```
Import RPi.GPIO as GPIO
Import time
GPIO.setwarnings(False)
GPIO.setmode(GPIO.BOARD)
GPIO.setup(13, GPIO.IN)
GPIO.setup(12, GPIO.OUT)
While True:
    Pir_Sensor = GPIO.input(13)
    If Pir_Sensor ==1
        print("WARNING")
        GPIO.output(12,1)
        time.sleep(0.1)
    elif Pir_Sensor == 0
        print("NO WARNING")
        GPIO.output(12,0)
        time.sleep(0.1)
```