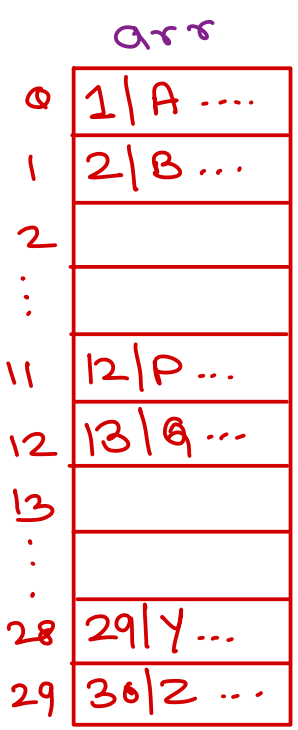
Data Structure & Algorithms

Nilesh Ghule

Hash Table

- Associative data structure → key-value pair (association)
- Stores key-value so that for a given key, value can be searched in fastest possible time. Ideal time complexity is O(1).
- Example: ↳ no collision



hash fn

$f(r) = r - 1$

roll no = r
↳ index = r-1

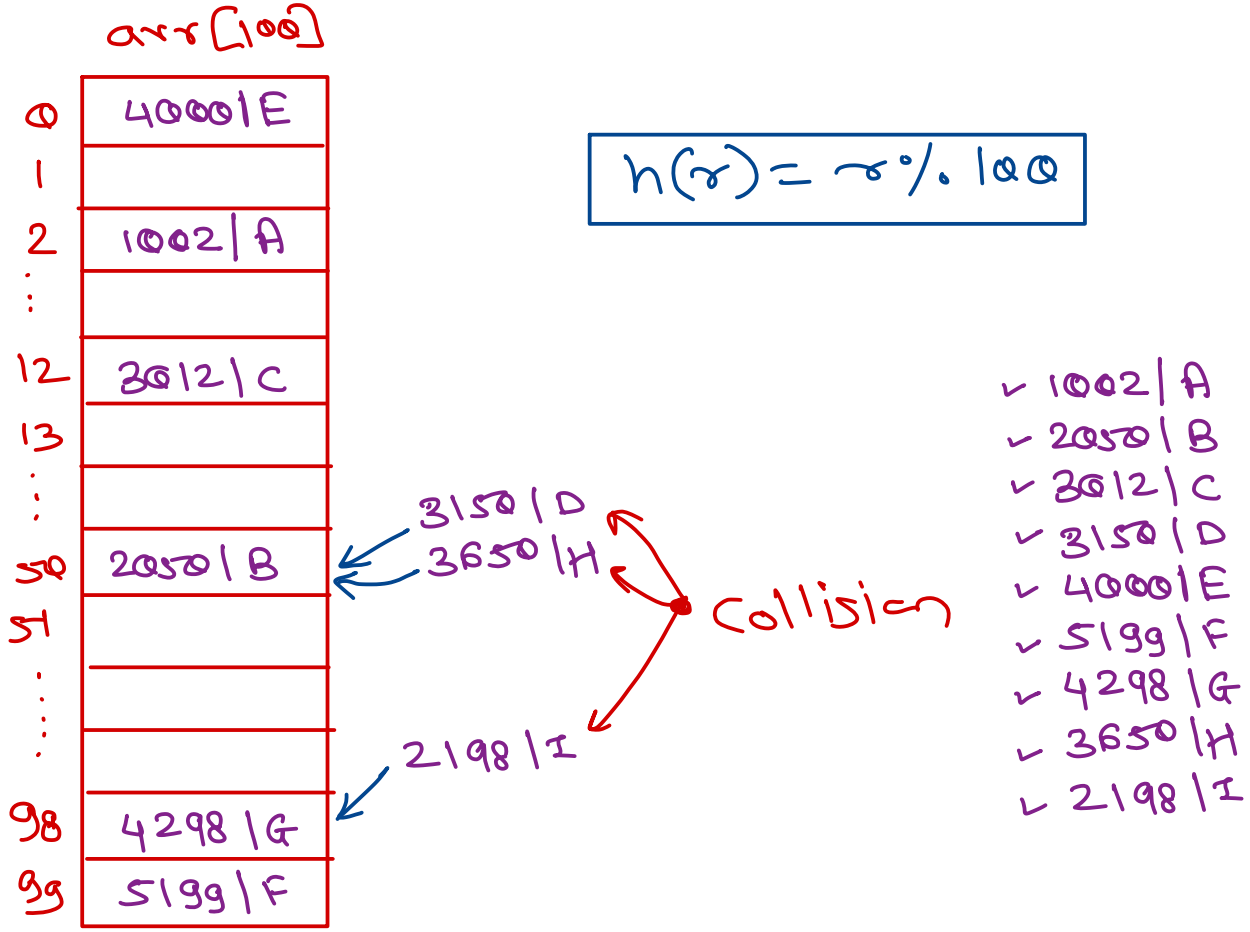
```
put(r, stud):
    arr[r-1] = stud;

get(r):
    return arr[r-1];
```

programming language terms	data structure & algorithm terms
① array	① table
② index	② slot
③ math fn to decide the index in which value to be stored	③ math fn of key ($f(k)$) to decide the slot or table in which value to be stored ↳ hash fn

Hash Table

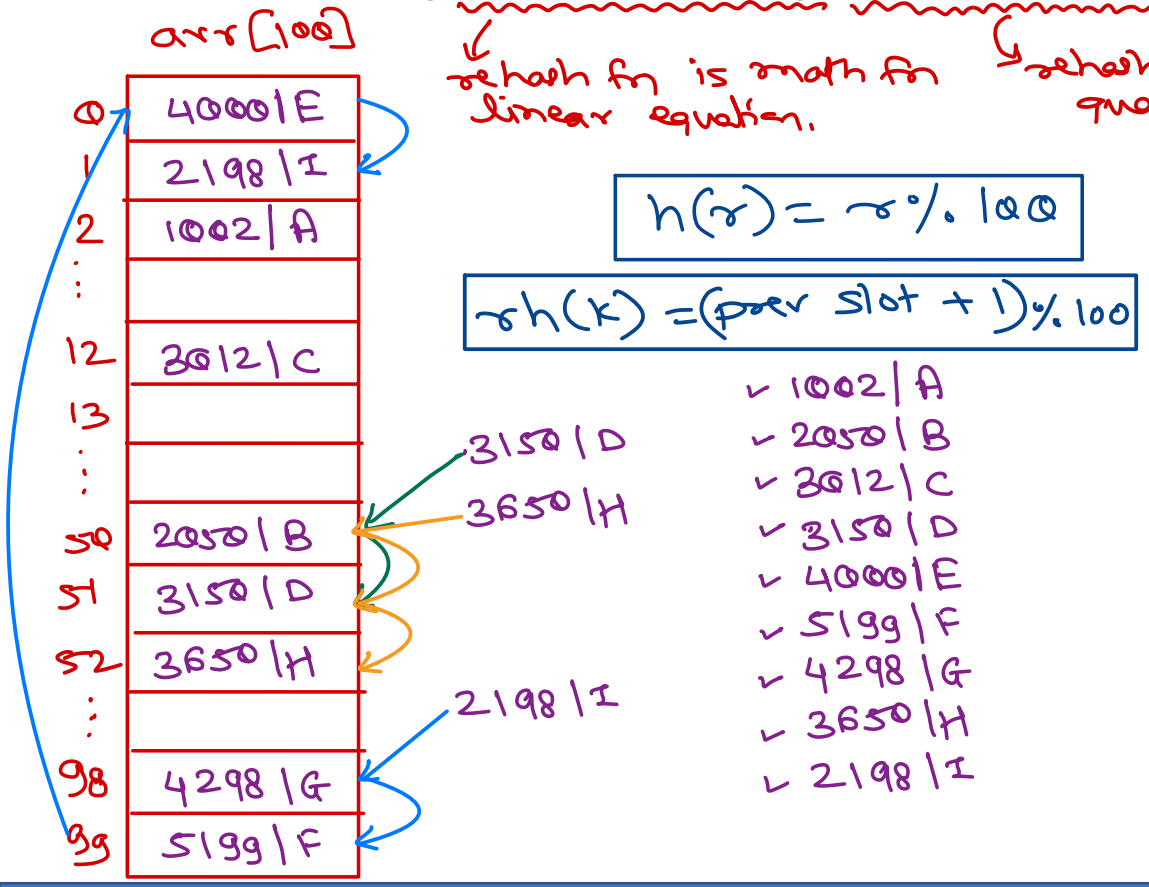
- Hash Function is math function of key, that yields slot in the table.
- If different keys resulting in same slot in the table, it is called as collision.



Hash Table

- Collision handling methods: Open addressing or Chaining
- Open addressing
  - Rehashing: Linear probing, Quadratic probing, …

h(k) → slot of table
if slot is already occupied,
call another math fn to find next possible slot. (Repeat it until an empty slot is found).
Rehash fn
e.g. rh = (h(k)+1)%.size
or rh = (rh(k)+1)%.size



rehash fn is math for linear equation.

rehash fn is math for quadratic equation.

$$h(r) = r \% .100$$

$$rh(k) = (\text{prev slot} + 1) \% .100$$

- 1002|A
- 2050|B
- 2012|C
- 3150|D
- 40000|E
- 5199|F
- 4298|G
- 3650|H
- 2198|I

```
KeyValue arr[100];
  ↳ fields: key, value.

put(K,V):
    index = K%.100; //hash fn
    while(arr[index] != null)
        index = (index+1)%.100; //rehash
    arr[index] = (K,V);

get(K):
    index = K%.100; //hash fn          → cnt = 1;
    while(arr[index] != null){         → if (cnt > 100) return null;
        if (arr[index].key == K)
            return arr[index].value;
        index = (index+1)%.100; //rehash → cnt++;
    }
    return null; //no KV found.
```

Hash Table

- Load factor = Number of entries / Number of slots
  - key-value pairs
  - array size
- Cases
  - Load factor < 1
  - Load factor = 1
  - Load factor > 1

open addressing:

- ✓ all entries (kv) are stored in the array/table.
- ✓ storage is internal to the table.
- ✓ if occupied (↳ insert) / not match (↳ find), then find the next address (infinitely), until empty (↳ insert) / desired slot found (↳ find)

arr(100)
kv pairs = 75
entries < arr size
L.F. < 1

arr(100)
kv pairs = 100
entries == arr size
L.F. = 1

arr(100)
kv pairs = 120
entries > arr size
L.F. > 1

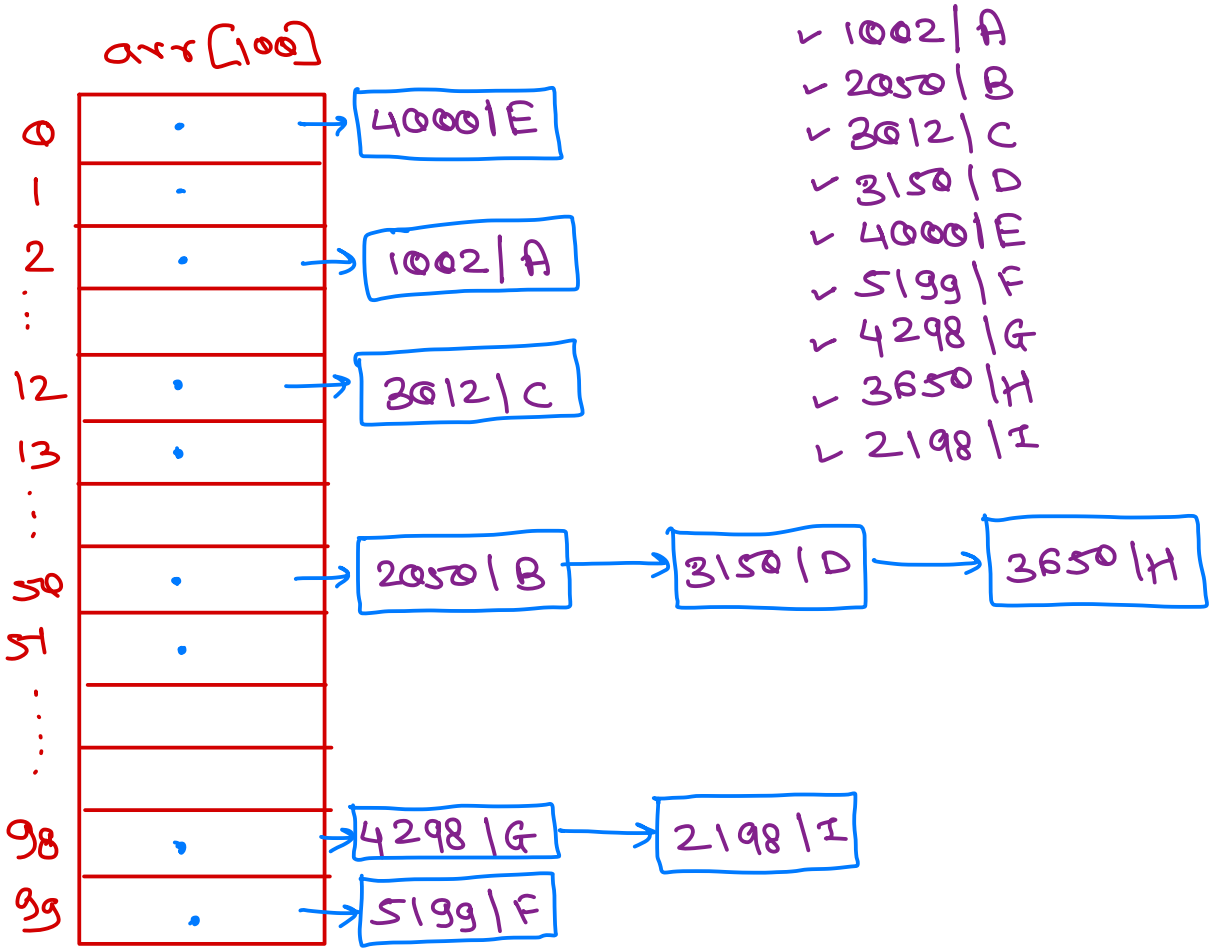
open addressing or chaining

chaining

Hash Table

- Chaining

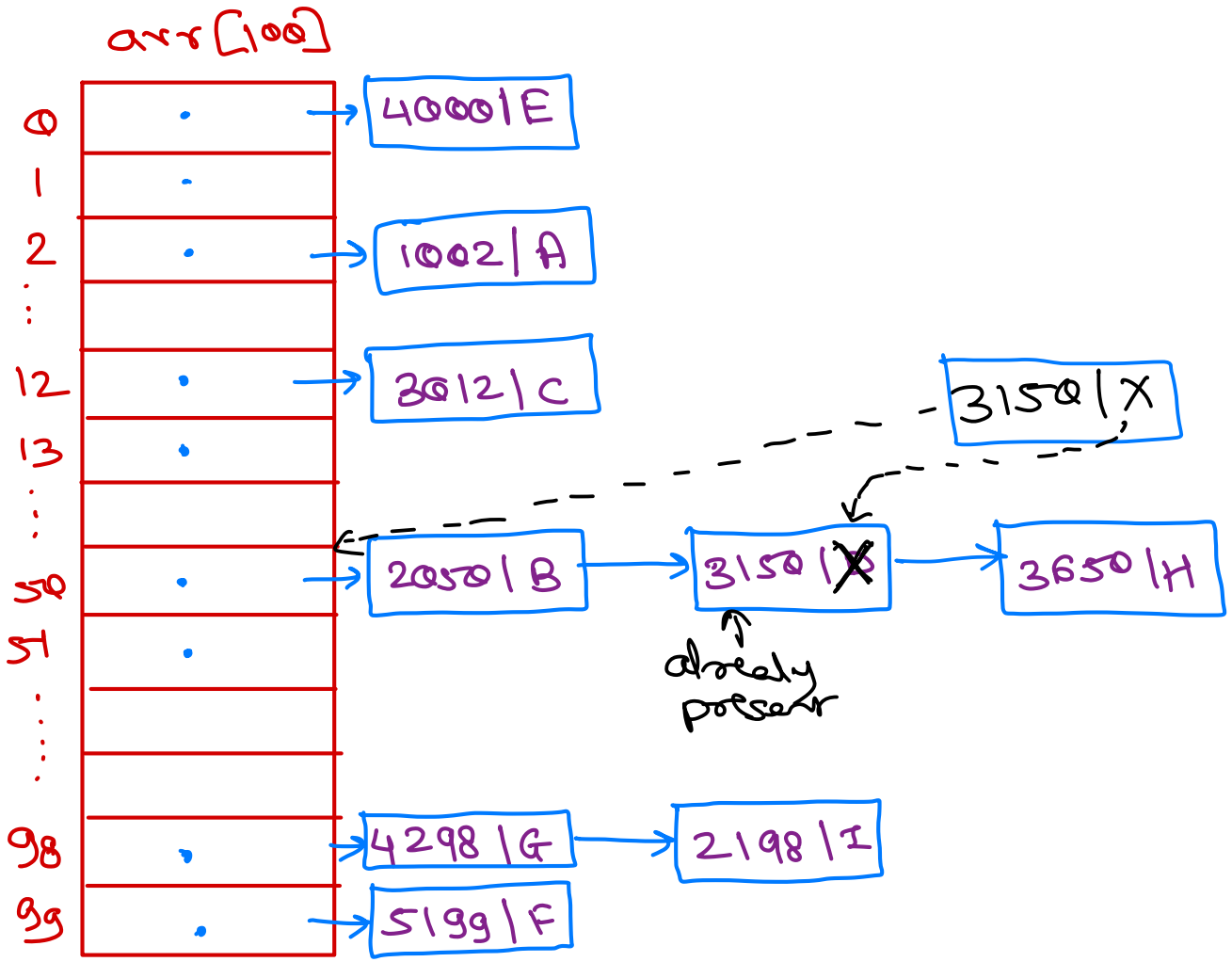
$h(r) = r \% 100$



- 1002|A
- 2050|B
- 3012|C
- 3150|D
- 40001|E
- 5199|F
- 4298|G
- 3650|H
- 2198|I

- each slot in the table hold a collection of key-value pairs/entries called as buckets.
- Note that, actual KV pairs/entries are not stored in table. The storage is external to the table.
- if multiple entries collide (same slot in table), then they will be added in same bucket..
- num of entries can be greater, equal or lesser than table size (num of buckets).
- generic impl of hashtable (irrespective of load factor). So C++ STL map<>, Java HashMap/HashTable, Python/C# Dictionary internally follow chaining.

Hash Table




```
List arr[100]; // arr[i] is a list.
               // each entry in list is KeyValue pair.

put(K,V):
    index = K % 100; //hash fn
    for (KV : arr[index]) {
        if (KV.key == K) {
            KV.value = V;
            return;
        }
    }
    arr[index].add(new KV);

get(K):
    index = K % 100; //hash fn
    for (KV : arr[index]) {
        if (KV.key == K)
            return KV.value;
    }
    return null;
```

Thank you!

Nilesh Ghule <nilesh@sunbeaminfo.com>