

HOME-WORK-2
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Problem 2-B =

$$P(x) = c_1 + c_2 x + \dots + c_n x^{n-1}$$

(a) = find an n -vector a for which, (where $\alpha < 0$)

$$a^T c = \int_{\alpha}^{\beta} P(x) dx, \text{ always holds.}$$

$$a^T c = \int_{\alpha}^{\beta} (c_1 + c_2 x + \dots + c_n x^{n-1}) dx = 0$$

$$a^T c = \left[c_1 x + c_2 \frac{x^2}{2} + c_3 \frac{x^3}{3} + \dots + \frac{c_n x^{n+1}}{(n+1)+1} \right]_{\alpha}^{\beta}$$

$$a^T c = \left[c_1 x + \frac{c_2 x^2}{2} + \frac{c_3 x^3}{3} + \dots + \frac{c_n x^n}{n} \right]_{\alpha}^{\beta}$$

$$a^T c = \left(c_1 \beta + \frac{c_2 \beta^2}{2} + \frac{c_3 \beta^3}{3} + \dots + \frac{c_n \beta^n}{n} \right) - \left(c_1 \alpha + \frac{c_2 \alpha^2}{2} + \frac{c_3 \alpha^3}{3} + \dots + \frac{c_n \alpha^n}{n} \right)$$

$$a^T c = c_1 (\beta - \alpha) + c_2 \left(\frac{\beta^2 - \alpha^2}{2} \right) + c_3 \left(\frac{\beta^3 - \alpha^3}{3} \right) + \dots + c_n \left(\frac{\beta^n - \alpha^n}{n} \right)$$

$$a^T c = (\beta - \alpha) c_1 + \left(\frac{\beta^2 - \alpha^2}{2} \right) c_2 + \left(\frac{\beta^3 - \alpha^3}{3} \right) c_3 + \dots + \left(\frac{\beta^n - \alpha^n}{n} \right) c_n$$

$$a^T c = \begin{bmatrix} (\beta - \alpha) \\ \left(\frac{\beta^2 - \alpha^2}{2} \right) \\ \vdots \\ \left(\frac{\beta^n - \alpha^n}{n} \right) \end{bmatrix}^T \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$$

Hence n vector $a = \begin{bmatrix} (\beta - \alpha) \\ \left(\frac{\beta^2}{2} - \frac{\alpha^2}{2}\right) \\ \left(\frac{\beta^3}{3} - \frac{\alpha^3}{3}\right) \\ \vdots \\ \left(\frac{\beta^n}{n} - \frac{\alpha^n}{n}\right) \end{bmatrix}$

(b) Let α be a number, find n-vector b for which

$$b^T c = p'(\alpha)$$

$$P(x) = c_1 + c_2 x + c_3 x^2 + \dots + c_n x^{n-1}$$

$$\text{Then } P'(x) = \frac{d}{dx} P(x) = \frac{d}{dx} (c_1 + c_2 x + \dots + c_n x^{n-1})$$

$$P'(x) = \frac{d}{dx} c_1 + \frac{d}{dx} c_2 x + \frac{d}{dx} c_3 x^2 + \dots + \frac{d}{dx} c_n x^{n-1}$$

$$P'(x) = 0 + c_2 \left(\frac{d}{dx} x \right) + c_3 \left(\frac{d}{dx} x^2 \right) + \dots + c_n \left(\frac{d}{dx} x^{n-1} \right)$$

$$P'(x) = 0 + c_2 + 2c_3 x + \dots + (n-1)c_n x^{(n-1)-1}$$

$$P''(x) = 0 + c_2 + 2c_3 x + \dots + (n-1)c_n x^{n-2}$$

$$P'(\alpha) = 0 + c_2 + 2c_3(\alpha) + \dots + (n-1)c_n \alpha^{n-2}$$

$$P'(\alpha) = 0 \cdot c_1 + 1 \cdot c_2 + 2\alpha \cdot c_3 + \dots + (n-1)\alpha^{n-2} \cdot c_n$$

$$b^T c = P'(\alpha) = 0 \cdot c_1 + 1 \cdot c_2 + 2\alpha \cdot c_3 + \dots + (n-1)\alpha^{n-2} \cdot c_n$$

Hence,

$$b^T c = \begin{bmatrix} 0 \\ 1 \\ 2d \\ \vdots \\ (n-1)d^{n-2} \end{bmatrix}^T \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ \vdots \\ c_n \end{bmatrix}$$

Hence n -vector $b =$

$$\begin{bmatrix} 0 \\ 1 \\ 2d \\ \vdots \\ (n-1)d^{n-2} \end{bmatrix}$$

Problem 2.12 = n - method of least squares $\hat{P} = b^T c = 9$

Regression Model to predict the profit total when the product prices are changed is given by $\hat{P} = b^T c = 9$

$$\hat{P} = \beta^T x + p \quad \text{where } \hat{P} = \text{Predicted profit}$$

$p = \text{profit with current prices}$

$$\alpha_i = (p_i^{\text{new}} - p_i) / p_i \quad \begin{array}{l} \text{fractional change} \\ \text{in price of product } x_i \end{array}$$

We can write,

$$\hat{P} = \begin{bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \\ \vdots \\ \beta_n \end{bmatrix}^T \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} + p$$

$$\hat{P} = (\beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \dots + \beta_n x_n) + p$$

(a) = what does it mean if $\beta_3 < 0$

$$\hat{P} = (\beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 - \dots - \beta_n x_n) + P$$

If $\beta_3 < 0$, that means value of regressive coefficient for product x_3 is negative. So if the Product Price of x_3 is increased that will reduce the overall profit, and if the product price of x_3 is decreased from previous value then overall predicted profit will increase.

lets consider x_3 is the product for which prices are changed while other products have same prices as before.

Then in that can fractional change for all products where prices are not changed becomes 0.

$$\hat{P} = (\beta_1 \cdot 0 + \beta_2 \cdot 0 + \beta_3 x_3 - \dots - \beta_n \cdot 0) + P$$

$$\hat{P} = \beta_3 x_3 + P \quad (\text{Price of Product } - 3 \text{ is changed.})$$

Case 1 = $(\beta_3 < 0)$ and if x_3 increases i.e. the product price is increased from previous value -

$(P_3^{\text{new}} > P_3)$. Then value of \hat{P} will decrease

Case 2 = $(\beta_3 < 0)$ and if x_3 decreases i.e. the product price is decreased from previous value

$(P_3^{\text{new}} < P_3)$ Then value of \hat{P} will increase.

case 3 = if x_3 remains 0 (i.e. Product price is not changed, i.e. $(P_3^{\text{new}} = P_3)$) in that case it does not impact predicted profit.

we can say if B_3 is negative,

Then predicted (\hat{P}) is inversely proportional to fractional change (x_i) in Product-3 ($x_3 = \frac{P_3^{\text{new}} - P_3}{P_3}$).

(b) = if I am given permission to change the price of one product by up to 1%, to increase total profit.

Then I will choose i th product for which the absolute value of regressive coefficient is maximum.

i.e. $|B_i|$ is maximum among all ($B_1, B_2, B_3, \dots, B_n$) coefficients.

case 1 = if (B_i is positive) and ($|B_i| = \text{maximum}$) Then I will increase the price of product i by 1%. i.e P_i^{new} will be 1% more than P_i . In that case.

$$x_i = \left(\frac{P_i^{\text{new}} - P_i}{P_i} \right) \Rightarrow \text{Positive value.}$$

Hence $\hat{P} = B_i x_i + \hat{P}$

$\downarrow \quad \downarrow$ $(+ve) \quad (+ve)$ → will have +ve product and add maximum value to predicted profit.

case 2 = if (B_i is negative) and ($|B_i| = \text{maximum}$) Then I will decrease the price of product i by 1%. i.e. P_i^{new} will be 1% less than P_i . In that case.

$$x_i = \left(\frac{P_i^{\text{new}} - P_i}{P_i} \right) \Rightarrow -ve \text{ value}$$

Hence $\hat{P} = B_i x_i + \hat{P}$

$\downarrow \quad \downarrow$ $(-ve) \quad (-ve)$ → will have +ve product and add maximum value to predicted profit.

(C) = If I am allowed to change the prices of two products each by upto 1% to maximize the profit.

Then I will choose the product i and k such that the absolute values of regression coefficients for product i and k are maximum values among all other coefficients.

i.e. $|\beta_i|$ and $|\beta_k|$ = are two largest values in the set $(\beta_1, \beta_2, \dots, \beta_n)$

the relation could be described as —

$$|\beta_1| \leq |\beta_2| \leq |\beta_3| \leq \dots \leq |\beta_k| \leq |\beta_i|$$

Now $|\beta_i|$ and $|\beta_k|$ are Two largest values.

Case 1 = if (β_i = positive, β_k = positive) Then I will increase the price of both Products i and k by 1%.

$$[P_i^{\text{new}} = 1\% \text{ more than } P_i] [P_k^{\text{new}} = 1\% \text{ more than } P_k]$$

In that case ($\hat{P} = P_i x_i + \beta_k x_k + P$) will be maximized.

Case 2 = if (β_i = Positive, β_k = negative) Then I will increase the price of Product i by 1%.

and decrease the price of Product k by 1%.

In that case $\hat{P} = P_i x_i + \beta_k x_k + P$ will maximize profit.

$$\begin{array}{c} + \downarrow - \downarrow \\ \text{inc} \quad \text{dec} \\ \hline \text{the product} & \text{the product} \end{array}$$

case.3 = if (β_i = negative) (β_K = positive) Then I will decrease the price of Product i by 1%.

and increase the price of Product K by 1%.

In that case = $\hat{P} = \beta_i z_i + \beta_K z_K + P$ will maximize profit

$$\frac{\downarrow \downarrow \downarrow \downarrow}{\text{all the terms are positive}} = \text{positive}$$

$$\frac{-ve \quad -ve \quad +ve \quad +ve}{\downarrow \quad \downarrow \quad \downarrow \quad \downarrow}$$

$$\frac{\text{all the terms are positive}}{\text{all the terms are positive}}$$

case.4 = if (β_i = negative) (β_K = negative) Then I will decrease the price of Product i by 1%.

and decrease the price of Product K by 1%.

In that case = $\hat{P} = \beta_i z_i + \beta_K z_K + P$ will maximize the profit

$$\frac{\downarrow \downarrow \downarrow \downarrow}{\text{all the terms are negative}} = \text{negative}$$

$$\frac{-ve \quad -ve \quad -ve \quad -ve}{\downarrow \quad \downarrow}$$

$$\frac{\text{all the terms are negative}}{\text{all the terms are negative}}$$

Problem 3.5 \Rightarrow

for an n -vector x , vector norm 1 -norm $\|x\|_1$ and ∞ -norm $\|x\|_\infty$ are defined as -

$$\|x\|_1 = |x_1| + |x_2| + \dots + |x_n|$$

$$\|x\|_\infty = \max \{ |x_1|, |x_2|, \dots, |x_n| \}$$

Show that 1 -norm $\|x\|_1$ and ∞ -norm $\|x\|_\infty$ satisfy the four norm properties.

Verification for 1 -norm \Rightarrow

a) Non-negative Homogeneity $\Rightarrow \|Bx\|_1 = |\beta| \|x\|_1$

Let's consider n -vector $x \Rightarrow$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

then $\|x\|_1 = |x_1| + |x_2| + \dots + |x_n| \rightarrow ①$

Now let's multiply vector x with scalar $\beta \Rightarrow$

$$\beta x = \begin{bmatrix} \beta x_1 \\ \beta x_2 \\ \vdots \\ \beta x_n \end{bmatrix}$$

$$\|Bx\|_1 = |\beta x_1| + |\beta x_2| + \dots + |\beta x_n|$$

$$\|Bx\|_1 = |\beta| |x_1| + |\beta| |x_2| + \dots + |\beta| |x_n|$$

$$\|Bx\|_1 = |\beta| [|x_1| + |x_2| + \dots + |x_n|]$$

$$\|Bx\|_1 = |\beta| \|x\|_1 \quad [\text{By equation } ①]$$

(b) Triangle Inequality

$$\|x+y\|_1 \leq \|x\|_1 + \|y\|_1$$

lets consider two n-vectors, x and y .

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}, \quad y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{bmatrix}$$

then $x+y = \begin{bmatrix} x_1+y_1 \\ x_2+y_2 \\ x_3+y_3 \\ \vdots \\ x_n+y_n \end{bmatrix}$

now $\|x+y\|_1 = |x_1+y_1| + |x_2+y_2| + \dots + |x_n+y_n|$ equation ①

$$\|x\|_1 = |x_1| + |x_2| + \dots + |x_n| \rightarrow \text{equation ②}$$

$$\|y\|_1 = |y_1| + |y_2| + \dots + |y_n| \rightarrow \text{equation ③}$$

By $\|x\|_1 + \|y\|_1 \rightarrow \text{equation ②} + \text{equation ③}$,

(we get)

$$\begin{aligned} \|x\|_1 + \|y\|_1 &= [|x_1| + |x_2| + \dots + |x_n|] + [|y_1| + |y_2| + \dots + |y_n|] \\ &= (|x_1| + |y_1|) + (|x_2| + |y_2|) + \dots + (|x_n| + |y_n|) \end{aligned} \quad \rightarrow \text{equation ④}$$

By Properties of modulus operator we know that \Rightarrow

$$|a+b| \leq |a| + |b|$$

for all values of real numbers a, b .

Hence we can say that \exists

$$|x_1 + y_1| \leq |x_1| + |y_1|$$

$$|x_2 + y_2| \leq |x_2| + |y_2|$$

⋮

⋮

$$|x_n + y_n| \leq |x_n| + |y_n|$$

(L.H.S)

(R.H.S)

Summing the equations on left and right we get \Rightarrow

$$|x_1 + y_1| + |x_2 + y_2| + \dots + |x_n + y_n| \leq$$

$$(|x_1| + |y_1|) + (|x_2| + |y_2|) + \dots + (|x_n| + |y_n|)$$

using previously derived equations ① and ④ we can write.

$$\boxed{\|x+y\|_1 \leq \|x\|_1 + \|y\|_1} \quad \text{Proved}$$

(C) = Non-negativity.

$$\boxed{\|x\|_1 \geq 0}$$

n vector $x =$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$\text{Then } \|x\|_1 = |x_1| + |x_2| + \dots + |x_n|$$

↳ equation ①

we know that

$$\boxed{|a| \geq 0}$$

always for all real values of a .

Then we can say that

$$|x_1| \geq 0$$

$$|x_2| \geq 0$$

$$|x_3| \geq 0$$

⋮

⋮

$$|x_n| \geq 0$$

Summing Right and left side we get

$$|x_1| + |x_2| + |x_3| + \dots + |x_n| \geq 0$$

By using equation ① we can write

$$\|x\|_1 \geq 0$$

Proved

(b) = Definiteness \Rightarrow

$$\|x\|_1 = 0 \text{ only if } x=0$$

n-vector $x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$

then $\|x\|_1 = |x_1| + |x_2| + \dots + |x_n|$

↪ equation ①

We know that modulus of any real number is zero only when the number itself is zero.

$$|a| = 0 \text{ when } a=0$$

Hence we can say,

$$|x_1| = 0 \text{ only if } x_1=0$$

$$|x_2| = 0 \text{ only if } x_2=0$$

⋮

⋮

$$|x_n| = 0 \text{ only if } x_n=0$$

Summing Right & left sides we get -

$$|x_1| + |x_2| + \dots + |x_n| = 0 \quad [\text{only if } x_1, x_2, \dots, x_n \text{ all are zero}]$$

$$\therefore \|x\|_1 = 0$$

$$\text{Hence } \|\mathbf{x}\|_1 = 0$$

only when x_1, x_2, \dots, x_n all entries are zero.

If $x_1 = x_2 = x_3 = \dots = x_n = 0$ Then \mathbf{x} becomes a zero vector.

$$\text{i.e. } \boxed{\mathbf{x} = 0}$$

$$0 \leq \|\mathbf{x}\|$$

we can say that $\boxed{\|\mathbf{x}\|_1 = 0}$ only if vector $\mathbf{x} = 0$

Verification for ∞ -norm \Rightarrow

a) Non-negative Homogeneity \Rightarrow $\boxed{\|B\mathbf{x}\|_\infty = |B| \|\mathbf{x}\|_\infty}$

let's consider n-vector $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$ \Rightarrow satisfies $C = (b)$

$B\mathbf{x} = \begin{bmatrix} Bx_1 \\ Bx_2 \\ \vdots \\ Bx_n \end{bmatrix}$ \Rightarrow satisfies $C = (b)$

Then $\|\mathbf{x}\|_\infty = \max \{ |x_1|, |x_2|, \dots, |x_n| \} \rightarrow \text{equation ①}$

Multiplying vector \mathbf{x} with scalar B . we get,

$$B\mathbf{x} = \begin{bmatrix} Bx_1 \\ Bx_2 \\ \vdots \\ Bx_n \end{bmatrix}$$

$$\boxed{B\mathbf{x} \text{ also satisfies } C = (b)}$$

Then $\|B\mathbf{x}\|_\infty = \max \{ |Bx_1|, |Bx_2|, \dots, |Bx_n| \}$

we know that $|ab| = |a||b|$

Hence we can write -

$$\boxed{\|B\mathbf{x}\|_\infty = \max \{ |B||x_1|, |B||x_2|, \dots, |B||x_n| \}}$$

since B is constant and multiplied to all the terms
we can say that.

$$\|Bx\|_\infty = \max \{ |B|x_1|, |B|x_2|, \dots, |B|x_n| \}$$

$$\|Bx\|_\infty = |B| \cdot \max \{ |x_1|, |x_2|, \dots, |x_n| \}$$

$$\boxed{\|Bx\|_\infty = |B| \|x\|_\infty} \quad (\text{from equation ①})$$

(b) = Triangle Inequality $\boxed{\|x+y\|_\infty \leq \|x\|_\infty + \|y\|_\infty}$

let consider two n-vectors x and y .

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \text{and} \quad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

then $x+y = \begin{bmatrix} x_1+y_1 \\ x_2+y_2 \\ \vdots \\ x_n+y_n \end{bmatrix}$

$$\|x\|_\infty = \max \{ |x_1|, |x_2|, \dots, |x_n| \}$$

$$\|y\|_\infty = \max \{ |y_1|, |y_2|, \dots, |y_n| \}$$

$$\|x+y\|_\infty = \max \{ |x_1+y_1|, |x_2+y_2|, \dots, |x_n+y_n| \}$$

let assume that $\boxed{\|x+y\|_\infty = |x_i+y_i|} \quad (\text{ith term is maximum})$

in that case

$$\boxed{|x_i+y_i| \leq |x_i| + |y_i|} \quad \begin{array}{l} [\text{b/c we know that}] \\ [|ab| \leq |a| + |b|] \end{array}$$

①

We can say that,

$|x_i|$ could be the largest value in the set $(|x_1|, |x_2| \dots |x_n|)$ or it could be lesser than the largest value in this set so we can write-

$$|x_i| \leq \max\{|x_1|, |x_2| \dots |x_n|\} \quad \text{②}$$

Similarly,

$|y_i|$ could be the largest value in the set $(|y_1|, |y_2| \dots |y_n|)$ or it could be lesser than the largest value, so we can write.

$$|y_i| \leq \max\{|y_1|, |y_2| \dots |y_n|\} \quad \text{③}$$

Summing Equation ② and ③ we get -

$$\begin{aligned} |x_i| + |y_i| &\leq \max\{|x_1|, |x_2| \dots |x_n|\} \\ &\quad + \max\{|y_1|, |y_2| \dots |y_n|\}. \end{aligned}$$

Hence we know that, It will be true to write \Rightarrow

$$|x_i| + |y_i| \leq \|x\|_\infty + \|y\|_\infty$$

But we also know that.

$$|x_i + y_i| \leq |x_i| + |y_i|$$

so we can say that.

$$|x_i + y_i| \leq |x_i| + |y_i| \leq \|x\|_\infty + \|y\|_\infty$$

$$\text{But } |x_i + y_i| = \|x + y\|_{\infty}$$

so we can write the equation as -

$$\boxed{\|x + y\|_{\infty} \leq \|x\|_{\infty} + \|y\|_{\infty}} \quad \text{Proved}$$

(c) Non-negativity $\boxed{\|x\|_{\infty} \geq 0}$

n vector $x =$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

Then $\|x\|_{\infty} = \max\{|x_1|, |x_2|, \dots, |x_n|\}$

$\|x\|_{\infty}$ = maximum value among absolute values of entries of x -vector.

We know that $|a| \geq 0$ for all real numbers.

Hence all the absolute values of entries of $x \rightarrow$

$$|x_1| \geq 0, |x_2| \geq 0, \dots, |x_n| \geq 0$$

Hence $\max\{|x_1|, |x_2|, \dots, |x_n|\} \geq 0$

Hence we can say $\boxed{\|x\|_{\infty} \geq 0}$ proved

(d) Definiteness $\Rightarrow \boxed{\|x\|_{\infty} = 0 \text{ only if } x=0}$

n vector $x =$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \text{Then } \|x\|_{\infty} = \max\{|x_1|, |x_2|, \dots, |x_n|\}$$

$\max\{|x_1|, |x_2|, \dots, |x_n|\}$ could be zero if all elements in the set $(|x_1|, |x_2|, \dots, |x_n|)$ are zero i.e.

$$|x_1| = 0, |x_2| = 0, \dots, |x_n| = 0$$

i.e. $x_1 = 0, x_2 = 0, \dots, x_n = 0$

(*) = Definition

Hence we can say that.

$\|x\|_\infty = 0$, only if all the absolute values of vector x entries are zero.

we know that $|a| = 0$. Then $a = 0$.

so if $|x_1| = 0$, Then $x_1 = 0$

$|x_2| = 0$ Then $x_2 = 0$

\vdots

$|x_n| = 0$ Then $x_n = 0$

This means if $\|x\|_\infty = 0$

Then $x = \text{zero vector with all entries } = 0$.

$$x = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

NOTE - If any element in the entry set is lesser than zero, or greater than zero.

i.e. $x_i < 0$ or $x_i > 0$

in that case $|x_i| = \text{Positive non zero value.}$

in that case $\|x\|_\infty = \text{can never be zero.}$

Problem 3.24 $\Rightarrow z_1, z_2 \dots z_m$ is collection of n -vector.
 α is another n -vector.

vector z_j is the (distance) nearest neighbour of x

$$\text{if } \|x - z_j\| \leq \|x - z_i\|, i=1, 2, \dots, m$$

vector z_j is the angle nearest neighbour of x if

$$\angle(x, z_j) \leq \angle(x, z_i), i=1, 2, \dots, n$$

(a) = Give a simple specific numerical Example where
the distance nearest neighbour is not the same as
the angle nearest neighbour.

Let consider n -vector x , (where $n=5$).

$$x = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{bmatrix}$$

z_1 and z_2 is the collection of two vector. (5-vector)

Such that $z_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 10 \end{bmatrix}$

$$z_2 = 3x = \begin{bmatrix} 3 \\ 6 \\ 9 \\ 12 \\ 15 \end{bmatrix}$$

Then distances of vectors z_1 and z_2 from x are

① $\|x - z_1\| = \text{distance of vector } x \text{ from } z_1$

$$x - z_1 = \begin{bmatrix} 1-0 \\ 2-0 \\ 3-0 \\ 4-0 \\ 5-0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ -5 \end{bmatrix} \Rightarrow \|x - z_1\| = \sqrt{1^2 + 2^2 + 3^2 + 4^2 + (-5)^2} = \sqrt{55}$$

$$\begin{aligned} \|x - z_1\| &= \sqrt{(1)^2 + (2)^2 + (3)^2 + (4)^2 + (-5)^2} \\ &= \sqrt{1+4+9+16+25} \\ &= \sqrt{55} \\ &\approx 7.41 \end{aligned}$$

② $\|x - z_2\| = \text{distance of } x \text{ from } z_2$

$$x - z_2 = \begin{bmatrix} 1-3 \\ 2-6 \\ 3-9 \\ 4-12 \\ 5-15 \end{bmatrix} = \begin{bmatrix} -2 \\ -4 \\ -6 \\ -8 \\ -10 \end{bmatrix}$$

$$\begin{aligned} \|x - z_2\| &= \sqrt{(-2)^2 + (-4)^2 + (-6)^2 + (-8)^2 + (-10)^2} \\ &= \sqrt{4+16+36+64+100} \\ &= \sqrt{220} \\ &\approx 14.83 \end{aligned}$$

$$\|x - z_2\| > \|x - z_1\|$$

Hence distance nearest neighbour of x is z_1 .

now the angles of vectors z_1 and z_2 with respect to x are

① $\angle(x, z_1) \Rightarrow$ angle b/w x and z_1 vector.

$$\theta = \arccos \left(\frac{x^T z_1}{\|x\| \|z_1\|} \right)$$

$$\theta = \arccos \left(\frac{\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{bmatrix}^T \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 10 \end{bmatrix}}{\sqrt{1^2 + 2^2 + 3^2 + 4^2 + 5^2} \sqrt{0^2 + 0^2 + 0^2 + 0^2 + 10^2}} \right)$$

$$\theta = \arccos \left(\frac{1.0 + 2.0 + 3.0 + 4.0 + 5.0}{\sqrt{55} \sqrt{100}} \right)$$

$$\theta = \arccos \left(\frac{15}{10\sqrt{55}} \right)$$

$$\theta = \arccos \left(\frac{1.5}{\sqrt{55}} \right)$$

$$\theta = \arccos \left(\frac{1.5}{7.41} \right)$$

$$\theta = \arccos (0.6747)$$

$$\theta \approx 47.56$$

hence $\boxed{\angle(x, z_1) = \theta \approx 47.56}$

$$\textcircled{2} = \angle(x_1 z_2) = \text{angle b/w } x \text{ and } z_2 \text{ vector}$$

$$\cos \theta = \frac{x^T z_2}{\|x\| \|z_2\|}$$

$$\theta = \arccos \left[\frac{\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{bmatrix}^T \begin{bmatrix} 3 \\ 6 \\ 9 \\ 12 \\ 15 \end{bmatrix}}{\sqrt{1^2 + 2^2 + 3^2 + 4^2 + 5^2} \sqrt{3^2 + 6^2 + 9^2 + 12^2 + 15^2}} \right]$$

$$\theta = \arccos \left[\frac{3+12+27+48+75}{\sqrt{55} \sqrt{9+36+81+144+225}} \right]$$

$$\theta = \arccos \left[\frac{165}{\sqrt{55} \sqrt{495}} \right]$$

$$\theta = \arccos \left[\frac{165}{\sqrt{27225}} \right]$$

$$\theta = \arccos \left[\frac{165}{165} \right]$$

$$\theta = \arccos [1]$$

$$\boxed{\theta = 0^\circ}$$

Hence angle b/w vectors x and z_2 is 0 .

we can see that

$$\angle(x, z_1) > \angle(x, z_2)$$

$$(47.56^\circ > 0^\circ)$$

Hence we can say that angle nearest neighbour of x is z_2 .

we saw in that Example that-

distance nearest neighbour of vector x is z_1

while angle nearest neighbour of vector x is z_2 .

where $x = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{bmatrix}$, $z_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 10 \end{bmatrix}$, $z_2 = \begin{bmatrix} 3 \\ 6 \\ 9 \\ 12 \\ 15 \end{bmatrix}$

(b) = vectors z_1, z_2, \dots, z_n are normalized.

$$\text{i.e. } \|z_i\| = 1, i=1, 2, \dots, n$$

Show that in this case distance nearest neighbour and angle nearest neighbour is always same.

Let consider n -vector $x =$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}$$

Let consider z_i is the vector which is angle nearest neighbour of vector x .

if z_i is the vector which is nearest angle neighbour of x then we can say -

$$\angle(x, z_i) < \angle(x, z_j) \quad \left[\begin{array}{l} \text{where } j = 1, 2, \dots \\ \text{Excluding } i \end{array} \right]$$

we can write -

$$\arccos\left(\frac{x^T z_i}{\|x\| \|z_i\|}\right) < \arccos\left(\frac{x^T z_j}{\|x\| \|z_j\|}\right)$$

It is given that if $\boxed{\arccos(u) > \arccos(v)}$

Then

$$[-1 \leq u < v \leq 1]$$

so we can write that -

$$\frac{x^T z_i}{\|x\| \|z_i\|} > \arccos\left(\frac{x^T z_j}{\|x\| \|z_j\|}\right) \rightarrow ①$$

we know that $\boxed{\|z_1\| = \|z_2\| = \dots = \|z_n\| = 1}$

so we can rewrite equation ① as

$$\frac{x^T z_i}{\|x\| \cdot 1} > \frac{x^T z_j}{\|x\| \cdot 1}$$

$$\Rightarrow \boxed{x^T z_i > x^T z_j} \quad \left[\begin{array}{l} \|x\| = \text{positive} \\ \text{multiply both side by } \|x\| \end{array} \right]$$

we have equation =

$$x^T z_i > x^T z_j$$

Multiply by scalar -2 on both sides \rightarrow

$$-2(x^T z_i) < -2(x^T z_j)$$

add $[1 + \|x\|^2]$ on both sides, it's a positive value \rightarrow

$$1 + \|x\|^2 - 2(x^T z_i) < 1 + \|x\|^2 - 2(x^T z_j)$$

(we know that) $\|z_i\| = \|z_j\| = 1$ so we can write =

$$\|x\|^2 + \|z_i\|^2 - 2(x^T z_i) < \|x\|^2 + \|z_j\|^2 - 2(x^T z_j)$$

$$\Rightarrow (\|x - z_i\|)^2 < (\|x - z_j\|)^2$$

Taking square root both sides we get =

$$\sqrt{(\|x - z_i\|)^2} < \sqrt{(\|x - z_j\|)^2}$$

$$\|x - z_i\| < \|x - z_j\| \quad \text{proved}$$

$\|x - z_i\| \Rightarrow$ is the distance of vector x from z_i

$\|x - z_j\| =$ is the distance of vector x from all other vectors z_j where ($j = 1, 2, 3, \dots, n$) (excluding i)

Here we can see that, when $\|z_i\| = 1$

$$\angle(x, z_i) < \angle(x, z_j)$$

Then $\|x - z_i\| < \|x - z_j\|$

i.e. The angle nearest neighbour is same as distance nearest neighbour.

Problem 3.26 =

T-vector α is a non constant time series.

$$\mu = \frac{(\mathbf{1}^T \alpha)}{T}$$

= Mean Value.

Auto Correlation, $R(\tau)$ = Defined as correlation coefficient of two vectors for $\tau = 0, 1, 2, \dots$
 $(\alpha, \mu_{1\tau})$ and $(\mu_{1\tau}, \alpha)$

Vector $(\alpha, \mu_{1\tau})$ and $(\mu_{1\tau}, \alpha)$ have mean μ .

(a) Explain why $R(0) = 1$ and $R(\tau) = 0$ for $\tau \neq 0$.

when $\tau = 0$ Then \rightarrow if $\alpha = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_T \end{bmatrix}$
if T-vector $\alpha = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_T \end{bmatrix}$

Then vector (α, μ_{10}) and (μ_{10}, α) will also be same as α .

vector $(\alpha, \mu_{10}) = (\mu_{10}, \alpha)$ for $(\tau = 0)$

$$= \frac{1}{T} \begin{bmatrix} \alpha_1 & \alpha_2 & \cdots & \alpha_T \end{bmatrix}^T \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_T \end{bmatrix}$$

correlation coefficient (ρ)

lets denote vector (x, u_{10}) by a .
and vector (u_{10}, x) by b .

Then correlation coefficient $\rho = \frac{\hat{a}^T \hat{b}}{\|\hat{a}\| \|\hat{b}\|}$

where $\hat{a} = a - \text{avg}(a) \mathbf{1}$
 $\hat{b} = b - \text{avg}(b) \mathbf{1}$

$$\hat{a} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} - \bar{u} \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} x_1 - \bar{u} \\ x_2 - \bar{u} \\ \vdots \\ x_T - \bar{u} \end{bmatrix}$$

similarly

$$\hat{b} = \begin{bmatrix} u_{10} - \bar{u} \\ u_{20} - \bar{u} \\ \vdots \\ u_{T0} - \bar{u} \end{bmatrix}$$

($\forall i$ \hat{a} and \hat{b} will be same b/c
 a and b are same for $i=0$)

$$\|\hat{a}\| = \sqrt{(x_1 - \bar{u})^2 + (x_2 - \bar{u})^2 + \dots + (x_T - \bar{u})^2}$$

$$\|\hat{b}\| = \sqrt{(u_{10} - \bar{u})^2 + (u_{20} - \bar{u})^2 + \dots + (u_{T0} - \bar{u})^2}$$

lets calculate the value of $R(\tau) = \text{correlation coefficient}$
(where $\tau=0$)

$$R(0) = \delta = \begin{bmatrix} x_1 - u \\ x_2 - u \\ \vdots \\ x_T - u \end{bmatrix}^T \begin{bmatrix} x_1 - u \\ x_2 - u \\ \vdots \\ x_T - u \end{bmatrix}$$

$$\sqrt{(x_1 - u)^2 + (x_2 - u)^2 + \dots + (x_T - u)^2} = \sqrt{(x_1 - u)^2 + (x_2 - u)^2 + \dots + (x_T - u)^2}$$

$$R(0) = \frac{(x_1 - u)^2 + (x_2 - u)^2 + \dots + (x_T - u)^2}{(x_1 - u)^2 + (x_2 - u)^2 + \dots + (x_T - u)^2}$$

$$R(0) = 1 \quad \left(\frac{b}{c} \right) \quad \begin{array}{l} \text{numerator} = 1, \text{ since both } \\ \text{denominator have } \end{array}$$

$$(2) R(\tau) = 0, \text{ for } \tau \geq T$$

$$a = \text{vector}(x_1, u, x_2) =$$

a is $T+\tau$ vector

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \\ u \\ u \\ \vdots \\ u \end{bmatrix} \quad \begin{array}{l} \uparrow \\ T \\ \downarrow \\ \uparrow \\ \tau \\ \downarrow \\ \uparrow \\ \tau \end{array}$$

$$b = \text{vector}(u, x_2, x) =$$

b is $(T+\tau)$ vector

$$\begin{bmatrix} u \\ u \\ \vdots \\ u \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} \quad \begin{array}{l} \uparrow \\ T \\ \downarrow \\ \uparrow \\ \tau \\ \downarrow \\ \uparrow \\ T+\tau \end{array}$$

mean of $a = u$, mean of $b = u$

$$\hat{a} = a - \text{avg}(a) \stackrel{0 \cdot (x_1-u) + 0 \cdot (x_2-u) + \dots + 0 \cdot (x_T-u)}{=} \hat{a} = \hat{a}$$

$$= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \\ \vdots \\ x_T \end{bmatrix}_{T+2} - u \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}_{T+2} + (u-\bar{x}) \cdot 0 \begin{bmatrix} x_1-u \\ x_2-u \\ \vdots \\ x_T-u \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}_T$$

$$\hat{b} = b - \text{avg}(b) \stackrel{\text{new fact from above}}{=} b - u \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}_{T+2} + (u-\bar{x}) \cdot 0 \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ x_1-u \\ x_2-u \\ \vdots \\ x_T-u \end{bmatrix}_T$$

let's calculate $\hat{a}^T \hat{b} \Rightarrow \text{when } \tau \geq T \quad (\tau = T \text{ and when } \tau > T)$

$$\begin{bmatrix} x_1-u \\ x_2-u \\ \vdots \\ x_T-u \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}_T^T \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ x_1-u \\ x_2-u \\ \vdots \\ x_T-u \end{bmatrix}_{T+2}$$

(when $\tau = T$)

$$\Rightarrow (x_1-u) \cdot 0 + (x_2-u) \cdot 0 + \dots + (x_T-u) \cdot 0 \\ + 0 \cdot (x_1-u) + 0 \cdot (x_2-u) + \dots + 0 \cdot (x_T-u)$$

$$= 0$$

when $\tau > T$ In that case

$$\hat{a}^\top \hat{b} = (x_1 - u) \cdot 0 + (x_2 - u) \cdot 0 + \dots + (x_T - u) \cdot 0,$$

$$+ 0 \cdot 0 + 0 \cdot 0 + \dots + 0 \cdot (x_1 - u) + 0 \cdot (x_2 - u) + \dots + 0 \cdot (x_T - u)$$

$$\boxed{\hat{a}^\top \hat{b} = 0}$$

Hence $[0 \cdot 0 + 0 \cdot 0 + \dots]$ term will come for $(T-T)$ times

we know that when

$$\boxed{\tau \geq T} \quad \boxed{\hat{a}^\top \hat{b} = 0}$$

$$\text{Hence } R(\tau) - \beta = \frac{\hat{a}^\top \hat{b}}{\|\hat{a}\| \|\hat{b}\|}$$

$$R(\tau) - \beta = \frac{0}{\|\hat{a}\| \|\hat{b}\|} = 0$$

Hence

$$\boxed{R(\tau) = 0}$$

when $\boxed{\tau \geq T}$

(b) = if z denote standardized or z scored version of x
 show that for $\tau=0, 1, \dots, T-1$

$$R(\tau) = \frac{1}{T} \sum_{t=\tau}^{T-1} z_t z_{t+\tau} = \hat{\alpha}^T \hat{\beta}$$

vector $a = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix}$

$$\begin{aligned} &= (x_1 - \bar{x})(x_2 - \bar{x}) + (x_2 - \bar{x})(x_3 - \bar{x}) + \dots \\ &\quad + (x_{T-1} - \bar{x})(x_T - \bar{x}) + (x_T - \bar{x})(x_1 - \bar{x}) = \hat{\alpha}^T \hat{\beta} \end{aligned}$$

vector $(x, u, 1) = a = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \\ u \\ 1 \end{bmatrix}$

vector $(u, z, x) = b = \begin{bmatrix} u \\ u \\ \vdots \\ u \\ x_1 - \bar{x} \\ x_2 - \bar{x} \\ \vdots \\ x_T - \bar{x} \end{bmatrix}$

$$\hat{a} = a - \text{avg}(a) \mathbf{1}$$

$$= a - u \mathbf{1}$$

$$= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \\ u \end{bmatrix} - u \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} x_1 - u \\ x_2 - u \\ \vdots \\ x_T - u \\ 0 \end{bmatrix} = \frac{1}{T} \begin{bmatrix} \|x\|_2^2 \\ \|x\|_2^2 \\ \vdots \\ \|x\|_2^2 \\ \|x\|_2^2 \end{bmatrix}$$

$$\hat{b} = b - \text{avg}(b) \mathbf{1}$$

$$= b - u \mathbf{1}$$

$$= \begin{bmatrix} u \\ u \\ \vdots \\ u \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} - u \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ x_1 - u \\ x_2 - u \\ \vdots \\ x_T - u \end{bmatrix} = \frac{1}{T} \begin{bmatrix} \|u\|_2^2 \\ \|u\|_2^2 \\ \vdots \\ \|u\|_2^2 \\ \|x\|_2^2 \\ \|x\|_2^2 \\ \vdots \\ \|x\|_2^2 \end{bmatrix}$$

let's calculate $\hat{a}^T \hat{b}$

$$\begin{aligned}\hat{a}^T \hat{b} &= (x_1 - u) \cdot 0 + (x_2 - u) \cdot 0 + \dots + (x_T - u) \cdot 0 \\ &\quad + (x_{T+1} - u) (x_1 - u) + (x_{T+2} - u) (x_2 - u) + \dots + (x_T - u) (x_{T+1} - u) \\ &\quad + 0 \cdot (x_{T+2} - u) + \dots + 0 \cdot (x_T - u)\end{aligned}$$

$$\begin{aligned}\hat{a}^T \hat{b} &= (x_{T+1} - u) (x_1 - u) + (x_{T+2} - u) (x_2 - u) + \dots \\ &\quad + (x_T - u) (x_{T+1} - u)\end{aligned}$$

$$\begin{aligned}&\cancel{x_1 x_{T+1} - u x_{T+1} - u x_1 + u^2} + \cancel{x_2 x_{T+2} - u x_{T+2} - u x_2 + u^2} \\ &\cancel{- u x_{T+2} - u x_2 + u^2} - \dots - \cancel{(x_{T+1} - u)(x_T - u)} \\ &\dots + \cancel{x_T x_{T+1} - u x_T - u x_{T+1} + u^2}\end{aligned}$$

then divide both sides by $(\|\hat{a}\| \cdot \|\hat{b}\|)$. \Rightarrow

$$\frac{\hat{a}^T \hat{b}}{\|\hat{a}\| \|\hat{b}\|} = \frac{(x_{T+1} - u) (x_1 - u) + (x_{T+2} - u) (x_2 - u) + \dots + (x_T - u) (x_{T+1} - u)}{\|\hat{a}\| \|\hat{b}\|}$$

Now let's multiply both sides by T .

$$T \cdot \left[\frac{\hat{a}^T \hat{b}}{\|\hat{a}\| \|\hat{b}\|} \right] = T \cdot \left[\frac{(x_{T+1} - u) (x_1 - u) + (x_{T+2} - u) (x_2 - u) + \dots + (x_T - u) (x_{T+1} - u)}{\|\hat{a}\| \|\hat{b}\|} \right]$$

By spreading expression we can write -

$$T(R(z)) = \frac{\sqrt{r(x_1-u)} \cdot \sqrt{r(x_{z+1}-u)}}{\|\hat{a}\| \|\hat{b}\|} + \frac{\sqrt{r(x_2-u)} \cdot \sqrt{r(x_{z+2}-u)}}{\|\hat{a}\| \|\hat{b}\|} + \dots + \frac{\sqrt{r(x_{T-z}-u)} \cdot \sqrt{r(x_T-u)}}{\|\hat{a}\| \|\hat{b}\|}$$

Put value of $\|\hat{a}\|$ and $\|\hat{b}\|$ in above equation -

$$T(R(z)) = \frac{\sqrt{r(x_1-u)} \cdot \sqrt{(x_1-u)^2 + (x_2-u)^2 + \dots + (x_T-u)^2}}{\sqrt{(x_1-u)^2 + (x_2-u)^2 + \dots + (x_T-u)^2}} \cdot \frac{\sqrt{r(x_{z+1}-u)} \cdot \sqrt{(x_{z+1}-u)^2 + (x_{z+2}-u)^2 + \dots + (x_T-u)^2}}{\sqrt{(x_{z+1}-u)^2 + (x_{z+2}-u)^2 + \dots + (x_T-u)^2}} + \frac{\sqrt{r(x_2-u)} \cdot \sqrt{(x_1-u)^2 + (x_2-u)^2 + \dots + (x_T-u)^2}}{\sqrt{(x_1-u)^2 + (x_2-u)^2 + \dots + (x_T-u)^2}} \cdot \frac{\sqrt{r(x_{z+2}-u)} \cdot \sqrt{(x_{z+1}-u)^2 + (x_{z+2}-u)^2 + \dots + (x_T-u)^2}}{\sqrt{(x_{z+1}-u)^2 + (x_{z+2}-u)^2 + \dots + (x_T-u)^2}} + \dots + \frac{\sqrt{r(x_{T-z}-u)} \cdot \sqrt{(x_{T-z}-u)^2 + (x_T-u)^2}}{\sqrt{(x_{T-z}-u)^2 + (x_T-u)^2}} \cdot \frac{\sqrt{r(x_T-u)} \cdot \sqrt{(x_{T-z}-u)^2 + (x_T-u)^2}}{\sqrt{(x_{T-z}-u)^2 + (x_T-u)^2}}$$

Note - $\|\hat{a}\| = \|\hat{b}\| = \sqrt{(x_1-u)^2 + (x_2-u)^2 + \dots + (x_T-u)^2}$

→ Equation ①

now let's calculate Standardized version of x .

which is given by $Z = \frac{1}{\text{std}(x)} (x - \text{avg}(x) \cdot 1)$

$$\text{std}(x) = \sqrt{\frac{\sum_{i=1}^T (x_i - \bar{x})^2}{T}}, \quad (\text{avg}(x) = \bar{x})$$

$$\Rightarrow \frac{\|x - \text{avg}(x) \cdot 1\|}{\sqrt{T}} = \left\| \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} - \bar{x} \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} \right\|$$

$$= \left\| \begin{bmatrix} x_1 - \bar{x} \\ x_2 - \bar{x} \\ \vdots \\ x_T - \bar{x} \end{bmatrix} \right\|$$

$$= \frac{\sqrt{(x_1 - \bar{x})^2 + (x_2 - \bar{x})^2 + \dots + (x_T - \bar{x})^2}}{\sqrt{T}}$$

Then $Z_1 = \frac{\sqrt{T} \cdot (x_1 - \bar{x})}{\sqrt{(x_1 - \bar{x})^2 + (x_2 - \bar{x})^2 + \dots + (x_T - \bar{x})^2}}$

$$\sqrt{(x_1 - \bar{x})^2 + (x_2 - \bar{x})^2 + \dots + (x_T - \bar{x})^2}$$

$$Z_2 = \frac{\sqrt{T} \cdot (x_2 - \bar{x})}{\sqrt{(x_1 - \bar{x})^2 + (x_2 - \bar{x})^2 + \dots + (x_T - \bar{x})^2}}$$

$$z_t = \frac{\sqrt{T} (x_t - u)}{\sqrt{(x_1 - u)^2 + (x_2 - u)^2 - (x_T - u)^2}}$$

Let's compare equation ① with values of z_1, z_2, \dots, z_T
 then we find that

$$T \cdot R(z) = \sum_{t=1}^{T-z} z_t \cdot z_{t+z}$$

Hence,

$$R(z) = \frac{1}{T} \sum_{t=1}^{T-z} z_t \cdot z_{t+z}$$

$$0 = (1) \text{ and } (T) \text{ norm}$$

Only when (z_t, z_{t+z}) value = 0



(c) = find the auto correlation for time series

$$x = (+1, -1, +1, -1, \dots, +1, -1)$$

where T is even.

If T is even then mean of x can be calculated as.

$$\begin{aligned}\frac{x^T 1}{T} &= \frac{\begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \\ \vdots \\ 1 \end{bmatrix}^T \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}}{T} \\ &= \frac{1 \cdot 1 + (-1) \cdot 1 + \dots + 1 \cdot 1 + (-1) \cdot 1}{T} \\ &= \frac{1 + (-1) + 1 + (-1) + \dots + 1 + (-1)}{T}\end{aligned}$$

$$\text{mean}(x) = \frac{0}{T} = 0 \quad \left[\begin{array}{l} \text{sum of Series } 1, -1, \dots \\ \text{till even number of times} \\ \text{is zero} \end{array} \right]$$

$$\boxed{\text{mean}(x) \text{ or avg}(x) = 0}$$

a = vector (x_1, x_2, \dots, x_T) where $x_1 = 0$

$$a = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \begin{array}{c} \uparrow T \\ \downarrow \\ \uparrow \\ \downarrow \\ 2 \end{array}$$

similarly $b = \text{vector}(x_{1:T}, 1)$ where $x = 0$

$$b = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} \xrightarrow{T} \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix}$$

$\text{avg}(a)$ and $\text{avg}(b)$ is also $= u = 0 \cdot 1 = 0$

$$\hat{a} = a - \text{avg}(a) \cdot 1 \quad \| \hat{a} \| = \| a \| = \| b \| \text{ since } \text{avg}(a) = 0$$

$$= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \\ 0 \\ \vdots \\ 0 \end{bmatrix} - 0 \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \\ 0 \\ \vdots \\ 0 \end{bmatrix} \xrightarrow{\text{mult}} \hat{a} = (5)A$$

Similarly

$$\hat{b} = b - \text{avg}(b) \cdot 1$$

$$(5)A = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} - (0 \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 1 \end{bmatrix}) + (1 \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix}) = (5)B$$

lets calculate $(\hat{a}^T \hat{b}) \Rightarrow$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_T \\ 0 \\ \vdots \\ 0 \end{bmatrix}^T \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ x_1 \\ x_2 \\ \vdots \\ x_T \end{bmatrix} \Rightarrow x_1 \cdot 0 + x_2 \cdot 0 + \dots + (x_T) \cdot 0 + (x_{T+1} \cdot x_1) + (x_{T+2} \cdot x_2) + \dots + (x_T \cdot x_{T-2}) + 0 \cdot (x_{T-1}) + \dots + 0 \cdot (x_T) \Rightarrow (x_{T+1} \cdot x_1) + (x_{T+2} \cdot x_2) + \dots + (x_T \cdot x_{T-2})$$

$$\|\hat{a}\| = \sqrt{x_1^2 + x_2^2 + \dots + x_T^2} = \sqrt{1^2 + (-1)^2 + \dots + (-1)^2} = \sqrt{T}$$

$$\|\hat{b}\| = \sqrt{(1)^2 + (-1)^2 + \dots + (-1)^2} = \sqrt{1+1+1+1+\dots+1} = \sqrt{T}$$

Hence $\|\hat{a}\| = \|\hat{b}\| = \sqrt{T}$

Then

$$R(z) = \beta = \frac{\hat{a}^T \hat{b}}{\|\hat{a}\| \|\hat{b}\|}$$

$$R(z) = \frac{(x_{z+1}, x_1) + (x_{z+2}, x_2) + \dots + (x_T, x_{T-z})}{\sqrt{T} \cdot \sqrt{T}}$$

$$R(z) = \frac{1}{T} \sum_{t=1}^{T-z} x_t x_{t+z}$$

Answer

$$(x \cdot x) + (x \cdot xk) + (xk \cdot xk) + \dots$$

$$(x \cdot xk) + \dots$$

$$= (x \cdot xk) + (xk \cdot xk) + \dots$$

$$= (x \cdot xk) + (xk \cdot xk) + \dots$$

$$= (x \cdot xk) + (xk \cdot xk) + \dots$$

(d) τ denotes the number of meals served by a restaurant on day τ .

It is observed that $R(7)$ = fairly High

$R(14)$ = also High but not as high.

Explanation \Rightarrow

with previous examples we understand that.

$$R(0) = 1$$

i.e. correlation b/w data points is highest when there is no time lag ($\tau=0$), data points are same.

but as we increase time lag. Then $R(\tau)$ start decreasing b/c correlation b/w data points will decrease over time.

ultimately when ($\tau \geq 7$) $R(\tau) = 0$.

In above question $R(7)$ = fairly high

b/c autocorrelation function is telling us that numbers of meals served from day 1 to 7 form patterns which are highly correlated

but $R(14)$ is not as high b/c since there are more data points for over 14 days the correlation b/w the data pattern decreases.

Hence $R(14)$ is less.

Problem 4.2 \Rightarrow

(a) Repeating k-means algorithm on given dataset twice for $k=2$, $k=5$, $k=10$ value & observing result.

$k=2$ Observations =

1st Repetition = In first repetition final convergence was achieved in 8 iterations. and data was grouped into two clusters. Below are the values of J_{clust} in each iteration.

$$[J_1 = 0.914, J_2 = 0.897, J_3 = 0.896, J_4 = 0.897, \\ J_5 = 0.874, J_6 = 0.873, J_7 = 0.872, J_8 = 0.872]$$

convergence was achieved in 7th and 8th iteration. and data was grouped in two clusters.

2nd Repetition = In second Repetition result changed dramatically. data was grouped into clusters in 6 iterations. J_{clust} values =
[$J_1 = 0.93, J_2 = 0.917, J_3 = 0.902, J_4 = 0.90, J_5 = 0.899 \\ J_6 = 0.899$]

convergence was achieved in 5th and 6th iteration.

Conclusion = For ($k=2$) the first run was slower which took more iterations to cluster the data but it minimized J effectively. Hence it did clustering more effectively ($J_B = 0.872$)

On the other hand 2nd run was fast but clustering was not effective b/c value of J is high.

$J_B = 0.899$ compared to 1st run.

K=5 Observations

1st repetition = In first repetition clustering process was little faster, data was clustered into 5 clusters in 7 iterations. J values are given as -

$$[J_1 = 0.875, J_2 = 0.825, J_3 = 0.810, J_4 = 0.775, \\ J_5 = 0.770, J_6 = 0.770]$$

convergence was achieved in 7th iteration.

2nd repetition = In second repetition clustering process was little slower than the first repetition, data was clustered into 5 clusters in 9 iterations. J values are given as follows →

$$[J_1 = 0.864, J_2 = 0.790, J_3 = 0.787, J_4 = 0.785, J_5 = 0.775, \\ J_6 = 0.775, J_7 = 0.775]$$

$$[J_1 = 0.864, J_2 = 0.796, J_3 = 0.794, J_4 = 0.790, J_5 = 0.787, \\ J_6 = 0.786, J_7 = 0.785, J_8 = 0.780, J_9 = 0.780]$$

Conclusion = for K=5, 1st repetition was more effective and efficient, it completed only in 6 iteration compared to 2nd repetition which completed in 9 iterations. also in 1 repetition value of J was minimized effectively. we can see final J. value which is $J_6 = 0.770$.

$J_{min} = 0.770$ $J_{min} = 0.780$
In first Run In second Run

K=10 observations =

1st repetition \Rightarrow for K=10 first repetition took Total 8 iterations to do the data clustering, to group data into 10 clusters. value of J are as below -

$[J_1 = 0.825, J_2 = 0.765, J_3 = 0.745, J_4 = 0.740]$
 $[J_5 = 0.739, J_6 = 0.738, J_7 = 0.738, J_8 = 0.738]$

convergence was achieved in 6th, 7th & 8th iteration.

2nd Repetition = for K=10, second run also took 8 iterations to cluster the data into 10 groups. value of J are as follow -

$[J_1 = 0.820, J_2 = 0.736, J_3 = 0.734, J_4 = 0.731]$
 $[J_5 = 0.730, J_6 = 0.729, J_7 = 0.727, J_8 = 0.727]$

convergence was achieved in 8th iteration.

Conclusion = Both the runs took same number of iterations to cluster the data into 10 groups but the second iteration run was more effective than the first run because in the second run value of J was minimized in better way.

In First Run $J_{\min} = 0.738$ $>$ In Second Run $J_{\min} = 0.727$

Hence 2nd Run was more effective

(b) = Topic discovery | Titles | words →

I chose $K=5$. and below are the results =
 $K=5$ mean There would be 5 cluster of
documents articles. My analysis gives following
information.

(Titles)

Centroid 1

Top articles associated

- BoocK
- Bulbasaur
- Deoxy
- Evee
- Gameplay of pokémon
- new
- Pikachu
- Pokémon anime

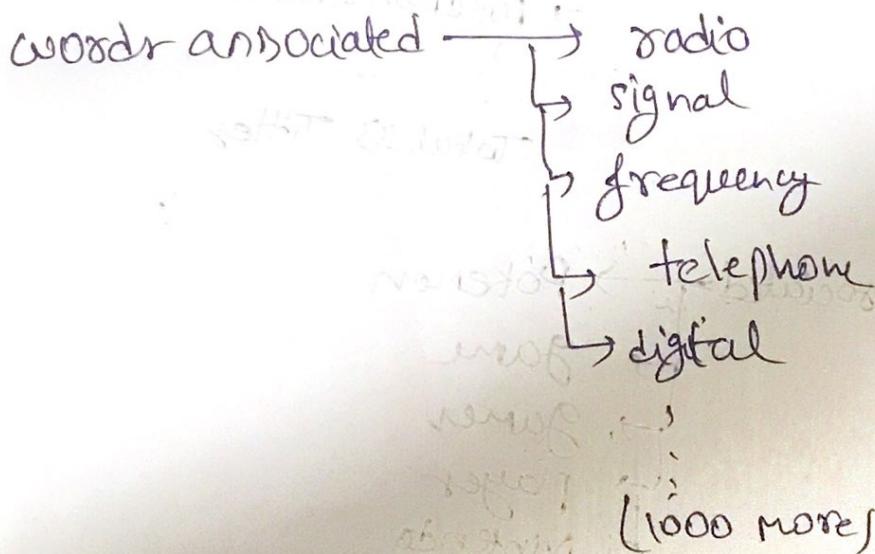
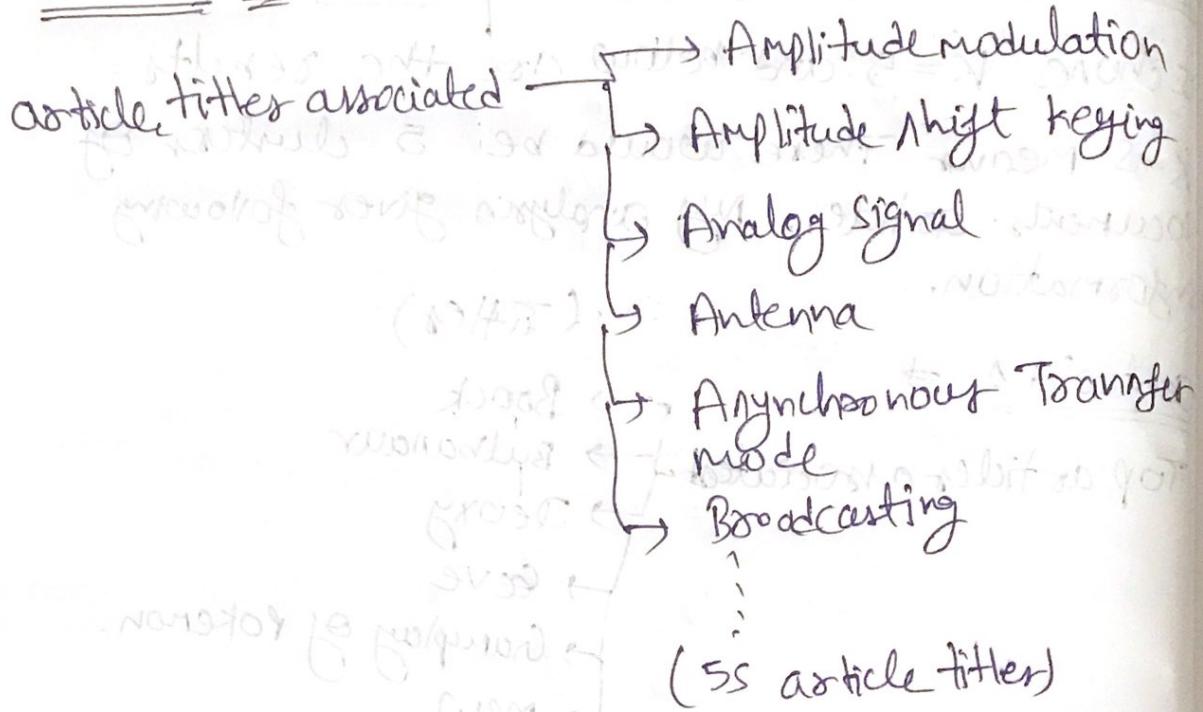
Total 33 Titles

Top words associated

- Pokémon
- game
- gamer
- player
- Nintendo
- Pikachu

Description - This cluster indicates that the
most articles are about a specific
game for Pokemons which players can play
on nintendo.

Centroid 2 = 3000 | 62.5 | (Titter)



Description = The articles in cluster 2 are about "Transmission of Signals" and Signal Properties.

Centroid 3 =

= Phenomena

Article titles associated

Acid rain

Albedo

Anemometer

Atmosphere

Atmosphere of Earth

Barograph

Barometer

cession

famine

flood

(100 titles more)

associated words

weather

wind

pressure

air

temperature

Ice

articles are mostly written about weather & environment

Description = articles associated to this group

are mainly about, earth climate,

Atmosphere & weather.

Centroid 4 =

= & Centroids

article Title

Associated

convention on the Rights of
Persons with disabilities

Headquarters of the United
Nations

International Bank for Reconstruction
and Development

World Bank group
United Nations

UN Women

UNESCO

UNICEF

Associated
words

nations

International
members

council

general

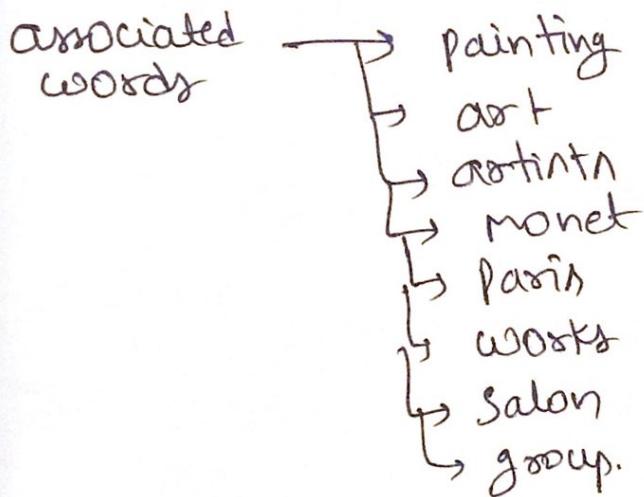
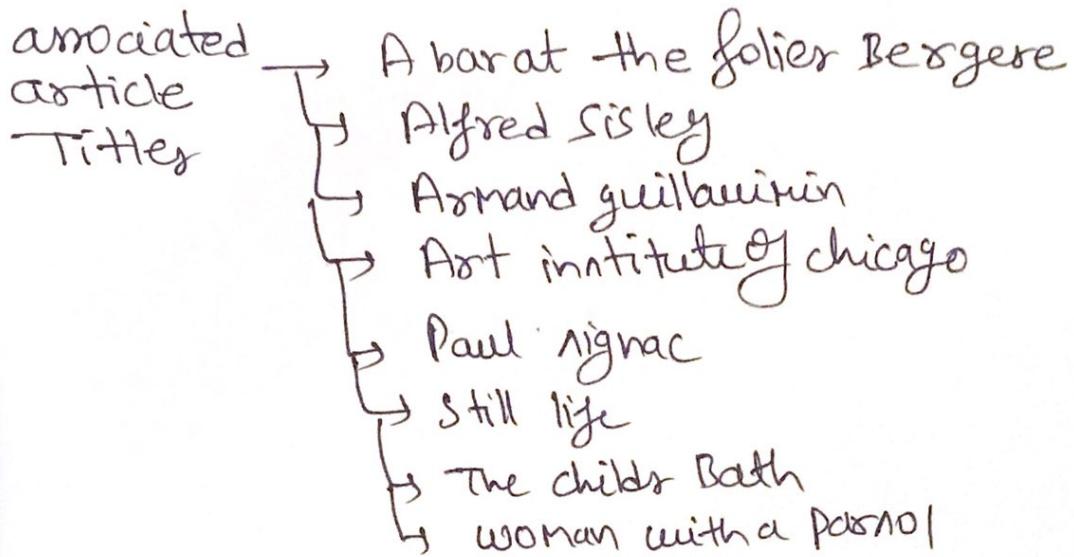
convention

assembly

rights.

Description = The articles in this Cluster are mainly about International organization which work for people around the world globally like UN, UNESCO etc.

Centroid 5 =



Description = The articles in this group will mainly be about different art forms like acting, painting and different famous artworks or famous artists in their respective field.