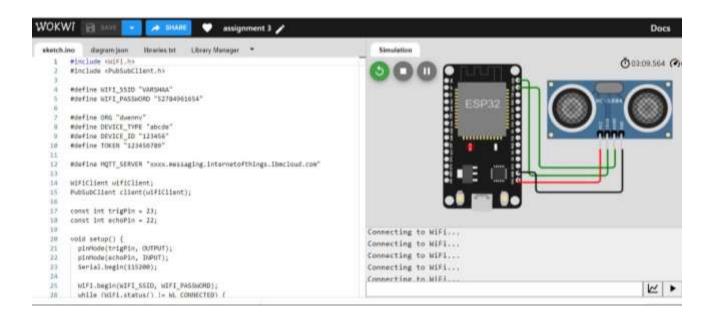
# **ASSIGNMENT 3**

Build a wokwi product, use ultrasonic sensor and detect the Distance from the object.

Whenever distance is less than 100cms upload the value to the ibm cloud.in recent device events upload the data from wokwi

Vijayalakshmi B Group 5

### **CONNECTIONS:**



#### **WOKWILINK:**

https://wokwi.com/projects/new/esp32

### **PROGRAM**

```
#include <WiFi.h>
#include <PubSubClient.h>
#define WIFI_SSID "VIJAYALAKSHMI"
#define WIFI_PASSWORD "52784961654"
#define ORG "dwennv"
#define DEVICE_TYPE "abcde"
#define DEVICE ID "123456"
#define TOKEN "123456789"
#define MQTT_SERVER "xxxx.messaging.internetofthings.ibmcloud.com"
WiFiClient wifiClient;
PubSubClient client(wifiClient);
const int trigPin = 23;
const int echoPin = 22;
void setup() {
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  Serial.begin(115200);
  WiFi.begin(WIFI SSID, WIFI PASSWORD);
  while (WiFi.status() != WL CONNECTED) {
  delay(1000);
    Serial.println("Connecting to WiFi...");
  }
  client.setServer(MQTT SERVER, 1883);
client.setCallback(callback); }
```

```
void loop() { long duration,
  distance; digitalWrite(trigPin,
  LOW); delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  duration = pulseIn(echoPin, HIGH);
  distance = duration * 0.034 / 2;
  Serial.print("Distance: ");
  Serial.print(distance);
  Serial.println(" cm");
  if(distance < 100) {</pre>
  publishMessage(distance);
  client.loop();
  delay(500);
}
void callback(char* topic, byte* payload, unsigned int length) {
  // Handle callback function here
}
void publishMessage(long distance) {
  String payload = "{\"distance\": " + String(distance) + "}";
  char topic[100];
  sprintf(topic, "iot-2/evt/status/fmt/json");
  client.connect(DEVICE_ID, TOKEN, "");
  client.publish(topic, (char*) payload.c str());
  client.disconnect();
}
```

## **IBM CLOUD**

