

Operating Systems

Deadlock

Deadlock Bugs

Thread 1:

```
lock(L1);
```

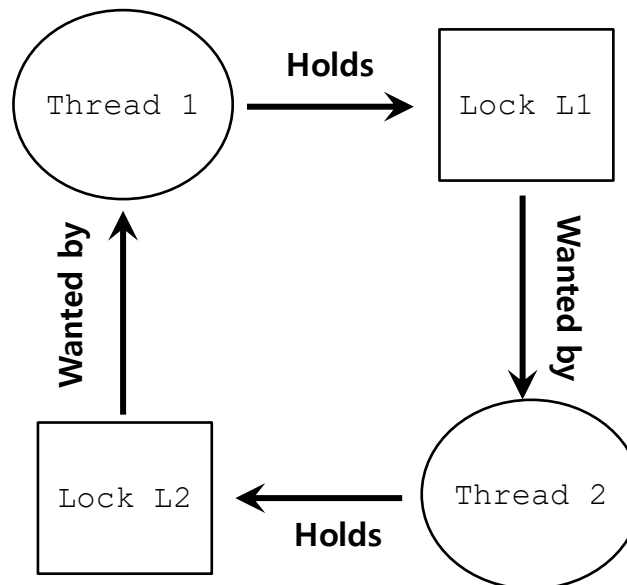
```
lock(L2);
```

Thread 2:

```
lock(L2);
```

```
lock(L1);
```

- ◆ The presence of a cycle
 - Thread1 is holding a lock L1 and waiting for another one, L2.
 - Thread2 that holds lock L2 is waiting for L1 to be released.



Why Do Deadlocks Occur?

▣ Reason 1:

- ◆ In large code bases, **complex dependencies** arise between components.

▣ Reason 2:

- ◆ Due to the nature of **encapsulation**
 - Hide details of implementations and make software easier to build in a modular way.
 - Such **modularity** *does not mesh* well with locking.

Conditions for Deadlock

- ▣ Four conditions need to hold for a deadlock to occur.

Condition	Description
Mutual Exclusion	Threads claim exclusive control of resources that they require.
Hold-and-wait	Threads hold resources allocated to them while waiting for additional resources
No preemption	Resources cannot be forcibly removed from threads that are holding them.
Circular wait	There exists a circular chain of threads such that each thread holds one more resources that are being requested by the next thread in the chain

- ◆ If any of these four conditions are not met, **deadlock cannot occur**.

Solutions to Deadlock

- ▣ Prevention
- ▣ Avoidance
- ▣ Detect and Recover

Prevention – Circular Wait

- ▣ Provide a total ordering on lock acquisition
 - ◆ This approach requires *careful design* of global locking strategies.
- ▣ **Example:**
 - ◆ There are two locks in the system (L1 and L2)
 - ◆ We can prevent deadlock by always acquiring L1 before L2.

Prevention – Hold-and-wait

- ▣ Acquire all locks **at once, atomically**.

```
1    lock(prevention);  
2    lock(L1);  
3    lock(L2);  
4    ...  
5    unlock(prevention);
```

- ◆ This code guarantees that **no untimely thread switch can occur** *in the midst of* lock acquisition.
- ◆ **Problem:**
 - Require us to know when calling a routine exactly which locks must be held and to acquire them ahead of time.
 - Decrease *concurrency* as all locks must be acquired early on (at once) instead of when they are truly needed.

Prevention – No Preemption

- ❑ **Multiple lock acquisition** often gets us into trouble because when waiting for one lock **we are holding another**.
- ❑ `trylock()`
 - ◆ Used to build a *deadlock-free, ordering-robust* lock acquisition protocol.
 - ◆ Grab the lock (if it is available).
 - ◆ Or, return -1: you should try again later.

```
1  top:
2      lock(L1);
3      if( tryLock(L2) == -1 ){
4          unlock(L1);
5          goto top;
6      }
```


Prevention – No Preemption (Cont.)

▣ livelock

- ◆ Both systems are running through the code sequence *over and over again*.
- ◆ Progress is not being made.
- ◆ Solution:
 - Add a **random delay** before looping back and trying the entire thing over again.

Prevention – Mutual Exclusion

□ wait-free

- ◆ Using powerful **hardware instruction**.
- ◆ You can build data structures in a manner that *does not require explicit locking*.

```
1  int CompareAndSwap(int *address, int expected, int new) {  
2      if(*address == expected) {  
3          *address = new;  
4          return 1; // success  
5      }  
6      return 0;  
7  }
```

Prevention – Mutual Exclusion (Cont.)

❑ Example: list insertion

- ◆ Surrounding this code with a **lock acquire** and **release**.

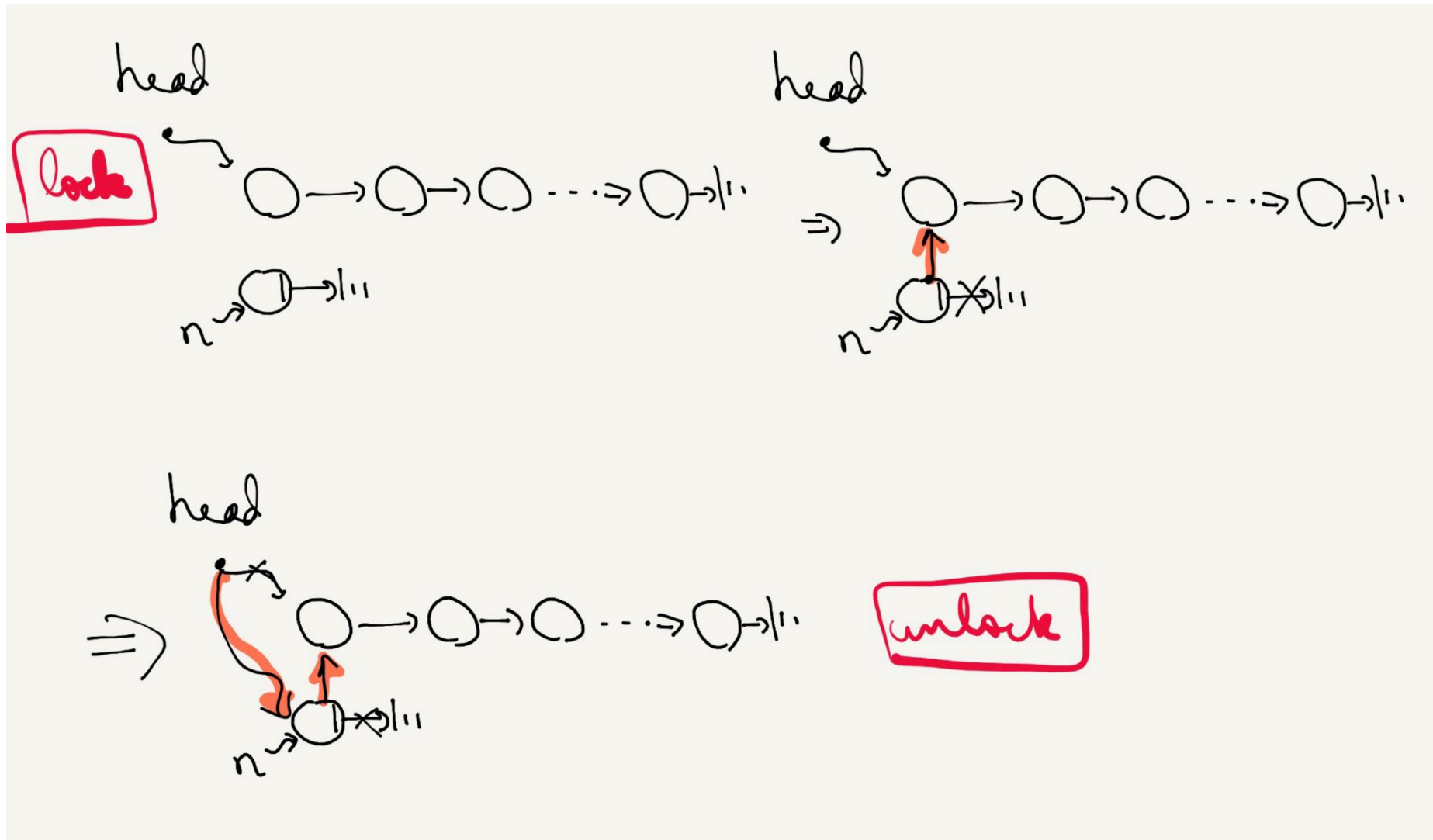
```
1  void insert(int value){
2      node_t * n = malloc(sizeof(node_t));
3      assert( n != NULL );
4      n->value = value ;
5      lock(listlock); // begin critical section
6      n->next  = head;
7      head     = n;
8      unlock(listlock) ; //end critical section
9  }
```

- ◆ **wait-free manner** using the compare-and-swap instruction

```
1  int CompareAndSwap(int *address, int expected, int new){
2      if(*address == expected){
3          *address = new;
4          return 1; // success
5      }
6      return 0;
7  }
```

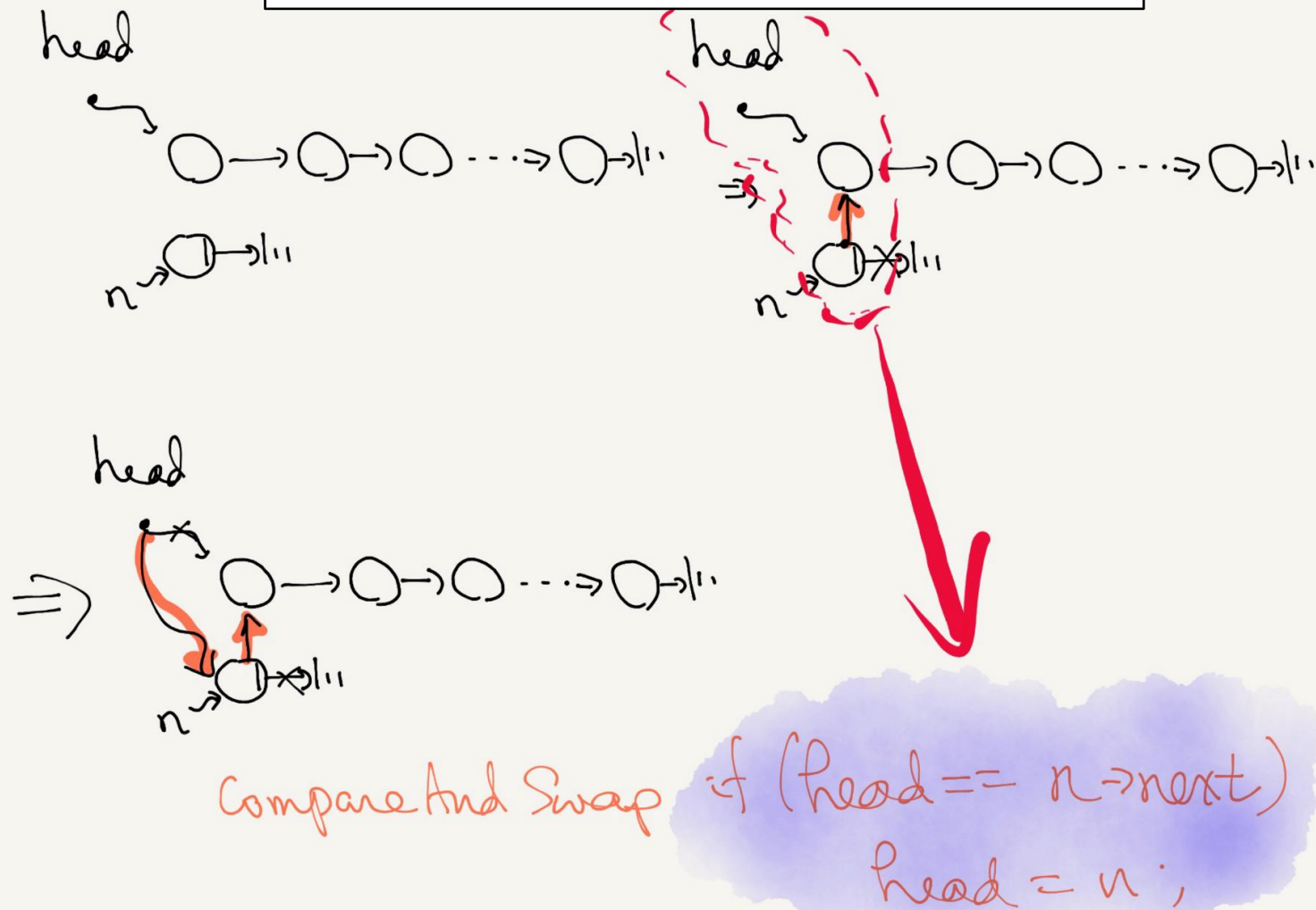
```
1  void insert(int value) {
2      node_t *n = malloc(sizeof(node_t));
3      assert(n != NULL);
4      n->value = value;
5      do {
6          n->next = head;
7      } while (CompareAndSwap(&head, n->next, n));
8  }
```

Insert with lock



Lock-free insert

```
1 void insert(int value) {  
2     node_t *n = malloc(sizeof(node_t));  
3     assert(n != NULL);  
4     n->value = value;  
5     do {  
6         n->next = head;  
7     } while (CompareAndSwap(&head, n->next, n));  
8 }
```



Deadlock Avoidance via Scheduling

- ▣ Deadlock Avoidance
 - ◆ Get the information about the locks various threads might grab during their execution.
 - ◆ schedule the threads in a way to guarantee no deadlock can occur.
- ▣ In some scenarios, **deadlock avoidance** is preferable.
- ▣ Problem: Global knowledge is required.

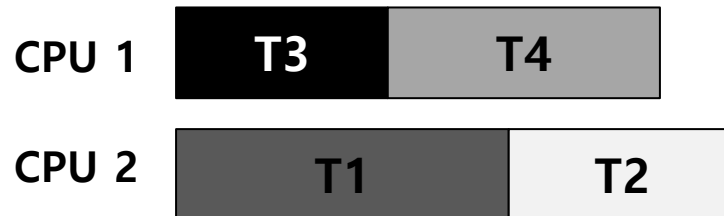
Example of Deadlock Avoidance via Scheduling (1)

- We have two processors and four threads.

- ◆ Lock acquisition demands of the threads:

	T1	T2	T3	T4
L1	yes	yes	no	no
L2	yes	yes	yes	no

- ◆ A smart scheduler could compute that as long as T1 and T2 are not run at the same time, no deadlock could ever arise.



Example of Deadlock Avoidance via Scheduling (2)

- More contention for the same resources

	T1	T2	T3	T4
L1	yes	yes	yes	no
L2	yes	yes	yes	no

- A possible schedule that guarantees that *no deadlock* could ever occur.



- The total time to complete the jobs is lengthened considerably.

Detect and Recover

- ▣ Allow **deadlock** to occasionally occur and then *take some action*.
 - ◆ **Example:** if an OS froze, you would reboot it.
- ▣ View system as graph
 - ◆ Processes and Resources are nodes
 - ◆ Resource Requests and Assignments are edges
- ▣ If graph has no cycles → no deadlock
- ▣ If graph contains a cycle
 - ◆ Definitely deadlock if only one instance per resource
 - ◆ Otherwise, maybe deadlock, maybe no
- ▣ Many database systems employ *deadlock detection* and *recovery technique*.
 - ◆ A deadlock detector **runs periodically**.
 - ◆ Building a **resource graph** and checking it for cycles.
 - ◆ In deadlock, the system **need to be restarted**.