Vijayasri Iyer view_frames Result Recorded at time: 1648.039 map Broadcaster: /rtabmap/rtabmap Average rate: 20.204 Hz Most recent transform: 1648.099 (-0.060 sec old) Buffer length: 4.801 sec odom Broadcaster: /gazebo Average rate: 10.208 Hz Most recent transform: 1648.026 (0.013 sec old) Buffer length: 4.800 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1648.039 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 0.000 (1648.039 sec old) Most recent transform: 0.000 (1648.039 sec old) Most recent transform: 1648.026 (0.013 sec old) Most recent transform: 1648.026 (0.013 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.800 sec Buffer length: 4.800 sec hokuyo left_wheel right_wheel camera Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1648.039 sec old) Buffer length: 0.000 sec camera_rgbd_frame Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1648.039 sec old)

Buffer length: 0.000 sec

camera_link_optical