



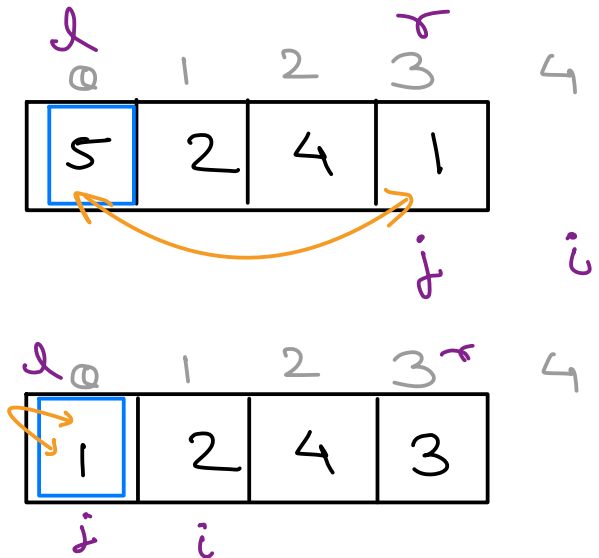
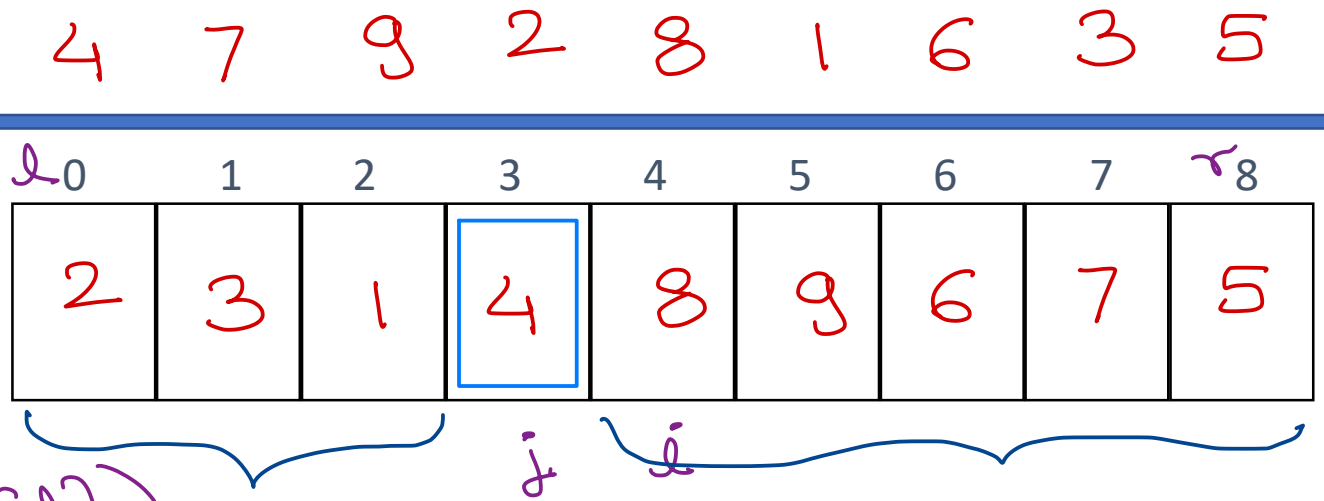
Data Structure & Algorithms

Nilesh Ghule

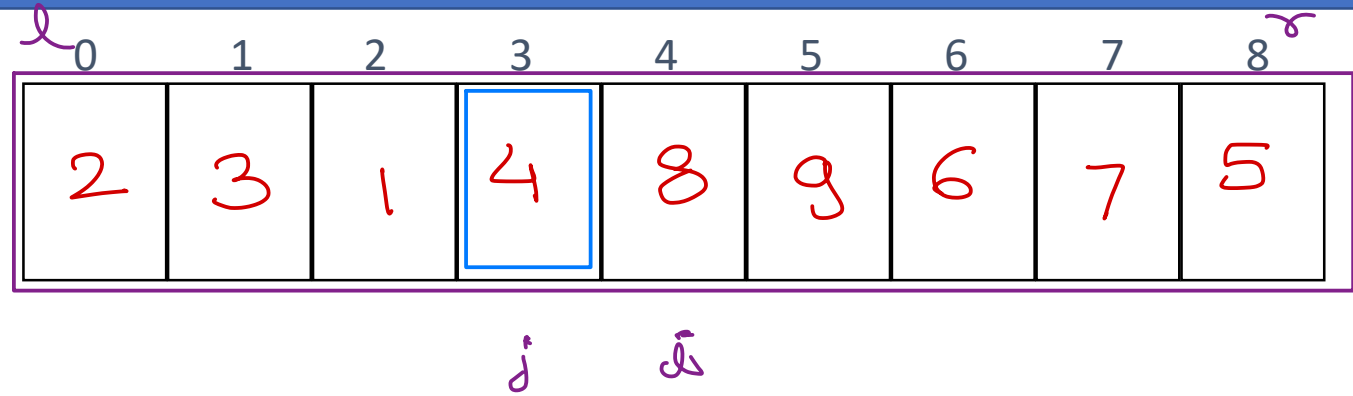


Quick Sort

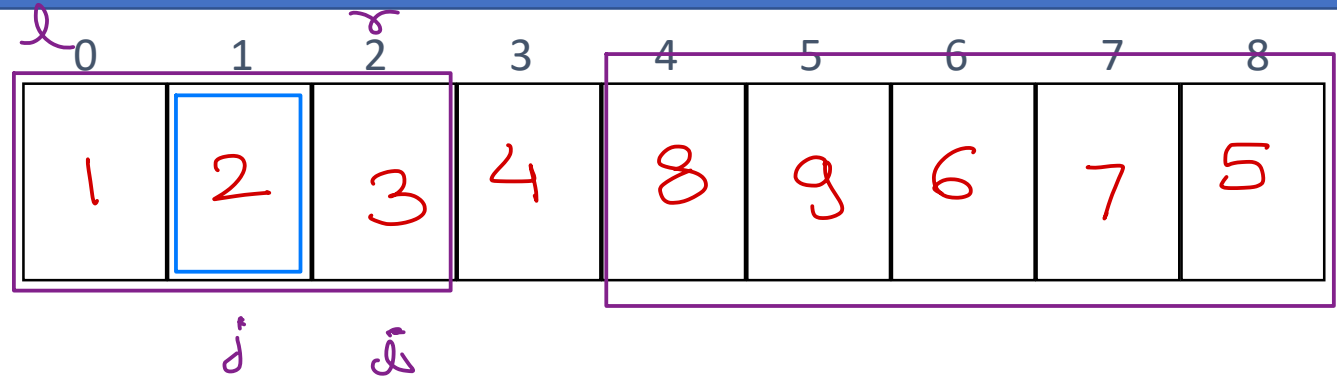
```
if (l >= r)
    return;
// a[l] → pivot
i = l; j = r;
while (i < j) {
    while (i < size && a[i] <= a[l])
        i++;
    while (a[j] > a[l])
        j--;
    if (i < j)
        swap(a[i], a[j]);
}
swap(a[j], a[l]);
quicksort(a, l, j-1);
quicksort(a, j+1, r);
```



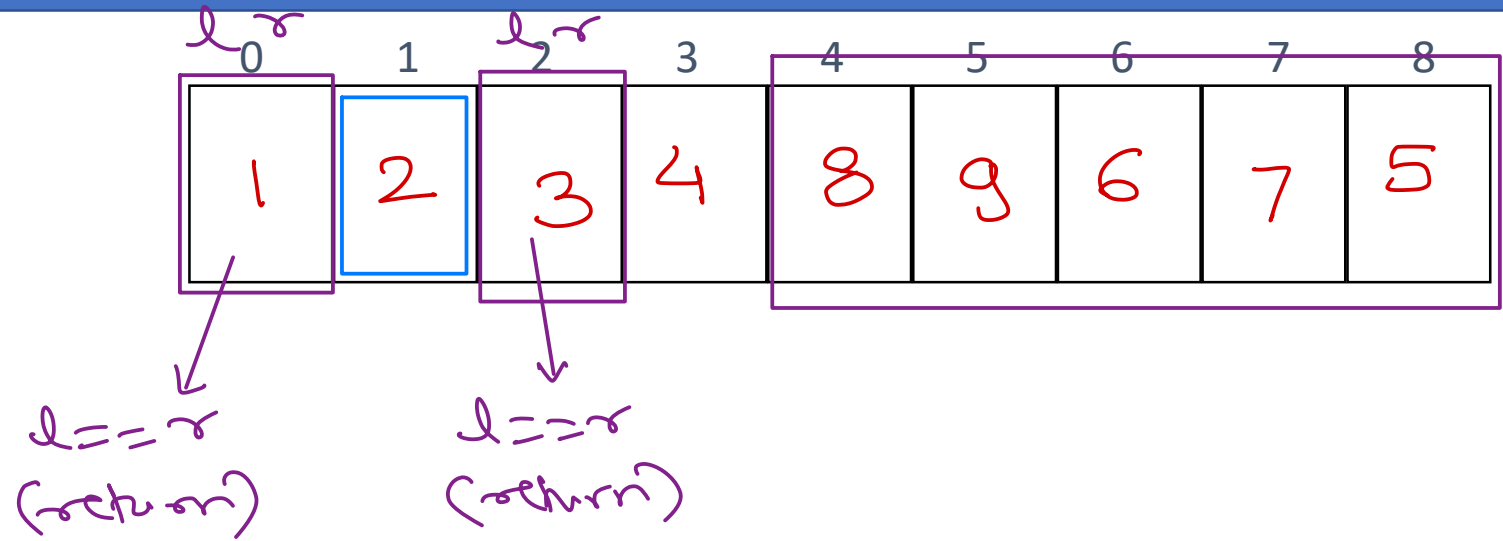
Quick Sort



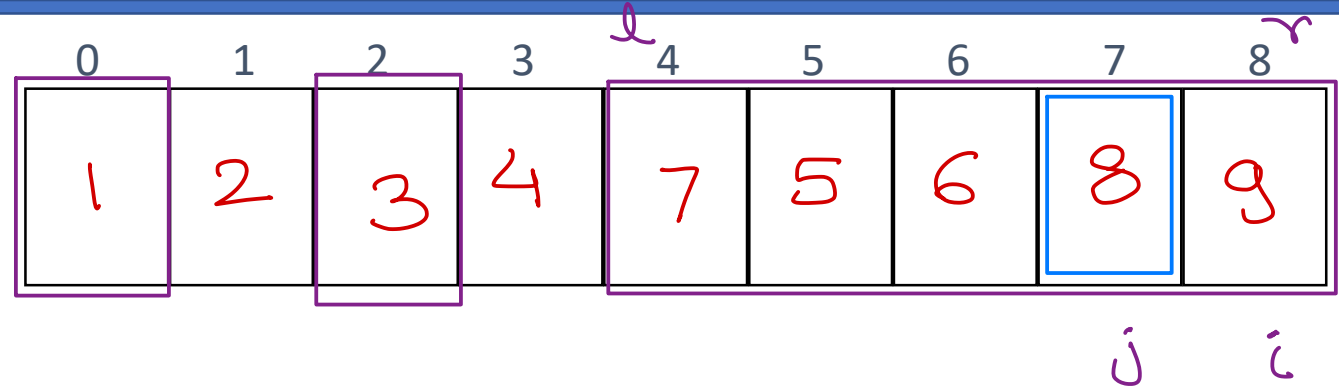
Quick Sort



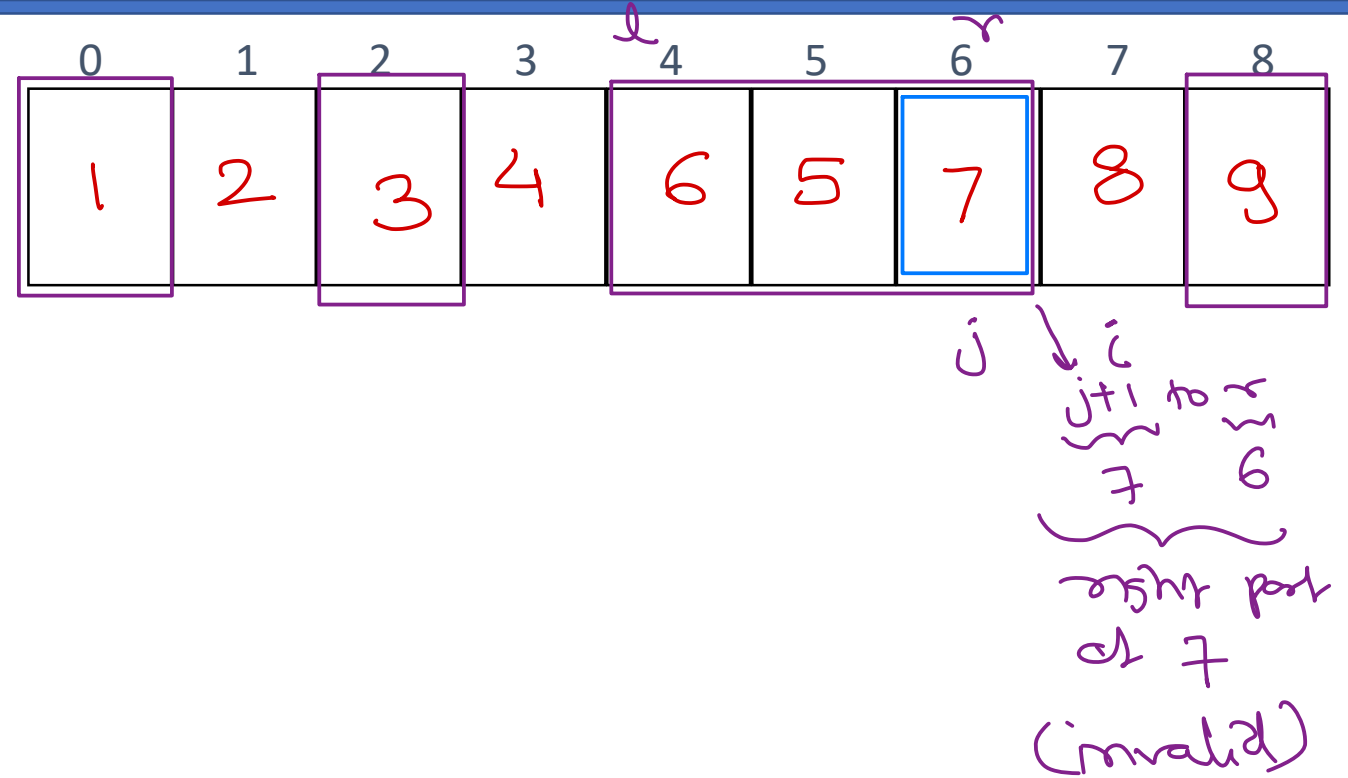
Quick Sort



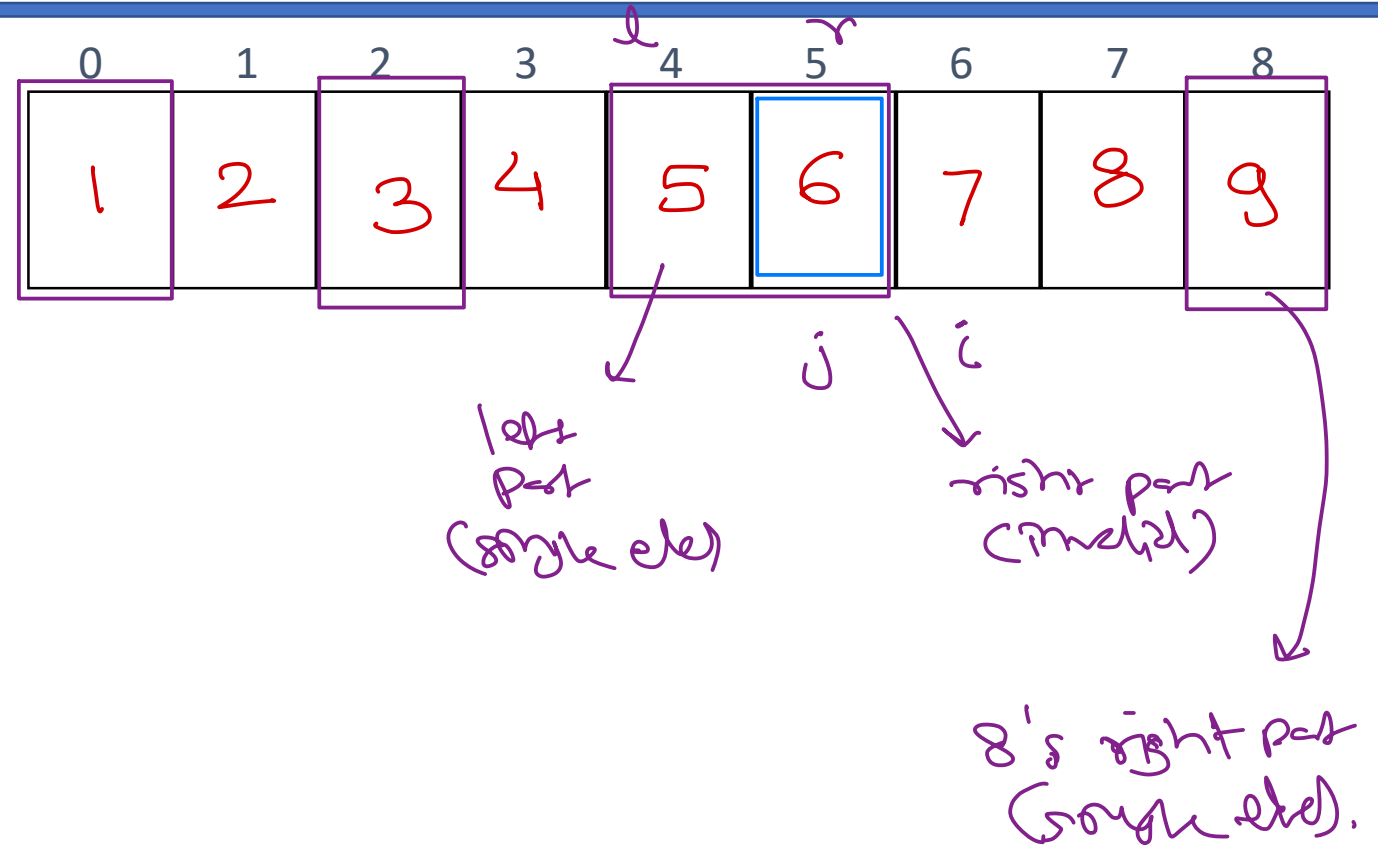
Quick Sort



Quick Sort



Quick Sort

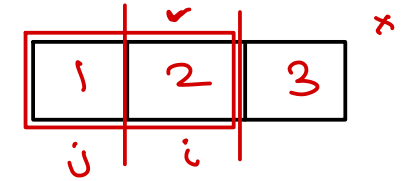


Quick Sort – Time complexity

- Quick sort pivot element can be

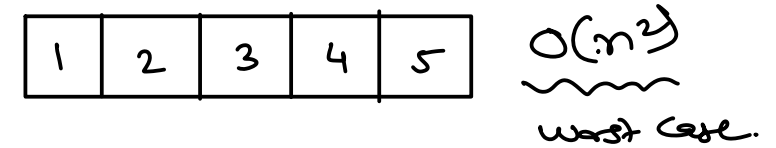
- First element or Last element
- Random element
- Median of the array

← though seems efficient,
calc median is time taking.



- Quick sort time

- Time to partition as per pivot – $T(n)$
- Time to sort left partition – $T(k)$
- Time to sort ~~left~~ right partition – $T(n-k-1)$



- Worst case

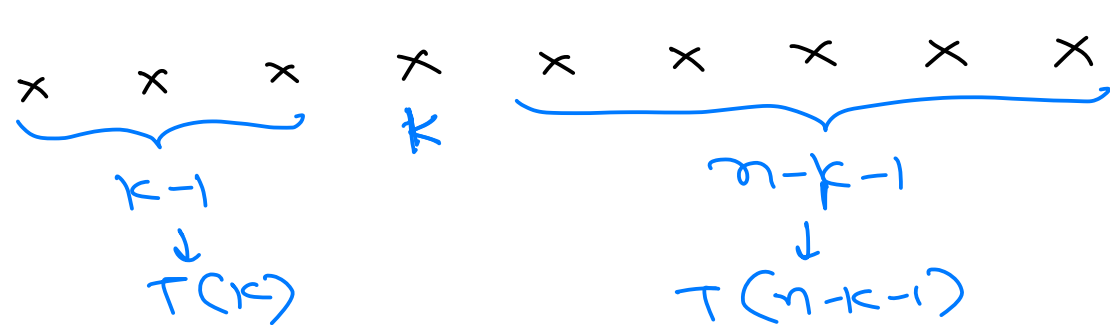
- $T(n) = T(0) + T(n-1) + O(n) \Rightarrow O(n^2)$

- Best case

- $T(n) = T(n/2) + T(n/2) + O(n) \Rightarrow O(\check{n} \log \check{n})$

- Average case

- $T(n) = T(n/9) + T(9n/10) + O(n) \Rightarrow \underline{O(n \log n)}$



Recursion – QuickSort

- Algorithm

1. If single element in partition, return.
2. Last element as pivot.
3. From left find element greater than pivot (x^{th} ele).
4. From right find element less than pivot (y^{th} ele).
5. Swap x^{th} ele with y^{th} ele.
6. Repeat 2 to 4 until $x < y$.
7. Swap y^{th} ele with pivot.
8. Apply QuickSort to left partition (left to $y-1$).
9. Apply QuickSort to right partition ($y+1$ to right).

- QS(arr, 0, 8)

- QS(arr, 0, 3)

- QS(arr, 0, 1)

- QS(arr, 0, 0)

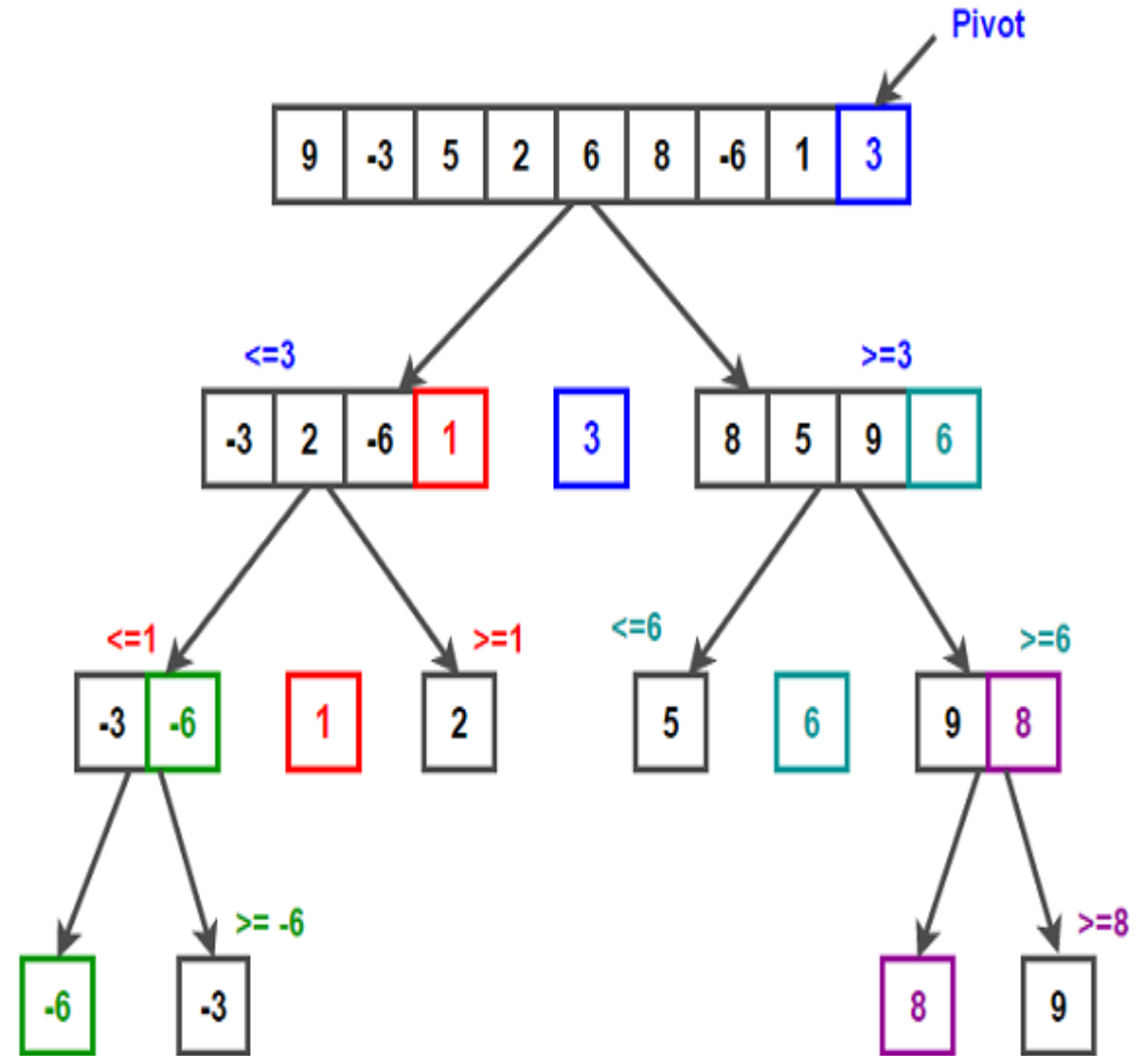
- QS(arr, 3, 3)

- QS(arr, 5, 8)

- QS(arr, 5, 5)

- QS(arr, 7, 8)

- QS(arr, 9, 9)



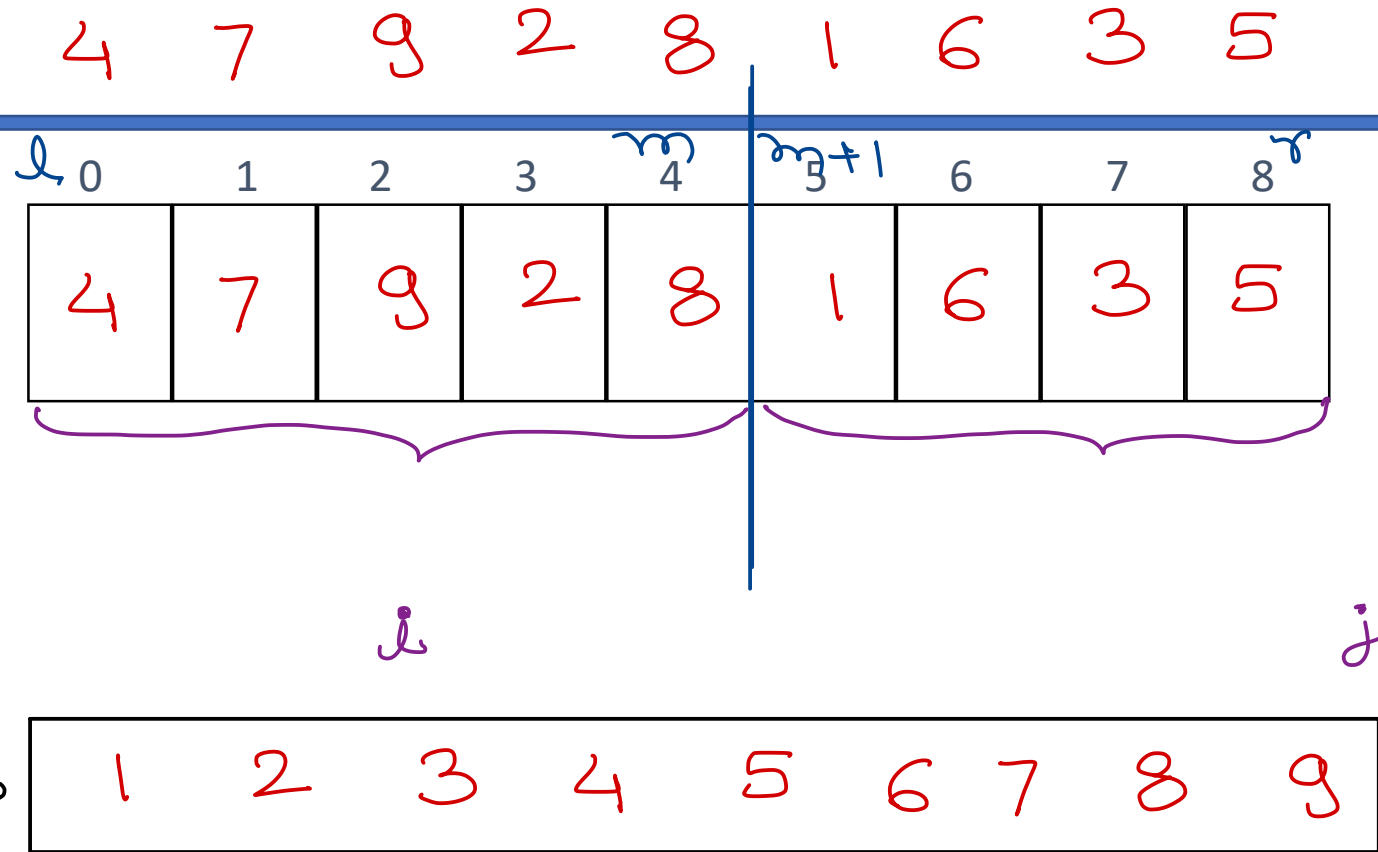
Merge Sort

merge two sorted partitions into a single array

```

if (l >= r)
    return;
m = (l + r) / 2;
mergesort(arr, l, m);
mergesort(arr, m+1, r);
i = left; j = m+1; k = 0;
temp = new int[r-l+1];
while (i <= m && j <= r) {
    if (a[i] < a[j]) {
        temp[k] = a[i];
        i++; k++;
    }
    else {
        temp[k] = a[j];
        j++; k++;
    }
}

```



```

while (i <= m) {
    temp[k] = a[i];
    i++; k++;
}
while (j <= r) {
    temp[k] = a[j];
    j++; k++;
}

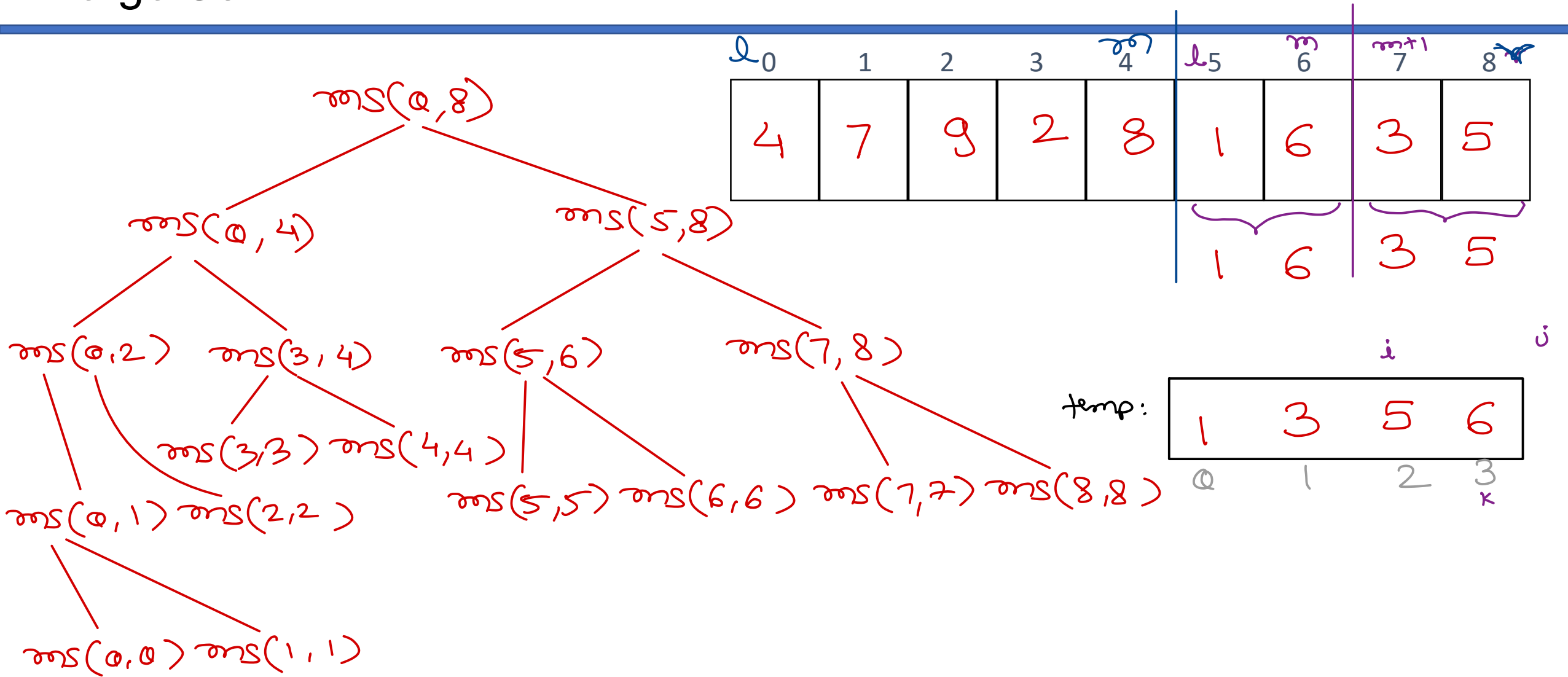
```

```

for (k = 0; k < temp.length; k++)
    a[l+k] = temp[k];

```

Merge Sort - Recursion Tree

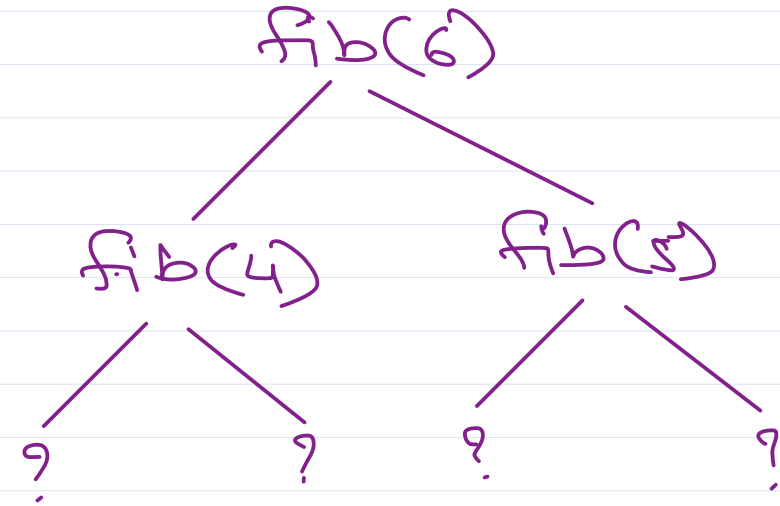


```

int fib(int n) {
    if (n == 1 || n == 2)
        return 1;
    int r = fib(n-1) + fib(n-2);
    return r;
}

```

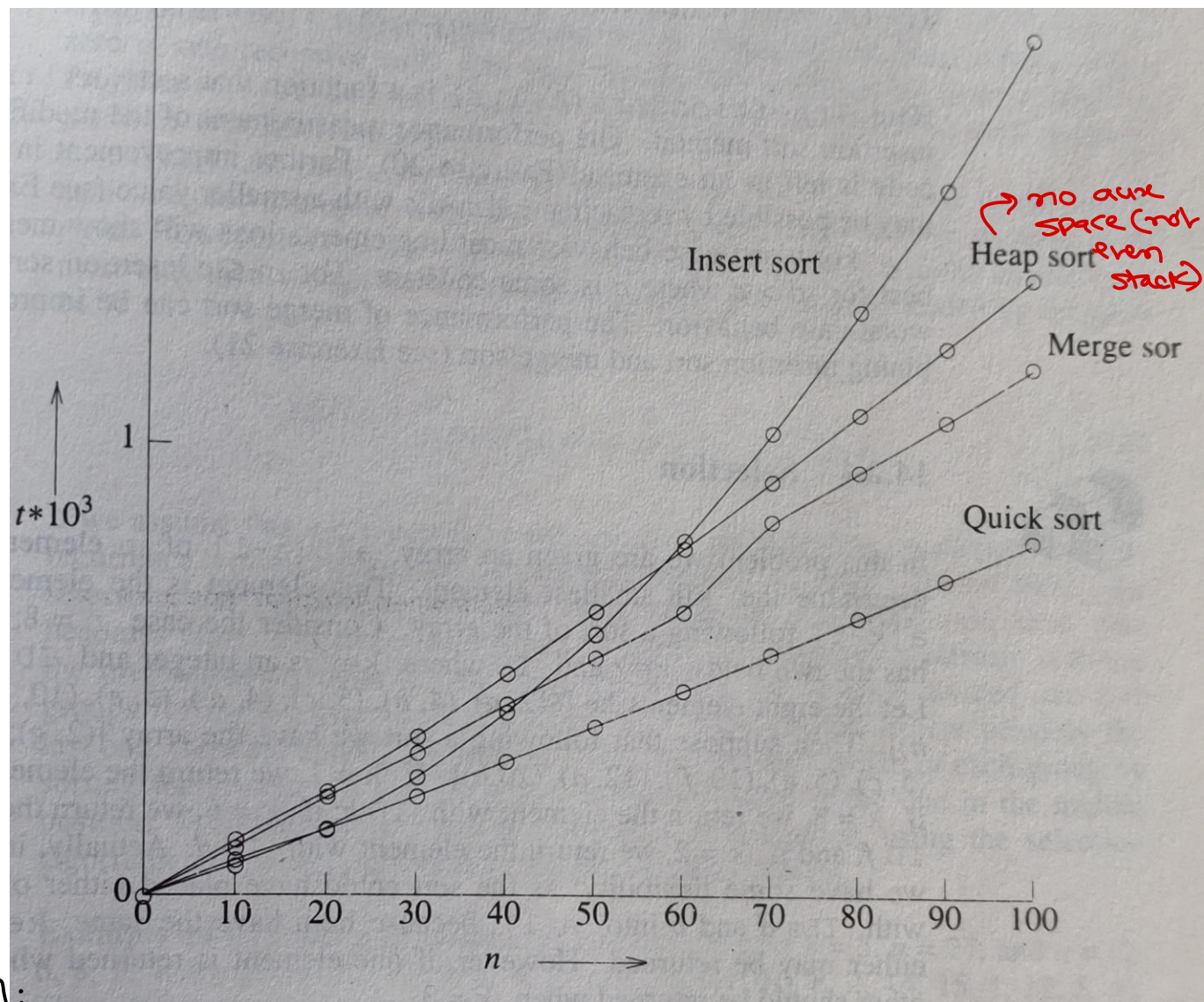
1 1 2 3 5 8 13 21 ...
 ① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ...



Sorting Algorithm Comparison

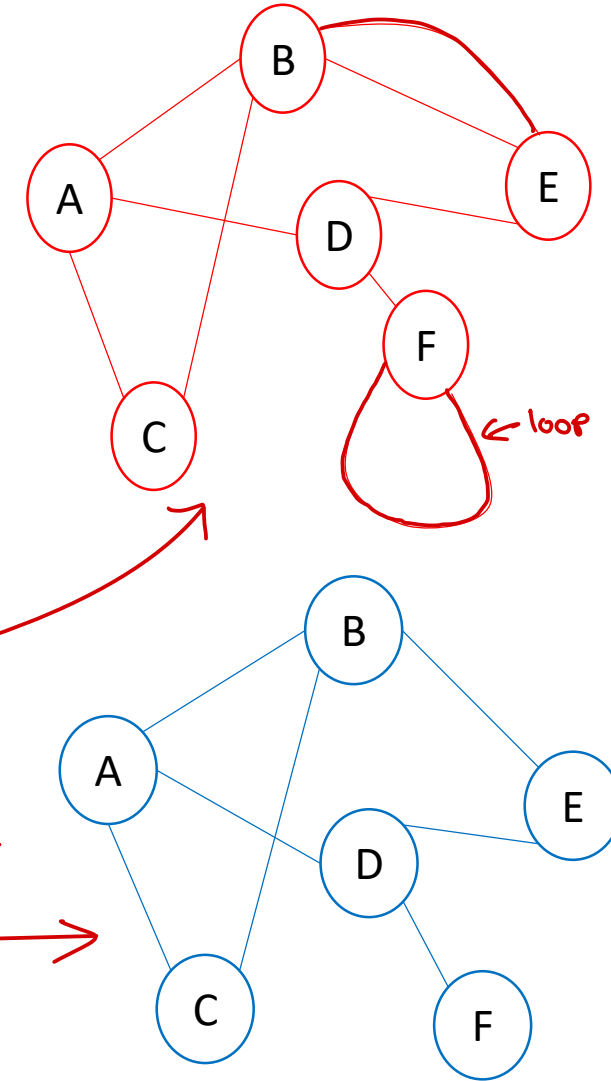
- Selection sort algorithm is too simple, but performs poor and no optimization possible.
- Bubble sort can be improved to reduce number of iterations.
- Insertion sort performs well if number of elements are too less. Good if adding elements and resorting.
- Quick sort is stable if number of elements increase. However worst case performance is poor. $O(n^2)$
- Merge sort also perform good, but need extra auxiliary space.

temp = new int [r - l + 1];



Graph

- Graph is a non-linear data structure.
- Graph is defined as set of vertices and edges. Vertices (also called as nodes) hold data, while edges connect vertices and represent relations between them. $V = \{A, B, C, D, E, F\}$
 $E = \{(A, B), (A, C), (A, D), (B, C), (B, E), (B, F), (D, E), (D, F), (F, F)\}$
 - $G = \{V, E\}$
- Vertices hold the data and Edges represents relation between vertices.
- When there is an edge from vertex P to vertex Q, P is said to be adjacent to Q.
- Multi-graph
 - Contains multiple edges in adjacent vertices or loops (edge connecting a vertex to it-self).
- Simple graph
 - Doesn't contain multiple edges in adjacent vertices or loops.

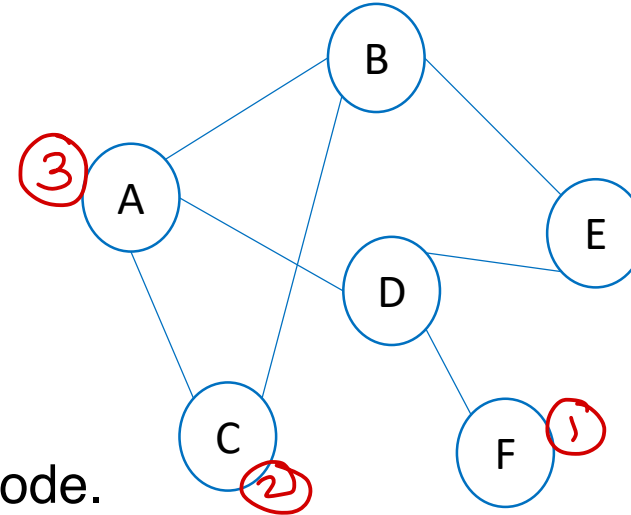


Graph

- Graph edges may or may not have directions.

- Undirected Graph: $G = \{ V, E \}$

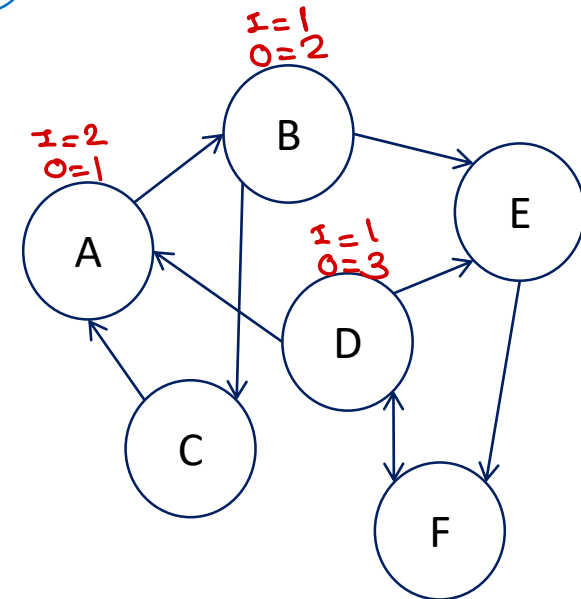
- $V = \{ A, B, C, D, E, F \}$
- $E = \{ (A,B), (A,C), (A,D), (B,C), (B,E), (D,E), (D,F) \}$
- If P is adjacent to Q, then Q is also adjacent to P.
- Degree of node: Number of nodes adjacent to the node.
- Degree of graph: Maximum degree of any node in graph.



- Directed Graph: $G = \{ V, E \}$

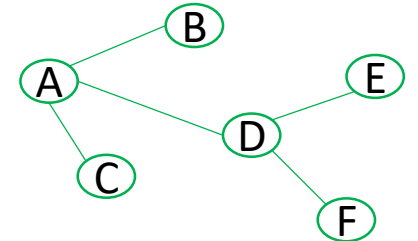
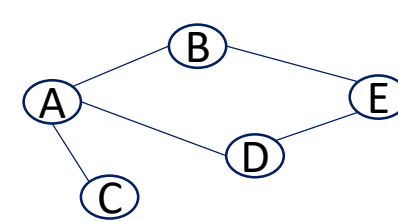
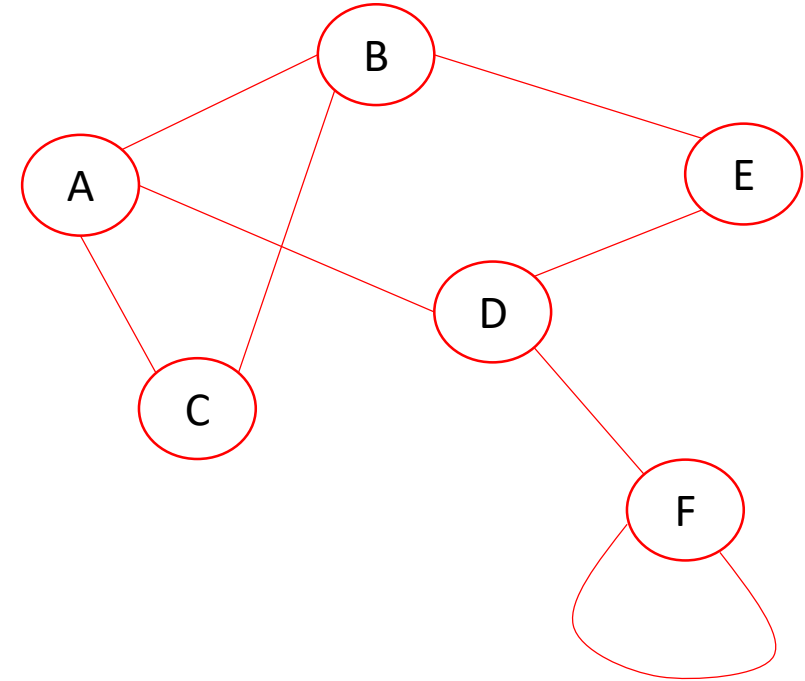
Di-graph

- $V = \{ A, B, C, D, E, F \}$
- $E = \{ \langle A,B \rangle, \langle B,C \rangle, \langle B,E \rangle, \langle C,A \rangle, \langle D,A \rangle, \langle D,E \rangle, \langle D,F \rangle, \langle E,F \rangle, \langle F,D \rangle \}$
- If P is adjacent to Q, then Q is may or may not be adjacent to P.
- Out-degree: Number of edges originated from the node
- In-degree: Number of edges terminated on the node



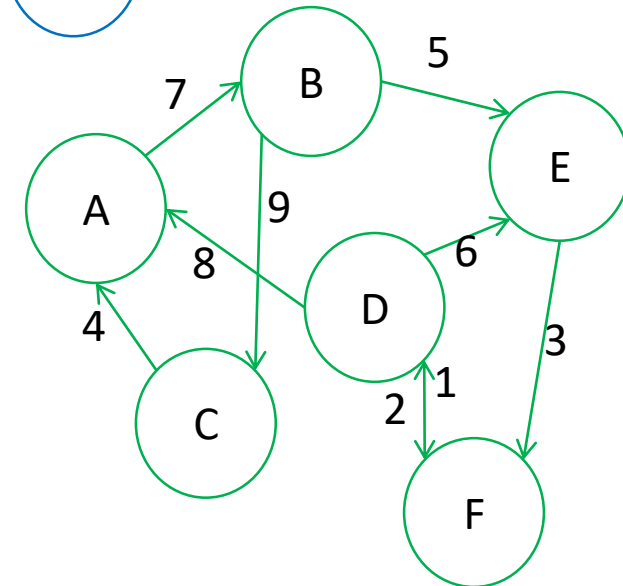
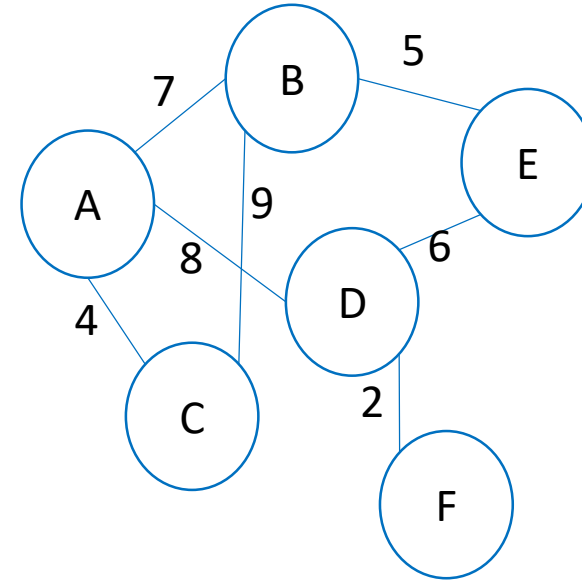
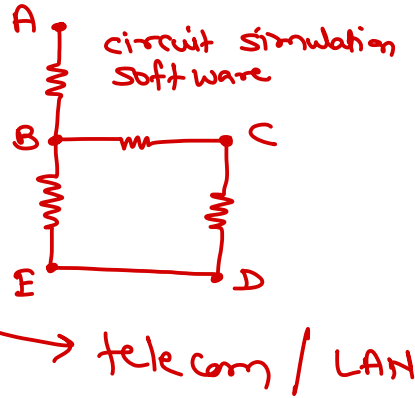
Graph

- Path: Set of edges between two vertices. There can be multiple paths between two vertices.
 - A – D – E
 - A – B – E
 - A – C – B – E
- Cycle: Path whose start and end vertex is same.
 - A – B – C – A
 - A – B – E – D – A
- Loop: Edge connecting vertex to itself. It is smallest cycle.
 - F – F
- Sub-Graph: A graph having few vertices and few edges in the given graph, is said to be sub-graph of given graph.



Graph

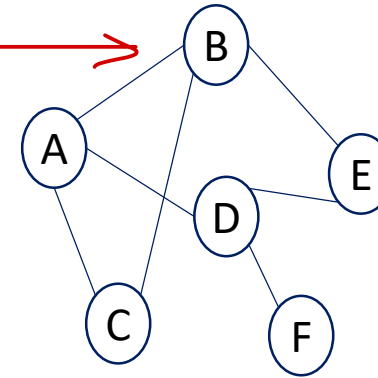
- Weighted graph
 - Graph edges have weight associated with them.
 - Weight represent some value e.g. distance, resistance.
- Directed Weighted graph (Network)
 - Graph edges have directions as well as weights.
- Applications of graph
 - Electronic circuits
 - Social media
 - Communication network
 - Road network
 - Flight/Train/Bus services
 - Bio-logical & Chemical experiments
 - Deep learning (Neural network, Tensor flow)
 - Graph databases (Neo4j)



Graph

- Connected graph

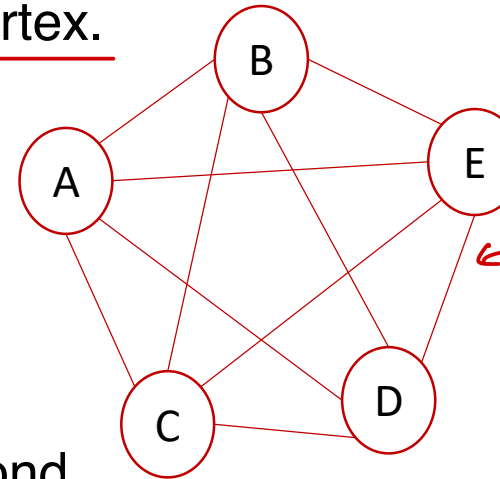
- From each vertex some path exists for every other vertex.
- Can traverse the entire graph starting from any vertex.



- Complete graph

- Each vertex of a graph is adjacent to every other vertex.
- Un-directed graph: Number of edges = $n(n-1) / 2$
- Directed graph: Number of edges = $n(n-1)$

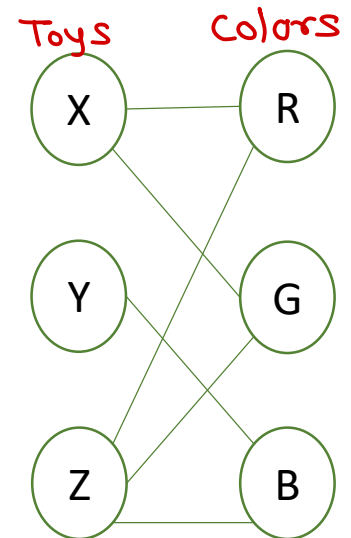
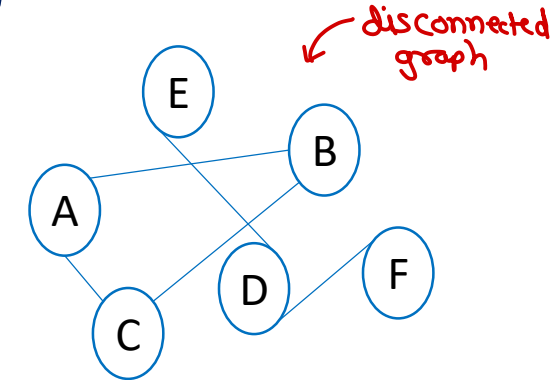
direct edge



*← undirected
Complete
graph*

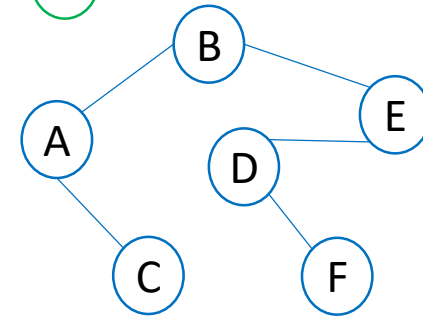
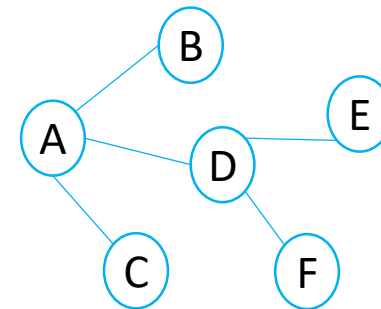
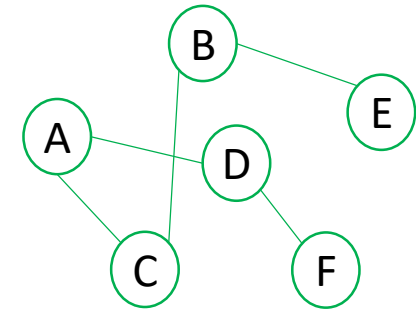
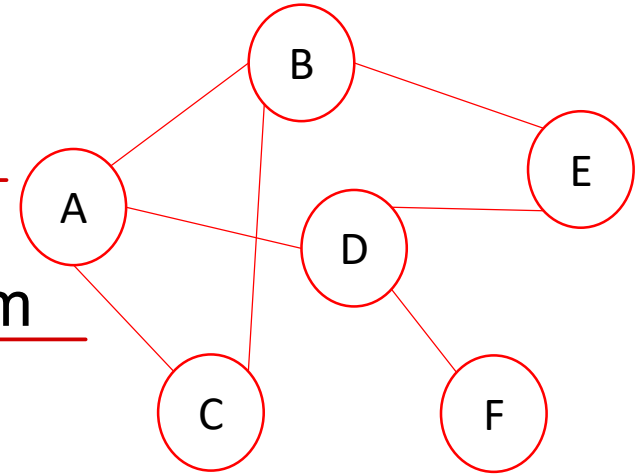
- Bi-partite graph

- Vertices can be divided in two disjoint sets.
- Vertices in first set are connected to vertices in second set.
- Vertices in a set are not directly connected to each other.



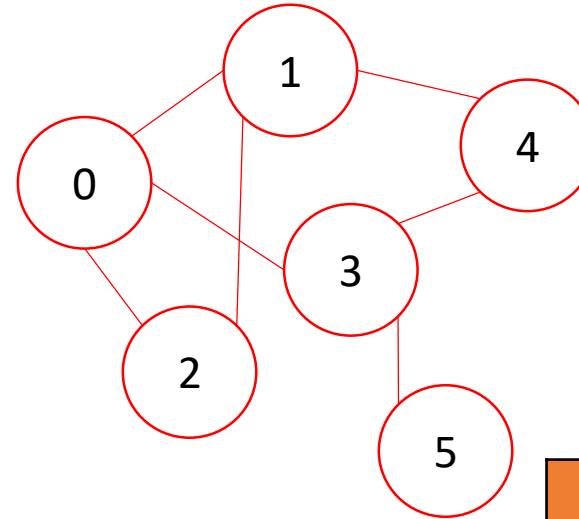
Spanning Tree

- Tree is a graph without cycles.
- Spanning tree is connected sub-graph of the given graph that contains all the vertices and sub-set of edges ($V-1$).
- Spanning tree can be created by removing few edges from the graph which are causing cycles to form.
- One graph can have multiple different spanning trees.
- In weighted graph, spanning tree can be made who has minimum weight (sum of weights of edges). Such spanning tree is called as Minimum Spanning Tree. (MST)
- Spanning tree can be made by various algorithms.
 - BFS Spanning tree
 - DFS Spanning tree
 - Prim's MST
 - Kruskal's MST



Graph Implementation – Adjacency Matrix

- If graph have V vertices, a $V \times V$ matrix can be formed to store edges of the graph.
- Each matrix element represent presence or absence of the edge between vertices.
- For non-weighted graph, 1 indicate edge and 0 indicate no edge.
- For un-directed graph, adjacency matrix is always symmetric across the diagonal.
- Space complexity of this implementation is $O(V^2)$.

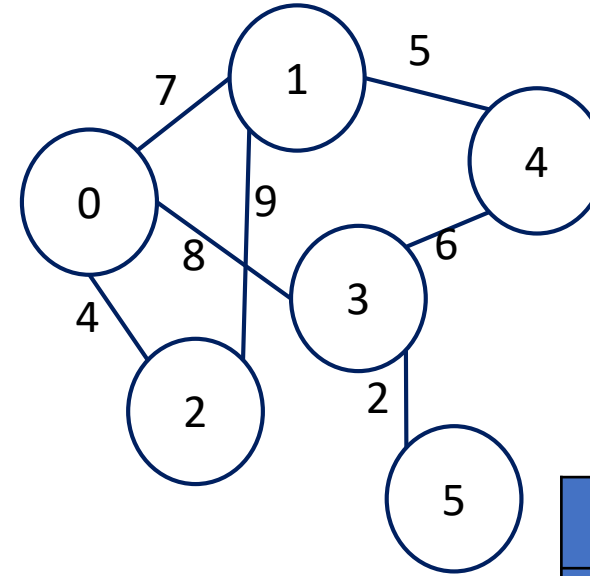


	0	1	2	3	4	5
0	0	1	1	1	0	0
1	1	0	1	0	1	0
2	1	1	0	0	0	0
3	1	0	0	0	1	1
4	0	1	0	1	0	0
5	0	0	0	1	0	0



Graph Implementation – Adjacency Matrix

- If graph have V vertices, a $V \times V$ matrix can be formed to store edges of the graph.
- Each matrix element represent presence or absence of the edge between vertices.
- For weighted graph, weight value indicate the edge and infinity sign ∞ represent no edge.
- For un-directed graph, adjacency matrix is always symmetric across the diagonal.
- Space complexity of this implementation is $O(V^2)$.



	0	1	2	3	4	5
0	∞	7	4	8	∞	∞
1	7	∞	9	∞	5	∞
2	4	9	∞	∞	∞	∞
3	8	∞	∞	∞	6	2
4	∞	5	∞	6	∞	∞
5	∞	∞	∞	2	∞	∞





Thank you!

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