view_frames Result Recorded at time: 212.294 odom Broadcaster: /gazebo Average rate: 10.204 Hz Most recent transform: 212.220 (0.074 sec old) Buffer length: 4.900 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (212.294 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 0.000 (212.294 sec old) Most recent transform: 0.000 (212.294 sec old) Most recent transform: 212.200 (0.094 sec old) Most recent transform: 212.200 (0.094 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.800 sec Buffer length: 4.800 sec hokuyo left_wheel right_wheel camera