97                     filtered_data.append(member)
98     return array(filtered_data)
99
100    def shady_plot(self, color="Blues"):
101        """
102        """
103        data = array(self.fobject,dtype=float)

```

```

105     # [here] can be better memort handling !
106     common_array = []
107     index = float(data[0][0])
108     count = 0
109     for datapoint in data:
110         if float(datapoint[0]) == index:
111             try:
112                 common_array[count].append([float(datapoint[0]), float(datapo
113                                     ↵ int[1])])
114                 count+=1
115             except IndexError:
116                 common_array.append([])
117                 common_array[count].append([float(datapoint[0]), float(datapo
118                                     ↵ int[1])])
119                 count+=1
120             else:
121                 count=0
122                 index = float(datapoint[0])
123
124             delete = []
125             common_array.pop()
126             for i in range(len(common_array)-1):
127                 if len(common_array[len(common_array)-1])<len(common_array[i]):
128                     common_array[i].pop()
129             common_array = array(common_array)
130             from matplotlib import cm
131             colormap = cm.get_cmap(color, len(common_array))
132             return common_array,colormap
133
134     def point_mean(self,data):
135         freq = []
136         vo = []
137         freq.append(float(data[0][0]))
138         vo.append(float(data[0][1]))
139         count = 1
140         for i in range(1,len(data)):
141             lenth = len(freq)
142             if float(data[i][0]) == freq[lenth-1]:
143                 vo[lenth-1]+=float(data[i][1])
144                 count+=1
145             else:
146                 vo[lenth-1]=vo[lenth-1]/count
147                 count=1
148                 freq.append(float(data[i][0]))
149                 vo.append(float(data[i][1]))
150             freq.pop()
151             vo.pop()

```

```
150         return array(freq,dtype=float),array(vo,dtype=float)
151
152 if __name__=="__main__":
153     print("No Error")
```

# Zener diode datasheet



[www.vishay.com](http://www.vishay.com)

BZX55-Series

Vishay Semiconductors

## Small Signal Zener Diodes



### FEATURES

- Very sharp reverse characteristic
- Low reverse current level
- Very high stability
- Low noise
- Material categorization:  
for definitions of compliance please see  
[www.vishay.com/doc?99912](http://www.vishay.com/doc?99912)



**RoHS**  
COMPLIANT  
HALOGEN  
**FREE**

### APPLICATIONS

- Voltage stabilization

### LINKS TO ADDITIONAL RESOURCES



PRIMARY CHARACTERISTICS		
PARAMETER	VALUE	UNIT
$V_Z$ range nom.	2.4 to 75	V
Test current $I_{ZT}$	2.5; 5	mA
$V_Z$ specification	Pulse current	
Circuit configuration	Single	

ORDERING INFORMATION			
DEVICE NAME	ORDERING CODE	TAPED UNITS PER REEL	MINIMUM ORDER QUANTITY
BZX55-series	BZX55-series-TR	10 000 per 13" reel	30 000/box
BZX55-series	BZX55-series-TAP	10 000 per ammopack (52 mm tape)	30 000/box

PACKAGE				
PACKAGE NAME	WEIGHT	MOLDING COMPOUND FLAMMABILITY RATING	MOISTURE SENSITIVITY LEVEL	SOLDERING CONDITIONS
DO-35 (DO-204AH)	125 mg	UL 94 V-0	MSL level 1 (according J-STD-020)	Peak temperature max. 260 °C

ABSOLUTE MAXIMUM RATINGS ( $T_{amb} = 25$ °C, unless otherwise specified)				
PARAMETER	TEST CONDITION	SYMBOL	VALUE	UNIT
Power dissipation	$I = 4$ mm, $T_L = 25$ °C	$P_{tot}$	500	mW
Zener current		$I_Z$	$P_{tot}/V_Z$	mA
Junction to ambient air	$I = 4$ mm, $T_L = \text{constant}$	$R_{thJA}$	300	K/W
Junction temperature		$T_j$	175	°C
Storage temperature range		$T_{stg}$	-65 to +175	°C
Forward voltage (max.)	$I_F = 200$ mA	$V_F$	1.5	V



www.vishay.com

## BZX55-Series

Vishay Semiconductors

### ELECTRICAL CHARACTERISTICS ( $T_{amb} = 25^\circ\text{C}$ , unless otherwise specified)

PART NUMBER	ZENER VOLTAGE RANGE			TEST CURRENT		REVERSE LEAKAGE CURRENT		DYNAMIC RESISTANCE		TEMPERATURE COEFFICIENT	
	V <sub>Z</sub> at I <sub>ZT1</sub>			I <sub>ZT1</sub>	I <sub>ZT2</sub>	I <sub>R</sub> at V <sub>R</sub>		Z <sub>Z</sub> at I <sub>ZT1</sub>	Z <sub>ZK</sub> at I <sub>ZT2</sub>	TK <sub>VZ</sub>	
	V					mA		μA			
	MIN.	NOM.	MAX.							MAX.	MAX.
BZX55C2V4	2.28	2.4	2.56	5	1	< 50	< 100	1	< 85	< 600	- 0.09
BZX55C2V7	2.5	2.7	2.9	5	1	< 10	< 50	1	< 85	< 600	- 0.09
BZX55C3V0	2.8	3.0	3.2	5	1	< 4	< 40	1	< 85	< 600	- 0.08
BZX55C3V3	3.1	3.3	3.5	5	1	< 2	< 40	1	< 85	< 600	- 0.08
BZX55C3V6	3.4	3.6	3.8	5	1	< 2	< 40	1	< 85	< 600	- 0.08
BZX55C3V9	3.7	3.9	4.1	5	1	< 2	< 40	1	< 85	< 600	- 0.08
BZX55C4V3	4	4.3	4.6	5	1	< 1	< 20	1	< 75	< 600	- 0.06
BZX55C4V7	4.4	4.7	5	5	1	< 0.5	< 10	1	< 60	< 600	- 0.05
BZX55C5V1	4.8	5.1	5.4	5	1	< 0.1	< 2	1	< 35	< 550	- 0.02
BZX55C5V6	5.2	5.6	6	5	1	< 0.1	< 2	1	< 25	< 450	- 0.05
BZX55C6V2	5.8	6.2	6.6	5	1	< 0.1	< 2	2	< 10	< 200	0.03
BZX55C6V8	6.4	6.8	7.2	5	1	< 0.1	< 2	3	< 8	< 150	0.03
BZX55C7V5	7	7.5	7.9	5	1	< 0.1	< 2	5	< 7	< 50	0.03
BZX55C8V2	7.7	8.2	8.7	5	1	< 0.1	< 2	6.2	< 7	< 50	0.03
BZX55C9V1	8.5	9.1	9.6	5	1	< 0.1	< 2	6.8	< 10	< 50	0.03
BZX55C10	9.4	10	10.6	5	1	< 0.1	< 2	7.5	< 15	< 70	0.03
BZX55C11	10.4	11	11.6	5	1	< 0.1	< 2	8.2	< 20	< 70	0.03
BZX55C12	11.4	12	12.7	5	1	< 0.1	< 2	9.1	< 20	< 90	0.03
BZX55C13	12.4	13	14.1	5	1	< 0.1	< 2	10	< 26	< 110	0.03
BZX55C15	13.8	15	15.6	5	1	< 0.1	< 2	11	< 30	< 110	0.03
BZX55C16	15.3	16	17.1	5	1	< 0.1	< 2	12	< 40	< 170	0.03
BZX55C18	16.8	18	19.1	5	1	< 0.1	< 2	13	< 50	< 170	0.03
BZX55C20	18.8	20	21.2	5	1	< 0.1	< 2	15	< 55	< 220	0.03
BZX55C22	20.8	22	23.3	5	1	< 0.1	< 2	16	< 55	< 220	0.04
BZX55C24	22.8	24	25.6	5	1	< 0.1	< 2	18	< 80	< 220	0.04
BZX55C27	25.1	27	28.9	5	1	< 0.1	< 2	20	< 80	< 220	0.04
BZX55C30	28	30	32	5	1	< 0.1	< 2	22	< 80	< 220	0.04
BZX55C33	31	33	35	5	1	< 0.1	< 2	24	< 80	< 220	0.04
BZX55C36	34	36	38	5	1	< 0.1	< 2	27	< 80	< 220	0.04
BZX55C39	37	39	41	2.5	0.5	< 0.1	< 5	30	< 90	< 500	0.04
BZX55C43	40	43	46	2.5	0.5	< 0.1	< 5	33	< 90	< 600	0.04
BZX55C47	44	47	50	2.5	0.5	< 0.1	< 5	36	< 110	< 700	0.04
BZX55C51	48	51	54	2.5	0.5	< 0.1	< 10	39	< 125	< 700	0.04
BZX55C56	52	56	60	2.5	0.5	< 0.1	< 10	43	< 135	< 1000	0.04
BZX55C62	58	62	66	2.5	0.5	< 0.1	< 10	47	< 150	< 1000	0.04
BZX55C68	64	68	72	2.5	0.5	< 0.1	< 10	51	< 200	< 1000	0.04
BZX55C75	70	75	79	2.5	0.5	< 0.1	< 10	56	< 250	< 1500	0.04
											0.12

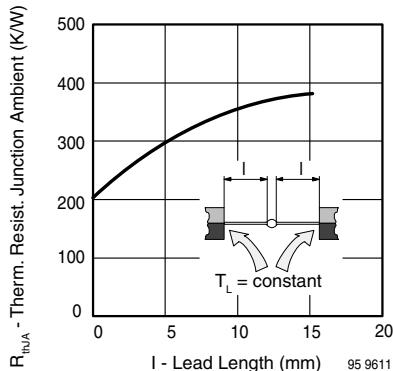
**BASIC CHARACTERISTICS** ( $T_{amb} = 25^{\circ}\text{C}$ , unless otherwise specified)


Fig. 1 - Thermal Resistance vs. Lead Length

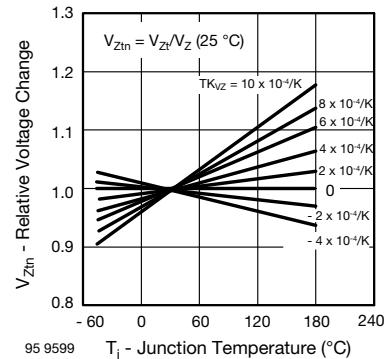


Fig. 4 - Typical Change of Working Voltage vs. Junction Temperature

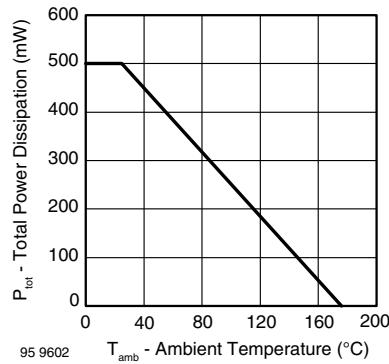


Fig. 2 - Total Power Dissipation vs. Ambient Temperature

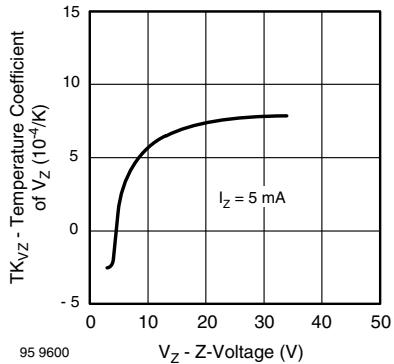
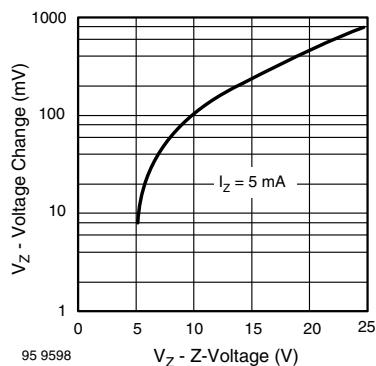
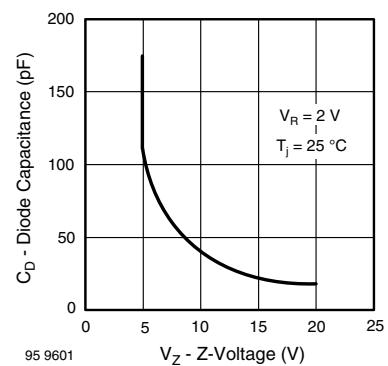

Fig. 5 - Temperature Coefficient of  $V_Z$  vs. Z-Voltage

Fig. 3 - Typical Change of Working Voltage under Operating Conditions at  $T_{amb} = 25^{\circ}\text{C}$ 


Fig. 6 - Diode Capacitance vs. Z-Voltage